## Problem 1

a) betermine whether M and N are positive definite arnot

$$M = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \qquad N = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$

A matrix is positive definite if all the nupper left deferminants are positive.

determinants are positive.

H)

det [1] = 1

det [2] = 1-2-2=-3 -3<0, hence Mis not

positive definite

N det[2]=2

$$\det \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} = 4 - ((-1) \cdot (-1)) = 3$$

2,3,4 >0, hence M is positive definite

$$f(x,y) = 3x^{2}y + y^{3} - 3x^{2} - 3y^{2} + 2$$

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$$f(x,y) = 3x^{2}y + y^{3} - 3x^{2} - 3y^{2} + 2$$

$$f(x,y) = 3x^{2}y + y^{3} - 6x$$

$$f(x,y) = 3x^{2}y + 3y^{2} - 6y$$

$$f(x,y) = 3x^{2}y + 3y^{2}$$

$$\begin{cases} xy = x \\ x^2 = y(2-y) \end{cases}$$

Solutions:

$$A_{1}(0,0)$$
 $A_{2}(1,1)$ 
 $A_{3}(-1,1)$ 
 $A_{4}(0,2)$ 

$$H_{f} = \begin{bmatrix} \frac{\partial^{2} f}{\partial x^{2}} & \frac{\partial^{2} f}{\partial x \partial y} \\ \frac{\partial^{2} f}{\partial y \partial x} & \frac{\partial^{2} f}{\partial y^{2}} \end{bmatrix} = \begin{bmatrix} 6y - 6 & 6x \\ 6x & 6y - 6 \end{bmatrix}$$

Computing 
$$H_{f}$$
 for  $A_{f}$ :  $(-6x_{1}-6x_{2})(x_{1} x_{2})$   
 $-6x_{1}^{2}-6x_{2}^{2}$ 

$$-H_{1}(0,0) = \begin{bmatrix} -6 & 0 \\ 0 & -6 \end{bmatrix} \text{ is negative definite}$$

because  $H_{\mathcal{J}}(0,0)$  is a diagonal matrix with negative values on the diagonal entries.

for the same reason as above, but this time it's the case with positive values.

$$-+ H_{1}(1,1) = \begin{bmatrix} 0 & 6 \\ 6 & 0 \end{bmatrix}$$

$$\begin{bmatrix} \times_1 & \times_2 \end{bmatrix} \begin{bmatrix} \circ & \circ \\ \circ & \circ \end{bmatrix} \begin{bmatrix} \times_1 \\ \times_2 \end{bmatrix} = \begin{bmatrix} \circ & \times_2 & \circ \\ \times_2 \end{bmatrix} = \begin{bmatrix} \times_1 & \times_2 \\ \times_2 \end{bmatrix} = \begin{bmatrix} \times_2 & \circ \\ \times_2 \end{bmatrix}$$

12×2×1 Indefinite  $\forall \hat{x} \in \mathbb{R}^2$ 

$$-\frac{1}{2} = \begin{bmatrix} 0 & -\zeta \\ -\zeta & 0 \end{bmatrix}$$

$$x^{t} \mathcal{H}_{p}(-1,1) \times = \boxed{-12 \times_{2} \times_{1}}$$

Indefinite  $\forall \vec{x} \in \mathbb{R}^{2}$ 

Az neither max non min point

Problem 2 | \_ , ,

$$X = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 2 \\ 1 & 2 & 2 & 4 \end{bmatrix} \qquad \vec{x} = \begin{bmatrix} 2 \\ 3 \\ 3 \\ 4 \end{bmatrix}$$

$$\omega = (x^{T}x)^{-1} x^{T}y \iff x^{T}x \omega = x^{T}y$$

$$x^{T}x = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 2 \\ 1 & 2 & 2 & 4 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 2 \\ 1 & 2 & 2 \end{bmatrix} = \begin{bmatrix} 4 & 6 & 9 \\ 6 & 10 & 15 \\ 9 & 15 & 25 \end{bmatrix}$$

• 
$$X^{T} Y = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 2 \\ 1 & 2 & 2 & 4 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 12 \\ 19 \\ 30 \end{bmatrix}$$

. Solving the linear system. 
$$(x^Tx)\vec{\omega} = (x^T\vec{y})$$

$$\begin{bmatrix} 4 & 6 & 9 & | & 12 \\ 6 & 10 & 15 & | & 19 \\ 9 & 15 & 25 & | & 30 \end{bmatrix} \longrightarrow \begin{bmatrix} 4 & 6 & 9 & | & 12 \\ 0 & 1 & 15 & | & 1 \\ 0 & 1 & 15 & | & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 4 & 6 & 9 & | & 12 \\ 0 & 1 & 3/2 & | & 1 \\ 0 & 0 & 5/2 & | & 3/2 \end{bmatrix}$$

By back substitution we have:
$$\omega_2 = \frac{3}{5} \quad \omega_1 = \frac{1}{10} \quad \omega_0 = \frac{3}{2} \quad \vec{\omega} = \begin{bmatrix} \frac{3}{2} \\ \frac{1}{10} \\ \frac{3}{5} \end{bmatrix} \text{ and } \vec{x}_T = \begin{bmatrix} 1 \\ 1.5 \\ \frac{1}{1.5} \end{bmatrix}$$

$$f_{\omega}(\dot{x}) = \omega^{t} \times = \frac{3}{2} + \frac{3}{20} + \frac{9}{10} = \boxed{\frac{51}{20}}$$