Calibration results
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Camera-system parameters:
cam0 (/usb_cam/image_raw):
    type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
    distortion: [-0.41523504 0.17319494 -0.00110577 0.00004254] +- [0.00280082 0.0044404 0.0003716 0.00032564]
    projection: [545.50166165 547.20747895 318.35456239 249.78628849] +- [1.525322   1.50768708 0.88349127
0.95576645]
    reprojection error: [0.000002, -0.000001] +- [0.319645, 0.354546]

Target configuration
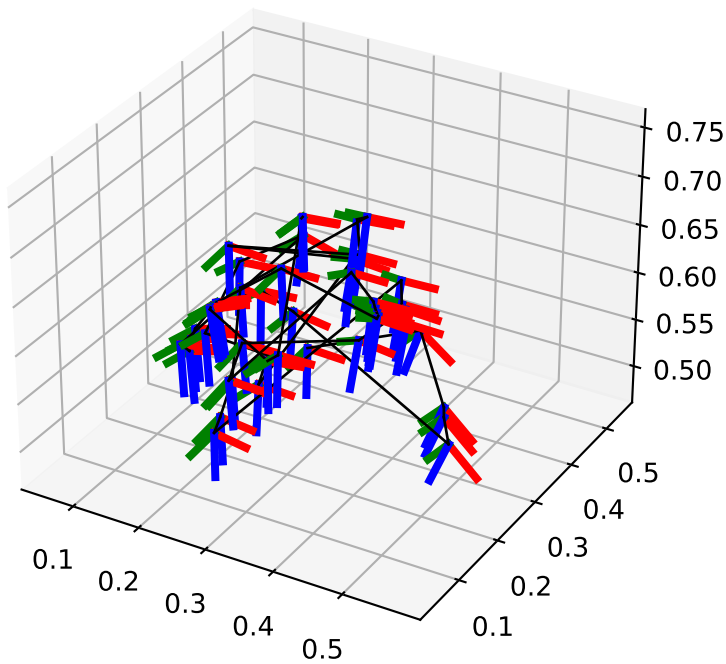====================

  Type: aprilgrid
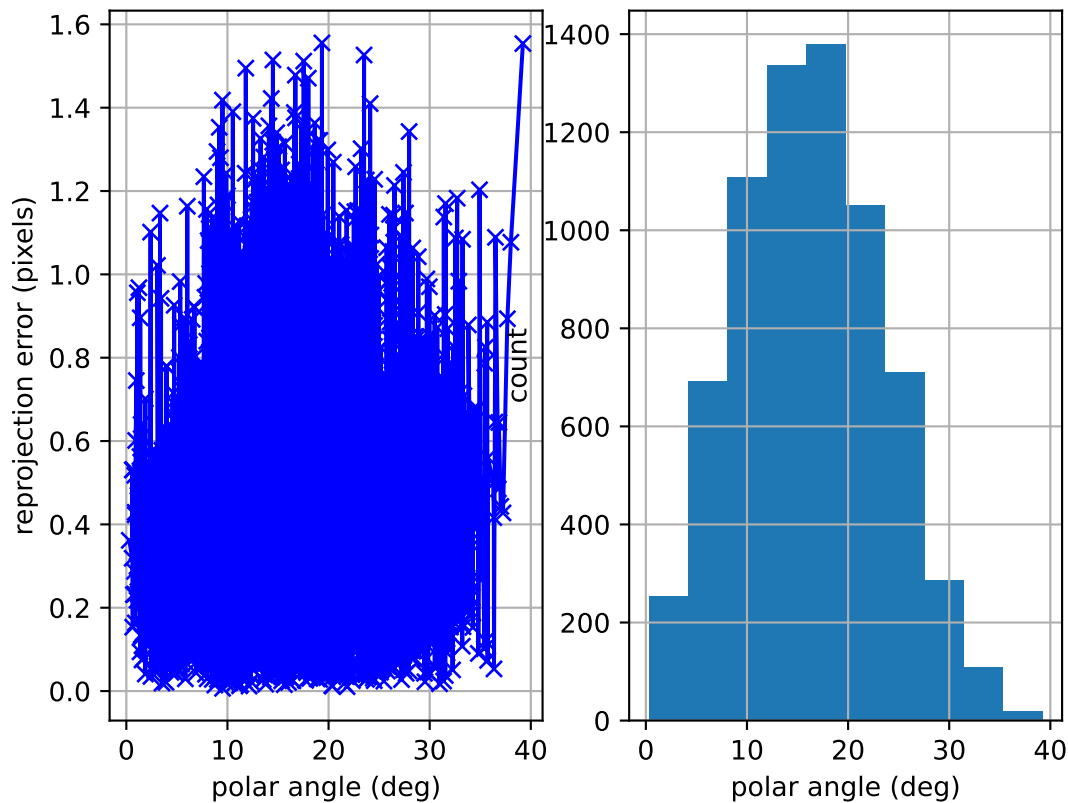 Tags:
    Rows: 6
    Cols: 6
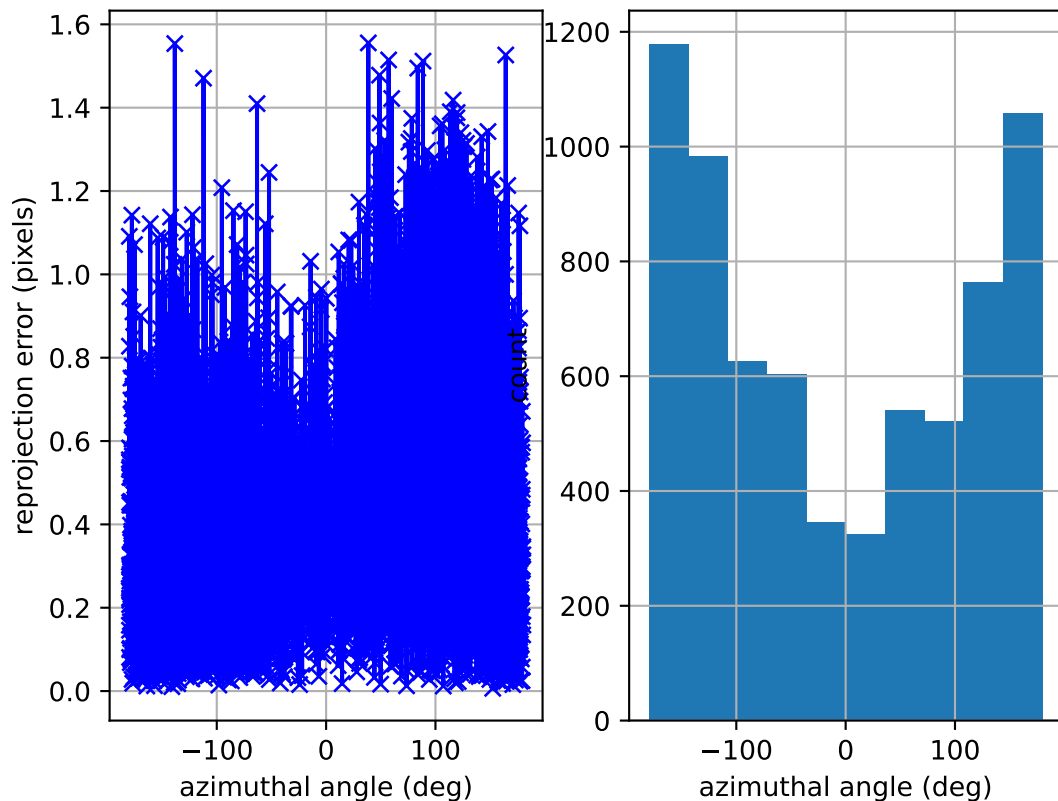   Size: 0.055 [m]
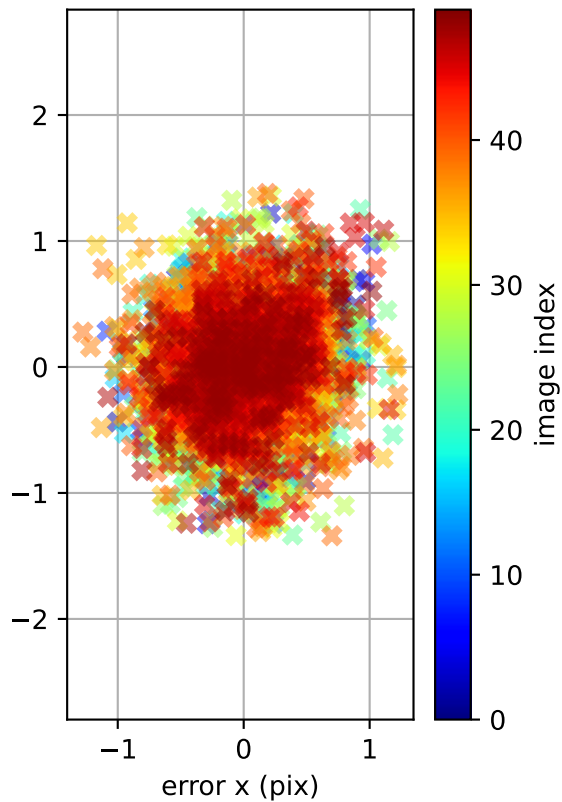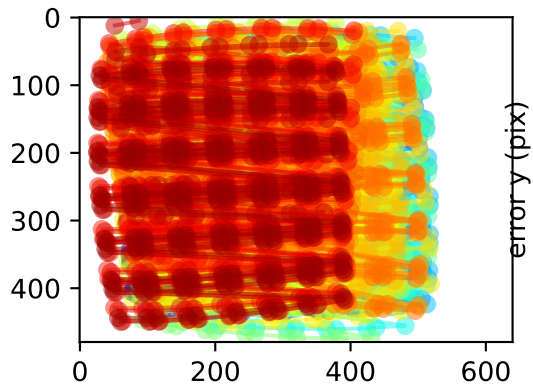   Spacing 0.0165 [m]

cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0