

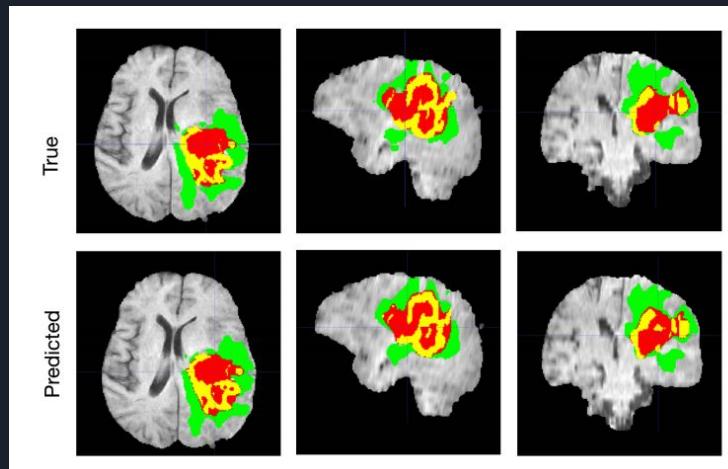


Deep Learning for Brain Tumor Segmentation on MRI

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Motivation

- Brain tumors are life-threatening diseases
 - Glioblastoma (focus of this project) are fast-growing and very aggressive
- MRI is necessary, though analysis is time-consuming and often difficult
 - Manual tumor outlining is not only tedious but also biased
 - May not even be performed in busier hospitals
 - Segmenting tumor into different subregions is important to improve diagnosis/treatment
 - It's important to know where the tumor is and how big each subregion is



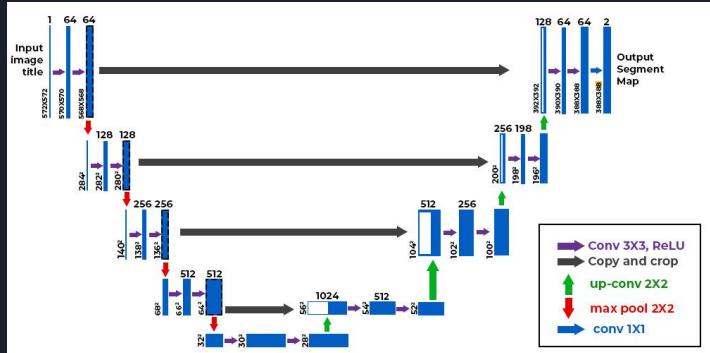
Background

- **Dataset:** Brain Tumor Segmentation Challenge (BraTS)
 - Input: uses magnetic resonance imaging (mpMRI) scans
 - Output: segmentation of different glioma subregions
- The different glioma subregions include:
 - Enhancing tumor (ET)
 - Tumor core (TC)
 - ET + NCR (necrotic core – dead/non-enhancing)
 - Whole tumor (WT)
 - TC + ED (edema – surrounding tissue)



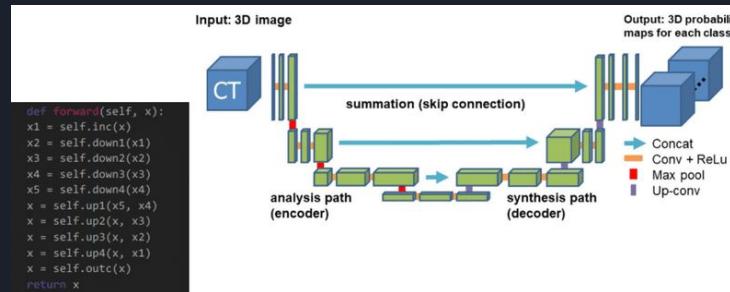
Related Work

- U-Net (including 3D U-net)
 - Popular convolutional neural network architecture used for image segmentation
 - Contracting path: repeated convolutions + max pooling
 - Expansive path: upsamples feature maps
 - Encoding/decoding is strictly CNN
- Transformers (TransUNet)
 - Some new methods have combined CNNs with transformers as a novel hybrid approach
 - Uses vision transformer later in encoding
 - They perform well, though are much harder to implement and train
- It seems that the best and most reliable choice here would be a 2D U-Net.



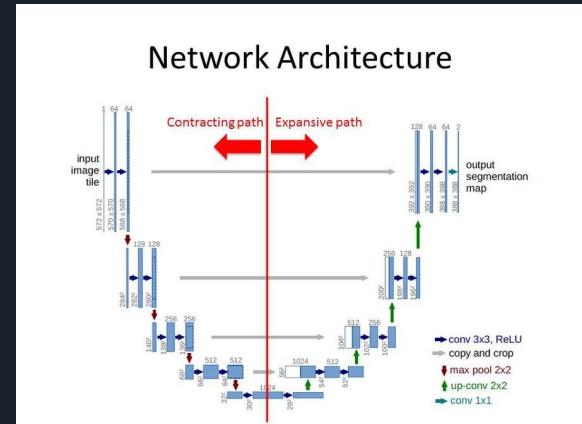
Target Task

- Input
 - Multimodal brain MRI scans (T1, T1Gd, T2, FLAIR)
 - 3D volumetric brain MRI scans
 - Get 2D slices, where each slice has different channels corresponding to different modalities
- Intermediary: pass through a U-Net CNN
- Output
 - For every pixel, predict which tumor subregion it belongs to
 - Necrotic and non-enhancing tumor core (NCR/NET)
 - Peritumoral edema (ED)
 - GD-enhancing tumor (ET)



Proposed Solution

- Preprocessing
 - 3D volumes of T1, T1Gd, T2, FLAIR
 - Slice 3D into 2D slices and create channel images
 - Model architecture
 - Repeatedly feed slices
 - Contracting path:
 - Conv → ReLU → Conv → ReLU → Max pool
 - Repeat about 4 times over
 - Expansive path:
 - Up-convolution until original resolution is reached
 - Softmax to predict class per each pixel





Implementation

- Data splitting
 - Split data by volumes instead of slices to prevent data leakage
- Preprocessing
 - Use Keras Sequence to feed batches and save RAM
 - Only after splitting, shuffle slices
 - Convert multi-channel mask to a class map (0=BG, 1=NCR, 2=ED, 3=ET)
 - Model predicts NCR, ED, or ET
- Training
 - Input: (240, 240, 4) slice of T1, T1Gd, T2, FLAIR
 - Feed through U-Net
 - Output: (240, 240) softmax
 - Loss: sparse categorical crossentropy

Results

- Test loss: 0.0194
- Test accuracy: 0.9954

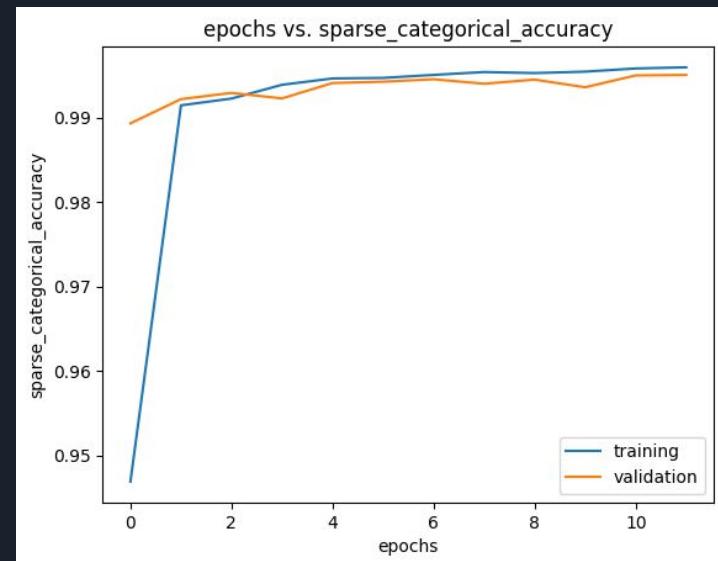
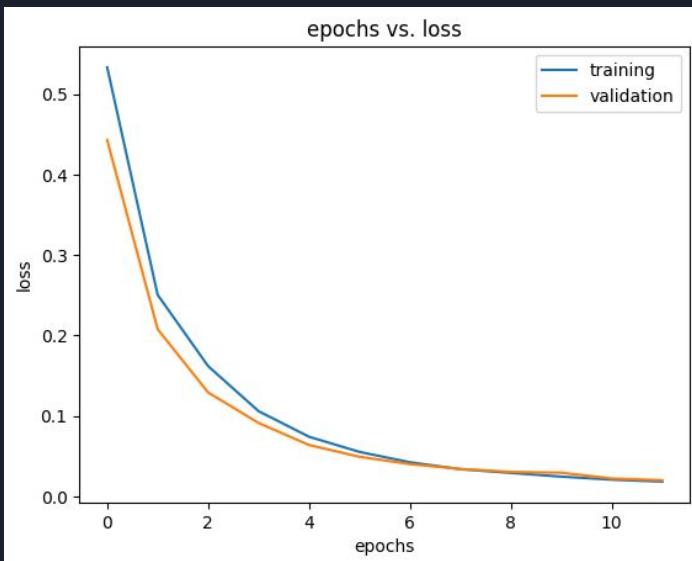
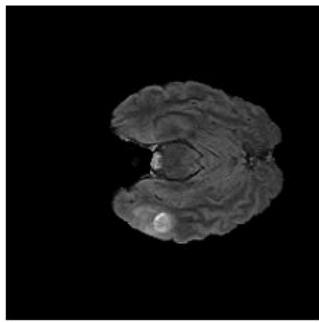
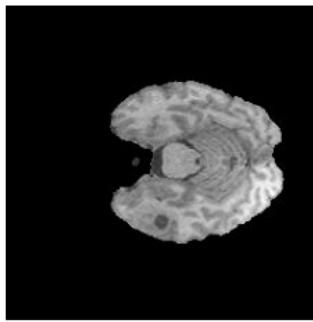


Image Example

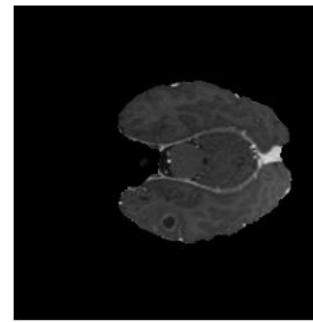
T1



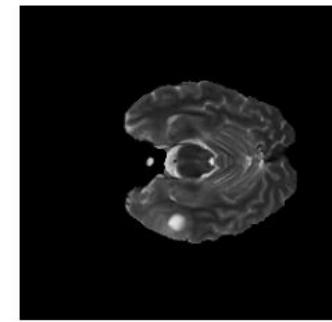
T1Gd



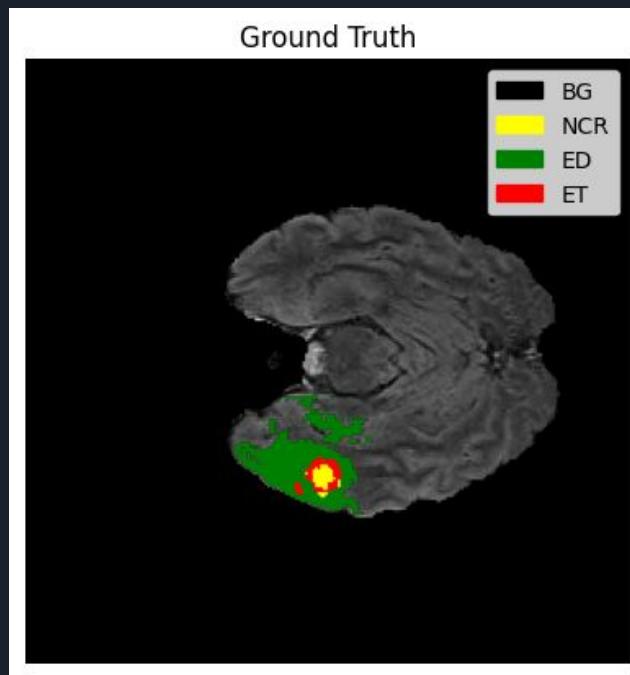
T2



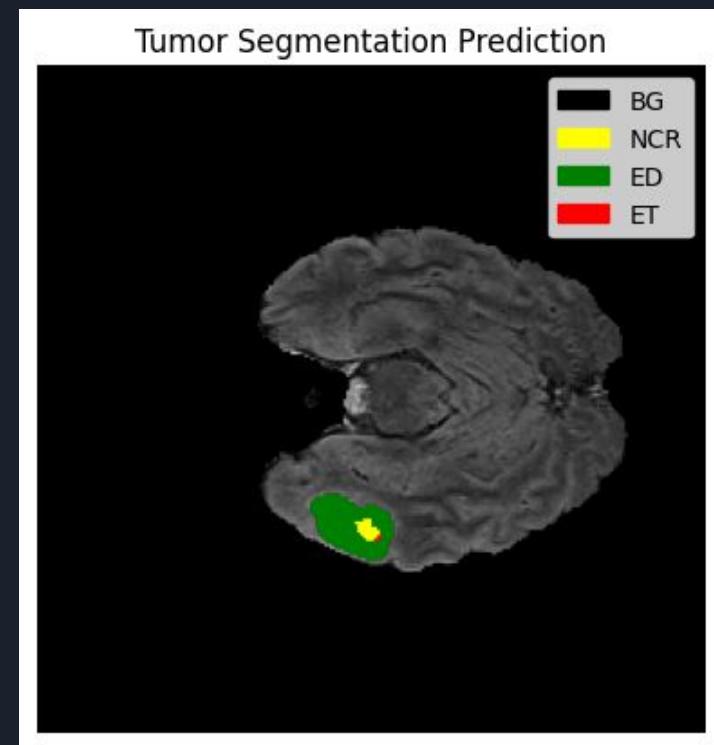
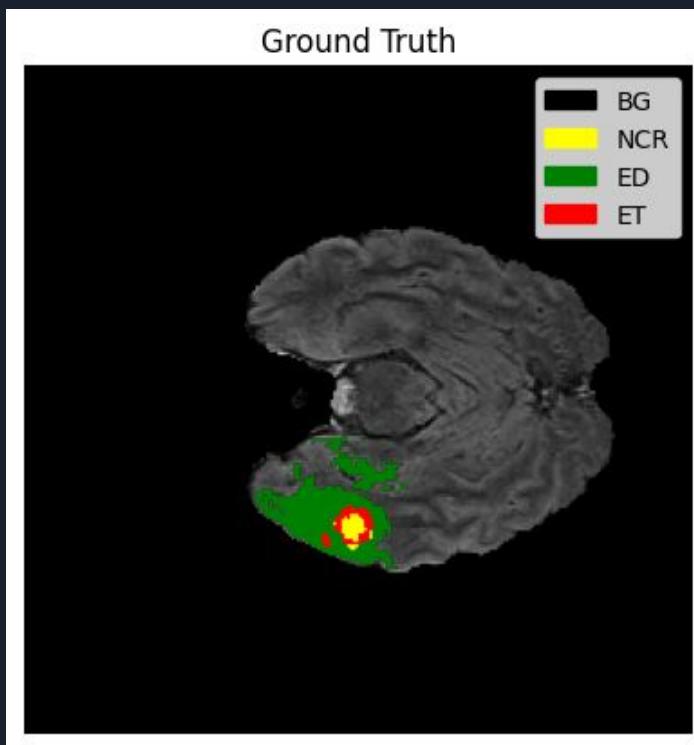
FLAIR



Mask Example

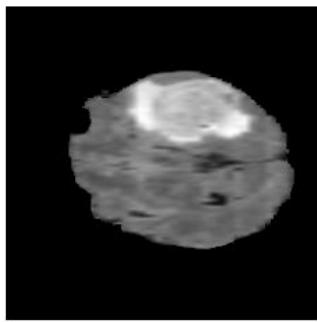


Prediction Example

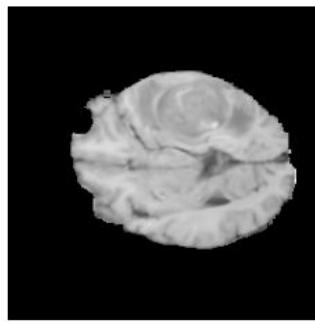


Another Image

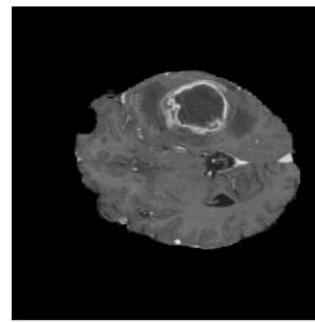
T1



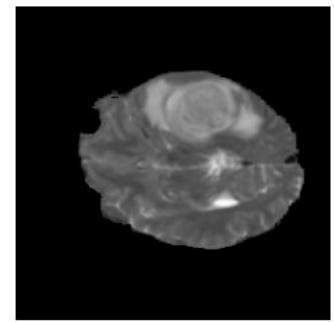
T1Gd



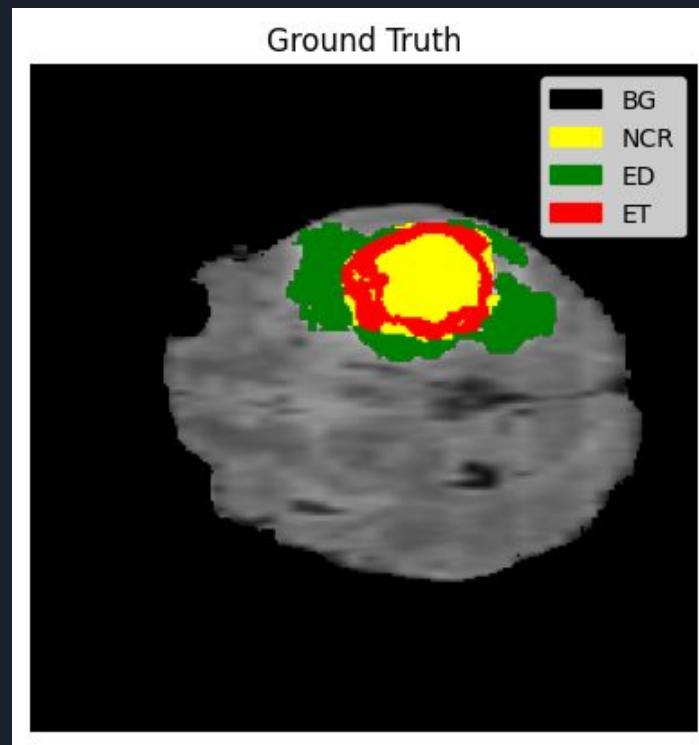
T2



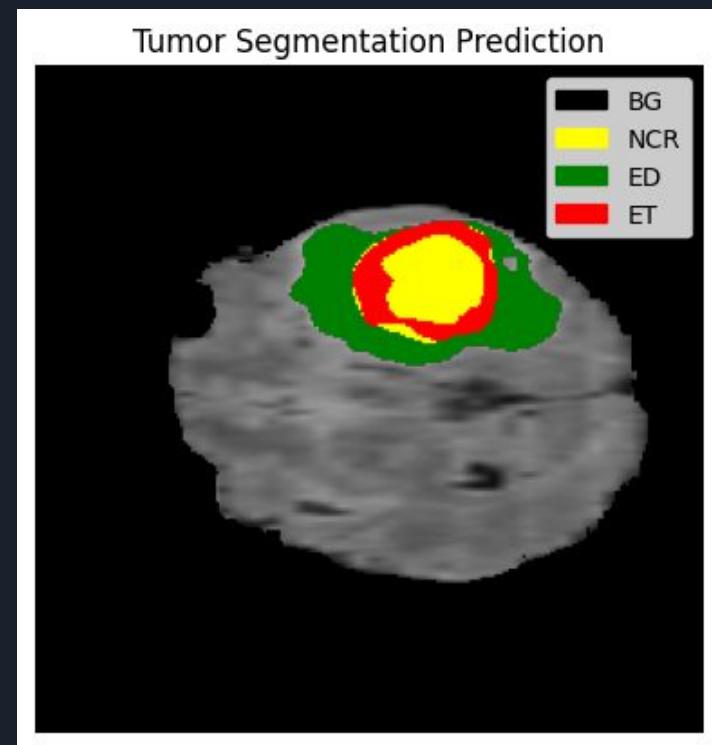
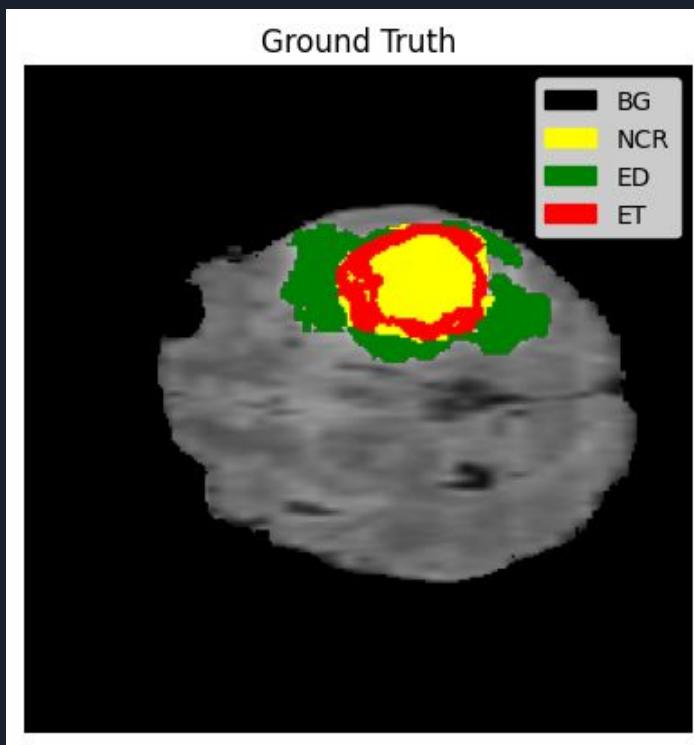
FLAIR



Mask



Prediction





Extra Video

<https://youtu.be/jqPlX29tkfM>



References

Kamara, Alpha Alimamy. "Comprehensive Guide to Mastering the UNET Model for Image Segmentation." Medium, 15 Oct. 2024,
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