

Calibration results

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Camera-system parameters:

cam0 (/usb_cam/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedOmniCameraGeometry'>

distortion: [-0.77130125 0.44168155 -0.00197266 0.00763335] +- [0.00883155 0.0256788 0.00089233 0.00157631]

projection: [0.88840784 698.52348668 933.77106845 312.78387743 247.14924625] +- [0.00708055 0.18188637
0.13646975 1.22821227 1.14137302]

reprojection error: [-0.000007, -0.000000] +- [0.247957, 0.241656]

Target configuration

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Type: aprilgrid

Tags:

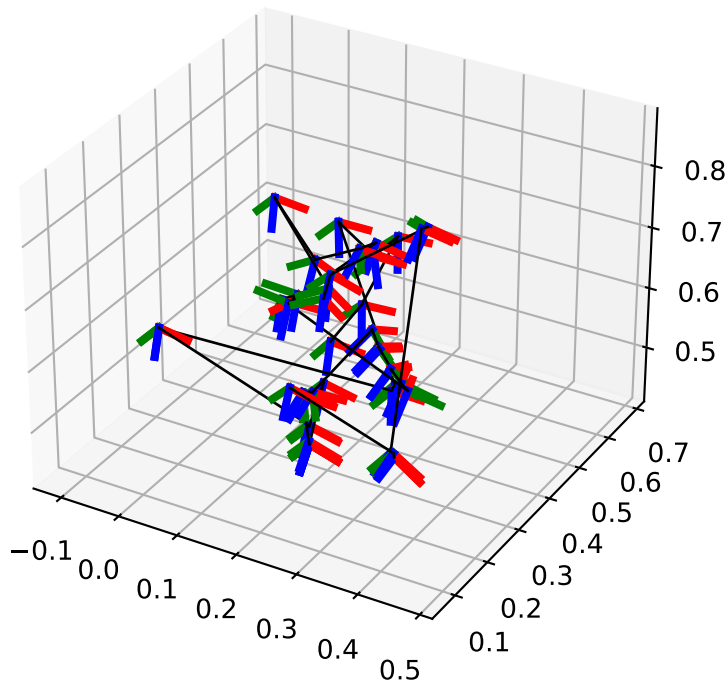
Rows: 6

Cols: 6

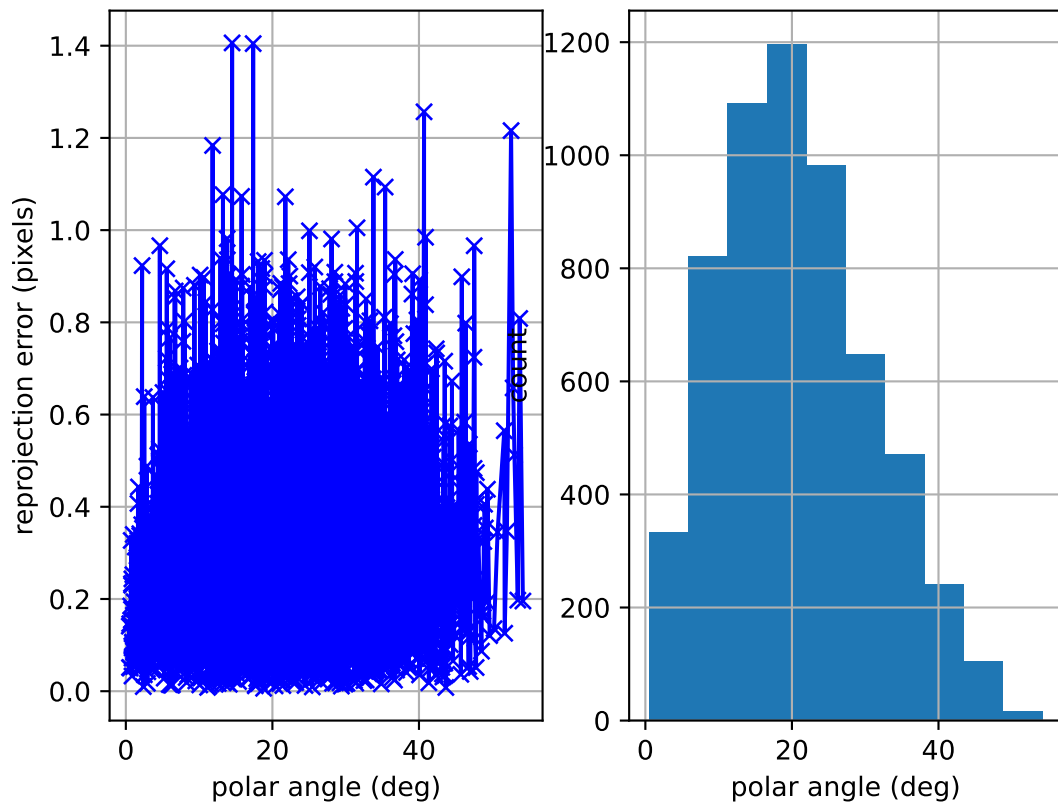
Size: 0.055 [m]

Spacing 0.0165 [m]

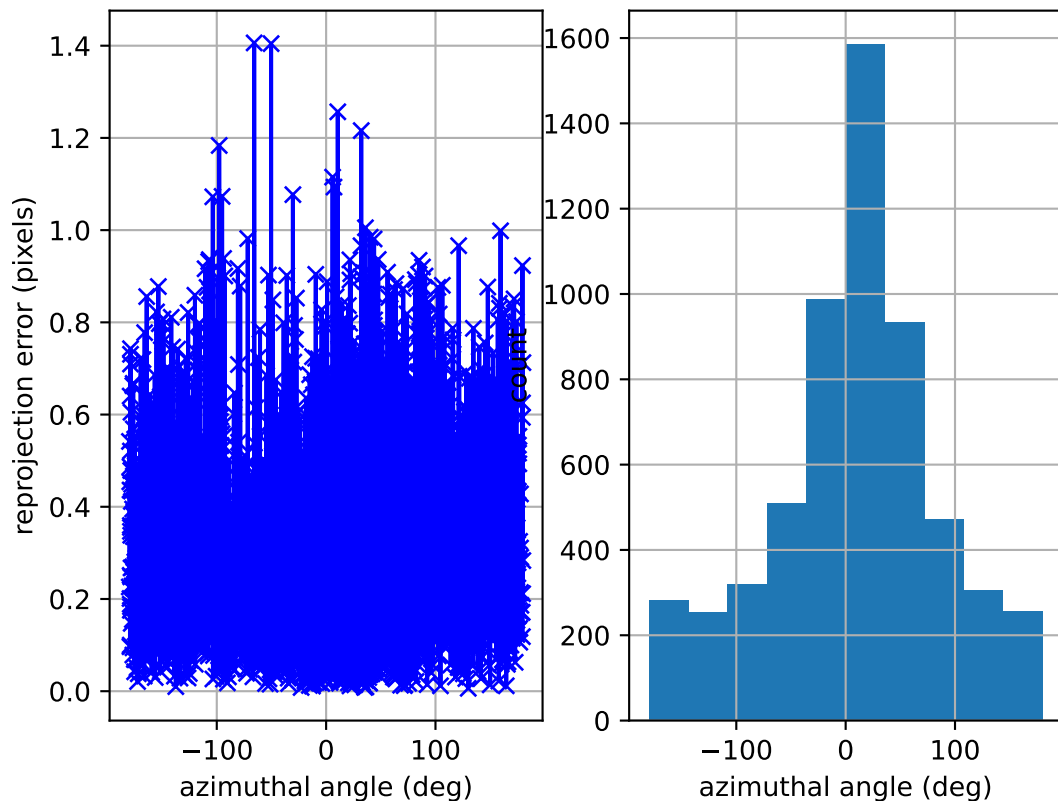
cam0: estimated poses



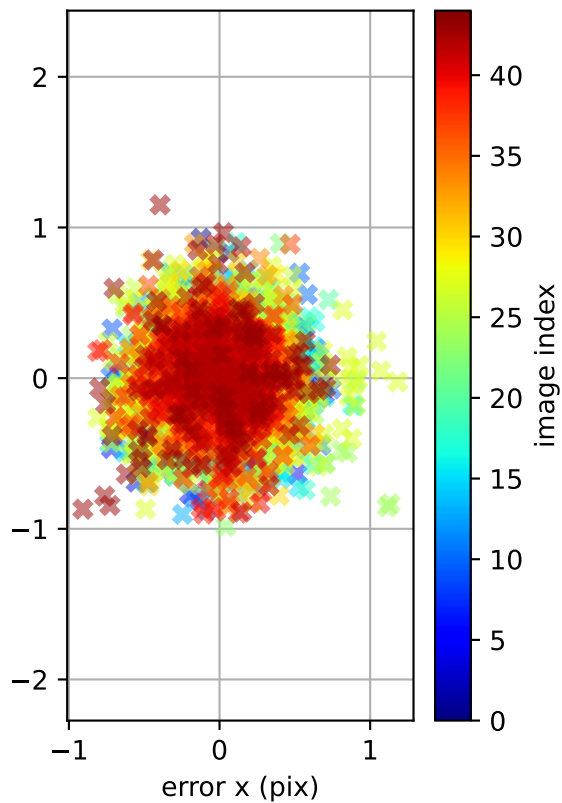
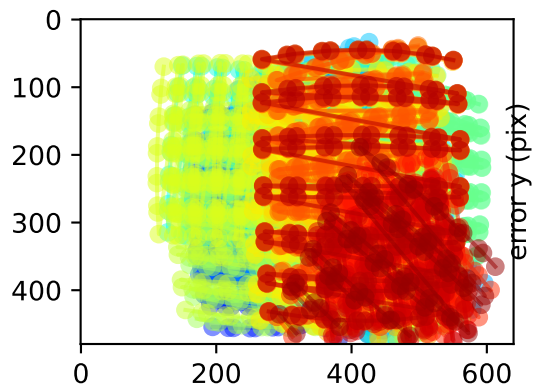
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

