

### Deep Learning DS-GA 1008.

#### Lab session Agenda - 01/31

## Agenda

- Grader introduction
- PyTorch

## **Attendees**

DSGA 1008 enrolled students.

# Assignment logistic

- Teams: 2-3. Restricted #members.
  - Send Hao Liu ( <u>hl2514@nyu.edu</u> ) an email, following the format highlighted from the course website. "[DS-GA-1008 YOUR\_TEAM\_NAME]"
  - Who has sent me email, but not following the format, please resent to Hao Liu.
  - o DEADLINE: Feb 5th.
  - Once again, the unregistered students won't be able to compete on Kaggle.
- Other preparation: LaTeX is a must for the submission.

# **PyTorch**

- Installation from the documentation of the page
  - Anaconda is recommended
  - Pip or from source is also valid
- Go through the first part of : <a href="https://github.com/pytorch/tutorials/blob/master/Deep%20Learning%20with%20PyTorch.ipvnb">https://github.com/pytorch/tutorials/blob/master/Deep%20Learning%20with%20PyTorch.ipvnb</a>

- Reference doc: <a href="http://pytorch.org/docs/tensors.html">http://pytorch.org/docs/tensors.html</a>
- Exercise 1:
  - Initialize random tensors a, b, c of size [2,3], [2,3], [3,2,3].
  - o Fill tensor a with all 10
  - Fill tensor b with elements being sampled from the normal distribution
  - o Point-wise multiply a with b, and put the result into tensor b
  - Print the mean and std of the elements of b
  - Fill tensor c with elements samples from the uniform distribution U(-1,1)
  - Transpose the second and third dimension of tensor c, and put the result into tensor c itself (in-place).
  - Show the contiguity property of the tensors
  - Print the second column of the third dimension of tensor c (note zero-indexed)
  - Perform operation a+b+c (note the broadcasting)
  - In-place storing the result into tensor c?
- Exercise 2 (image):
  - Image is naturally a 3D tensor: RGB channels + spatial dimension
  - A batch of images amounts to be 4D tensor: [batchSize x nchannels x width x height]
  - Download MNIST training dataset using torchvision
  - Show the size of train set data (just the size, don't dump them all out..)
  - Show the size of train set labels
  - Access the first image of MNIST train set (you may use any method to display it, such as matplotlib, where you might need to cast it into numpy)
  - Make a grid of a batch of train set data
    - Declare a DataLoader first, with size 4
    - Use the torchvision.make grid
  - Verify that the batch of samples are consistent with the batch of labels (by printing is enough)
  - What about a different size of batch, say 32?
- Exercise 3 (Classification Neural network):
  - Declare a similar network defined here:

https://github.com/pytorch/tutorials/blob/master/Deep%20Learning%20with%2 0PyTorch.ipynb

- This one is used for CIFAR32, which is RGB and of size 32x32
- You need to find a way to get it to work on MNIST, which is grayscale and of size 28x28
- Declare a loss functional using CrossEntropy used for classification
- Declare an optimizer using ADAM
- Prepare a batch of samples from MNIST
- Zeroize the gradient of the network
- Run forward pass
- Print the loss
- Run backward pass

- $\circ\quad$  Print the mean, max and min value of gradient module by module
- Let the optimizer act a step