

Artificial Intelligence CS 534 Fall-2017

Reinforcement Learning and Searching in Game

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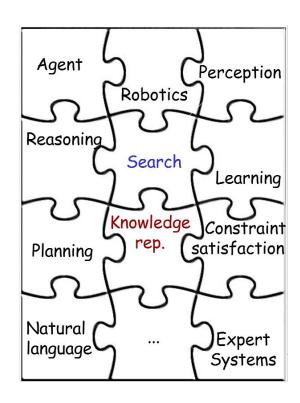
Introduction & Motivation

Artificial Intelligence

- Now Al technology has become far more effective and widely available
- All is the study of ideas that enable computers to be intelligent
- Main areas of Al
- Video game

Motivation

- In video games, Pac-man constitutes a very interested test environment (for learning AI techniques)
- Complex enough to be challenging
- Implement learning algorithms in the Pac-man game and visualize the results
- > Better understanding foundational AI concepts



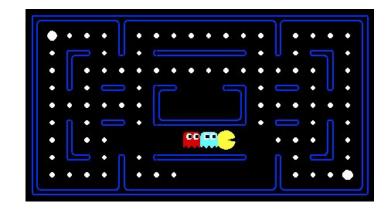
Background

The Pac-man Game

- Pac-man developed by Namco 1980 (Japan). Simple maze game
- Ghosts played by the computer and chase the Pac-man and try to catch it
- Pac-man wins if it has eaten all dots □, loses if caught by a Ghost
- Pac-Man can move (at most) up, down, left and right

Learning Algorithms

- Reinforcement learning methods are widely used in computer games
- A method to generate policies for agent tasked with making decisions.
- Typically represented by a Markov Decision Process



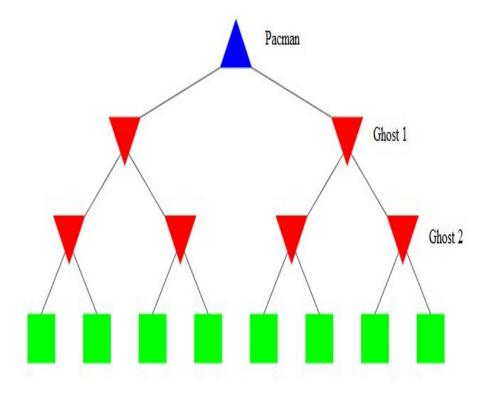
Method and Technical Approach

We will discuss two approaches for programming intelligence, learnability and adaptability into the game:

- Adversarial Search algorithms
 - O Minimax
 - Alpha-beta Pruning
 - Expectimax
- Reinforcement Learning
 - Q-Learning
 - Approximate Q-Learning

Method-Adversarial Search

- Minimax Search
 - choose move with the highest minimax value
 - Propagate the utility values bottom
 -up using MIN and MAX operator
 - At the root node selects the move with the max utility value
- Minimax with Alpha-beta pruning
 - avoid searching subtrees of moves which won't be selected



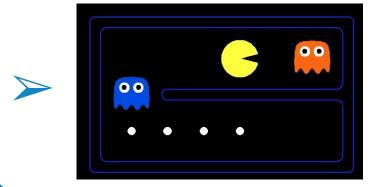
Method-Adversarial Search

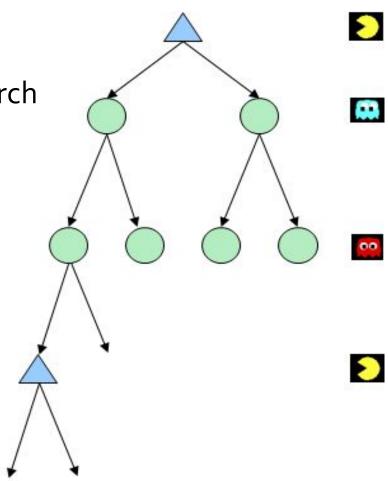
Expectimax Search

Max nodes (Pacman) as in Minimax Search

 Chance nodes (ghosts), like min nodes, except the outcome is uncertain

Take weight average (expectation)
 as expected utilities





Q-Learning

- $> Q(s,a) \approx r + \gamma \max_{a'} Q(s',a')$
 - Q is the utility, r is the reward by taking action a, rmax(s',a') is the future reward by taking action a.
- Incorporate the new estimate into a running average

$$Q(s,a) \leftarrow (1-\alpha)Q(s,a) + (\alpha)\left[r + \gamma \max_{a'} Q(s',a')\right]$$

However, basic Q-Learning keeps a table of all q-values. In reality, we cannot possibly learn about every single state.

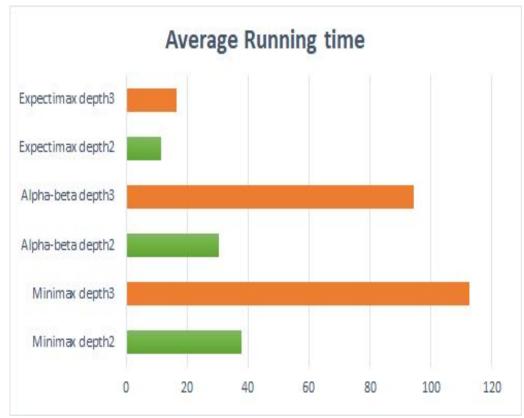
Approximate Q-Learning

- New method to calculate the Q value

 - $Q(s,a) = w_1 f_1(s,a) + w_2 f_2(s,a) + \ldots + w_n f_n(s,a)$ difference = $\left[r + \gamma \max_{a'} Q(s',a')\right] Q(s,a)$
 - $w_i \leftarrow w_i + \alpha$ [difference] $f_i(s, a)$
- Learn about some small number of training states from experience. Generalize that experience to new, similar situations.

Results

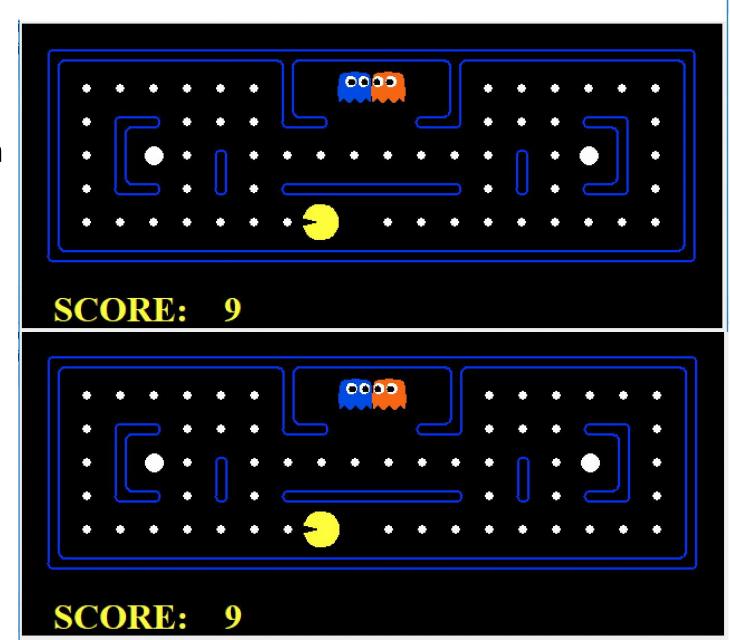




Results

Expectimax Search

Minimax Search



Results













Conclusion

- Expectimax algorithm is much better than the minimax algorithm and alpha-beta pruning search. However, it has less foresight than Q-Learning and approximate Q-Learning.
- Pac-man using the approximate Q learning approach win 80 percent of the games for merely 25 times of training. But doesn't have a dramatic improvement of performance with more training.

Thank You !!!

