CSE250B Homework 5

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1 Voting perceptrons

1.1

The final decision boundary is not linear.

For plotting the non-linear decision boundary, I choose 10000 points on the 2-D plane and classify them into 2 categories.

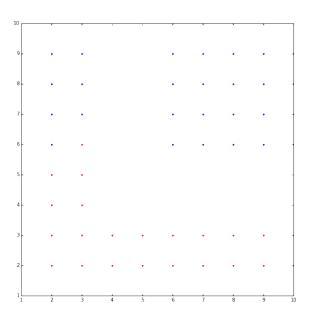


Figure 1: classified points, T = 10

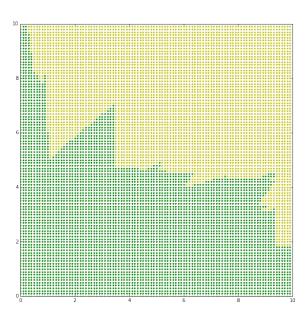


Figure 2: decision boundary, T = 10

1.2 downsample

Pseudo code

```
\begin{aligned} &\mathbf{l} = 1,\, c_l = 0,\, w_l = \vec{0} \\ &\mathbf{repeat} \; \mathbf{T} \; \mathbf{times:} \\ &\mathbf{randomly} \; \mathbf{shuffle} \; (\mathbf{X},\, \mathbf{Y}) \\ &\mathbf{for} \; \mathbf{every} \; X^{(i)},\, Y^{(i)} \mathbf{:} \\ &\mathbf{if} \; \mathbf{L} \; \mathbf{different} \; \mathbf{values} \; \mathbf{of} \; \mathbf{w} \; \mathbf{are} \; \mathbf{stored:} \\ &\mathbf{combine} \; \mathbf{the} \; \mathbf{former} \; \mathbf{L} \mathbf{-1} \; \mathbf{w} \; \mathbf{into} \; \mathbf{one} \; \mathbf{weighted} \; \mathbf{average} \; \mathbf{result} \\ &\mathbf{combine} \; \mathbf{the} \; \mathbf{former} \; \mathbf{L} \mathbf{-1} \; \mathbf{c} \; \mathbf{into} \; \mathbf{one} \; \mathbf{sum} \\ &\mathbf{keep} \; \mathbf{the} \; \mathbf{last} \; \mathbf{item} \; \mathbf{of} \; \mathbf{w} \; \mathbf{and} \; \mathbf{c} \\ &\mathbf{if} \; X^{(i)},\, Y^{(i)} \; \mathbf{is} \; \mathbf{misclassified:} \\ &w_{l+1} = w_l + Y^{(i)} X^{(i)} \\ &c_{l+1} = 1 \\ &l = l+1 \\ &\mathbf{else:} \\ &c_l = c_l + 1 \end{aligned}
```

Performance

Since the length of w in part a is less than 400 and L = 400 here in part b, we can simply compare the result shown in part a and b to assess the downsampling.

From the image, we can find that downsampling does not hamper the performance. Actually it classifies the points on the top left corner better partially as a result of increase in T.

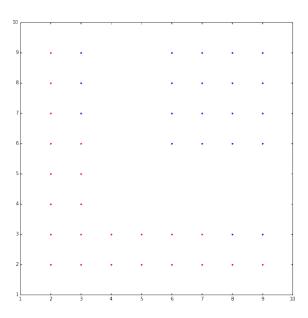


Figure 3: classified points, T = 20, L = 400

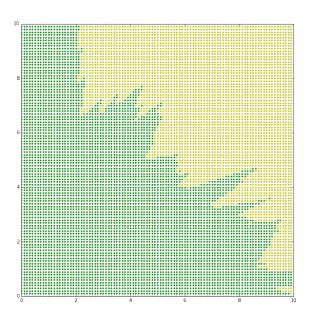


Figure 4: decision boundary, T = 20, L = 400

1.3

Pseudo code

```
\begin{split} & \text{repeat T times:} \\ & \text{randomly shuffle (X, Y)} \\ & \text{for every } X^{(i)}, Y^{(i)}\text{:} \\ & \text{if } X^{(i)}, Y^{(i)} \text{ is misclassified:} \\ & w_{l+1} = w_l + Y^{(i)}X^{(i)} \\ & c_{l+1} = 1 \\ & \text{combine the two existing w into one using average perceptron and store at the first place combine the two existing c into one using summation and store at the first place append the new <math>w_{l+1} to the tail of the list w append the new c_{l+1} to the tail of the list c & l = l+1 \\ & \text{else:} \\ & c_l = c_l + 1 \end{split}
```

Performance

From the result we can see that the average perceptron algorithm helps us obtain a more linear decision boundary.

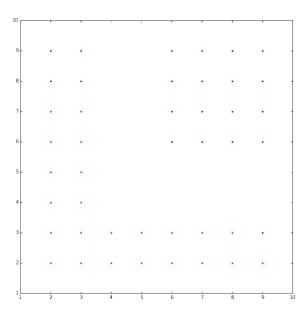


Figure 5: classified points, T = 10

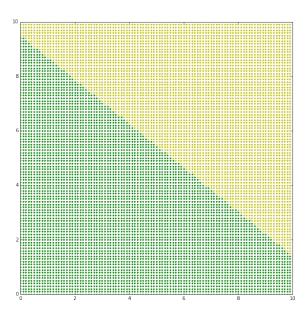


Figure 6: decision boundary, T = 10

2 Kernelized perceptrons

2.1 Quadratic kernel – data1.txt

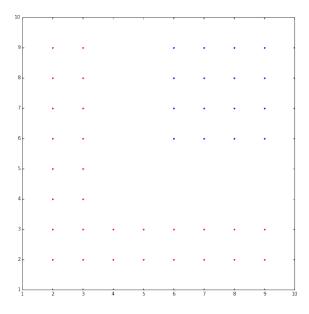


Figure 7: classified samples, T = 1

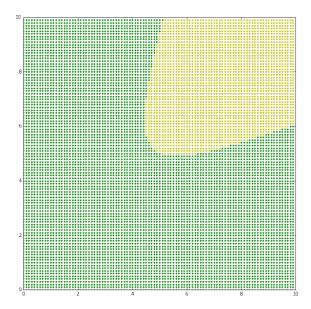


Figure 8: decision boundary, T = 1

2.2 Quadratic kernel – data2.txt

Quadratic kernel is not suitable for this situation.

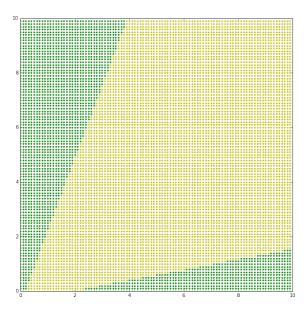


Figure 9: decision boundary, T = 5

2.3 RBF kernel – data1.txt

Generally speaking, RBF kernel performs better than quadratic kernel on both data set 1 and data set 2.

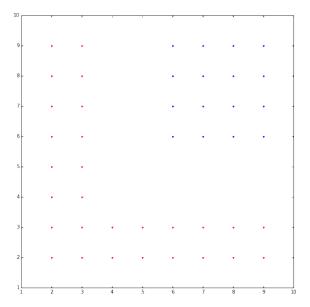


Figure 10: classified samples, T = 1, sigma = 2

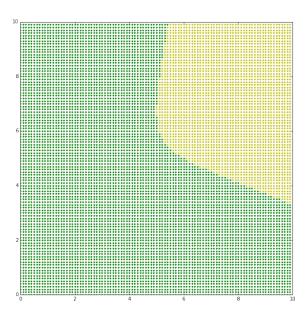


Figure 11: decision boundary, T = 1, sigma = 2

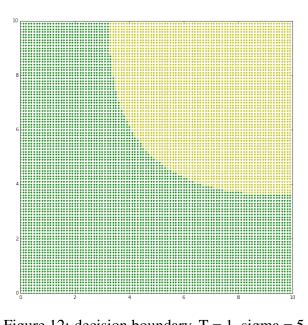


Figure 12: decision boundary, T = 1, sigma = 5

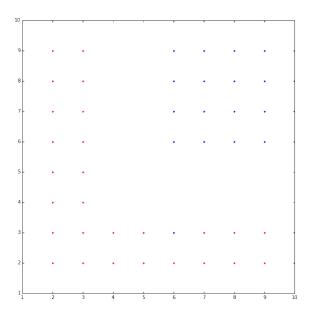


Figure 13: classified samples, T = 1, sigma = 0.2

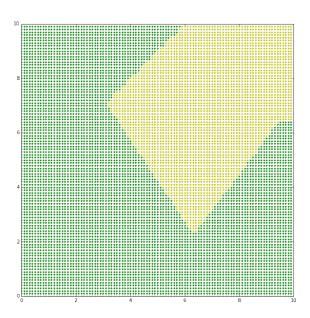


Figure 14: decision boundary, T = 1, sigma = 0.2

2.4 RBF kernel – data2.txt

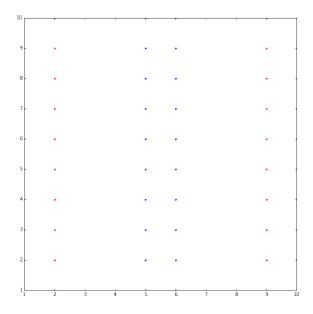


Figure 15: classified samples, T = 1, sigma = 2

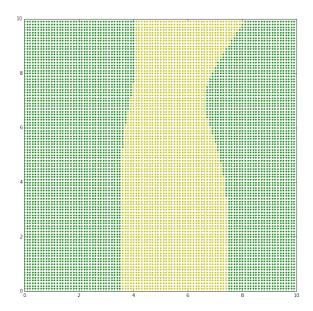


Figure 16: decision boundary, T = 1, sigma = 2

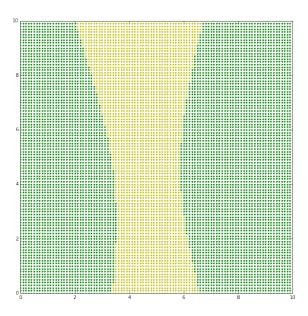


Figure 17: decision boundary, T = 1, sigma = 5

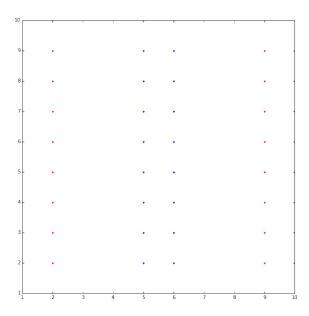


Figure 18: classified samples, T = 1, sigma = 0.2

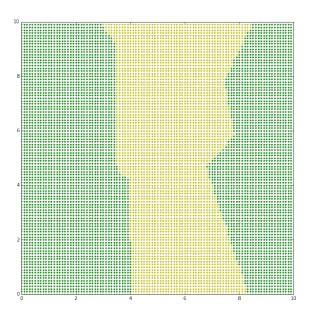


Figure 19: decision boundary, T = 1, sigma = 0.2