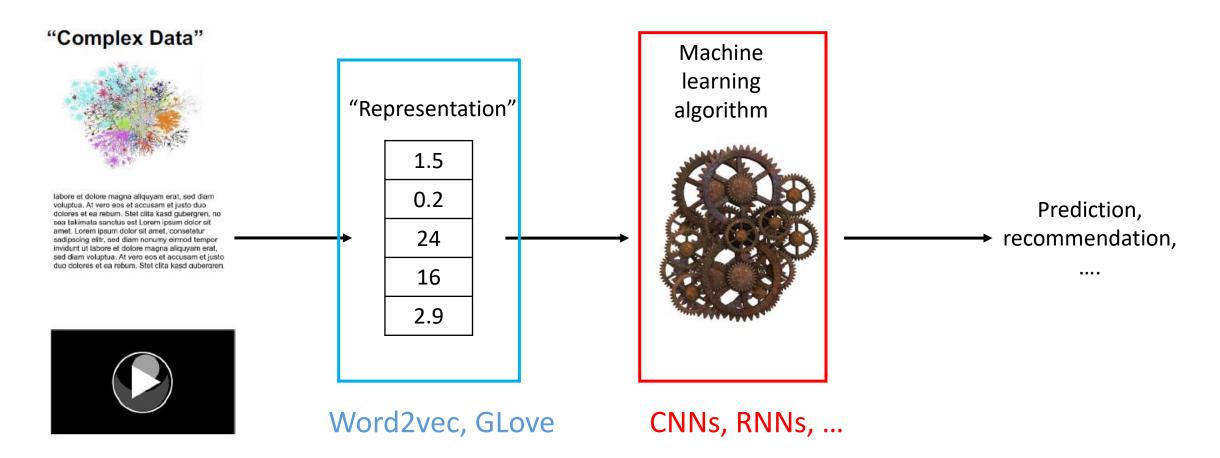
Text Mining

Summer term 2025

Sandipan Sikdar



Word embeddings



Text Classification

- Supervised learning task
- Given a text, map it to a class
- Example: Sentiment classification
- The staff were extremely helpful and friendly. Positioning is great, close to bus/train station and within walking distance to all main sights. Had view over square and room was very clean and comfortable.
- Was expensive but perhaps this is simply Venice.

Text Classification

• Train data: $\{(x^i, y^i)\}_{i=1}^N$

$$y^i \in \{0,1\}$$



The staff were extremely helpful and friendly. Positioning is great, close to bus/train station and within walking distance to all main sights. Had view over square and room was very clean and comfortable.

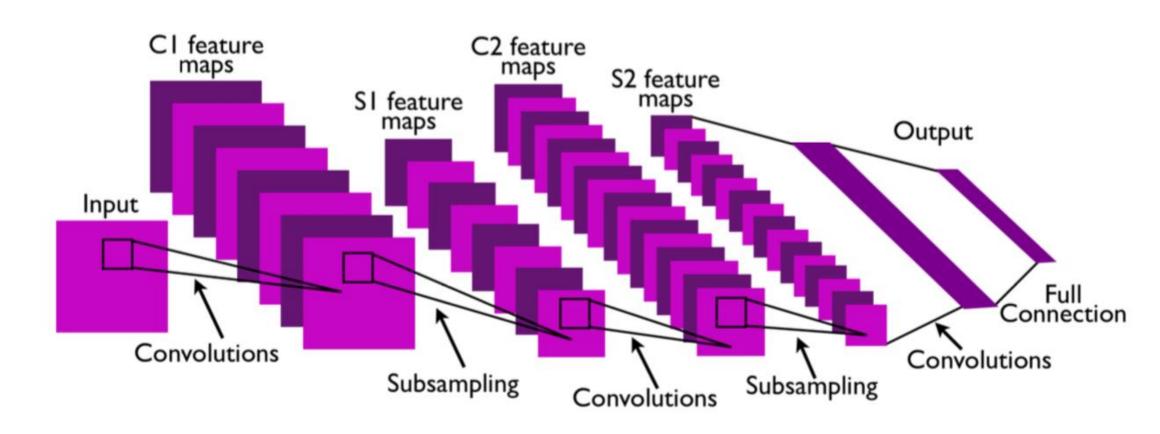
Loss: Binary cross-entropy loss

$$J(\theta) = -\sum_{i=1}^{N} y^{i} \log \left(f_{\theta}(x^{i}) \right) + (1 - y^{i}) \log (1 - f_{\theta}(x^{i}))$$
Prediction model with parameters₄ θ

Convolutional neural networks

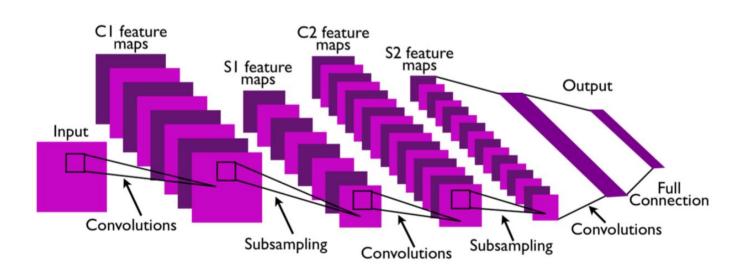
- ... are a type of partially connected "feedforward networks" (details later)
- ... originated from computer vision
- ... are often used for image classification
- ... outperform classical image recognition by a large margin
- ... model features over areas of growing size in images
 - Early layers model local neighbourhoods detect edges ,
 - Later layers combine the features to detect larger objects

Convolutional neural networks



CNNs in Computer Vision

- Typical structure of CNN
 - 1. Convolutional layer
 - 2. Pooling layer
 - 3. Repeat 1 and 2 multiple times
 - 4. Fully connected layer
 - 5. Softmax



A bit of history:

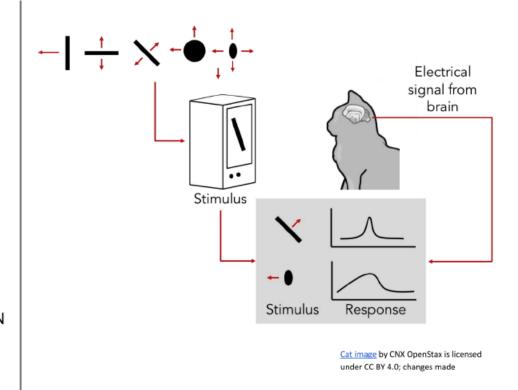
Hubel & Wiesel, 1959

RECEPTIVE FIELDS OF SINGLE NEURONES IN THE CAT'S STRIATE CORTEX

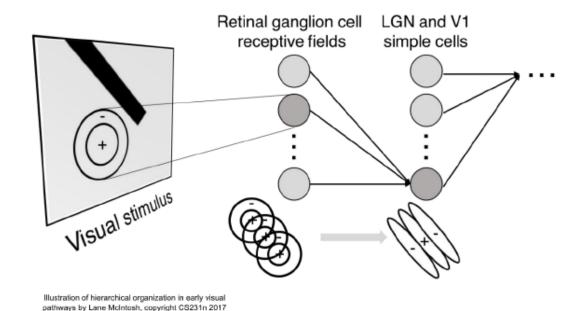
1962

RECEPTIVE FIELDS, BINOCULAR INTERACTION AND FUNCTIONAL ARCHITECTURE IN THE CAT'S VISUAL CORTEX

1968...



Hierarchical organization



Simple cells:

Response to light orientation

Complex cells:

Response to light orientation and movement

Hypercomplex cells:

response to movement with an end point





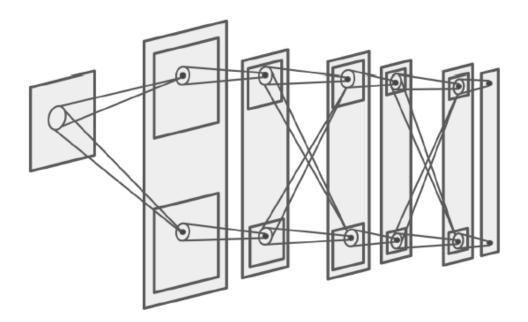
No response

Response (end point)

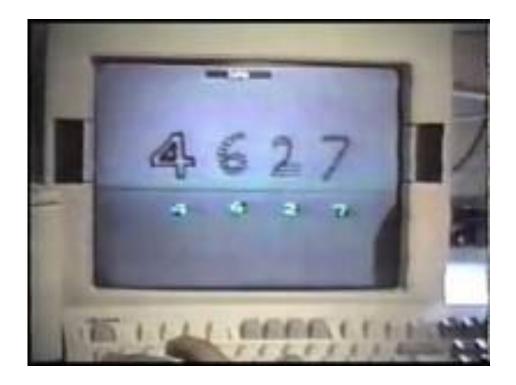
A bit of history:

Neocognitron [Fukushima 1980]

"sandwich" architecture (SCSCSC...) simple cells: modifiable parameters complex cells: perform pooling

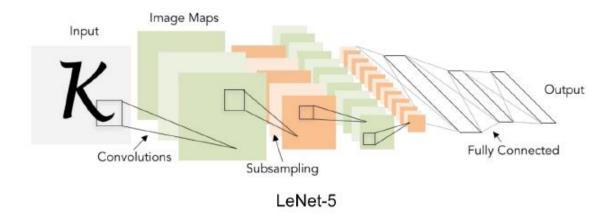


"LeNet 1", the first convolutional network that could recognize handwritten digits with good speed and accuracy (1989)



Gradient-based learning applied to document recognition

[LeCun, Bottou, Bengio, Haffner 1998]



ImageNet Classification with Deep Convolutional Neural Networks

[Krizhevsky, Sutskever, Hinton, 2012]

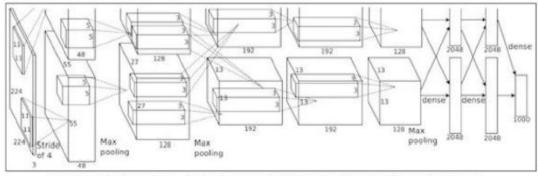
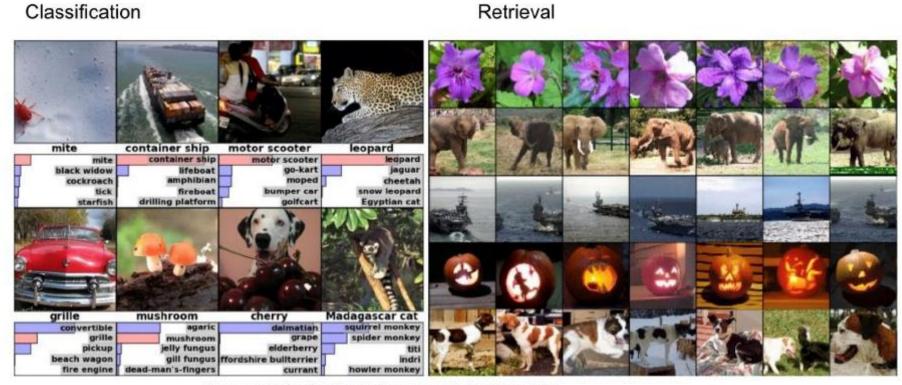


Figure copyright Alex Krizhevsky, Ilya Sutskever, and Geoffrey Hinton, 2012. Reproduced with permission.

"AlexNet"

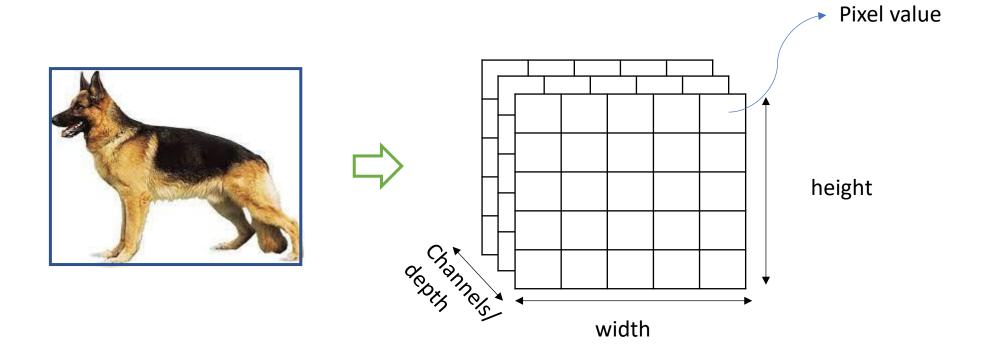
CNNs are everywhere



Figures copyright Alex Krizhevsky, Ilya Sutskever, and Geoffrey Hinton, 2012.

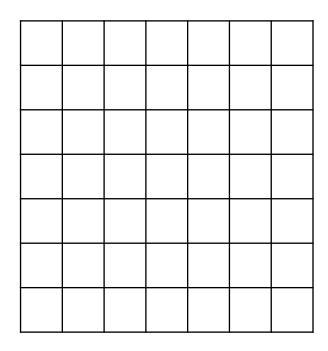
- To understand CNNs, we take a look at their basic building blocks Convolutions
- Convolution = classic tool in image processing even without machine learning
- Intuition: Slide a function over an image, create a modified image
- Can model operations like edge detection, blurring, sharpening

Representing image

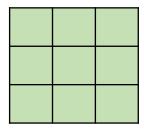


We consider a single channel image

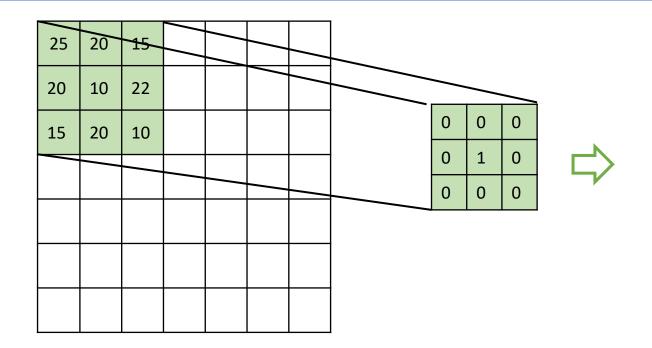




Filter



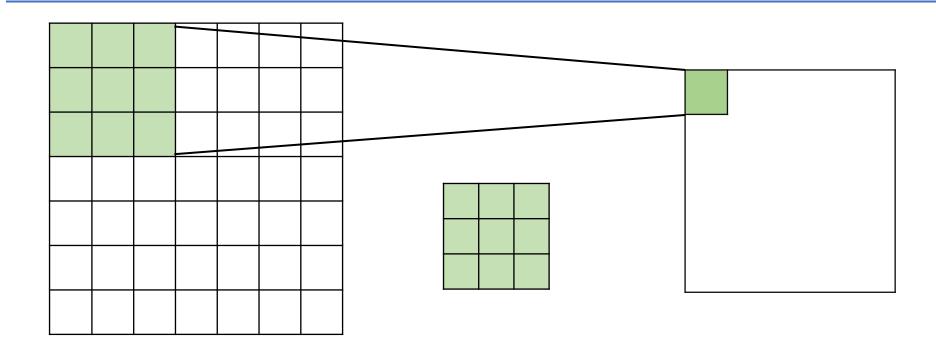
- Input image (matrix)
- Kernel/filter (matrix)
- Convolve the filter over the image i.e., slide over the image spatially computing dot products

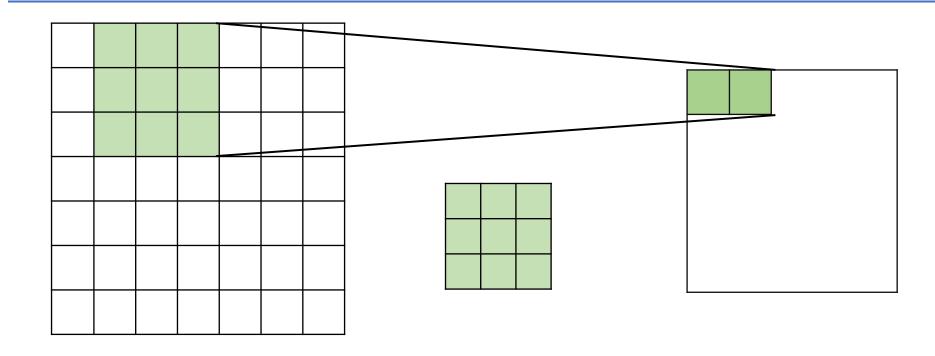


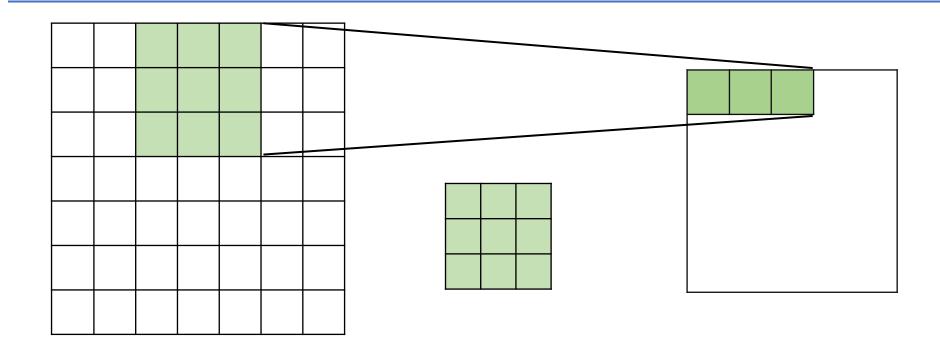
$$out = w^T x + b$$

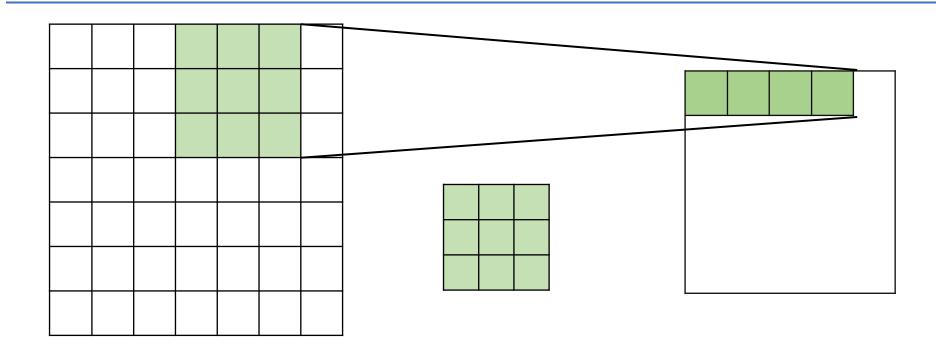
$$25 * 0 + 20 * 0 + 15 * 0 + 20 * 0 + 10$$

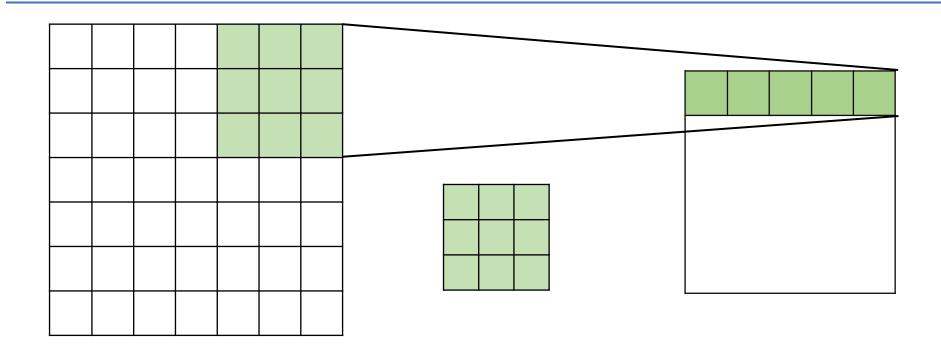
 $* 1 + 22 * 0 + 15 * 0 + 20 * 0 + 10 * 0$
 $+ 0 = 10$
(assuming $b = 0$)

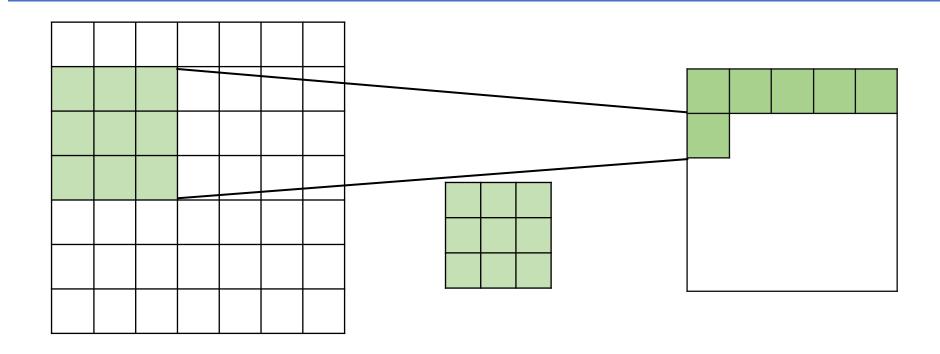


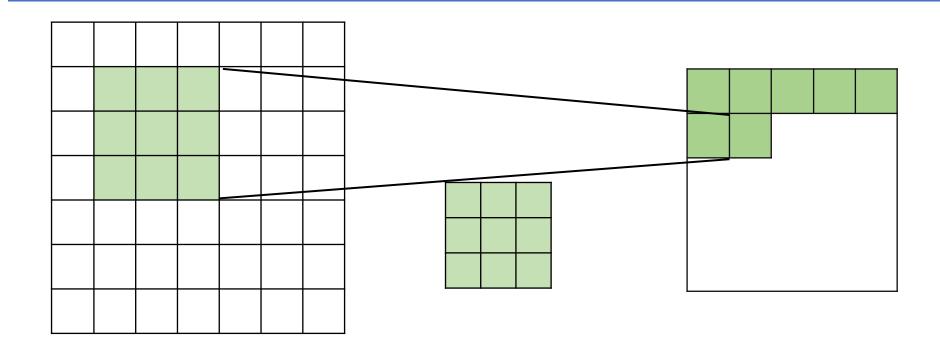


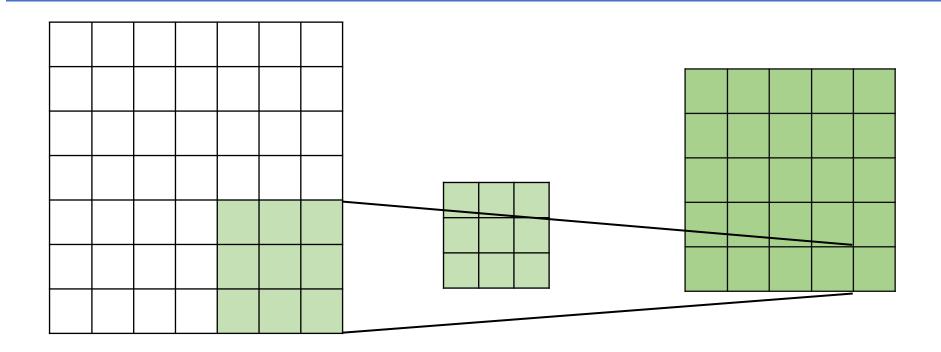




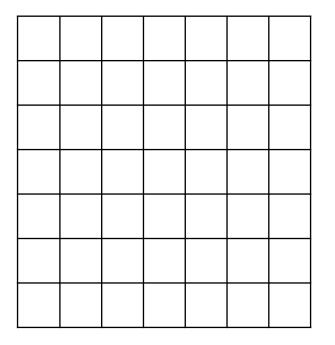




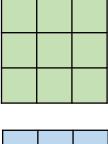


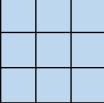


Image

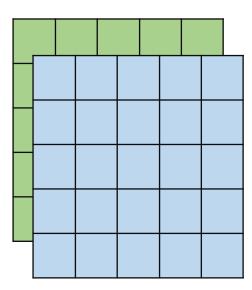


Filters





Feature maps



What are these feature maps actually?



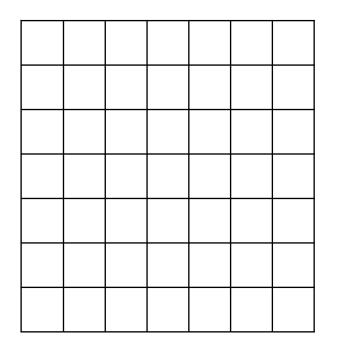
Input Image



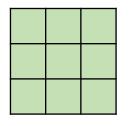
Feature map obtained Feature map obtained after first convolution at upper layers operation



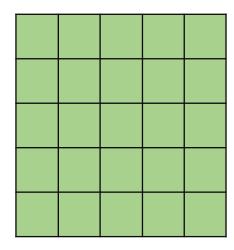
Image



Filter

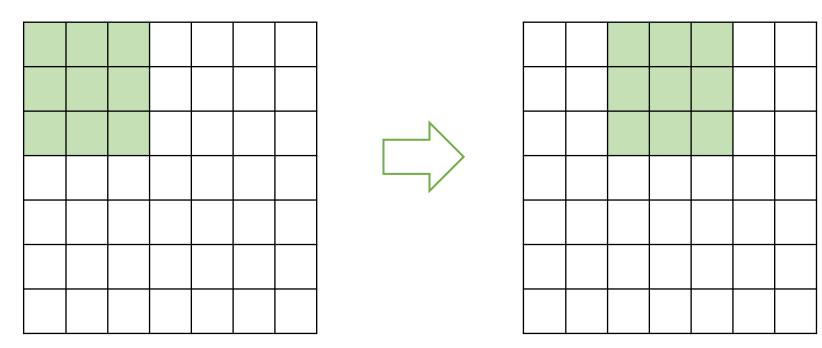


Feature map



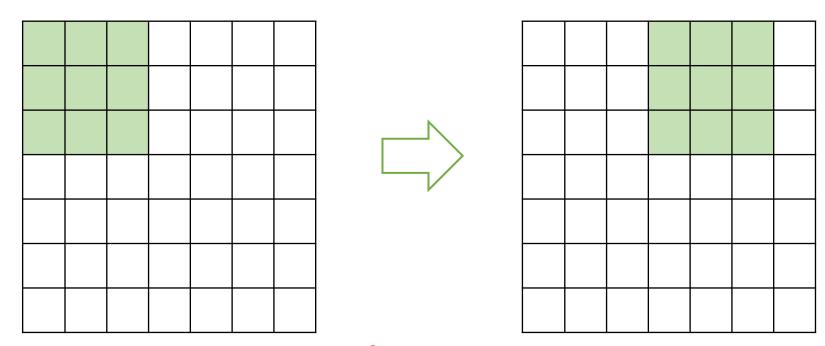
- Image dimension: 7x7
- Filter dimension: 3x3
- Stride: 1 (the number of pixels/units) the filter moves towards right or bottom
- Feature map: 5x5

• What is the dimension of the feature map if the stride is 2?

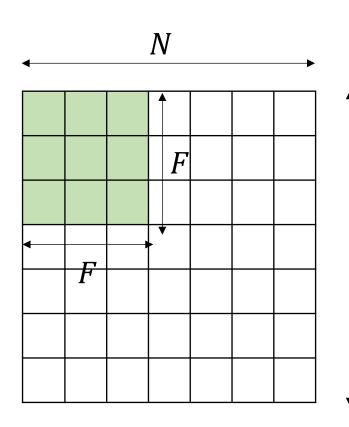


• Feaure map: 3x3

• What happens when the stride is 3?



• Feaure map: Does not fit



N

Output size =
$$\frac{N-F}{Stride}$$
 + 1
E.g.,
 $N = 7, F = 3, stride = 1$, Output = 5
 $N = 7, F = 3, stride = 2$, Output = 3
 $N = 7, F = 3, stride = 3$, Output = 2.33

Solution: Zero pad the border

| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
|---|---|---|---|---|---|---|---|---|
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Output size =
$$\frac{N-F}{Stride} + 1$$

E.g.,

Input: 7x7

Filter: 3x3

Stride: 1

Pad with 1 pixel border

Output? 7x7

Solution: Zero pad the border

| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
|---|---|---|---|---|---|---|---|---|
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | | | | | | | | 0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

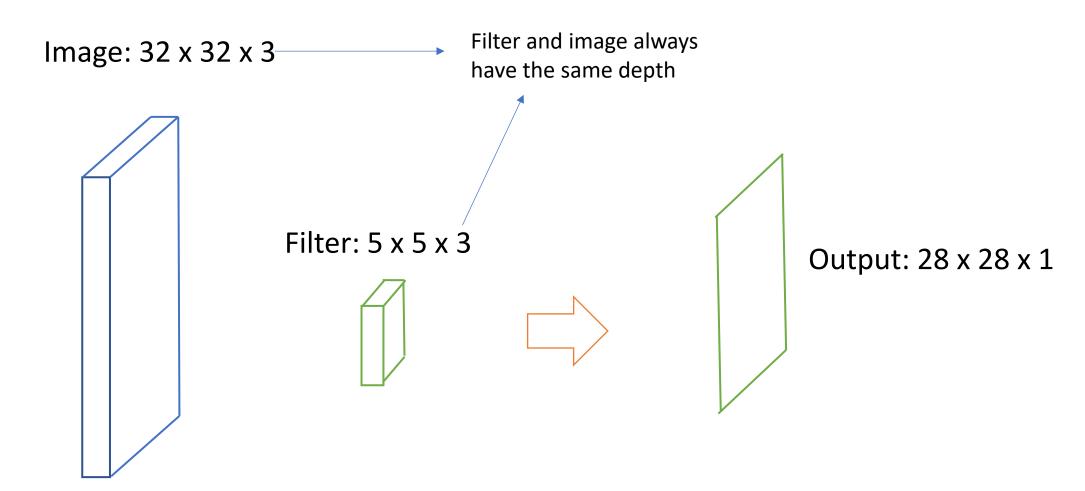
In general, common to see CONV layers with stride 1, filters of size $F \times F$, and zero-padding with (F-1)/2. (will preserve size spatially)

$$F = 3 \Rightarrow \text{zero pad with } 1$$

$$F = 5 \Rightarrow \text{zero pad with } 2$$

$$F = 7 \Rightarrow \text{zero pad with } 3$$

3D convolutions



- Input: $W_1 \times H_1 \times D_1$
- Number of filters: *K*
- Filter dimensions: $F \times F$
- Stride: S
- Padding: P
- Output

•
$$W_2 = \frac{W_1 + 2 \cdot P - F}{S} + 1$$

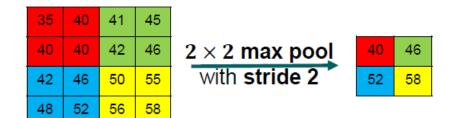
•
$$H_2 = \frac{H_1 + 2*P - F}{S} + 1$$

•
$$D_2 = K$$

Convolution operations are followed by non-linear activations such as Sigmoid or ReLU

Pooling

- Second component of CNNs: Pooling Layers
- Reduce the size of the input image in a predefined manner
- No learned weights! Purely deterministic operation
- Common types:
 - Max pooling
 - Extract the maximum of $n \times m$ (pool size) entries in the input
 - Move k (stride) entries ahead in the input



Average pooling: Compute the average of inputs instead of max

Pooling layers

- Why use pooling layers?
- Reduce the number of parameters in following layers
- Not all filters activated on all pixels
- Only use pixels in a close neighbourhood that provide the strongest signal

CNNs vs. Fully connected layers

- Massively fewer parameters than fully connected networks
- Example:
 - 300×300 pixel input, map to hidden layer of same size
 - Fully connected: $(300.300) \cdot (300.300) = 8,100,000,000$ parameters!
 - Convolutional with 100 filters of size 3×3 : $100\cdot3\cdot3 = 900$ parameters
- Less RAM needed, less prone to overfitting

CNNs for Text

CNNs in NLP

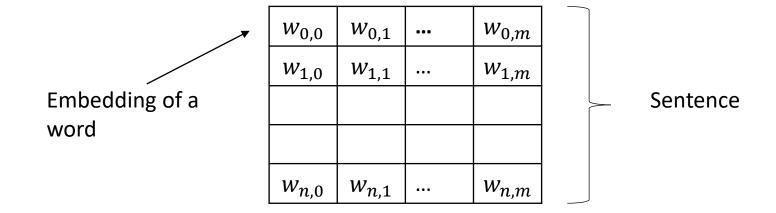
- So far: Only described use in Computer Vision...
- CNNs became popular in NLP, too:
 - Kalchbrenner et al., 2014: A Convolutional Neural Network for Modelling Sentences
 - Kim, 2014: Convolutional Neural Networks for Sentence Classification
 - Nguyen and Grishman, 2015: Relation Extraction: Perspective from Convolutional Neural Networks

• ...

- Kim, 2014 (EMNLP)
- Very simple CNN model...
- ... with very good results!
- Beat previous state-of-the-art in several tasks
 - Sentiment Analysis
 - Subjectivity Detection*
 - Question Answering

*didn't beat state-of-the-art, but came very close

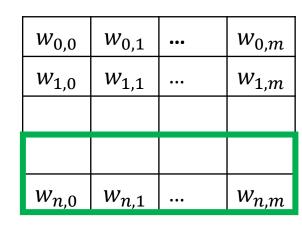
• Input representation: Concatenated word embeddings

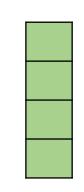


Convolution operation

| $w_{0,0}$ | $w_{0,1}$ | ••• | $w_{0,m}$ |
|-----------|-------------------------|-----|-----------|
| $w_{1,0}$ | <i>w</i> _{1,1} | | $w_{1,m}$ |
| | | | |
| | | | |
| $w_{n,0}$ | $w_{n,1}$ | | $W_{n,m}$ |

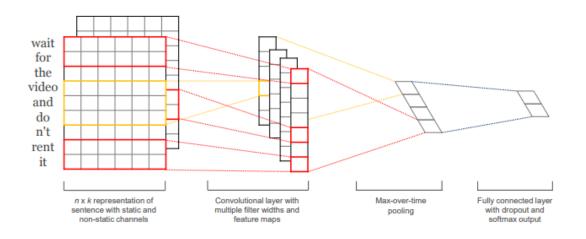
| $w_{0,0}$ | $w_{0,1}$ | ••• | $w_{0,m}$ |
|-----------|-----------|-----|-----------|
| $W_{1,0}$ | $W_{1,1}$ | ••• | $W_{1,m}$ |
| | | | |
| | | | |
| $W_{n,0}$ | $w_{n,1}$ | ••• | $W_{n,m}$ |



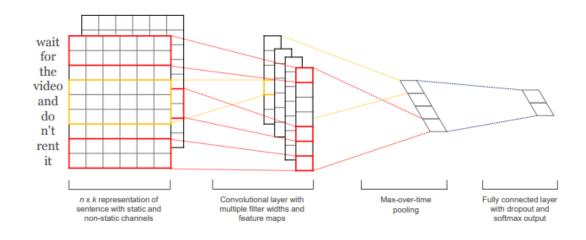


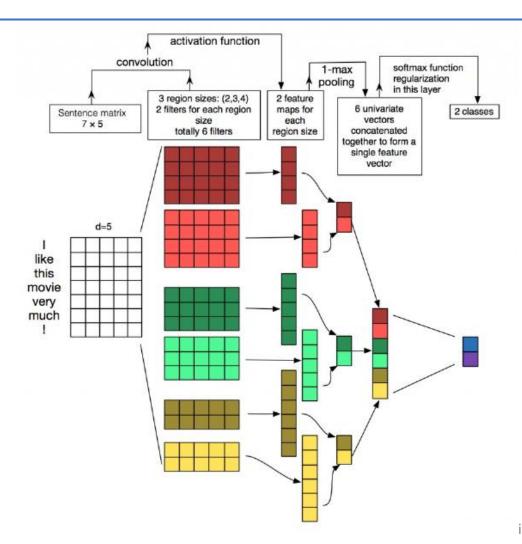
- Convolutions over full embeddings!
- Filter size $n \times m$ (n = variable, m = length of the embeddings)

- Network architecture
 - No stacked convolutional layers!
 - One layer of convolutions
 - Different filter sizes: $n \in \{3,4,5\}$
 - Each with 100 filters
 - Stride 1 -> Do not skip any words/n-grams



- Network architecture
 - Max-over-time pooling
 - Max Pooling over the full filter output -> Select the highest output for each filter
 - Fully connected layer
 - Dropout
 - Softmax





https://dennybritz.com/posts/wildml/understanding-convolutional-neural-networks-for-nlp/

ing, SS-25 47

CNNs for Sentence Classification: Embeddings

- Word embeddings used to encode the input
- Multiple variants:
 - Randomly initialize embeddings, train with model (cnn-rand)
 - Initialize word embeddings with Word2Vec, keep fixed (cnn-static)
 - Initialize word embeddings with Word2Vec, train with model (cnn-nonstatic)
- Finding: Using pre-trained embeddings and further optimizing them for the task at hand often works best!

CNNs for Sentence Classification: Embeddings

- Trick: Multi-channel word embeddings (cnn-multichannel)
 - Represent input as 3-dimensional matrix
 - 3rd dimension: different, independent word embedding vectors
 - Convolutions computed slightly differently, general ideas still apply
- During training:
 - keep one dimension fixed
 - Train the other
- Effect: Keep information from original embeddings, but also include "extra" for the task/dataset

| $w_{0,0,0}$ w | | 0,1,0 | | 1 | W | 0, m, 0 | |
|-----------------|-----------|-------|-----------|-----|-----|---------|-------------|
| ν | $w_{0,0}$ |),1 | $w_{0,1}$ | L,1 | ••• | | $w_{0,m,1}$ |
| | $w_{1,0}$ |),1 | $W_{1,1}$ | .,1 | | | $W_{1,m,1}$ |
| | | | | | | | |
| ν | | | | | | | |
| | $w_{n,0}$ |),1 | $w_{n,1}$ | l,1 | ••• | | $W_{n,m,1}$ |

CNNs for Sentence Classification: Regularization

- Multiple regularization methods used:
 - Dropout
 - Apply Dropout after the fully connected layer
 - L2-maxnorm constraint
 - Set a hard limit s on l2-norm for weights w of the fully connected layer
 - If, after the update step, $||w||_2 > s$, rescale w to $||w||_2 = s$
 - Prevents single weights from getting too large

CNNs for Sentence Classification: Evaluation

| Model | MR | SST-1 | SST-2 | Subj | TREC | CR | MPQA |
|---------------------------------------|------|-------|-------|------|------|------|------|
| CNN-rand | 76.1 | 45.0 | 82.7 | 89.6 | 91.2 | 79.8 | 83.4 |
| CNN-static | 81.0 | 45.5 | 86.8 | 93.0 | 92.8 | 84.7 | 89.6 |
| CNN-non-static | 81.5 | 48.0 | 87.2 | 93.4 | 93.6 | 84.3 | 89.5 |
| CNN-multichannel | 81.1 | 47.4 | 88.1 | 93.2 | 92.2 | 85.0 | 89.4 |
| RAE (Socher et al., 2011) | 77.7 | 43.2 | 82.4 | _ | _ | _ | 86.4 |
| MV-RNN (Socher et al., 2012) | 79.0 | 44.4 | 82.9 | _ | _ | _ | _ |
| RNTN (Socher et al., 2013) | _ | 45.7 | 85.4 | _ | _ | _ | _ |
| DCNN (Kalchbrenner et al., 2014) | _ | 48.5 | 86.8 | _ | 93.0 | _ | _ |
| Paragraph-Vec (Le and Mikolov, 2014) | _ | 48.7 | 87.8 | _ | _ | _ | _ |
| CCAE (Hermann and Blunsom, 2013) | 77.8 | _ | _ | _ | _ | _ | 87.2 |
| Sent-Parser (Dong et al., 2014) | 79.5 | _ | _ | _ | _ | _ | 86.3 |
| NBSVM (Wang and Manning, 2012) | 79.4 | _ | _ | 93.2 | _ | 81.8 | 86.3 |
| MNB (Wang and Manning, 2012) | 79.0 | _ | _ | 93.6 | _ | 80.0 | 86.3 |
| G-Dropout (Wang and Manning, 2013) | 79.0 | _ | _ | 93.4 | _ | 82.1 | 86.1 |
| F-Dropout (Wang and Manning, 2013) | 79.1 | _ | _ | 93.6 | _ | 81.9 | 86.3 |
| Tree-CRF (Nakagawa et al., 2010) | 77.3 | _ | _ | _ | _ | 81.4 | 86.1 |
| CRF-PR (Yang and Cardie, 2014) | _ | _ | _ | _ | _ | 82.7 | _ |
| SVM _S (Silva et al., 2011) | _ | _ | _ | _ | 95.0 | _ | |

CNNs for Sentence Classification: Evaluation

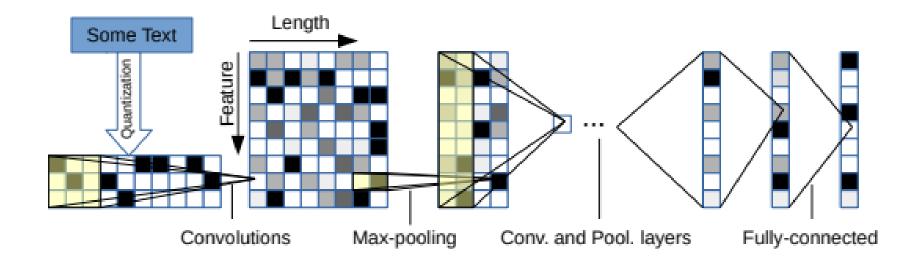
- General findings:
 - Model performs very well!
 - Using pre-trained word embeddings is better than randomly initializing
 - No clear advantage for using cnn-static, cnn-nonstatic or cnn-multichannel

Character level CNNs

- Idea: Learn from scratch, ignore notion of words (!)
- Instead of having a sequence of words for which we train embeddings: Train on sequence of characters with embeddings
- Alphabet used (70 different characters):

```
abcdefghijklmnopqrstuvwxyz0123456789,;.!?:'''/\| @#$%^&**+-=<>()[]{}
```

Character level CNNs



Training

 The algorithm used is stochastic gradient descent (SGD) with a minibatch of size 128, using momentum 0.9 and initial step size 0.01 which is halved every 3 epochs for 10 times.

- Problem: Text length
- Solution: Text a fixed length of 1014 characters (!). If necessary, padding with spaces

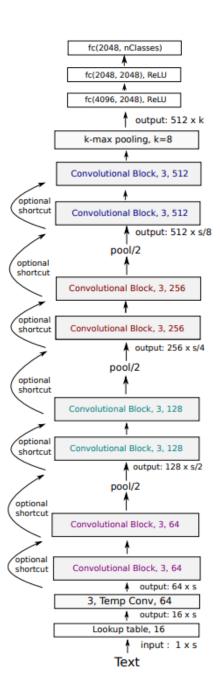
Evaluation

| Model | AG | Sogou | DBP. | Yelp P. | Yelp F. | Yah. A. | Amz. F. | Amz. P. |
|--------------------|-------|-------|------|---------|---------|---------|---------|---------|
| BoW | 11.19 | 7.15 | 3.39 | 7.76 | 42.01 | 31.11 | 45.36 | 9.60 |
| BoW TFIDF | 10.36 | 6.55 | 2.63 | 6.34 | 40.14 | 28.96 | 44.74 | 9.00 |
| ngrams | 7.96 | 2.92 | 1.37 | 4.36 | 43.74 | 31.53 | 45.73 | 7.98 |
| ngrams TFIDF | 7.64 | 2.81 | 1.31 | 4.56 | 45.20 | 31.49 | 47.56 | 8.46 |
| Bag-of-means | 16.91 | 10.79 | 9.55 | 12.67 | 47.46 | 39.45 | 55.87 | 18.39 |
| LSTM | 13.94 | 4.82 | 1.45 | 5.26 | 41.83 | 29.16 | 40.57 | 6.10 |
| Lg. w2v Conv. | 9.92 | 4.39 | 1.42 | 4.60 | 40.16 | 31.97 | 44.40 | 5.88 |
| Sm. w2v Conv. | 11.35 | 4.54 | 1.71 | 5.56 | 42.13 | 31.50 | 42.59 | 6.00 |
| Lg. w2v Conv. Th. | 9.91 | - | 1.37 | 4.63 | 39.58 | 31.23 | 43.75 | 5.80 |
| Sm. w2v Conv. Th. | 10.88 | - | 1.53 | 5.36 | 41.09 | 29.86 | 42.50 | 5.63 |
| Lg. Lk. Conv. | 8.55 | 4.95 | 1.72 | 4.89 | 40.52 | 29.06 | 45.95 | 5.84 |
| Sm. Lk. Conv. | 10.87 | 4.93 | 1.85 | 5.54 | 41.41 | 30.02 | 43.66 | 5.85 |
| Lg. Lk. Conv. Th. | 8.93 | - | 1.58 | 5.03 | 40.52 | 28.84 | 42.39 | 5.52 |
| Sm. Lk. Conv. Th. | 9.12 | - | 1.77 | 5.37 | 41.17 | 28.92 | 43.19 | 5.51 |
| Lg. Full Conv. | 9.85 | 8.80 | 1.66 | 5.25 | 38.40 | 29.90 | 40.89 | 5.78 |
| Sm. Full Conv. | 11.59 | 8.95 | 1.89 | 5.67 | 38.82 | 30.01 | 40.88 | 5.78 |
| Lg. Full Conv. Th. | 9.51 | - | 1.55 | 4.88 | 38.04 | 29 58 | 40 54 | 5 51 |
| Sm. Full Conv. Th. | 10.89 | - | 1.69 | 5.42 | 37.95 | 29.90 | 40.53 | 5.66 |
| Lg. Conv. | 12.82 | 4.88 | 1.73 | 5.89 | 39.62 | 29.55 | 41.31 | 5.51 |
| Sm. Conv. | 15.65 | 8.65 | 1.98 | 6.53 | 40.84 | 29.84 | 40.53 | 5.50 |
| Lg. Conv. Th. | 13.39 | - | 1.60 | 5.82 | 39.30 | 28.80 | 40.45 | 4.93 |
| Sm. Conv. Th. | 14.80 | - | 1.85 | 6.49 | 40.16 | 29.84 | 40.43 | 5.67 |
| | • | | | | | | | <u></u> |

Small Large Sikdar, Textmining, SS-25

Even deeper CNNs

- Same ideas, deeper architecture
- Upto 49 layers of blocks
- Achieves better performance
- High computational cost



Reference and further reading

- https://cs231n.github.io/convolutional-networks/
- https://www.youtube.com/watch?v=bNb2fEVKeEo