Pi Calculus

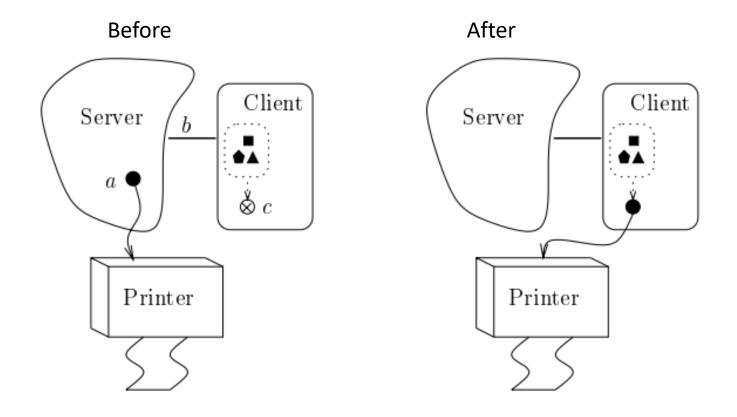
CS242

Lecture 13

Motivation

- Assume we have three entities
 - A server
 - A client
 - A resource controlled by the server, such as a printer
- How do we model the client requesting access to the printer from the server?

Picture



From "An Introduction to the Pi-Calculus". J. Parrow

Process Calculi

- The essence of this problem is modeling the interaction of concurrent processes
- Models are known as *process calculi*
- There are many!
 - Much more diverse than the situation with, say, sequential programming
 - With functions, the only thing to observe is the output for a given input
 - Many more choices about what can be observed/modeled with concurrent systems

Process Calculi

• All process calculi share communication over *channels*

- A prefix can
 - Send a message x on channel a: $\bar{a}x$
 - Receive a message x on channel a: a(x)
- An *agent* can be
 - Empty 0
 - A prefix p followed by an agent A: p.A
- Example
 - Parallel composition of two agents: $\bar{a}x$.P | a(y).Q

Pi Calculus

- The distinguishing feature of the Pi Calculus is that channels are values
 - Channels can themselves be sent as messages
- As we shall see, this gives the Pi Calculus great expressivity

Pi Calculus is one of the most popular process calculi

Syntax

```
• Prefixes p = \overline{a}x \mid a(x)
```

```
• Agents P = 0 empty p.P prefix P + P choice P \mid P parallel x \circ p \circ y \Rightarrow P match (op is = or \neq) vx \circ P restriction !P iteration
```

```
• Prefixes p = \overline{a}x \mid a(x)
```

```
• Agents P = 0 empty p.P prefix P + P choice P \mid P parallel x \circ p \circ y \Rightarrow P match (op is = or \neq) vx \circ P restriction !P iteration
```

$$\bar{a}x.P \mid a(y).Q \rightarrow P \mid Q\{y := x\}$$

```
• Prefixes p = \overline{a}x \mid a(x)
```

```
Agents P = 0 empty
p.P prefix
P + P choice
P | P parallel
x op y => P match (op is = or ≠)
vx P restriction
!P iteration
```

Idiom:
$$(x = y => P) + (x \neq y \Rightarrow Q) \rightarrow P$$
 if $x = y$

```
• Prefixes p = \overline{a}x \mid a(x)
```

```
• Agents P = 0 empty p.P prefix P + P choice P \mid P parallel p \mid P match (op is = or \neq) p \mid P restriction p \mid P iteration
```

$$!P \rightarrow P \mid !P$$

```
• Prefixes p = \overline{a}x \mid a(x)
• Agents P = 0
                                       empty
                                       prefix
                  p.P
                                       choice
                  P + P
                  P | P
                                      parallel
                                      match (op is = or \neq)
                 x op y => P
                  vx P
                                      restriction
                  !P
                                       iteration
           | x(y).0 | | \bar{x}z.0 \rightarrow x(y).0 | | x(y).0 | \bar{x}z.0 | | \bar{x}z.0 \rightarrow | x(y).0 | | \bar{x}z.0
```

```
• Prefixes p = \overline{a}x \mid a(x)
```

```
Agents P = 0 empty
p.P prefix
P + P choice
P | P parallel
x op y => P match (op is = or ≠)
vx P restriction
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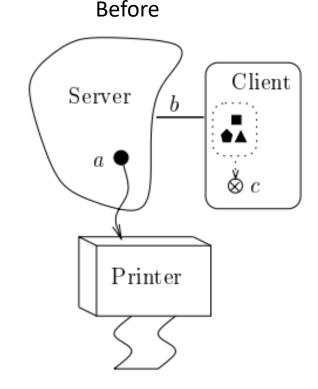
 $! x(y) | ! \bar{x}z \rightarrow x(y) | !x(y) | \bar{x}z | !\bar{x}z \rightarrow ! x(y) | !\bar{x}z$ Not: The trailing 0's are usually elided.

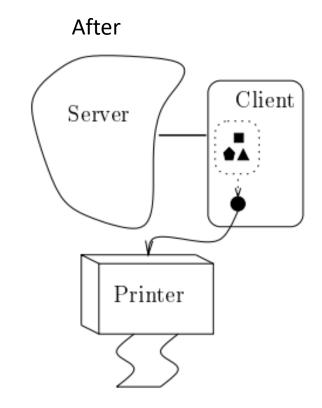
Restriction

• υx P introduces a channel local to P

- Example: R | vx (P | Q)
 - P and Q share the name x and can communicate with each other over x
 - R does not have access to x
 - R | vx ($\bar{x}a.P | x(b).Q$) $\rightarrow R vx$ (P | Q{b := a})
 - But x can be passed to R on a different channel that R shares with P or Q
 - Passing a restricted channel expands its scope to include the new agent
 - a(z).R | $vx (\bar{a}x.P \mid Q) \rightarrow vx (R\{z := x\} \mid P \mid Q)$
 - Note alpha renaming may be required to avoid capture of existing x in R

Back to the Example ...





 $(va\ (\overline{b}a.S \mid a(e).P)) \mid b(c).\overline{c}d.C$

Unbounded Computation

We can create as many fresh channel names as we like:

```
!(\upsilon x P) \rightarrow \\ \upsilon x P \mid !(\upsilon x P) \rightarrow \\ \upsilon x P \mid \upsilon x P \mid !(\upsilon x P) \rightarrow \\ \upsilon x P \mid \upsilon y P\{x := y\} \mid !(\upsilon x P)
```

What Can We Do With That?

A lot!

• Example: Linked Lists

Lists

- Use two constants (unused channels) Nil and Cons
- The translation function L takes a list I and a channel c and returns an agent that provides access to a representation of I through c
- Idea: A list element communicates its kind (Nil or Cons) and then its arguments over c.

```
L(Nil, x) = \bar{x} Nil
L(Cons H T, x) = vy \, vz \, \bar{x}Cons.\bar{x}y \, \bar{x}z \, | \, L(H,y) \, | \, L(T,z)
```

```
L(Nil, x) = \bar{x} Nil
L(Cons H T, x) = vy \, vz \, \bar{x}Cons.\bar{x}y \, \bar{x}z \, | \, L(H,y) \, | \, L(T,z)
```

```
L(Cons Nil Nil, x) = vy vz \bar{x}Cons.\bar{x}y.\bar{x}z \mid L(Nil,y) \mid L(Nil,z) = vy vz \bar{x}Cons.\bar{x}y.\bar{x}z \mid \bar{y} Nil \mid L(Nil,z) = vy vz \bar{x}Cons.\bar{x}y.\bar{x}z \mid \bar{y} Nil \mid \bar{z} Nil
```

Length of a List

Len computes the length of a list x and leaves the result on channel a.

```
Len(x,a) = vp \ vk \ vs \ Fold(k,s) \ | \ Sum(s,p,a) \ | \ \bar{p}0 \ | \ \bar{k}x

Sum(s,p,a) = !(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} \ n+i

Fold(k,s) = !(k(z).z(y). y = Nil => \bar{s}0 + y = Cons => \bar{s}1.z(h).z(t).\bar{k}t)
```

```
(vy vz \bar{x}Cons.\bar{x}y.\bar{x}z \mid \bar{y} Nil \mid \bar{z} Nil)
|
Len(x,a)
```

```
(vy vz \bar{x}Cons.\bar{x}y.\bar{x}z | \bar{y} Nil | \bar{z} Nil)
Fold(k,s)
Sum(s,p,a)
\bar{p}0
```

(dropping top-level binders for p, k and s for brevity)

```
(vy vz \bar{x}Cons.\bar{x}y.\bar{x}z | \bar{y} Nil | \bar{z} Nil)
!(k(z).z(y). y = Nil => \bar{s}0 + y = Cons => \bar{s}1.z(h).z(t).kt)
!(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i)
\bar{p}0
```

```
(vy vz \bar{x}Cons.\bar{x}y.\bar{x}z | \bar{y} Nil | \bar{z} Nil)
(k(z).z(y). y = Nil => \bar{s}0 + y = Cons => \bar{s}1.z(h).z(t).kt) | Fold(k,s)
!(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i)
\bar{p}0
```

```
(vy vz \bar{x}Cons.\bar{x}y.\bar{x}z | \bar{y} Nil | \bar{z} Nil)
x(y). y = Nil => \bar{s}0 + y = Cons => \bar{s}1. x(h).x(t).kt | Fold(k,s)
!(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i)
\bar{p}0
```

```
(vy vz \bar{x}y.\bar{x}z | \bar{y} Nil | \bar{z} Nil)
Cons = Nil => \bar{s}0 + Cons = Cons => \bar{s}1.x(h).x(t).kt | Fold(k,s)
!(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i)
\bar{p}0
```

```
(vy \ vz \ \bar{x}y . \bar{x}z \mid \bar{y} \ Nil \mid \bar{z} \ Nil)
Cons = Cons => \bar{s}1.x(h).x(t).\bar{k}t \mid Fold(k,s)
!(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i)
\bar{p}0
```

```
(vy vz \bar{x}y.\bar{x}z | \bar{y} Nil | \bar{z} Nil)
\bar{s}1.x(h).x(t).\bar{k}t \mid Fold(k,s)
!(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i)
\bar{p}0
```

```
(vy vz \bar{x}y.\bar{x}z | \bar{y} Nil | \bar{z} Nil)
\bar{s}1.x(h).x(t).\bar{k}t \mid Fold(k,s)
(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i) \mid Sum(s,p,a)
\bar{p}0
```

```
(vy \ vz \ \bar{x}y . \bar{x}z \mid \bar{y} \ Nil \mid \bar{z} \ Nil)
x(h).x(t).\overline{k}t \mid Fold(k,s)
p(n). 1 = 0 => \bar{a}n + 1 \neq 0 => \bar{p} n+1 | Sum(s,p,a)
\bar{p}0
```

```
(vy \ vz \ \bar{x}y. \bar{x}z \mid \bar{y} \ Nil \mid \bar{z} \ Nil)
x(h).x(t).\overline{k}t \mid Fold(k,s)
1 = 0 \Rightarrow \bar{a}n + 1 \neq 0 \Rightarrow \bar{p} + 1 \mid Sum(s,p,a)
```

```
(vy \ vz \ \bar{x}y.\bar{x}z \ | \ \bar{y} \ Nil \ | \ \bar{z} \ Nil)
x(h).x(t).\overline{k}t \mid Fold(k,s)
1 \neq 0 => \bar{p} \ 0+1 \mid Sum(s,p,a)
```

```
(vy \ vz \ \bar{x}y.\bar{x}z \ | \ \bar{y} \ Nil \ | \ \bar{z} \ Nil)
x(h).x(t).\overline{k}t \mid Fold(k,s)
\bar{p} 0+1| Sum(s,p,a)
```

```
(vy \ vz \ \bar{x}y. \bar{x}z \ | \ \bar{y} \ \text{Nil} \ | \ \bar{z} \ \text{Nil})
| \ x(h).x(t).\bar{k}t \ | \ \text{Fold(k,s)}
| \ \bar{p} \ 1
| \ \text{Sum(s,p,a)}
```

Remove 0 agents as they will not contribute further.

```
(vy \ vz \ \bar{x}z \mid \bar{y} \ Nil \mid \bar{z} \ Nil)
x(t).\overline{k}t \mid Fold(k,s)
\bar{p} 1
Sum(s,p,a)
```

```
(vy \ vz \ 0 \ | \ \overline{y} \ Nil \ | \ \overline{z} \ Nil)
| \overline{k}z \ | \ Fold(k,s)
| \overline{p} \ 1
| Sum(s,p,a)
```

```
(vy vz 0 | \overline{y} Nil | \overline{z} Nil)
\bar{k}z
Fold(k,s)
\bar{p} 1
Sum(s,p,a)
```

```
(vy vz 0 | \overline{y} Nil | \overline{z} Nil)
\overline{k}z
!(k(z).z(y). y = Nil => \bar{s}0 + y = Cons => \bar{s}1. z(h).z(t).kt)
\bar{p} 1
!(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i)
```

```
(vy vz 0 | \overline{y} Nil | \overline{z} Nil)
\overline{k}z
(k(z).z(y). y = Nil => \bar{s}0 + y = Cons => \bar{s}1. z(h).z(t).kt) | Fold(k,s)
\bar{p} 1
(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i) \mid Sum(s,p,a)
```

```
(vy vz 0 | \overline{y} Nil | \overline{z} Nil)
(z(y). y = Nil => \bar{s}0 + y = Cons => \bar{s}1. z(h).z(t).kt) | Fold(k,s)
\bar{p} 1
(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i) \mid Sum(s,p,a)
```

```
(vy vz 0 | \overline{y} Nil | 0)
(Nil = Nil => \bar{s}0 + Nil = Cons => \bar{s}1. z(h).z(t).kt) | Fold(k,s)
\bar{p} 1
(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i) \mid Sum(s,p,a)
```

```
(vy vz 0 | \overline{y} Nil | 0)
Nil = Nil => \bar{s}0 | Fold(k,s)
\bar{p} 1
(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i) \mid Sum(s,p,a)
```

```
(vy vz 0 | \overline{y} Nil | 0)
\bar{s}0 | Fold(k,s)
\bar{p} 1
(s(i).p(n). i = 0 => \bar{a}n + i \neq 0 => \bar{p} n+i) \mid Sum(s,p,a)
```

```
(vy vz 0 | \overline{y} Nil | 0)
0 | Fold(k,s)
\bar{p} 1
(p(n). 0 = 0 => \bar{a}n + 0 \neq 0 => \bar{p} n+0) \mid Sum(s,p,a)
```

```
(vy vz 0 | \overline{y} Nil | 0)
0 | Fold(k,s)
(0 = 0 => \bar{a}1 + 0 \neq 0 => \bar{p} 1+0) \mid Sum(s,p,a)
```

```
Fold(k,s)
|
(0 = 0 => \bar{a}1 + 0 \neq 0 => \bar{p} 1+0)
|
Sum(s,p,a)
```

Remove 0 and useless agents ...

```
Fold(k,s)

|
(0 = 0 => \bar{a}1)
|
Sum(s,p,a)
```

```
Fold(k,s)
| \\ \bar{a}1
| \\ Sum(s,p,a)
```

No further computation can be done at this point until an external agent decides to read the length from a.

SKI

• We can also encode the SKI calculus or the lambda calculus in pi calculus.

• SKI is a little easier to explain ...

Idea

• We represent combinator expressions as trees, as usual

Each combinator takes an extra (last argument) for its parent

- There is a separate combinator for each possible number of children
 - E.g., S₀(p) is S applied to no children and just the parent
 - $S_1(x, p)$ is S applied to 1 child x and the parent
 - $S_2(x, y, p)$ is S applied to 2 children x and y and the parent

One New Construct

Add recursive definitions

$$A(x_1,...,x_n) = P$$

- Now A(...) can also appear inside P
- Not necessary, can be simulated with !P
 - For definitions with single recursive calls:
 - Each invocation of P writes its result to a unique global channel p
 - Where the result of recursive call is needed P reads the value from p
 - See length of a list example ...

Collecting Children

```
S_{0}(p) = vw \, \bar{p}w.(\bar{w}s_{0} \mid S_{0}(p))
S_{1}(p,x) = vw \, \bar{p}w.(\bar{w}s_{1}. \, \bar{w}x \mid S_{1}(p,x))
S_{2}(p,x,y) = vw \, \bar{p}w.(\bar{w}s_{2}. \, \bar{w}x. \, \bar{w}y \mid S_{2}(p,x))
K_{0}(p) = vw \, \bar{p}w.(\bar{w}k_{0} \mid K_{0}(p))
K_{1}(p,x) = vw \, \bar{p}w.(\bar{w}k_{1}. \, \bar{w}x \mid K_{1}(p,x))
I_{0}(p) = vw \, \bar{p}w.(\bar{w}i_{0} \mid I_{0}(p))
I_{1}(p,x) = vw \, \bar{p}w.(\bar{w}i_{1}. \, \bar{w}x \mid I_{1}(p,x))
```

Each combinator sends a series of messages to its parent: first the private channel, then the combinator's identity, then its children. Afterwards, it resets itself for another application.

Application

The application agent @(x,y,p) applies a left child x to a right child y with parent p using the rules of SKI.

$$@(x,y,p) = x(w).w(a).$$

$$(a = s_0 => S_1(y,p) + a = s_1 => w(u).S_2(u,y,p) + a = s_2 => w(u).w(v). vp_1 vp_2 @(u,y,p_1) | @(v,y,p_2) | @(v,y,p_2) | @(p_1,p_2,p) + a = k_0 => K_1(y,p) + a = k_1 => w(u). l_1(u,p) + a = i_0 => l_1(y,p) + a = i_1 => w(u).@(u,y,p))$$

Comments

Note two new tree nodes are created for the two new applications in S u v y = (u y) (v y). Here $p_1 = u$ y and $p_2 = v$ y.

```
@(x,y,p) = x(w).w(a).

(a = s_0 => S_1(y,p) + a = s_1 => w(u).S_2(u,y,p) + a = s_2 => w(u).w(v). vp_1 vp_2 @(u,y,p_1) | @(v,y,p_2) | @(v,y,p_2) | @(p_1,p_2,p) + a = k_0 => K_1(y,p) + a = k_1 => w(u). l_1(u,p) + a = i_0 => l_1(y,p) + a = i_1 => w(u).@(u,y,p))
```

Comments

Ix is not immediately rewritten to x. Instead we wait until it is applied to something (Ix) y = x y, which allows us to use a uniform three argument application rule.

```
@(x,y,p) = x(w).w(a).

(a = s_0 => S_1(y,p) + a = s_1 => w(u).S_2(u,y,p) + a = s_2 => w(u).w(v). vp_1 vp_2 @(u,y,p_1) | @(v,y,p_2) | @(v,y,p_2) | @(p_1,p_2,p) + a = k_0 => K_1(y,p) + a = k_1 => w(u). l_1(u,p) + a = i_0 => l_1(y,p) + a = i_1 => w(u).@(u,y,p))
```

Comments

```
S_{0}(p) = vw \, \bar{p}w.(\bar{w}s_{0} \mid S_{0}(p))
S_{1}(p,x) = vw \, \bar{p}w.(\bar{w}s_{1}. \, \bar{w}x \mid S_{1}(p,x))
S_{2}(p,x,y) = vw \, \bar{p}w.(\bar{w}s_{2}. \, \bar{w}x. \, \bar{w}y \mid S_{2}(p,x))
K_{0}(p) = vw \, \bar{p}w.(\bar{w}k_{0} \mid K_{0}(p))
K_{1}(p,x) = vw \, \bar{p}w.(\bar{w}k_{1}. \, \bar{w}x \mid K_{1}(p,x))
I_{0}(p) = vw \, \bar{p}w.(\bar{w}i_{0} \mid I_{0}(p))
I_{1}(p,x) = vw \, \bar{p}w.(\bar{w}i_{1}. \, \bar{w}x \mid I_{1}(p,x))
```

The sharing of combinators means that the structure we build is actually a DAG not a tree – the same subterm may be shared by multiple parents. That is a much more efficient representation, as when a subterm is reduced it is shared by any other expressions that use that same subterm.

Applications of Pi Calculus

• Languages based on pi calculus are usually *modeling languages*, not programming languages

- A modeling language is used for building models
 - And proving things about them
 - But not for running the models

Applications of Pi Calculus

- Analysis of concurrent protocols
 - e.g., client/server
- Analysis of cryptographic protocols
- Systems biology
 - Building models of cell pathways
- Modeling business processes
- And more!

What is Modeled?

- Proving properties of protocols
 - That a protocol doesn't deadlock
 - That a cryptographic protocol is secure against an attacker (another agent)
- In general
 - That a system is guaranteed to reach some state
 - That a system is guaranteed not to reach some state

Summary

- Process calculi
 - Model concurrent agents
 - Fundamental operation is sending a message on a channel
 - Pi calculus allows the messages to also be channels
- A very active area
 - Lots of work
 - In many different fields where concurrent agents with a fixed set of interactions is a good description of how things work