

Calibration results

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Camera-system parameters:

cam0 (/usb_cam/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.39683646 0.13764127 0.0002224 0.00029607] +- [0.00172989 0.00186042 0.00024374 0.00037252]

projection: [361.65862437 483.66534419 318.58959714 243.62500577] +- [0.68985868 0.89698518 0.7729054
0.85183804]

reprojection error: [-0.000000, -0.000001] +- [0.292798, 0.300328]

Target configuration

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Type: aprilgrid

Tags:

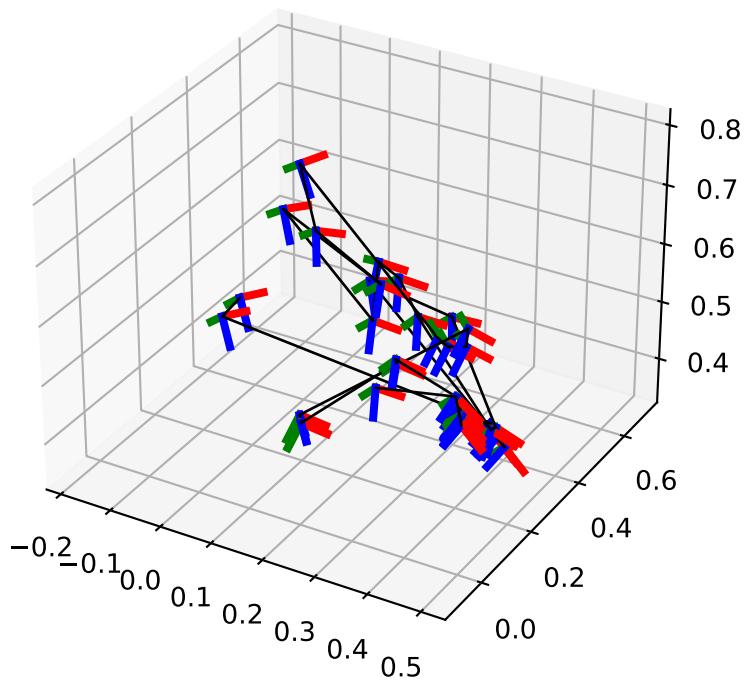
Rows: 6

Cols: 6

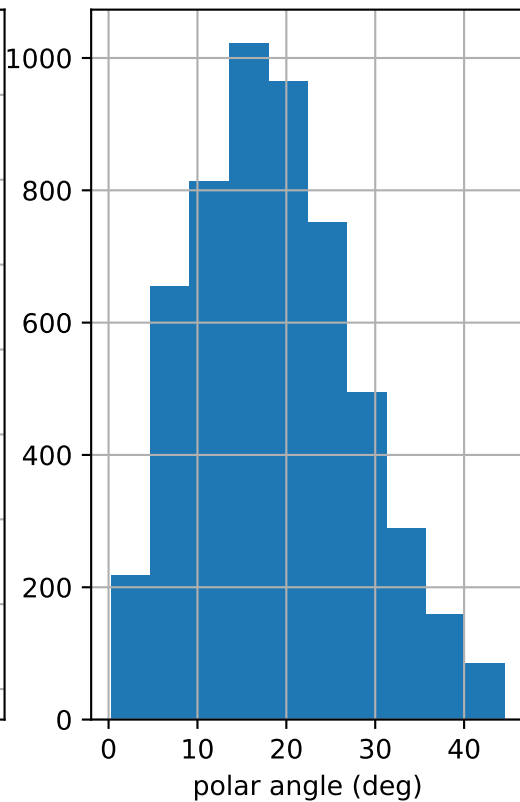
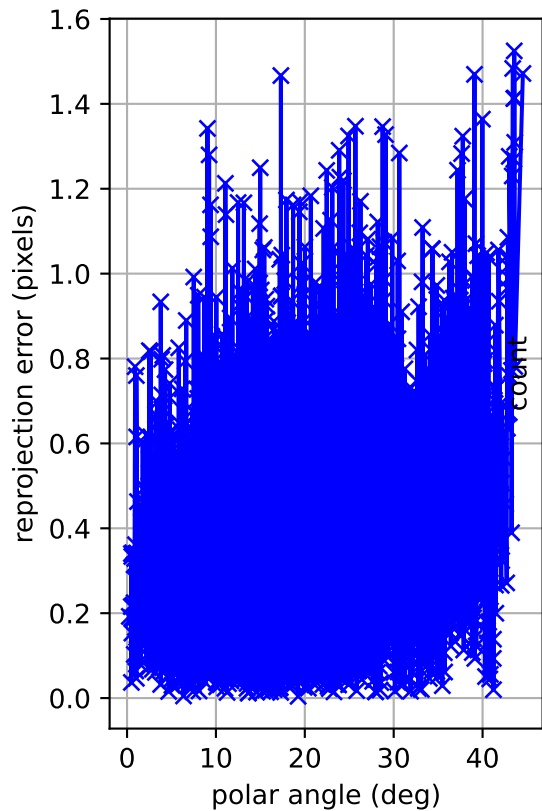
Size: 0.055 [m]

Spacing 0.0165 [m]

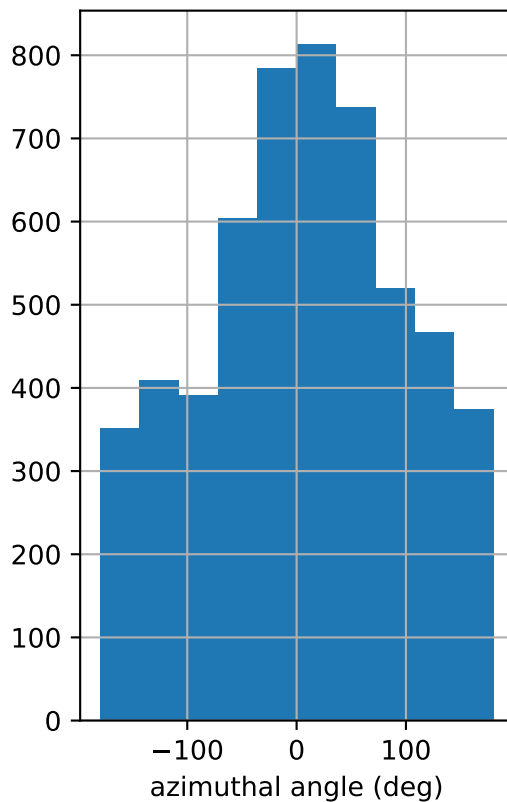
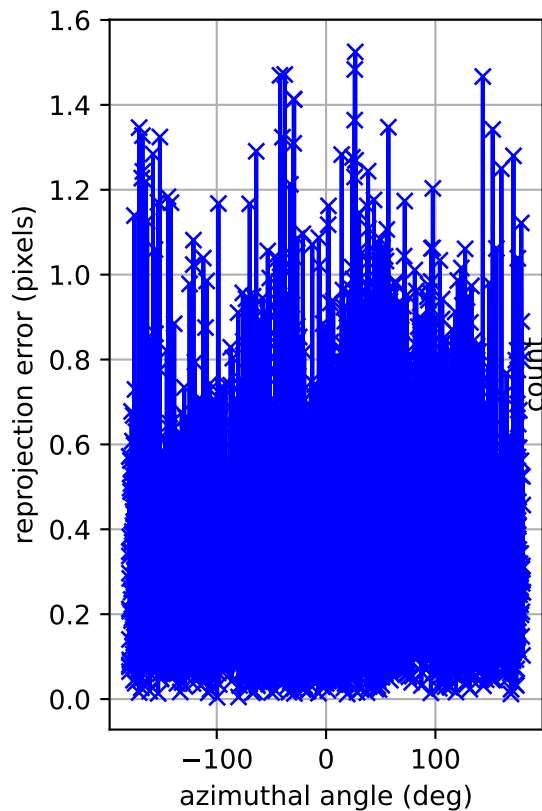
cam0: estimated poses



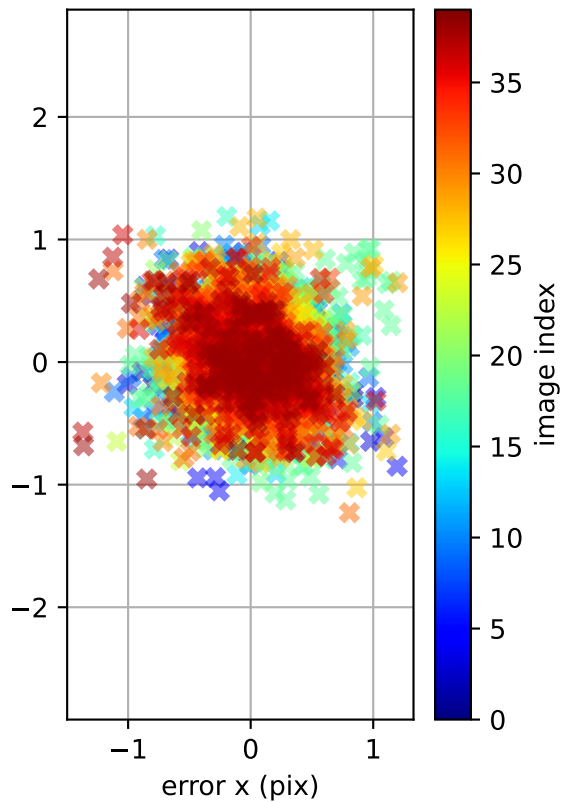
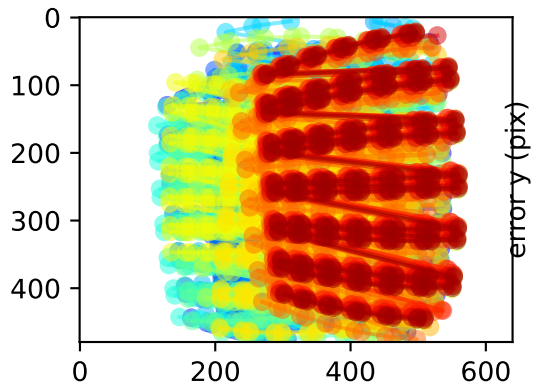
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

