## Problem 1.

## Algorithm:

#### **Information Gain:**

$$IG(X|Y) = H(X) - H(X|Y)$$

$$= \sum_{i=1}^{n} -p(x_i)log_2p(x_i) - \sum_{j=1}^{m} p(y_j)H(X|y_j)$$

The approaches used in this problem comes from the Lecture 19.

**Input:** Training set  $(x_1, y_1), ..., (x_n, y_n) \in \chi \times \{-1, 1\}$ 

**Algorithm:** Initialize  $w_1(i) = 1/n$ 

For t = 1, ..., T

- (1) Select a weak learner using information gain.
- (2) Get weak hypothesis  $G_t$  with error  $\epsilon_t = \sum_i w_t(i) \mathbb{1}[G_t(x_i) \neq y_i]$
- (3) Choose  $\alpha_i = \frac{1}{2} ln(\frac{1-\epsilon_t}{\epsilon_t})$
- (4) Update  $w_{t+1}(i) = \frac{w_t(i)exp(-\alpha_t y_i G_t(x_i))}{Z_t}$ , where  $Z_t$  is the normalization factor.

## **Output:**

$$g(x) = sign[\sum_{t=1}^{T} \alpha_t G_t(x)]$$

#### Result:

For the dataset, I entirely removed the features with missing data and the first attribute(id).

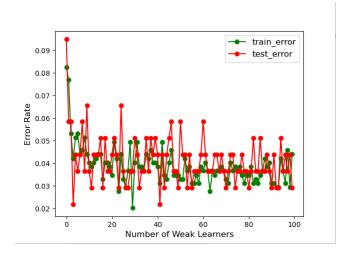


Figure 1: Adaboost Plot

#### Problem 2

#### Algorithm:

The approaches used in this problem comes from the Lecture 20.

## **Boostrap Sampling:**

- (1) Consider training set D with m training examples.
- (2) Create  $D^i$  by drawing m examples with replacement.
- (3)In expectation,  $D^i$  will leave out a fraction of examples.
- (4)Each  $D^i$  will approximate the distribution underlying D.

For Random Forest, we would build a forest of decision trees:

- (1)Create k bootstrap samples  $D^1, ..., D^k$ .
- (2)Learn an un-pruned decision tree on each sample.
- (3)Learning: At each internal node:

Randomly select m < d features.

Determine the best split using only these features.

(4)Prediction: Use output from all trees in the forest.

Classification: Majority vote.

#### Result:

For the dataset, I entirely removed the features with missing data and the first attribute(id).

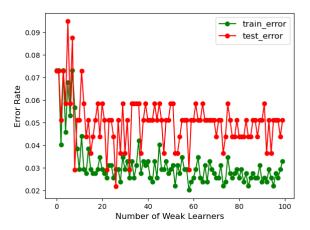


Figure 2: Random Forest with 3 attributes and vary decision stumps

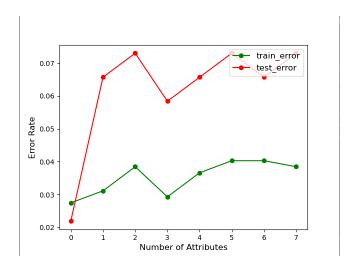


Figure 3: Random Forest with vary attributes and 100 decision stumps

## Problem 3

#### Algorithm:

The approaches used in this problem comes from the Lecture 22.

## K-means:

- (1) Consider a dataset  $\chi = \{x_1, ..., x_N\}, x_i \in R^d$
- (2)Assume there are K clusters  $C_1, ..., C_K$
- (3) Associate a prototype  $\mu_h, h=1,...,K$  with each cluster.
- (4)Let  $r_{nk} \in \{0,1\}$  be the indicator of  $x_n \in C_k$ .
- (5) The goal is to minimize the following distortion measure.

$$J = \sum_{n=1}^{N} \sum_{k=1}^{K} r_{nk} ||x_n - \mu_k||^2$$

Then, we optimize over  $\{r_{nk}\}$  for a fixed  $\{\mu_k\}$  and optimize over  $\{\mu_k\}$  for a fixed  $\{r_{nk}\}$ . Result:

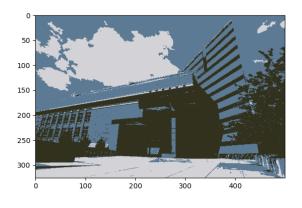


Figure 4: K means with 3 centroids

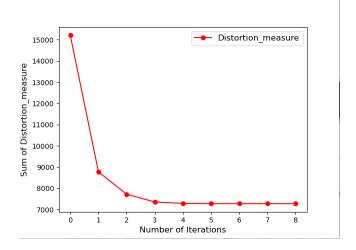


Figure 5: K means with 3 centroids

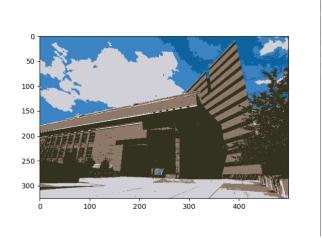


Figure 6: K means with 5 centroids

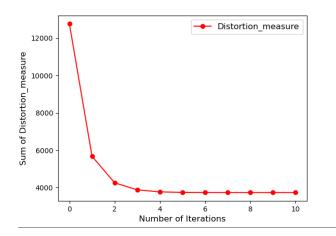


Figure 7: K means with 5 centroids

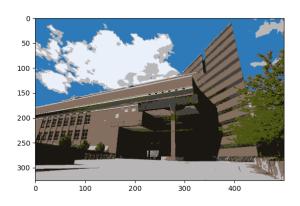


Figure 8: K means with 7 centroids

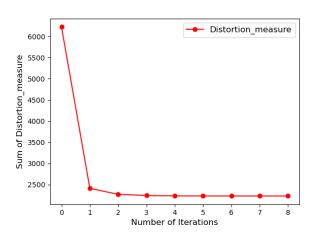


Figure 9: K means with 7 centroids

# Reference:

- $1.\mathrm{Pattern}$  Recognition and Machine Learning, CHRISTOPHER M.BISHOP
- 2.Lecture in Canvas, Nicholas Johnson