

Automotive Door Control System Design

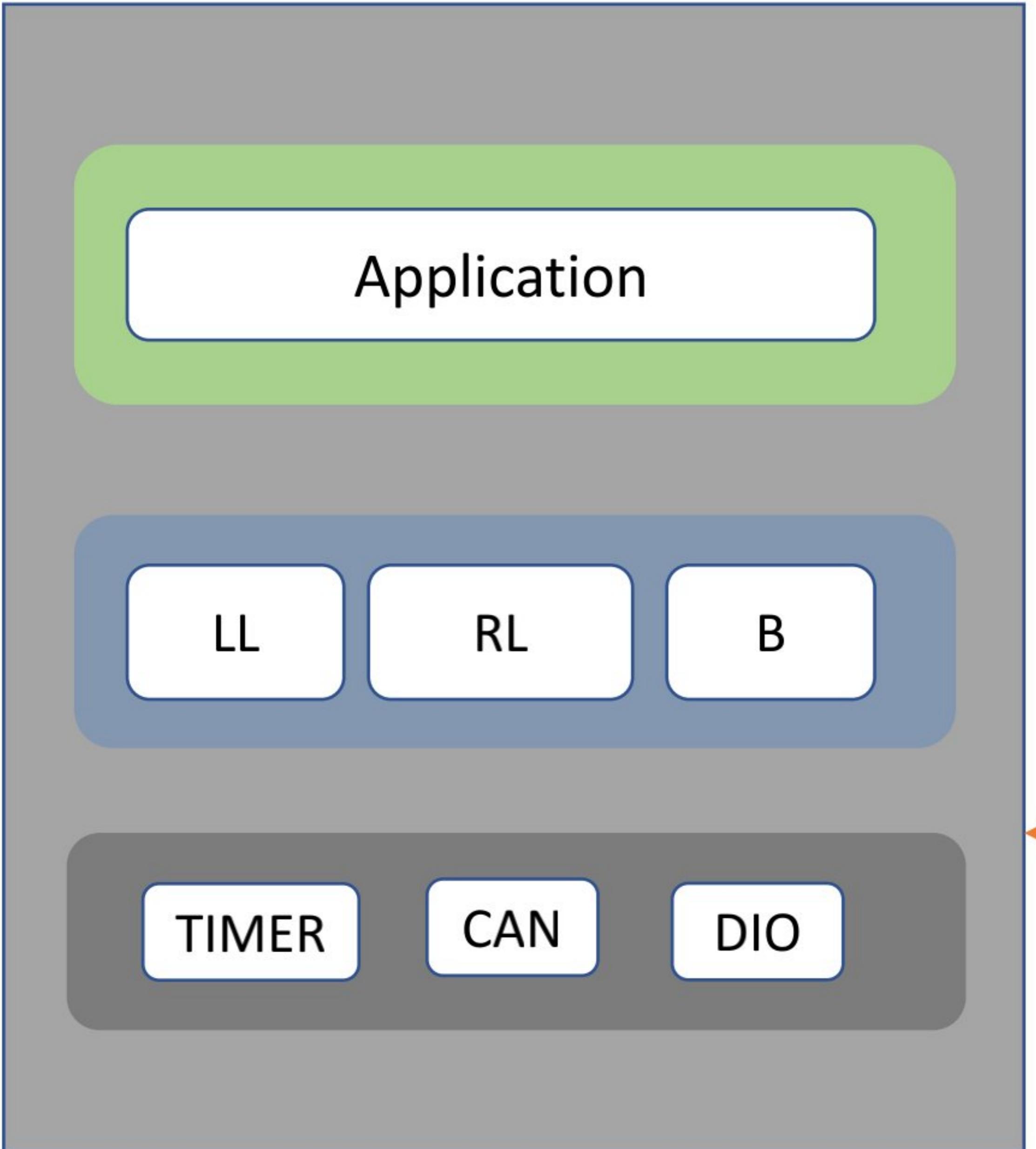
(Static Design)

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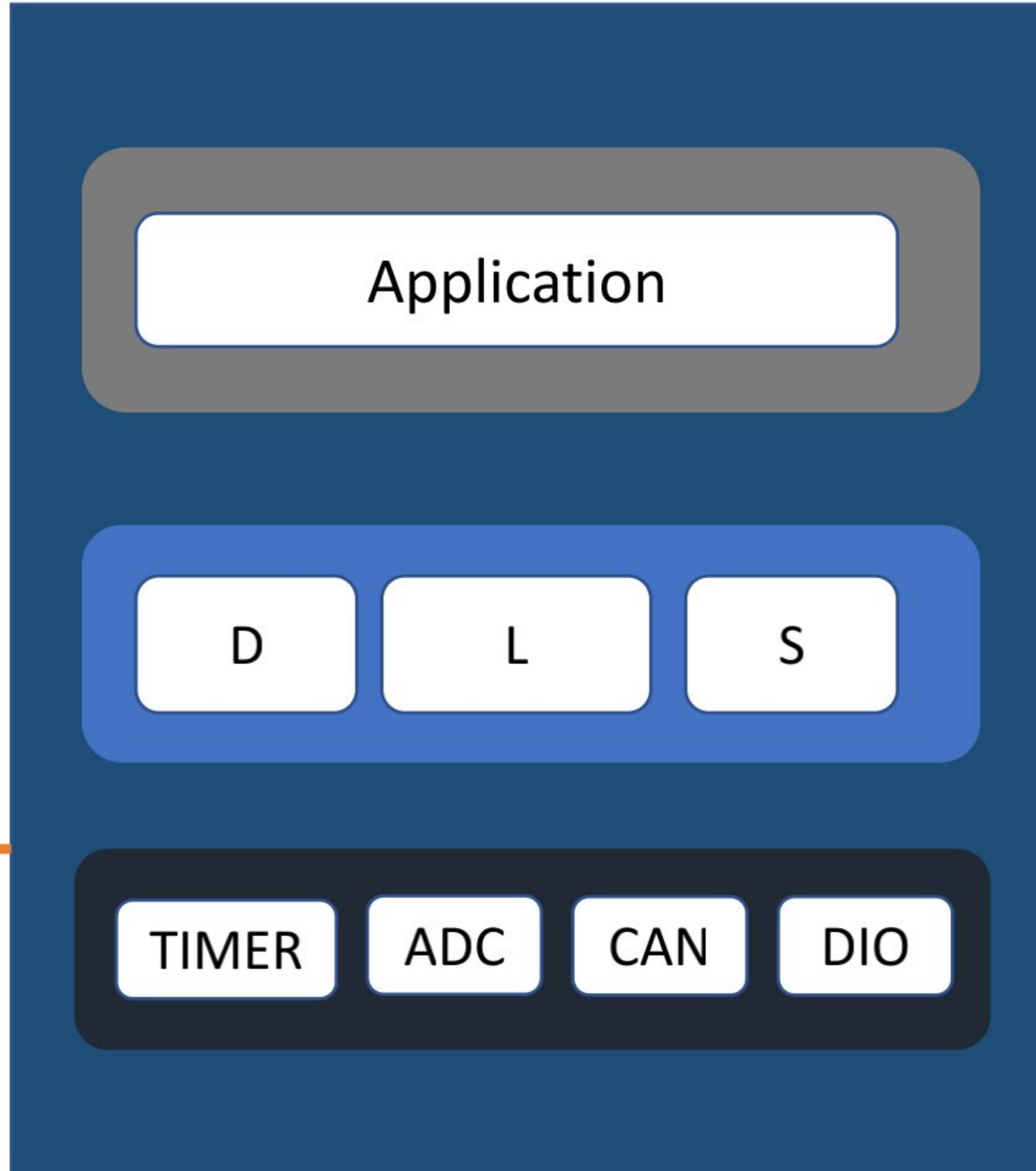
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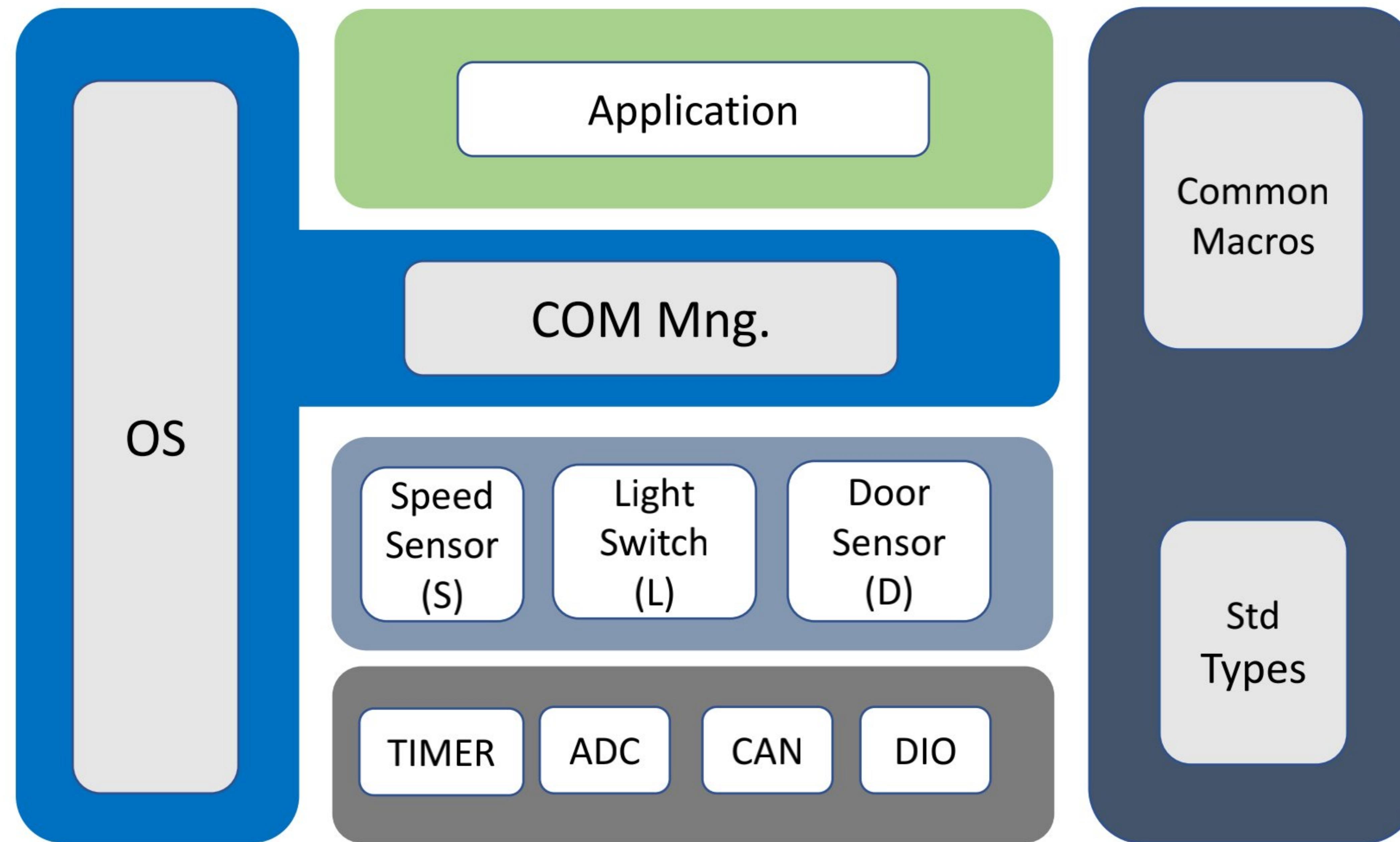
Static Design

ECU2



ECU1





ECU 1

DIO APIs:

Function Name	DIO_Init()	
API Type	Init	
Parameters (INPUT)	DIO_Port DIO_Channel DIO_PinLevel	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	initialization the Dio module	

Function Name	DIO_Read()	
API Type	Getter	
Parameters (INPUT)	DIO_Port DIO_Channel	
Parameters (OUTPUT)	DIO_PinLevel	
Return	E_OK	0
	E_NOK	1
Description	Reading the value of the channel	

Function Name	DIO_Write()	
API Type	Setter	
Parameters (INPUT)	DIO_Channel	
	DIO_PinLevel	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Write on the channel low or high	

Name	DIO_Port
Type	typedef enum
Range	{Port A to PortF }
Description	The decimal number for Port

Name	DIO_Channel
Type	typedef enum
Range	{ PIN0 to PIN7}
Description	The decimal number for Pin

Name	DIO_PinLevel	
Type	typedef enum	
Range	0	Low or Input Direction
	1	High or Output Direction
Description	The direction of the channel or the level on it.	

Timer APIs:

Function Name	TIMER_Inti()	
API Type	Init	
Parameters (INPUTS)	* ConfigPtr	TIMER_ConfigType
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	initialization the timer module	

Function Name	TIMER_Start()	
API Type	-	
Parameters (INPUTS)	Channel	TIMER_ChannelType
	Value	TIMER_ValueType
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Start the timer channel	

Function Name	TIMER_Stop()	
API Type	-	
Parameters (INPUTS)	Channel	TIMER_ChannelType
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Stop the timer channel	

Name	TIMER_ChannelType
Type	Uint8_t
Description	The channel of the timer

Name	TIMER_ValueType
Type	Uint8_t
Description	Type for reading and setting the timer value number of ticks

Name	TIMER_ConfigType
Type	Structure
Description	This structure is including the configuration set required for initializing the timer module

ADC APIs:

Function Name	ADC_Init()	
API Type	Init	
Parameters (INPUTS)	* ConfigPtr ADC_ConfigType	
Parameters (OUTPUT)	None	
Return	E_OK 0	
	E_NOK 1	
Description	initialization the ADC module	

Function Name	ADC_Read ()	
API Type	Init	
Parameters (INPUTS)	Channel	ADC_ChannelType
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	This API to read the value in ADC registers and return it.	

Name	ADC_ChannelType
Type	Uint8_t
Description	This the data of struct including config of ADC

Name	ADC_ConfigType
Type	structure
Description	

CAN APIs:

Function Name	CAN_Init()	
API Type	Init	
Parameters (INPUTS)	* ConfigPtr CAN_ConfigType	
Parameters (OUTPUT)	None	
Return	E_OK E_NOK	0 1
Description	Initializes the CAN Module	

Function Name	CAN_Baudrate()	
API Type		
Parameters (INPUTS)	Controller	Uint8_t
	Baudrate	Uint16_t
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Set the baudrate to CAN Module	

Function Name	CAN_SendData()	
API Type	-	
Parameters (INPUTS)	Data	Uint32_t
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Send the data by the CAN Module	

Function Name	CAN_ReceiveData()	
API Type	Getter	
Parameters (INPUTS)	void	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Receive data from CAN Module	



Name	CAN_ConfigType
Type	structure
Range	
Description	This Structure includes the configuration set required for initializing the CAN

Door Sensor APIs:

Function Name	DoorSen_Init()	
API Type	Init	
Parameters (INPUTS)	None	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Initializes the door sensor module	



Function Name	DoorSen_ReadValue()	
API Type	Getter	
Parameters (INPUTS)	None	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Get the state of door sensor module	



Light Switch APIs:

Function Name	LightSW_Init()	
API Type	Init	
Parameters (INPUTS)	None	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Initializes the Light Switch module	



Function Name	LightSW_ReadValue()	
API Type	Init	
Parameters (INPUTS)	None	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Get the state of Light Switch module	

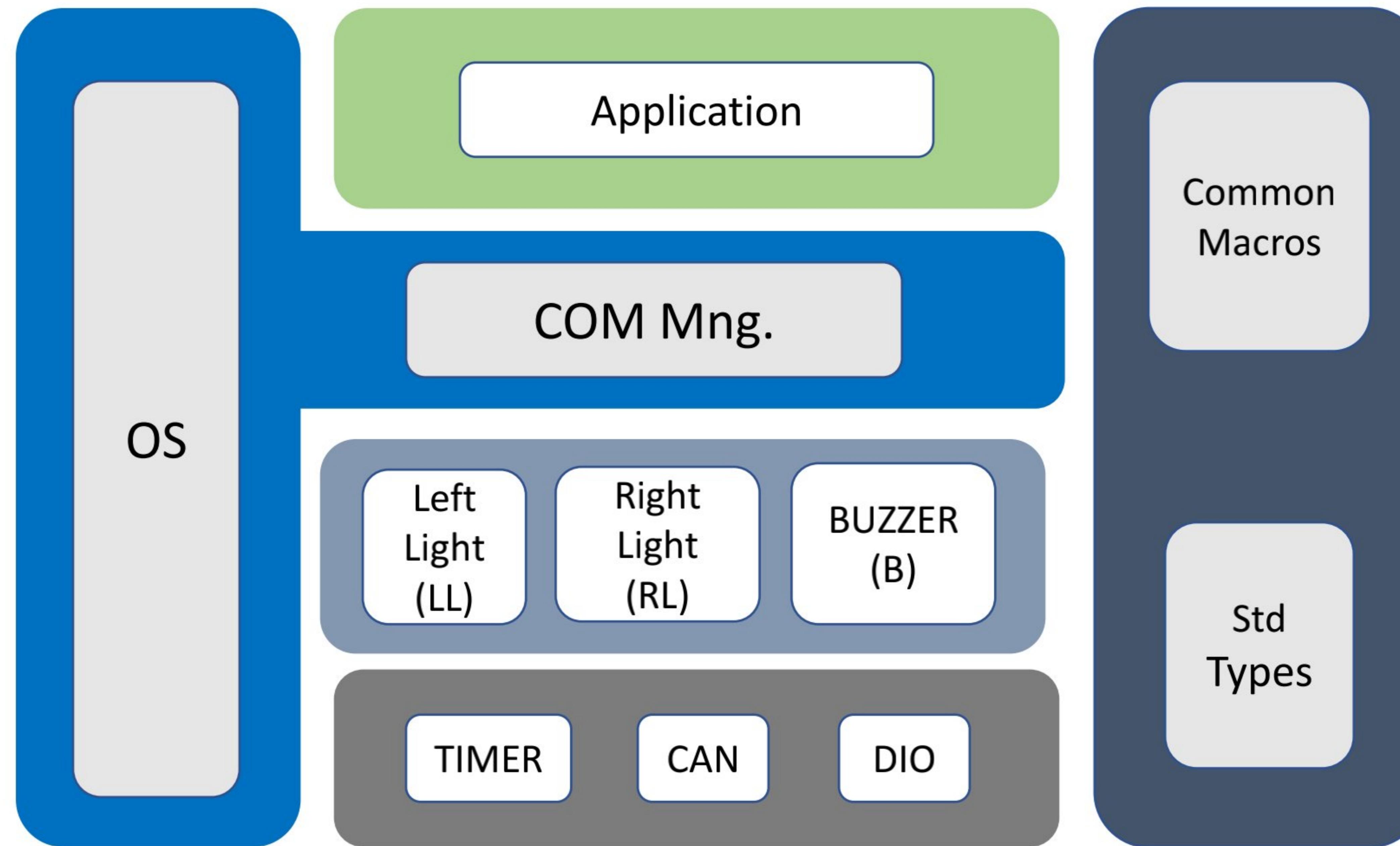


Speed Sensor APIs:

Function Name	SpeedSen_Init()	
API Type	Init	
Parameters (INPUTS)	None	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Initializes the timer module	

Function Name	SpeedSen_ReadValue()	
API Type	Init	
Parameters (INPUTS)	None	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Get the state of Speed Sensor module	





ECU 2

DIO APIs:

Function Name	DIO_Init()	
API Type	Init	
Parameters (INPUT)	DIO_Port DIO_Channel DIO_PinLevel	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	initialization the Dio module	

Function Name	DIO_Read()	
API Type	Getter	
Parameters (INPUT)	DIO_Port	
	DIO_Channel	
Parameters (OUTPUT)	DIO_PinLevel	
Return	E_OK	0
	E_NOK	1
Description	Reading the value of the channel	

Function Name	DIO_Write()	
API Type	Setter	
Parameters (INPUT)	DIO_Channel DIO_PinLevel	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Write on the channel low or high	

Name	DIO_Port
Type	typedef enum
Range	{Port A to PortF }
Description	The decimal number for Port

Name	DIO_Channel
Type	typedef enum
Range	{ PIN0 to PIN7}
Description	The decimal number for Pin

Name	DIO_PinLevel	
Type	typedef enum	
Range	0	Low or Input Direction
	1	High or Output Direction
Description	The direction of the channel or the level on it.	

Timer APIs:

Function Name	TIMER_Inti()	
API Type	Init	
Parameters (INPUTS)	* ConfigPtr TIMER_ConfigType	
Parameters (OUTPUT)	None	
Return	E_OK 0	
	E_NOK 1	
Description	initialization the timer module	

Function Name	TIMER_Start()	
API Type	-	
Parameters (INPUTS)	Channel	TIMER_ChannelType
	Value	TIMER_ValueType
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Start the timer channel	

Function Name	TIMER_Stop()	
API Type	-	
Parameters (INPUTS)	Channel	TIMER_ChannelType
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Stop the timer channel	

Name	TIMER_ChannelType
Type	Uint8_t
Description	The channel of the timer

Name	TIMER_ValueType
Type	Uint8_t
Description	Type for reading and setting the timer value number of ticks

Name	TIMER_ConfigType
Type	Structure
Description	This structure is including the configuration set required for initializing the timer module

CAN APIs:

Function Name	CAN_Init()	
API Type	Init	
Parameters (INPUTS)	* ConfigPtr CAN_ConfigType	
Parameters (OUTPUT)	None	
Return	E_OK E_NOK	0 1
Description	Initializes the CAN Module	

Function Name	CAN_Baudrate()	
API Type		
Parameters (INPUTS)	Controller	Uint8_t
	Baudrate	Uint16_t
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Set the baudrate to CAN Module	

Function Name	CAN_SendData()	
API Type	-	
Parameters (INPUTS)	Data	Uint32_t
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Send the data by the CAN Module	

Function Name	CAN_ReceiveData()	
API Type	Getter	
Parameters (INPUTS)	void	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Receive data from CAN Module	

Name	CAN_ConfigType
Type	structure
Range	
Description	This Structure includes the configuration set required for initializing the CAN

Light Right(LR) APIs:

Function Name	LR_Init()	
API Type	-	
Parameters (INPUTS)	DIO_Port , DIO_Pin	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Initializes the Light Right	

Function Name	LR_ON()	
API Type	-	
Parameters (INPUTS)	DIO_Port , DIO_Pin	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	make Light right on	

Function Name	LR_OFF()	
API Type	-	
Parameters (INPUTS)	DIO_Port , DIO_Pin	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Make Light right off	

Light Left (LL) APIs:

Function Name	LL_Init()	
API Type	-	
Parameters (INPUTS)	DIO_Port , DIO_Pin	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Initializes the Light lift	

Function Name	LL_ON()	
API Type	-	
Parameters (INPUTS)	DIO_Port , DIO_Pin	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Make Light lift on	

Function Name	LL_OFF()	
API Type	-	
Parameters (INPUTS)	DIO_Port , DIO_Pin	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Make Light lift off	

Buzzer (B) APIs:

Function Name	Buzzer_Init()	
API Type	Init	
Parameters (INPUTS)	DIO_Port , DIO_Pin	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Initializes the Buzzer module (make the pin output)	

Function Name	Buzzer_ON()	
API Type	-	
Parameters (INPUTS)	DIO_Port , DIO_Pin	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Turn on the buzzer	

Function Name	Buzzer_OFF()	
API Type	-	
Parameters (INPUTS)	DIO_Port , DIO_Pin	
Parameters (OUTPUT)	None	
Return	E_OK	0
	E_NOK	1
Description	Turn off the buzzer	