# Assignment 4 Report Surfin' U.S.A.

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## Purpose

This program uses graph theory to solve a version of the traveling salesman problem. Data structures will be in graph.c, stack.c, and path.c. These functions will then be accessed through one .c file tsp.c which takes in command line options and implements a harness to combine the algorithms to solve the traveling salesman problem by finding the shortest Hamiltonian cycle to the directed or undirected graph.

#### How to Run

Run the program from command line using a Makefile:

make

To create a version for debugging:

make debug

The program can then be ran directly:

./tsp

Or with an input txt file:

./tsp < input.txt > output.txt

Possible command line options for sorting.c include:

./sorting -i -o -d -h

Of which,

- -i : Sets the file to read from (input file). Requires a filename as an argument. The default file to read from is stdin
- -o : Sets the file to write to (output file). Requires a filename as an argument. The default file to write to is stdout
  - -d: Treats all graphs as directed. The default is to assume an undirected graph.
  - -h: Prints a help message to stdio.

# Program Design

The source code for the tsp program is found in 4 files. Of which, graph.c, stack.c, path.c, contain the data structures used. These structures are mainly composed of many functions that help add, remove, modify, etc data stored. The tsp.c file contains a main() function that the program runs with. In addition, the program uses existing libraries from C such as stdio.h and unistd.h.

#### **Data Structures**

The program uses customary Graph, Stack, Path structures to store data, as well as int for indexing into the arrays. Pseudocode as follows:

```
typedef struct graph {
      uint32_t vertices;
      bool directed;
      bool *visited;
      char **names;
      uint32_t **weights;
} Graph;
typedef struct stack {
      uint32_t capacity;
      uint32_t top;
      uint32_t *items;
} Stack;
typedef struct path {
      uint32_t total_weight;
      Stack *vertices;
} Path;
```

## Algorithms

The tsp program utilizes these following steps:

- 1. Path Validity Check: The algorithm ensures that the chosen path allows for traversal to all desired destinations, adhering to defined criteria.
- 2. Return Route Evaluation: After finding a valid path, the algorithm checks if the destination node has a connection or path back to the starting node. It may evaluate additional factors such as fuel efficiency.
- 3. Optimal Path Determination: The algorithm compares alternative paths encountered during the traversal, updating the current best path if a more efficient option is found. The final result is the most optimal path based on defined criteria.

## **Function Descriptions**

Each data structure algorithm performs steps below:

## **Graph**

```
- Graph *graph create(uint32 t vertices, bool directed)
      - input: int32 5 vertices, bool directed
      - output: Graph *
      - def Graph *graph_create(uint32_t vertices, bool directed):
                     calloc() memory for Graph struct
                     graph -> vertices
                     graph -> directed
                     graph -> visited = calloc() memory
                     graph -> weights = calloc() memory
                     populate graph -> weights with calloc()
                     return graph
void graph free(Graph **gp)
      - input: Graph **gp
      - output: void
      - def graph_free(gp):
               if gp is None or gp[0] is None:
               return
               q = qp[0]
               # Free memory for visited array
               free g['visited']
               # Free memory for names and weights arrays for each vertex
               for i in range(g['vertices']):
                     free g['names'][i]
                     free g['weights'][i]
               # Free memory for weights and names arrays
               free g['weights']
               free g['names']
               # Free memory for the graph structure
               free q
               # Set the graph pointer to None
               gp[0] = None
```

- uint32\_t graph\_vertices(const Graph \*g)

- input: const Graph \*goutput: uint32\_t
- Finds the number of vertices in a path.
- void graph add vertex(Graph \*g, const char \*name, uint32 t v)
  - Gives the city at vertex v the name passed in, makes a copy of the name and stores it in the graph object.

```
- def graph_add_vertex():
    if graph->name already exists:
        remove name
    set graph->name to copy of name
```

- const char\* graph\_get\_vertex\_name(const Graph \*g, uint32\_t v)
  - Gets the name of the city with vertex v from the array of city names.
- char \*\*graph\_get\_names(const Graph \*g)
  - Gets the names of every city in an array.
- void graph\_add\_edge(Graph \*g, uint32\_t start, uint32\_t end, uint32\_t weight)
  - Adds an edge between int start and int end with weight to the adjacency matrix of the graph.

```
- def graph_add_edge():
    if directed:
        graph->weightsp[start][end = weight
    otherwise:
        g->weights[start][end] = weight
        q->weights[end][start] = weight
```

- uint32 t graph get weight(const Graph \*g, uint32 t start, uint32 t end)
  - Returns the weight of the edge between start and end.
- void graph\_visit\_vertex(const Graph \*g, uint32\_t v)
  - Adds the vertex v to the list of visited vertices.
- void graph\_unvisit\_vertex(Graph \*g, uint32\_t v)
  - Removes the vertex v from the list of visited vertices.
- bool graph\_visited(Graph \*g, uint32\_t v)
  - Returns true if vertex v is visited in graph g, false otherwise.
- void graph\_print(const Graph \*g)
  - Prints the graph, helps for debugging.
  - def graph\_print():
     print all names in graph
     print all weights in graph using:
     printf("%2u ", weights[i][j])

#### **Stack**

```
Stack *stack create(uint32 t capacity)
   - input: uint32 capacity
```

```
- output: Stack *
- def create_stack(capacity):
         s = {} # Create an empty dictionary for the stack
         # Allocate memory for the stack
         s['capacity'] = capacity
         s['top'] = 0
         # Allocate memory for items array
         s['items'] = [0] * s['capacity']
         # Return the created stack
         return s
```

## void stack free(Stack \*\*sp)

```
input: Stack **sp
output: void
```

```
- def free_stack(sp):
```

```
if sp is not None and sp[0] is not None:
# Free memory for the array of items first
      if sp[0]['items']:
            free(sp[0]['items'])
            sp[0]['items'] = None
# Free memory allocated for the stack
free(sp[0])
if sp is not None:
      # Set the pointer to None to avoid double free
      sp[0] = None
```

# bool stack push(Stack \*s, uint32 t val)

```
- input: Stack *s, uint32 t val
```

- output: bool

```
- def stack_push():
```

Add val to top of stack increment counter return true if successful return false if stack full

# bool stack\_pop(Stack \*s, uint32 t \*val)

Sets the integer pointed to by val to the last item on the stack, and removes the last item on the stack. Returns true if successful, false otherwise.

```
def stack_pop():
      exit if stack is empty
      set val pointer value to stack->items[top-1]
```

```
top -= 1 return true
```

## bool stack peek(const Stack \*s, uint32 t \*val)

- Sets the integer pointed to by val to the last item on the stack, but does not modify the stack. Returns true if successful, false otherwise.
- def stack\_peek():
   exit if stack is empty
   set val pointer value to stack->items[top-1]
   return true

## bool stack\_empty(const Stack \*s)

- Returns true if the stack is empty, false otherwise.
- return whether or not top == 0

## bool stack\_full(const Stack \*s)

- Returns true if the stack is full, false otherwise
- return whether or not top == capacity

## - uint32 t stack size(const Stack \*s)

- Returns the number of elements in the stack.

## - void stack copy(Stack \*dst, const Stack \*src)

- Overwrites dst with all the items from src.
- def stack\_copy():
   exit if dst and src capacities are different
   iterate through src\_stack->items:
   copy each item from src to dst
   set dst->top to stc->top
   return

#### **Path**

- Path \*path create(uint32 t capacity)

- void path\_free(Path \*\*pp)
  - Frees a path, and all its associated memory.
  - def path\_free():
     exit if either pointers are NULL
     stack\_free path->vertices

```
free *pp
*pp = NULL
```

- uint32\_t path\_vertices(const Path \*p)
  - Finds the number of vertices in a path.
- uint32 t path\_distance(const Path \*p)
  - Finds the distance covered by a path.
- void path add(Path \*p, uint32 t val, const Graph \*g)
  - Adds vertex val from graph g to the path.
  - def path\_add():

```
if path->vertices is empty:
    path->total_weight = 0
else:
    weight = graph_get_weight(graph, last vertex, val)
    path->total_weight += weight
stack_push(path->vertices, val)
return
```

- uint32\_t path\_remove(Path \*p, const Graph \*g)
  - Removes the most recently added vertex from the path.
  - def path\_remove():

```
exit if path->vertices is empty
else:
         stack_pop(path->vertices, last vertex)
         if path has more than 1 vertices:
              stack_peek(p->vertices, last last vertex)
              distance = graph_get_weight(last last vertex,
last vertex)
              path->total_weight -= distance
              else (if path has only 1 vertex):
                    path->total_weight = 0
free pointers
return
```

- void path\_copy(Path \*dst, const Path \*src)
  - Copies a path from src to dst.
  - def path\_copy():
     exit if bad pointers
     set dst->total\_weight to src->total\_weight
     stack\_copy(dst->vertices, src->vertices)
     return

#### <u>tsp</u>

#### - main

- uses getopt to process arguments
- set infile and outfile to stdin and stdout unless user options prompt otherwise
- uses fscanf to read input files and create Graph \*g accordingly
- runs dsf()
- if bestPath after dsf() has 0 vertices, we know that there is not a hamiltonian cycle in the Graph, so write to outfile: "No path found! Alissa is lost!"
- otherwise, path print() the bestPath
- free associated paths and graphs

## - void dsf(uint32 t n, Graph \*g, uint32 t start, Path \*curr, Path \*best)

- input: int current\_node/vertex, Graph g, int starting\_node, Path current\_path, Path best\_path
- output: since current\_path and best\_path are pointers, those Path structures are directly modified. The function itself returns void.
- Performs a depth first search (DFS) graph search
- def dsf():

```
visit(current vertex)
add current vertex to currPath
if (all vertices are visited):
      if (current vertex has path back to start):
            get dist total_distance of full cycle
            if (bestPath is empty) or (dist <
bestPath.dist):
                  path_add(curr->start)
                  path_copy(curr->best)
                  path_remove(curr)
for (i in all adjacent vertices):
      if (there is a path to i):
            if (i is not visited yet):
                  dsf(i, g, start, curr, best)
unvisit(current vertex)
remove current vertex from currPath
```

# **Error Handling**

getopt() includes error handling where in the event that the user's input option does not exist, an error message will be printed to stderr. In addition, when using -h, a help message appears on stdout. Functions for the custom data structures also contain error checking to make sure pointers passed in aren't NULL. As per pseudocode above, when invalid pointers are passed into the functions, they will exit and display an error. Destructive functions for data structures involving heap memory allocation are thoroughly tested through valgrind to ensure no memory leaks.

## Result

Program works as intended. Valgrind: All heap blocks were freed -- no leaks possible. No false positives reported by scan-build. No known bugs or errors.

#### What I learned:

- From running clique 9-13.graph from maps, it seems that each subsequently larger graph takes exponentially longer times to run. I learned that depth-first-search has a rather high complexity and thus runtime.
- I also found an interesting online tool to plot graphs from adjacency matrices: <a href="https://graphonline.ru/en/">https://graphonline.ru/en/</a> (see figure 1).
- I've gained significantly more knowledge on how to use Valgrind.
- I learned more about input streams from reading and writing to files.
- Attempted 11db debugging, with some useful outcome.

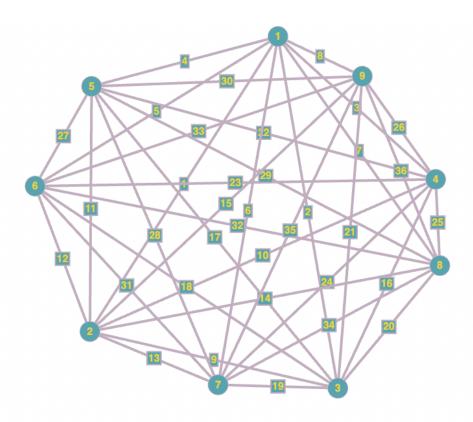


Figure 1. Screenshot of online graphing tool

```
==28505== All heap blocks were freed -- no leaks are possible
==28505==
==28505== ERROR SUMMARY: 0 errors from 0 contexts (suppressed: 0 from 0)
jasonz@vm-cse13:~/desktop/cse13s/asgn4$ ./tsp -i maps/bayarea.graph
Alissa starts at:
Santa Cruz
Half Moon Bay
San Mateo
Daly City
San Francisco
Oakland
Walnut Creek
Dublin
Havward
San Jose
Santa Cruz
Total Distance: 203
jasonz@vm-cse13:~/desktop/cse13s/asgn4$ ./tsp -i maps/bayarea.graph -o out.txt
jasonz@vm-cse13:~/desktop/cse13s/asgn4$ ls
graph.c
              Makefile path.o
                                     stack.c
                                                   tsp
                                                                     vertices.h
graph.h
                        path_test.c stack.h
                                                   tsp-arm
graph.o
              out.txt
                        path_test.o stack.o
                                                   tsp.c
graph_test.c path.c
                        README.md
                                     stack_test.c tsp.o
graph_test.o path.h
                        report.pdf
                                     stack_test.o valgrind-out.txt
jasonz@vm-cse13:~/desktop/cse13s/asgn4$ cat out.txt
Alissa starts at:
Santa Cruz
Half Moon Bay
San Mateo
Daly City
San Francisco
Oakland
Walnut Creek
Dublin
Hayward
San Jose
Santa Cruz
Total Distance: 203
```

Figure 2. Screenshot of program running