

# Qianjun Xia

100 Park Avenue, PH4F | qx2253@columbia.edu | (917)295-7344 | <https://qianjun-xia.github.io/>

[www.linkedin.com/in/qianjunxia2002](https://www.linkedin.com/in/qianjunxia2002) | <https://github.com/Qianjun-Xia>

## Education

- 
- Columbia University**, MS in Mechanical Engineering Sept 2024 – Present
- GPA: 4.12/4.3
  - Concentration: Robotics and Control
- Shanghai Jiao Tong University**, BS in Mechanical Engineering Sept 2020 – Jun 2024
- GPA: 82.76/100
  - Double Major: Mathematics and Applied Mathematics

## Internship

- 
- Shanghai ABB Engineering Co., Ltd**, Vision Algorithm Intern Jun 2023 – Sept 2023
- Assisted algorithm engineers with vision algorithm development and experiment.
  - Completed a demo of a binocular vision system with Halcon used for completing the work of auto tire assembly; achieved a positioning accuracy of 1mm.

## Research Experience

- 
- Video-Based Parameter Estimation, Creative Machine Lab** Mar 2025 – Present  
*Supervisor: Jiong Lin, Hod Lipson*
- Designed and implemented simulation environments to model the motion of elastic objects under gravity and actuator forces.
  - Generated large-scale datasets from simulation, incorporating varied object geometries, actuation patterns.
  - Applied the TimeSformer video understanding model to predict object physical parameters from multi-frame visual data.
- Magnetic Wire-Guiding Robot, – Shanghai Jiao Tong University** May 2023 – Aug 2024  
*Supervisor: Dong Wang*
- Led a team of three members to design a magnetic wire-guiding device to help doctors in interventional surgeries. The guide wire's is made up of magnetic material and soft material. A robotic arm is used to control the magnet and drive the rotation of the guide wire's head to guide the direction
  - Used SolidWorks to design and model the wire-guiding device; coded with Python to control the robot arm and two motors with a Xbox controller
  - Used PNP algorithm to calibrate the the tip of the wire with a monocular camera; achieved a position accuracy less than 1mm.
  - Based on the Cosserat Rod Theory, developed a Finite Element Algorithm to anticipate the Deformation of an elastic rod under a certain magnetic field.

## Extracurricular Activity

- 
- Shanghai Jiao Tong University Racing Car Team**, Car body Group Sept 2021 – Dec 2022
- Took charge of the manufacture of the monocoque shell and the rest of the body-related components, such as seat belts and seat fixtures.
  - Drew machining drawings; participated in car body making and assembly; conducted car maintenance and repairing.

## Technologies

---

**Languages:** Python, C++, MATLAB, R

**Technologies:** Solidworks, Fusion360, UG, Catia, Adams, Ansys