

Deliverable 2 - ENG PHYS 2E04  
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**Created Circuit:**

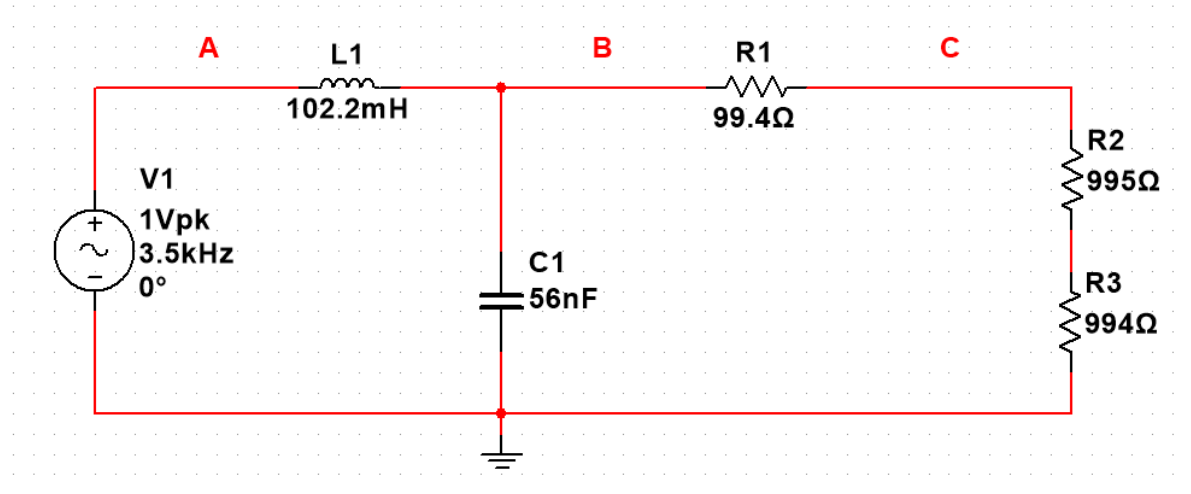


Fig 2.1

The circuit made above has an AC power source that has an amplitude of 1 V and a frequency of 3.5 kHz. The circuit also consists of 3 resistors, 1 capacitor and 1 inductor. The above circuit will be used to calculate the values of the voltage at nodes A, B and C, which will lead to finding the voltage and current through R1, C1, and L1.

The lab involves solving it in several ways. Firstly, solving it analytically, I used the voltage divider method and ohms law, and the nodal analysis method. Then, solving it digitally, where I used a single frequency sweep in Multisim to find the real and imaginary parts of each value, and then used a normal oscilloscope to compare solutions with the analytical method. Finally, solving it physically, where I used the breadboard, a Hantek 2D42, and oscilloscope from my lab kit.

The values of the resistors and capacitors was measured using the Hantek 2D42. However, the value obtained for the inductor was through averaging inductor values obtained by a VICHY LCR Meter DM4070.

Component	Actual Value	Measured Value
R1	100.0Ω	99.3Ω
R2	1000.0Ω	994.0Ω
R3	1000.0Ω	995.0Ω
C1	100.0nF	56.0nF
L1	100.0mH	102.2mH

Table 2.1

### Analytical Method

Using Maple Code, I outlined the results gotten from the formulas below. These formulas below were obtained using:

#### 1. Voltage divider and Ohms law

```

> restart :
> f := 3500 : w := 2·π·f : R1 := 99.4 : R2 := 995 : R3 := 994 : L1 := 102.2e-3 : C1 := 5.6e-8 :
> Reff := R1 + R2 + R3;
Reff := 2088.4 (1)
> VA := 1
VA := 1 (2)
> ZC := 1 / (I·w·C1);
ZC := -812.0150158 I (3)
> ZL := I·w·L1;
ZL := 2247.495385 I (4)
> Zpar := (1 / Reff + 1 / ZC)⁻¹;
Zpar := 274.2649806 - 705.3748691 I (5)
> VB := Zpar / (Zpar + ZL) · VA;
VB := -0.4127209337 - 0.2512513617 I (6)
> VC := (R2 + R3) / Reff · VB;
VC := -0.3930769667 - 0.2392927401 I (7)

> abs(VB); argument(VB); DeltaTVB := % / w;
0.4831830045
-2.594750912
DeltaTVB := -0.0001179906953 (8)

> abs(VC); argument(VC); DeltaTVC := % / w;
0.4601853075
-2.594750912
DeltaTVC := -0.0001179906953 (10)

```

Fig 2.2

- ❖ The voltage **VA** is the same as the source voltage and can be written in phasor form as

$$VA = 1e^{j0} = 1 \text{ V}$$

- ❖ The angular frequency, **ω** is calculated using the formula:

- $\omega = 2\pi f$

- $\omega = (2) (\pi) (3500) = \mathbf{21991.149 \text{ rad/s}} \approx \mathbf{22000 \text{ rad/s}}$

- ❖ The impedances, **ZR, ZL, and ZC**, of the components are calculated. **ZR** is the same as the value for **Reff**. On the other hand, the complex impedances **ZC** and **ZL** are calculated as follows:

- $ZR = R_{eff}$

- $ZL = j\omega L$

- $ZC = \frac{1}{j\omega C}$

- ❖ **VB** can be calculated by using the voltage divider formula. However, **ZC** and **Reff** need to be combined to find **VB**. Generally, Impedances can be treated like resistors and can be combined using the parallel resistor formula giving  $Z_{parallel}$

$$Z_{parallel} = \left( \frac{1}{R_{eff}} + \frac{1}{Z_c} \right)^{-1}$$

- ❖ **VB** is then calculated as follows:

$$VB = \frac{Z_{parallel}}{ZL + Z_{parallel}} \cdot VA$$

This gives a value in phasor form:

$$VB = 0.483e^{-j2.59} \text{ V}$$

- ❖ **VC** is also calculated using a voltage divider:

$$VC = \frac{R2 + R3}{R_{eff}} * VB$$

The value (phasor form) obtained is:

$$VC = 0.460e^{-j2.59}V$$

- ❖ The  $\Delta t$  for **VB**, **VC** and **IR** is calculated, and all give a result of  
 $\Delta t = 117.99 \mu s$

Therefore, we can find both the current and voltage through R1, C1, and L1.

➤ **Voltage: (Using Voltage Divider):**

- ❖  $VR_1 = VB - VC$
- ❖  $VL_1 = VA - VB$
- ❖  $VC_1 = VB - 0 = VB$

➤ **Current: (Using Ohms Law):**

- ❖  $IR_1 = \frac{VB}{R_{eff}}$
- ❖  $IL_1 = \frac{VL_1}{ZL_1}$
- ❖  $IC_1 = \frac{VC_1}{ZC_1}$

Qais Abu El Haija, abuelhaq  
400294443

### Maple Output and code:

```

"
> VRI := VB - VC; abs(VRI); argument(VRI); polar(VRI);
VRI := -0.0196439670 - 0.0119586216 I
0.02299769706
-2.594750910
polar(0.02299769706, -2.594750910)
(10)
"
> VLI := VA - VB; abs(VLI); argument(VLI); polar(VLI);
VLI := 1.412720934 + 0.2512513617 I
1.434889433
0.1760089093
polar(1.434889433, 0.1760089093)
(11)
"
> VCI := VB - 0; abs(VCI); argument(VCI); polar(VCI);
VCI := -0.4127209337 - 0.2512513617 I
0.4831830045
-2.594750912
polar(0.4831830045, -2.594750912)
(12)
"
> IRI :=  $\frac{VB}{Reff}$ ; abs(IRI); argument(IRI); polar(IRI);
IRI := -0.0001976254231 - 0.0001203080644 I
0.0002313651621
-2.594750912
polar(0.0002313651621, -2.594750912)
(13)
"
> ILI :=  $\frac{VLI}{ZL}$ ; abs(ILI); argument(ILI); polar(ILI);
ILI := 0.0001117917142 - 0.0006285756774 I
0.0006384393233
-1.394787417
polar(0.0006384393233, -1.394787417)
(14)
"
"
> ICI :=  $\frac{VCI}{ZC}$ ; abs(ICI); argument(ICI); polar(ICI);
ICI := 0.0003094171374 - 0.0005082676129 I
0.0005950419575
-1.023954585
polar(0.0005950419575, -1.023954585)
(15)
>

```

Figure 2.3

## 2. Nodal Analysis:

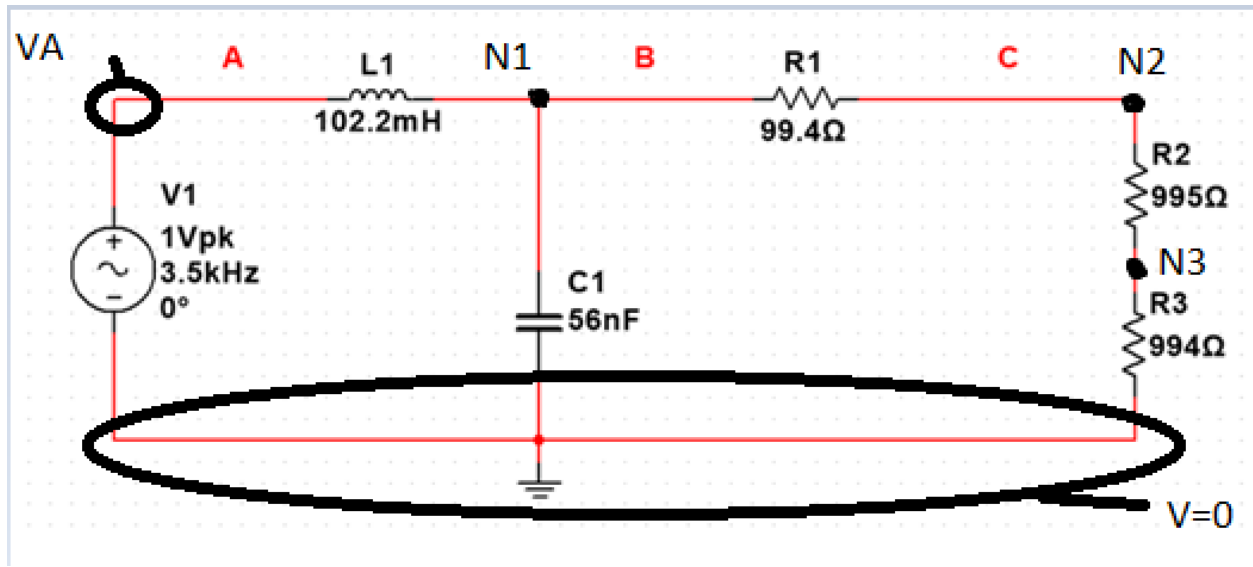


Figure 2.4

N1 = Voltage 1  
N2 = Voltage 2  
N3 = Voltage at R3

- V1:

$$\frac{V_A - V_1}{Z_L} + \frac{V_2 - V_1}{R_1} + \frac{0 - V_1}{Z_C} = 0$$

- V2:

$$\frac{V_1 - V_2}{R_1} + \frac{V_{R3} - V_2}{R_2} = 0$$

- VR3:

$$\frac{V_2 - V_{R3}}{R_2} = \frac{V_{R3}}{R_3}$$

### Maple Code and Output:

```
> RESTART:
f:=3500: T:=1/f; w:=2*3.14159*f; C1:= 5.6e-8: L1:=102.2e-3:
R1:=99.4: R2:=995: R3:=994:
ZC:=1/(w*I*C1); ZL:=I*w*L1;
VA:=1:
solve([(VA-V1)/ZL+(V2-V1)/R1+(0-V1)/ZC=0,
(V1-V2)/R1+(VR3-V2)/R2=0, (V2-VR3)/R2=VR3/R3])
```

$$T := \frac{1}{3500}$$

$$w := 21991.13000$$

$$ZC := -812.0157016I$$

$$ZL := 2247.493486I$$

$$\{V1 = -0.4127216218 - 0.2512522349I, V2 = -0.3930776218 - 0.2392935717I, VR3 = -0.1964399980 - 0.1195866316I\}$$

(1)

Figure 2.5

### Finding the Voltage and current along R1, L1, and C1:

```
> w:=2*3.14159*f;V1 := -0.4127216218 - 0.2512522349*I:
V2 := -0.3930776218 - 0.2392935717*I: VR3 := -0.1964399980 - 0.1195866316*I:
VR1:=V1-V2;
magnitudeVR1:=abs(VR1); phaseVR1:=argument(VR1);DeltaTVR1:=%/w; vR1:=Re (VR1);
VC1:=V1-0;
magnitudeVC1:=abs(VC1); phaseVC1:=argument(VC1);DeltaTVC1:=%/w;
VL1:=VA-V1;
magnitudeVL1:=abs(VL1); phaseVL1:=argument(VL1);DeltaTVL1:=%/w;
```

$$VR1 := -0.0196440000 - 0.0119586632I$$

$$\text{magnitudeVR1} := 0.02299774688$$

$$\text{phaseVR1} := -2.594750111$$

$$\text{DeltaTVR1} := -0.0001179907586$$

$$vR1 := -0.0196440000$$

$$VC1 := -0.4127216218 - 0.2512522349I$$

$$\text{magnitudeVC1} := 0.4831840463$$

$$\text{phaseVC1} := -2.594750109$$

$$\text{DeltaTVC1} := -0.0001179907585$$

$$VL1 := 1.412721622 + 0.2512522349I$$

$$\text{magnitudeVL1} := 1.434890263$$

$$\text{phaseVL1} := 0.1760094245$$

$$\text{DeltaTVL1} := 8.003655315 \times 10^{-6}$$

(2)

Figure 2.6

Qais Abu El Haija, abuelhaq

400294443

```
> VR1 := -0.0196440000 - 0.0119586632*I; VC1 := -0.4127216218 - 0.2512522349*I;
VL1 := 1.412721622 + 0.2512522349*I; f:=3500; w:=2*3.14159*f;

IR1:=(VR1)/R1;
magnitudeIR1:=abs(IR1); phaseIR1:=argument(IR1);DeltaTIR1:=%/w;
IL1:=VL1/(ZL);
magnitudeIL1:=abs(IL1); phaseIL1:=argument(IL1);DeltaTIL1:=%/w;
IC1:=(VC1)/ZC;
magnitudeIC1:=abs(IC1); phaseIC1:=argument(IC1);DeltaTIC1:=%/w;

IR1 := -0.0001976257545 - 0.0001203084829 I
magnitudeIR1 := 0.0002313656627
phaseIR1 := -2.594750111
DeltaTIR1 := -0.0001179907586
IL1 := 0.0001117921972 - 0.0006285765146 I
magnitudeIL1 := 0.0006384402322
phaseIL1 := -1.394786902
DeltaTIL1 := -0.00006342497643
IC1 := 0.0003094179514 - 0.0005082680310 I
magnitudeIC1 := 0.0005950427379
phaseIC1 := -1.023953782
DeltaTIC1 := -0.00004656212673
```

Figure 2.7

**Values using both analytical methods, (Voltage Divider & Ohms Law, and Nodal Analysis), where relatively identical (Reason: Pi was used differently in each of the methods).**

### Summary of Analytical results:

Value	Rectangular	Polar (phase reported in radians)
VA	1 V	1, 0 V
VB	(-0.4127209337 - 0.2512513617*I) V	0.4831830045, -2.594750111 V
VC	(-0.3930769667 - 0.2392927401*I) V	0.46018530750, -2.594750111 V
VR1	(-0.0196440000 - 0.0119586632*I) V	0.02299774688, -2.594750111 V
VC1	(-0.4127216218 - 0.2512522349*I) V	0.4831840463, -2.594750109 V
VL1	(1.412721622 + 0.2512522349*I) V	1.434890263, 0.1760094245 V
IR1	(-0.0001976257545 - 0.0001203084829*I) A	0.0002313656627, -2.594750111 A
IC1	(0.0003094179514 - 0.0005082680310*I) A	0.0005950427379, -1.023953782 A
IL1	(0.0001117921972 - 0.0006285765146*I) A	0.0006384402322, -1.394786902 A

Table 2.2



## Multisim Method

(a) Using the **Single Frequency sweep** simulation in Multisim to find the real and imaginary parts of each value.

Circuit

The circuit diagram shows an AC voltage source **V1** with a peak voltage of **1Vpk**, a frequency of **3.5kHz**, and a phase of **0°**. It is connected in series with an inductor **L1** having an inductance of **102.2mH**. Following the inductor, the circuit splits into two parallel branches. The first branch contains a capacitor **C1** with a capacitance of **56nF** connected to ground. The second branch contains a resistor **R1** (**99.4Ω**) in series with a series combination of two resistors, **R2** (**995Ω**) and **R3** (**994Ω**), which are also connected to ground. Measurement points **A**, **B**, and **C** are indicated at the input of the inductor, the node after the parallel branches, and the output of the resistor network, respectively.

Single  
frequency

## Design1

### Single Frequency AC Analysis @ 3500 Hz

	Variable	Real	Imaginary
1	V(a)	1.00000	0.00000e+00
2	V(b)	-412.72093 m	-251.25136 m
3	V(c)	-393.07697 m	-239.29274 m
4	I(C1)	-309.41714 u	508.26761 u
5	I(R1)	-197.62542 u	-120.30806 u
6	I(L1)	111.79171 u	-628.57568 u

Table 2.3

Inputing Values of **VA** and **VB** obtained by the single frequency simulation to find the voltage and current of **R1**, **C1**, and **L1**:

```
> f:=35000: w:=2*3.14159*f:
VA:=1: VB:=-0.41272093-0.25125136*I: VC:=-0.39307697
-0.23929274*I:
VR1:=VB-VC;
magnitudeVR1:=abs(VR1); phaseVR1:=argument(VR1);
DeltaTVR1:=%/w; vR1:=Re (VR1);
VC1:=VB-0;
magnitudeVC1:=abs(VC1); phaseVC1:=argument(VC1);
DeltaTVC1:=%/w;
VL1:=VA-VB;
magnitudeVL1:=abs(VL1); phaseVL1:=argument(VL1);
DeltaTVL1:=%/w;
```

```
VR1 := -0.01964396 - 0.01195862 I
magnitudeVR1 := 0.02299769025
phaseVR1 := -2.594750812
DeltaTVR1 := -0.00001179907905
vR1 := -0.01964396
VC1 := -0.41272093 - 0.25125136 I
magnitudeVC1 := 0.4831830005
phaseVC1 := -2.594750911
DeltaTVC1 := -0.00001179907950
VL1 := 1.41272093 + 0.25125136 I
magnitudeVL1 := 1.434889428
phaseVL1 := 0.1760089086
DeltaTVL1 := 8.003631855 × 10-7
```

(1)

```
> f:=35000: w:=2*3.14159*f:
VA:=1: VB:=-0.41272093-0.25125136*I: VC:=-0.39307697
-0.23929274*I:f := 3500:
w := 2*Pi*f:
R1 := 99.4:
R2 := 995:
R3 := 994:
L1 := 0.1022:
C1 := 0.56*10^(-7):Reff := R1 + R2 + R3:ZC := 1/(w*C1*
I):ZL := w*L1*I:|
IR1:=VB/Reff;
magnitudeIR1:=abs(IR1); phaseIR1:=argument(IR1);
DeltaTIR1:=%/w;
IL1:=(VA-VB)/ZL;
magnitudeIL1:=abs(IL1); phaseIL1:=argument(IL1);
DeltaTIL1:=%/w;
IC1:=(VB-0)/ZC;
magnitudeIC1:=abs(IC1); phaseIC1:=argument(IC1);
DeltaTIC1:=%/w;
IR1 := -0.0001976254214 - 0.0001203080636 I
magnitudeIR1 := 0.0002313651602
phaseIR1 := -2.594750911
DeltaTIR1 := -0.0001179906953
IL1 := 0.000117917134 - 0.0006285756756 I
magnitudeIL1 := 0.0006384393214
phaseIL1 := -1.394787418
DeltaTIL1 := -0.00006342494631
IC1 := 0.0003094171353 - 0.0005082676083 I
magnitudeIC1 := 0.0005950419525
phaseIC1 := -1.023954584
DeltaTIC1 := -0.00004656212387
```

(1)

Figure 2.8

(b) Using the normal oscilloscope:

❖ **VA & VB:**

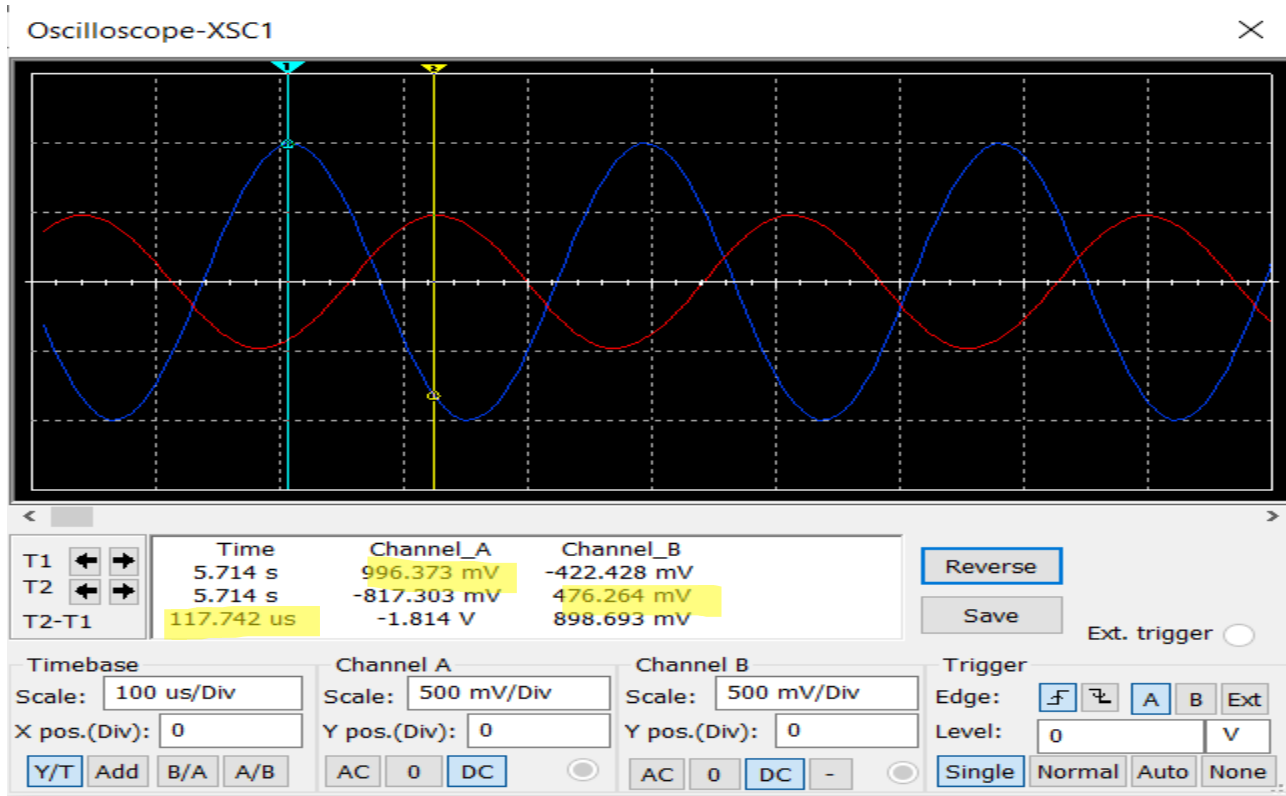
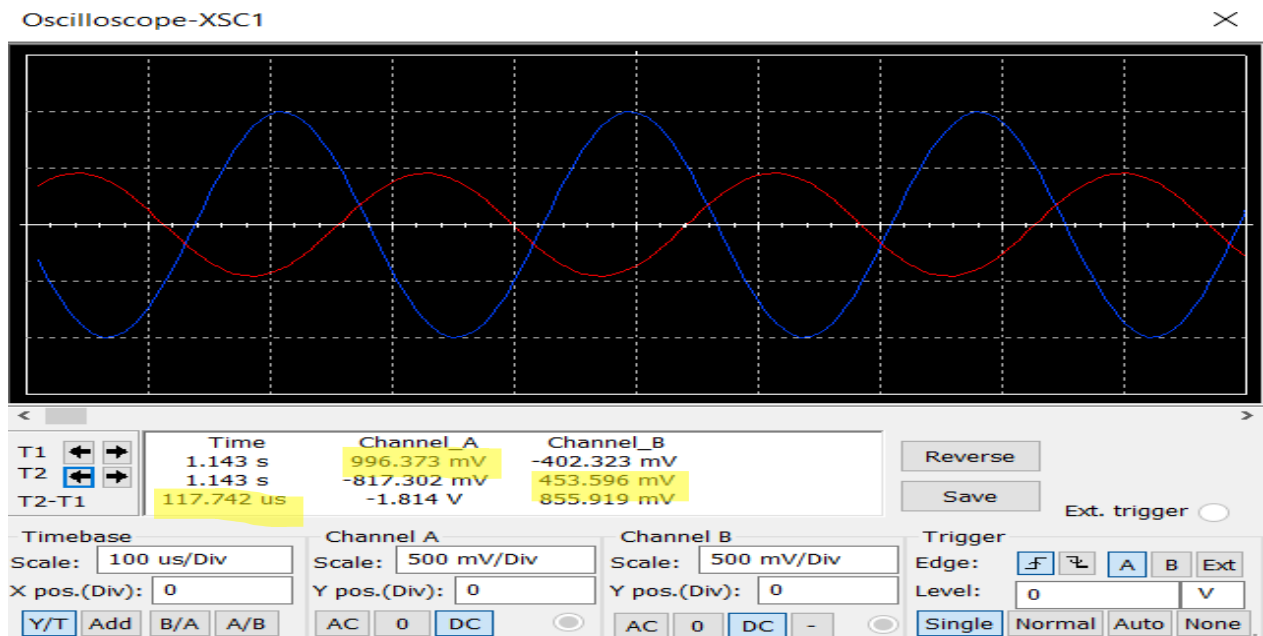


Figure 2.9

❖ **VA & VC:**



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The Oscilloscope read values of **VA**, **VB**, **VC**, and **deltaT**. **VA** is **996.373mV**, **VB** is **476.364mV** and **VC** is **453.596 mV**. The value of **deltaT** is **117.742  $\mu$ s**.

These values are very close compared to the values obtained using the analytical method as can be seen in the table below comparing them.

Value	Analytical	Multisim
VA	1.000V	0.996V
VB	0.483V	0.476V
VC	0.460V	0.454V
$\Delta t$	117.991 $\mu$ s	117.742 $\mu$ s

Table 2.4

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### **Experimental Method**

The circuit was set up tentatively using the at Home-Kit, a breadboard, and using the Hantek as the fundamental source AC voltage. Also, jumper links were used as the wires as displayed beneath:

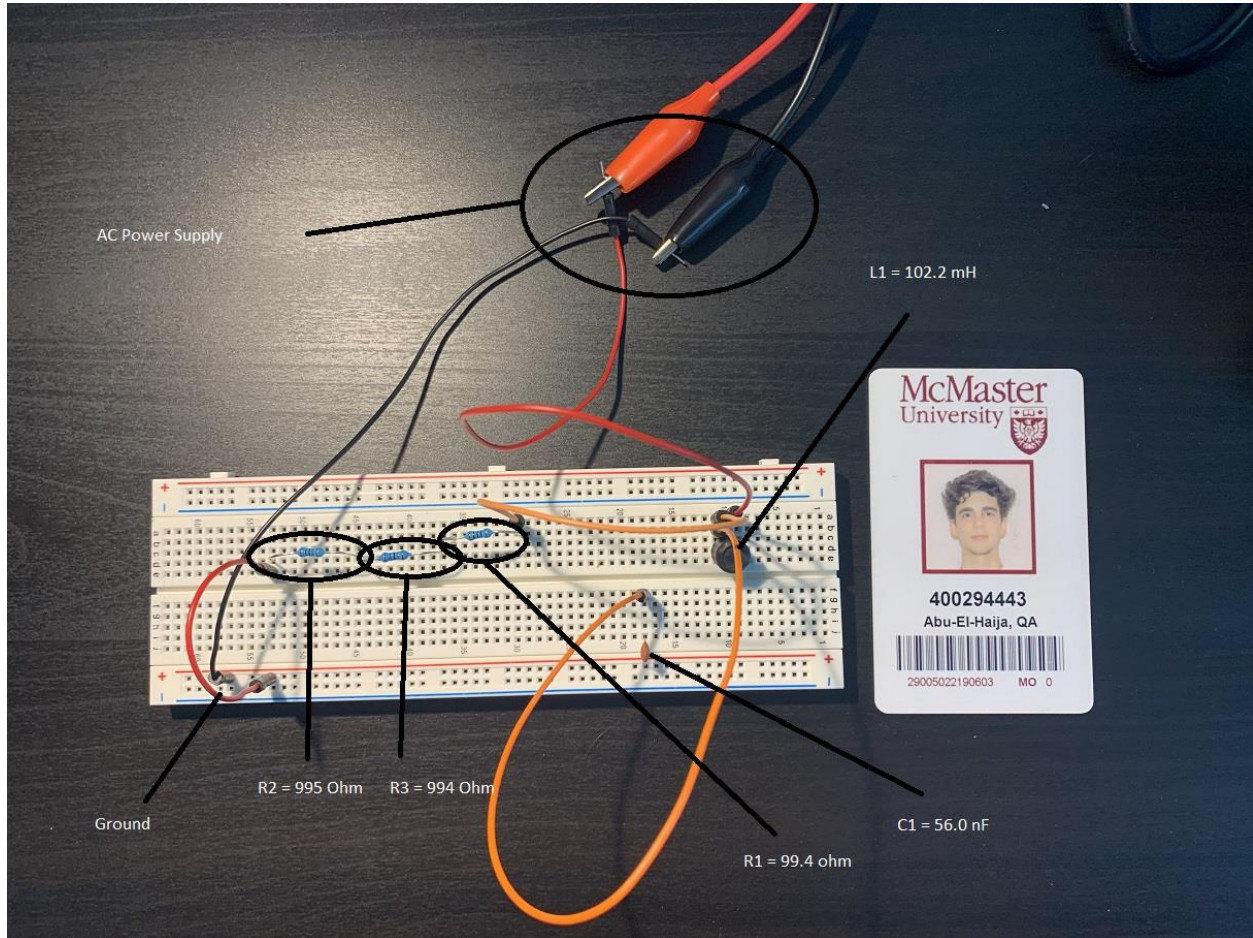


Figure 2.11

***AC Supply properties:***

***Frequency = 3.5 kHz***

***Amplitude = 1V***



- The Hantek was used to supply the power to the circuit. As mentioned above, it was set as follows:



Figure 2.12

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- The picture below shows the voltage measured at Node A, **VA**. According to the Hantek, **VA** has a max of **1.14V** and a minimum of **-900mV**. The frequency is **3.52KHz**.

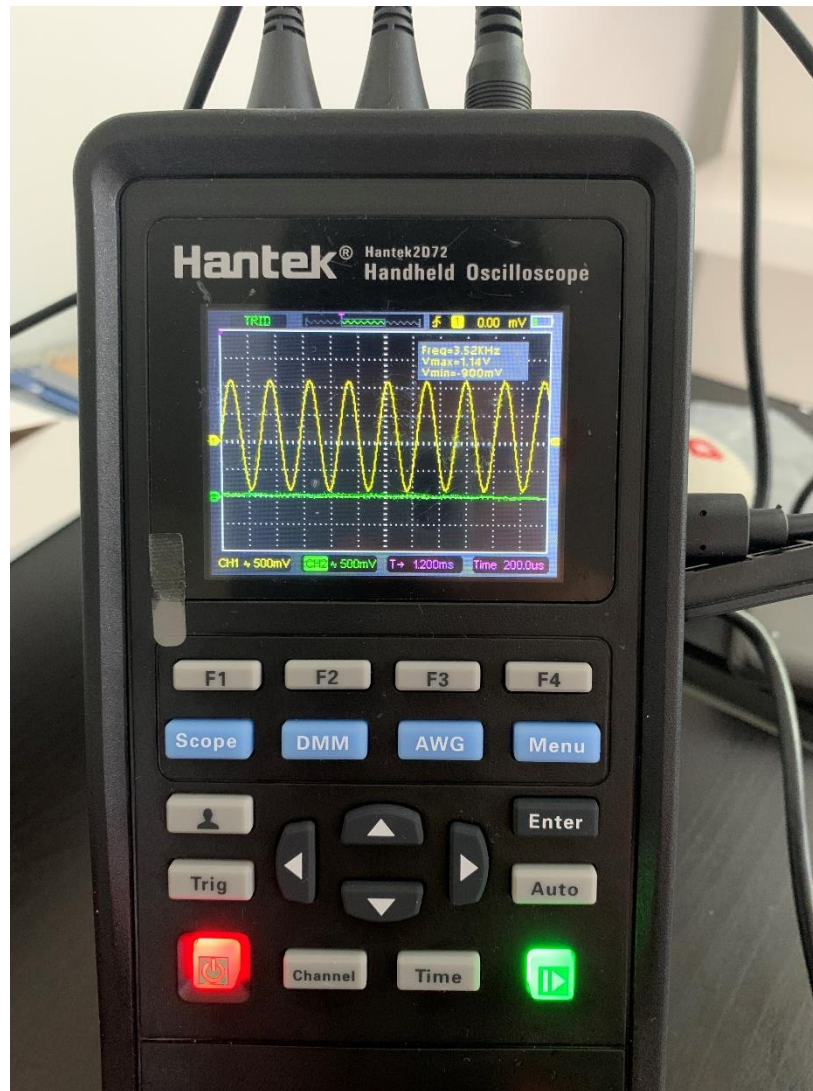


Figure 2.13



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- The picture below shows the voltage measured at Node B, **VB**. According to the Hantek, **VB** has a max of **480mV** and a minimum of **-460mV**. The frequency is **3.50KHz**.

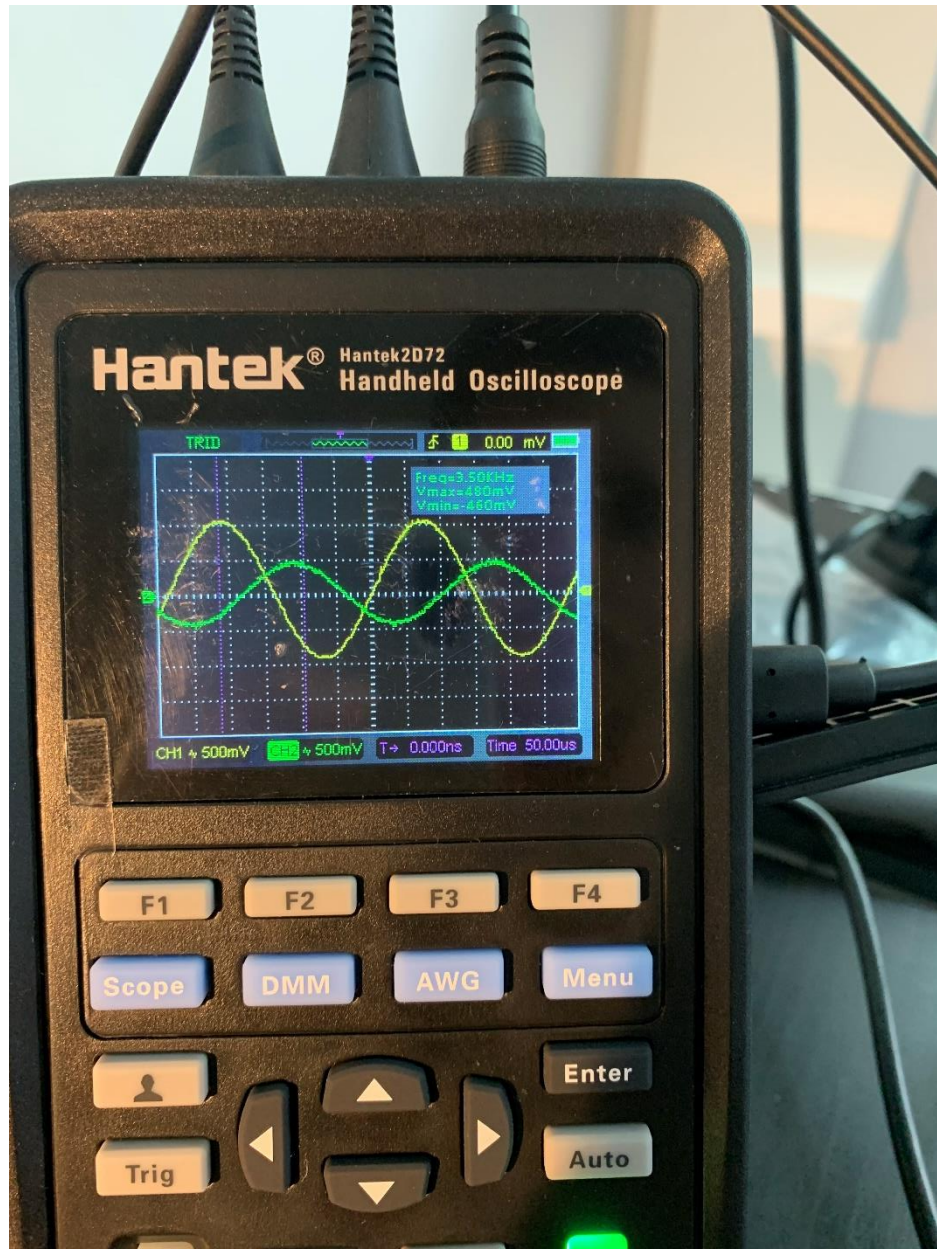


Figure 2.14



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- The picture below shows the voltage measured at Node C, **VC**. According to the Hantek, **VC** has a max of **456mV** and a minimum of **-472mV**. The frequency is **3.48KHz**.

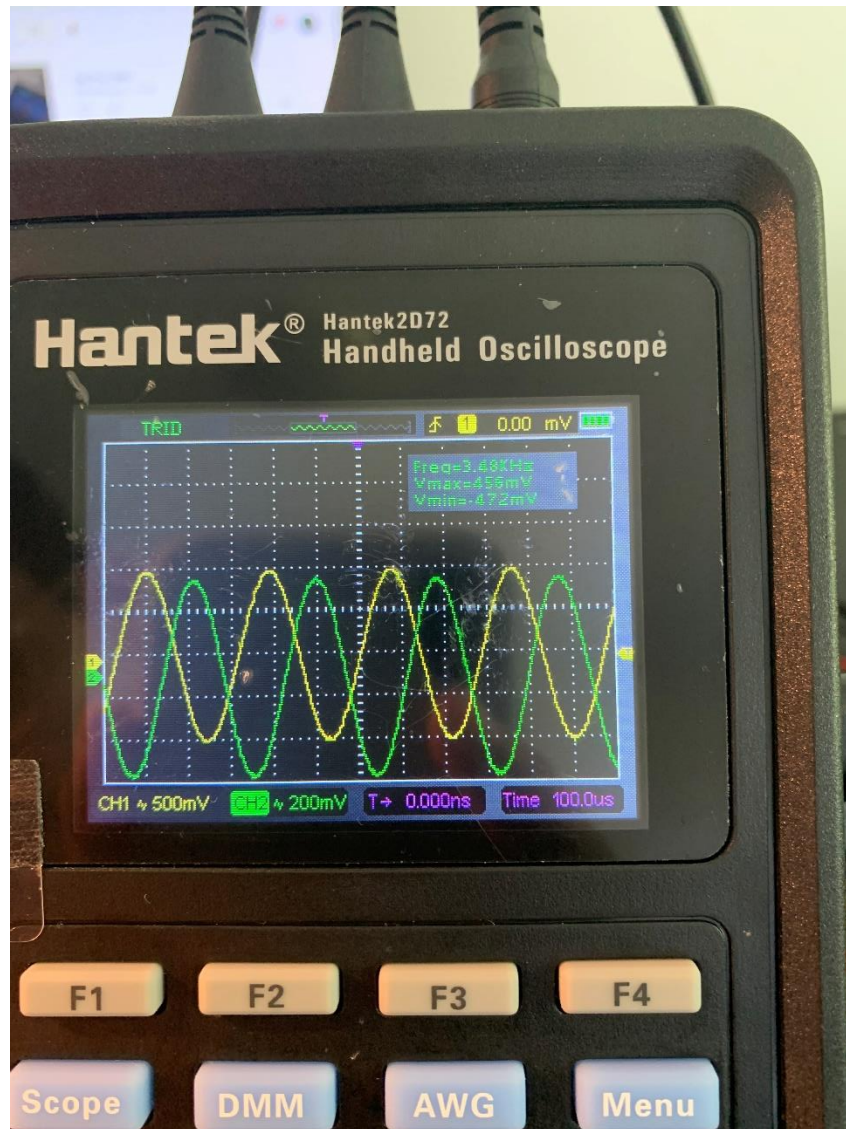


Figure 2.15

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- The  $\Delta t$  was measured between the two waves, through all nodes, using the **cursor function** and a value of **118  $\mu$ s** was obtained.

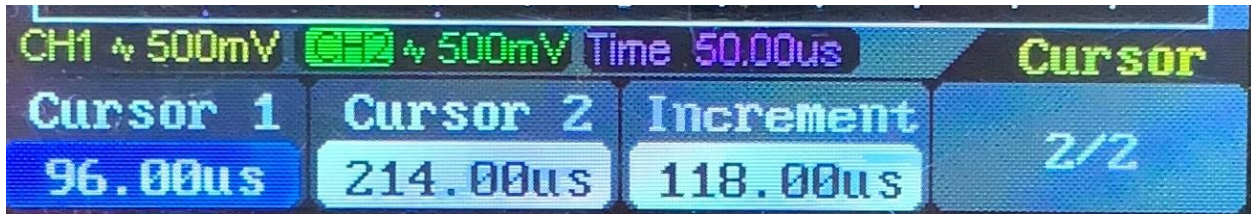


Figure 2.16

**EXTRA: (Just used for result analysis)**

- The current through the resistor **R1** was measured and a value of **0.218mA** was obtained.



Figure 2.17

**Results comparisons:**

Value	Analytical	Multisim	Experimental
VA	1.000V	1.000V	$1.000 \pm 0.1V$
VB	0.483V	0.476V	$0.480 \pm 0.02V$
VC	0.460V	0.454V	$0.456 \pm 0.02V$
I in R1	0.231mA	0.231mA	$0.218 \pm 0.003mA$
$\Delta t$ B and A	117.991 $\mu s$	117.742 $\mu s$	118.000 $\mu s$
$\Delta t$ C and A	117.991 $\mu s$	117.742 $\mu s$	118.000 $\mu s$

Table 2.5

***Analysis:***

The values obtained from the Analytical and Multisim methods are very similar, where the bound of error is rounded to approximately 1%. The voltage and current going through R1, C1, and L1 were obtained most feasibly and expediently, as their values in the analytical part and Multism were almost identical. Looking at the experimental values, there was a significant difference in some readings relative to the analytical and Multisim methods. The errors for the voltage measurements and DeltaT measurements are below 1% indicating they are accurate. There is a difference of 0.03V in the values for VB and a difference of 0.04V in the values for VC. As for the DeltaT, a value of 118microseconds is obtained by the Hantek. When comparing it to the values obtained by other methods, it shows that the phase of the voltages is identical. I chose R1 randomly to test it for the current passing through it using the Hantek and a significant difference in readings was detected when comparing them to the analytical and Multism methods. R1 was almost 0.013mA off relative to the other methods used. This leads the error to be as high as 6%. Reasons could be due to a significant loss of energy as there is also resistance in the wires. It is known for such components as inductors in an AC circuit to create an opposite emf to resist change in current. Some of the currents can also be lost in the inductor as it would create a varying magnetic field which would cause some energy to be lost by electromagnetic induction.

Overall, readings were relatively similar, and uncertainty values were comparatively small throughout the whole lab.

### **Reflection**

Steady-state AC Network analysis is important since it talks about a new representation of voltage and current. AC voltage is a voltage that shifts extremity with time. This idea permits us to manage two sorts of parts, (inductors and capacitors). It also talks about Phasors, which change the voltage and current from the time-space into a complex field making it simpler to ascertain. There are many utilizations for AC voltage. Some of which are, the utilization as the principal technique for moving power in the electrical framework. It is also likewise appropriated in electric engines where the changing of electric energy into mechanical energy occurs. A component that was reintroduced during this lab was the capacitor, which is used to store electricity. They tend to store energy and discharge later, therefore, making them useful in time delaying circuits such as RC circuits. They are also used in smoothing circuits, which are circuits that change from AC to DC. Another component was the Inductor, which is used in transformers to either increase or decrease the voltage based on the number of turns in the coil. They are commonly used in tuning circuits and induction motors.