Perceptrons

CSci 5525: Machine Learning

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October 6, 2020

Announcements

- HW2 is posted (due Oct 15)
- Exam 1 will be posted on Oct 20 (due 48 hours later)

Perceptrons

- Linear classifiers with weight vector w
- Labels are encoded as $y_i \in \{-1, 1\}$
- Prediction on \mathbf{x}_i is incorrect if $y_i \mathbf{w}^{\top} \mathbf{x}_i < 0$
- Let $\mathcal{M}(\mathbf{w})$ be the set of points on which prediction is incorrect
- The objective function to be minimized

$$E(\mathbf{w}) = -\sum_{i \in \mathcal{M}(\mathbf{w})} (y_i \mathbf{w}^\top \mathbf{x}_i)$$

- For any point $i \in \mathcal{M}(\mathbf{w})$, gradient $\nabla E_i(\mathbf{w}) = -y_i \mathbf{x}$
- The gradient based update

$$\mathbf{w}_{(new)} = \mathbf{w}_{(old)} - \eta \nabla E_i(\mathbf{w}) = \mathbf{w}_{(old)} + \eta y_i \mathbf{x}_i$$

- The learning rate parameter η can be set to 1
- No update corresponding to the correctly predicted points



Analysis of Perceptron Training

- Algorithm goes through all the points sequentially
 - If prediction is correct, do not change anything
 - If prediction is wrong, and $y_i = +1$ then $\mathbf{w}_{(new)} = \mathbf{w}_{(old)} + \mathbf{x}_i$
 - ullet If prediction is wrong, and $y_i = -1$ then $oldsymbol{w}_{(new)} = oldsymbol{w}_{(old)} oldsymbol{x}_i$
- Each update reduces the error contribution for that point

$$-\mathbf{w}_{(new)}^{\top}\mathbf{x}_{i}y_{i} = -\mathbf{w}_{(old)}^{\top}\mathbf{x}_{i}y_{i} - (\mathbf{x}_{i}y_{i})^{\top}\mathbf{x}_{i}y_{i} < -\mathbf{w}_{(old)}^{\top}\mathbf{x}_{i}y_{i}$$

$$\checkmark_{\downarrow + 1} - \checkmark_{\downarrow} + \gamma_{i} :$$

- But the update can increase the contribution of other terms
- Will this ever converge?



Perceptrons: Loss Function, SGD

The objective function to be minimized

$$E(\mathbf{w}) = -\sum_{i \in \mathcal{M}(\mathbf{w})} y_i \mathbf{w}^{\top} \mathbf{x}_i$$

- For any point $i \in \mathcal{M}(\mathbf{w})$, gradient $\nabla E_i(\mathbf{w}) = -y_i \mathbf{x}_i$
- Perceptron objective is hinge loss, with hinge at 0

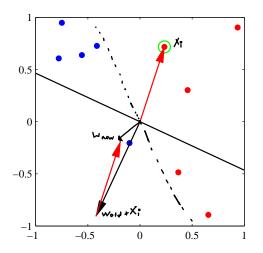
$$E(\mathbf{w}) = \sum_{i=1}^{n} \max(0, -y_i \mathbf{w}^{\top} \mathbf{x}_i)$$

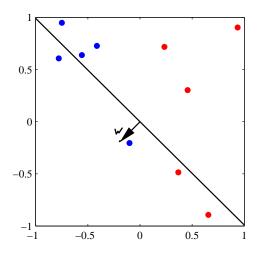
Recall SVM objective, hinge at 1 plus regularization

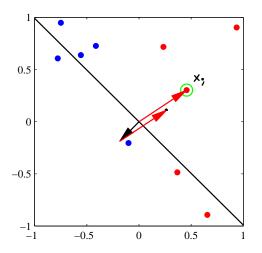
$$E(\mathbf{w}) = \sum_{i=1}^{n} \max(0, 1 - y_i \mathbf{w}^{\top} \mathbf{x}_i) + \frac{\lambda}{2} \|\mathbf{w}\|^2$$

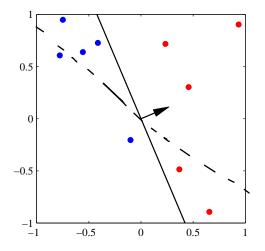
- Stochastic sub-gradient descent (SGD), fixed step-size
- Improvements: Use mini-batch?











Perceptron Convergence Theorem

- If the data is linearly separable
 - Training converges in finite number of iterations
- Consider a separable dataset $\{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)\}$
- Let \mathbf{u} , $\|\mathbf{u}\| = 1$ be a separator so that $\forall i, y_i \mathbf{u}^\top \mathbf{x}_i \geq \gamma > 0$
- Let $R = \max_i \|\mathbf{x}_i\|$
- Theorem: Training converges after at most $\left(\frac{R}{\gamma}\right)^2$ mistakes

Proof

- Let $v_1 = 0$
- Let \mathbf{v}_{k+1} be the vector making the k^{th} mistake

$$\mathbf{v}_{k+1} = \mathbf{v}_k + y_i \mathbf{x}_i$$

Then,

$$\mathbf{v}_{k+1}^{\top}\mathbf{u} = \mathbf{v}_{k}^{\top}\mathbf{u} + y_{i}\mathbf{u}^{\top}\mathbf{x}_{i}$$

$$\geq \mathbf{v}_{k}^{\top}\mathbf{u} + \gamma$$

$$\geq k\gamma$$

Also,

$$\|\mathbf{v}_{k+1}\|^2 = \|\mathbf{v}_k\|^2 + 2y_i\mathbf{v}_k^{\top}\mathbf{x}_i + \|\mathbf{x}_i\|^2$$

 $\leq \|\mathbf{v}_k\|^2 + R^2$
 $\leq kR^2$



Proof (cont.)

Since u is a unit vector

$$\mathbf{v}_{k+1}^{\top}\mathbf{u} \leq \|\mathbf{v}_{k+1}\|$$

$$k\gamma \leq \mathbf{v}_{k+1}^{\top}\mathbf{u} \leq \|\mathbf{v}_{k+1}\| \leq \sqrt{k}R$$

$$\sqrt{k} \leq \frac{R}{\gamma}$$

$$k \leq \left(\frac{R}{\gamma}\right)^{2}$$

Perceptrons: Ideas

Loss function is non-shifted hinge loss

$$E(\mathbf{w}) = -\sum_{i \in \mathcal{M}} y_i \mathbf{w}^{\top} \mathbf{x}_i = \sum_{i=1}^n \max(0, -y_i \mathbf{w}^{\top} \mathbf{x}_i)$$

- Perceptron training is stochastic gradient descent (SGD)
 - Gradient based updated considering one data point at random

$$\mathbf{w}_{(new)} = \mathbf{w}_{(old)} - \eta \nabla E_i(\mathbf{w}) = \mathbf{w}_{(old)} + \eta y_i \mathbf{x}_i$$

- The convergence depends on the margin γ as $\left(\frac{R}{\gamma}\right)^2$
 - Larger margin leads to faster convergence (in the worst case)