

Supplementary material

S1 Additional details on identification assumptions

S1.1 Causal mechanism of the placebo sample in the EITC study



Figure S1: Causal mechanism of a placebo sample in the EITC study. A encodes whether an individual's state of residence has enacted EITC laws, M whether she claimed the EITC, and Y whether she died of death of despair. A 's effect on Y is exclusively mediated by M . For individuals in the placebo sample, A does not affect M and thus has no effect on Y . A subset of state residents, e.g., college graduates, are unlikely to be eligible for the EITC and thus cannot claim the EITC with or without EITC laws, i.e., A has no effect on M (as illustrated in (b)). (a) DAG for the primary sample ($S = 1$) and (b) DAG for the placebo sample ($S = 0$).

S1.2 Further discussion of Assumption 2

Let U denote the set of unmeasured confounders such that $A \perp (Y^{(0)}, Y^{(1)}) | U, X, S$. One set of sufficient (but not necessary) conditions for Assumption 2 to hold is (i) $P(U | S = 1, A, X) = P(U | S = 0, A, X)$, and (ii) $E\{Y^{(0)} | U, X, S = 1\} - E\{Y^{(0)} | U, X, S = 0\}$ is a function of X alone. In words, Assumption 2 holds when the distribution of U is the same for $S = 0$ and $S = 1$ within each level of (A, X) , and there is no additive S - U interaction in $E\{Y^{(0)} | U, X, S\}$.

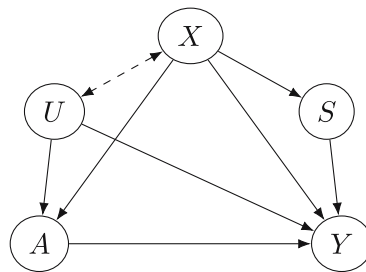


Figure S2: A DAG of a sufficient condition of Assumption 2.

We expect Assumption 2 to hold approximately in various applications. To give an example, in a study of the effect of intraoperative TEE on patients' post-surgery clinical outcomes, there is a concern of unmeasured confounding due to surgeons' experiences as a surgeon's preference for using intraoperative TEE may depend on her experience, and a surgeon's experience may affect complication management during the surgery and

hence the clinical outcome [1,2]. Unfortunately, the disease registry data does not contain surgeon-level characteristics. The proposed placebo samples approach could help in this case. The healthiest cardiac surgery group, those under the age of 40 with an ejection fraction > 55% (normal range: 55-75%) are likely not to benefit (or benefit minimally) from the intraoperative TEE (see, e.g., empirical results from [3]). Assumption 1 is likely to hold for this placebo sample. On the other hand, Within the same hospital, it is largely random which surgeon operates on which patient, so that the unmeasured confounder U is likely to have similar distribution for patients in the placebo sample and other patients and Assumption 2 approximately holds. Note that Assumption 2 will not likely to hold without conditioning on the hospital indicator X = hospital indicator. Community hospitals tend to refer complex surgeries on higher-risk patients to university hospitals; therefore, it is likely that more experienced surgeons in university hospitals (compared to those in community hospitals) would operate on higher-risk patients; however, conditioning on the hospital would render U (surgeons' experience) independent of S (a patient being in the placebo sample). Of course, even though both Assumptions 1 and 2 are likely to approximately hold in this case, we cannot completely rule out the possibility of minor violation, and a sensitivity analysis could be helpful. In the following, we propose sensitivity analysis based on two different sensitivity models that may be useful in a broad range of applications.

S1.3 Estimators for sensitivity analysis under marginal sensitivity models

The bounds in the sensitivity analysis can be estimated using an IPW estimator, a regression-based estimator, and a doubly-robust estimator. We provide formulas for each below.

Using the IPW estimator, we have

$$\begin{aligned}\hat{\theta}_{U,\text{ipw}} &= \hat{\theta}_{\text{ipw}} + \Lambda - (\Gamma^{-1} - 1) \frac{1}{n_{11}} \sum_{i=1}^n \frac{\pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{(1 - \pi_S(X_i; \hat{\psi})) \pi_A(X_i, 0; \hat{\alpha})} (1 - S_i) A_i Y_i \\ &\quad + (\Gamma - 1) \frac{1}{n_{11}} \sum_{i=1}^n \frac{\pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{(1 - \pi_S(X_i; \hat{\psi})) (1 - \pi_A(X_i, 0; \hat{\alpha}))} (1 - S_i) (1 - A_i) Y_i, \\ \hat{\theta}_{L,\text{ipw}} &= \hat{\theta}_{\text{ipw}} - \Lambda - (\Gamma - 1) \frac{1}{n_{11}} \sum_{i=1}^n \frac{\pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{(1 - \pi_S(X_i; \hat{\psi})) \pi_A(X_i, 0; \hat{\alpha})} (1 - S_i) A_i Y_i \\ &\quad + (\Gamma^{-1} - 1) \frac{1}{n_{11}} \sum_{i=1}^n \frac{\pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{(1 - \pi_S(X_i; \hat{\psi})) (1 - \pi_A(X_i, 0; \hat{\alpha}))} (1 - S_i) (1 - A_i) Y_i.\end{aligned}$$

Using the regression-based estimator, we have

$$\begin{aligned}\hat{\theta}_{U,\text{reg}} &= \hat{\theta}_{\text{reg}} + \Lambda - (\Gamma^{-1} - 1) \frac{1}{n_{11}} \sum_{i: S_i=A_i=1} \mu_Y(0, 1, X_i; \hat{\beta}) + (\Gamma - 1) \frac{1}{n_{11}} \sum_{i: S_i=A_i=1} \mu_Y(0, 0, X_i; \hat{\beta}), \\ \hat{\theta}_{L,\text{reg}} &= \hat{\theta}_{\text{reg}} - \Lambda - (\Gamma - 1) \frac{1}{n_{11}} \sum_{i: S_i=A_i=1} \mu_Y(0, 1, X_i; \hat{\beta}) + (\Gamma^{-1} - 1) \frac{1}{n_{11}} \sum_{i: S_i=A_i=1} \mu_Y(0, 0, X_i; \hat{\beta}).\end{aligned}$$

Using the doubly-robust estimator, we have

$$\begin{aligned}\hat{\theta}_{U,\text{dr}} &= \hat{\theta}_{\text{dr}} + \Lambda - (\Gamma^{-1} - 1) \frac{1}{n_{11}} \sum_{i: S_i=A_i=1} \mu_Y(0, 1, X_i; \hat{\beta}) \\ &\quad - (\Gamma^{-1} - 1) \frac{1}{n_{11}} \sum_{i=1}^n \frac{\pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{(1 - \pi_S(X_i; \hat{\psi})) \pi_A(X_i, 0; \hat{\alpha})} (1 - S_i) A_i \{Y_i - \mu_Y(0, 1, X_i; \hat{\beta})\} \\ &\quad + (\Gamma - 1) \frac{1}{n_{11}} \sum_{i: S_i=A_i=1} \mu_Y(0, 0, X_i; \hat{\beta}) \\ &\quad + (\Gamma - 1) \frac{1}{n_{11}} \sum_{i=1}^n \frac{\pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{(1 - \pi_S(X_i; \hat{\psi})) (1 - \pi_A(X_i, 0; \hat{\alpha}))} (1 - S_i) (1 - A_i) \{Y_i - \mu_Y(0, 0, X_i; \hat{\beta})\}\end{aligned}$$

$$\begin{aligned}
\hat{\theta}_{L,dr} &= \hat{\theta}_{dr} - \Lambda \\
&- (\Gamma - 1) \frac{1}{n_{11}} \sum_{i:S_i=A_i=1} \mu_Y(0, 1, X_i; \hat{\beta}) \\
&- (\Gamma - 1) \frac{1}{n_{11}} \sum_{i=1}^n \frac{\pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{(1 - \pi_S(X_i; \hat{\psi})) \pi_A(X_i, 0; \hat{\alpha})} (1 - S_i) A_i \{Y_i - \mu_Y(0, 1, X_i; \hat{\beta})\} \\
&+ (\Gamma^{-1} - 1) \frac{1}{n_{11}} \sum_{i:S_i=A_i=1} \mu_Y(0, 0, X_i; \hat{\beta}) \\
&+ (\Gamma^{-1} - 1) \frac{1}{n_{11}} \sum_{i=1}^n \frac{\pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{(1 - \pi_S(X_i; \hat{\psi})) (1 - \pi_A(X_i, 0; \hat{\alpha}))} (1 - S_i) (1 - A_i) \{Y_i - \mu_Y(0, 0, X_i; \hat{\beta})\}.
\end{aligned}$$

Under the Sensitivity Model 2.A and 2.B, and $Y_i \geq 0$ and for fixed Γ and Λ , the confidence interval for θ_0 is

$$[\hat{\theta}_{L,*} - z_{\alpha/2} \hat{\sigma}_{L,*}, \hat{\theta}_{U,*} + z_{\alpha/2} \hat{\sigma}_{U,*}], \quad (S1)$$

where $z_{\alpha/2}$ is the $\alpha/2$ -upper quantile of the standard normal distribution, and $\hat{\sigma}_{L,*}, \hat{\sigma}_{U,*}$ are respectively the standard error of $\hat{\theta}_{L,*}, \hat{\theta}_{U,*}$ for $* \in \{\text{ipw, reg, dr}\}$.

S1.4 Stabilized estimators

The idea of stabilization is to normalize the weights to sum to one [4]. The stabilized estimators are asymptotically equivalent to their unstabilized counterparts but they have better finite-sample performance.

The stabilized IPW is

$$\begin{aligned}
\hat{\theta}_{\text{sipw}} &= \frac{1}{n_{11}} \sum_{i=1}^n S_i A_i Y_i \\
&- \left[\sum_{i=1}^n \frac{S_i (1 - A_i) \pi_A(X_i, 1; \hat{\alpha})}{1 - \pi_A(X_i, 1; \hat{\alpha})} \right]^{-1} \sum_{i=1}^n \frac{S_i (1 - A_i) \pi_A(X_i, 1; \hat{\alpha})}{1 - \pi_A(X_i, 1; \hat{\alpha})} Y_i \\
&- \left[\sum_{i=1}^n \frac{(1 - S_i) A_i \pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{1 - \pi_S(X_i; \hat{\psi}) \pi_A(X_i, 0; \hat{\alpha})} \right]^{-1} \sum_{i=1}^n \frac{(1 - S_i) A_i \pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{1 - \pi_S(X_i; \hat{\psi}) \pi_A(X_i, 0; \hat{\alpha})} Y_i \\
&+ \left[\sum_{i=1}^n \frac{(1 - S_i) (1 - A_i) \pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{1 - \pi_S(X_i; \hat{\psi}) \pi_A(X_i, 0; \hat{\alpha})} \right]^{-1} \sum_{i=1}^n \frac{(1 - S_i) (1 - A_i) \pi_S(X_i; \hat{\psi}) \pi_A(X_i, 1; \hat{\alpha})}{1 - \pi_S(X_i; \hat{\psi}) \pi_A(X_i, 0; \hat{\alpha})} Y_i.
\end{aligned}$$

S2 Technical Proofs

S2.1 Proof of Proposition 1

The part (a) is directly from the assumptions. We only prove part (b). First note that

$$\begin{aligned}
&E \left[\frac{S - \pi_S(X)}{\pi_S(X) \{1 - \pi_S(X)\}} \frac{A - \pi_A(X, S)}{\pi_A(X, S) \{1 - \pi_A(X, S)\}} Y | X \right] \\
&= E \left[\frac{1}{\pi_S(X)} \frac{A - \pi_A(X, 1)}{\pi_A(X, 1) \{1 - \pi_A(X, 1)\}} Y | X, S = 1 \right] P(S = 1 | X) \\
&- E \left[\frac{1}{\{1 - \pi_S(X)\}} \frac{A - \pi_A(X, 0)}{\pi_A(X, 0) \{1 - \pi_A(X, 0)\}} Y | X, S = 0 \right] P(S = 0 | X)
\end{aligned}$$

$$\begin{aligned}
&= E \left[\frac{A - \pi_A(X, 1)}{\pi_A(X, 1)\{1 - \pi_A(X, 1)\}} Y | X, S = 1 \right] - E \left[\frac{A - \pi_A(X, 0)}{\pi_A(X, 0)\{1 - \pi_A(X, 0)\}} Y | X, S = 0 \right] \\
&= E \left[\frac{A - \pi_A(X, 1)}{\pi_A(X, 1)\{1 - \pi_A(X, 1)\}} Y | X, S = 1, A = 1 \right] P(A = 1 | X, S = 1) \\
&\quad + E \left[\frac{A - \pi_A(X, 1)}{\pi_A(X, 1)\{1 - \pi_A(X, 1)\}} Y | X, S = 1, A = 0 \right] P(A = 0 | X, S = 1) \\
&\quad - E \left[\frac{A - \pi_A(X, 0)}{\pi_A(X, 0)\{1 - \pi_A(X, 0)\}} Y | X, S = 0, A = 1 \right] P(A = 1 | X, S = 0) \\
&\quad - E \left[\frac{A - \pi_A(X, 0)}{\pi_A(X, 0)\{1 - \pi_A(X, 0)\}} Y | X, S = 0, A = 0 \right] P(A = 0 | X, S = 0) \\
&= E[Y | X, S = 1, A = 1] - E[Y | X, S = 1, A = 0] \\
&\quad - E[Y | X, S = 0, A = 1] + E[Y | X, S = 0, A = 0] \\
&= E\{Y(1) - Y(0) | S = 1, A = 1, X\}.
\end{aligned}$$

Then,

$$\begin{aligned}
\theta_0 &= E \left[E \left[\frac{S - \pi_S(X)}{\pi_S(X)\{1 - \pi_S(X)\}} \frac{A - \pi_A(X, S)}{\pi_A(X, S)\{1 - \pi_A(X, S)\}} Y | X \right] \frac{P(A = 1 | S = 1, X) P(S = 1 | X)}{P(S = 1, A = 1)} \right] \\
&= \frac{1}{P(S = 1, A = 1)} E \left[\frac{S - \pi_S(X)}{1 - \pi_S(X)} \frac{\pi_A(X, 1)\{A - \pi_A(X, S)\}}{\pi_A(X, S)\{1 - \pi_A(X, S)\}} Y \right].
\end{aligned}$$

S2.2 Proof of Theorem 1

In this section, we use subscripts to explicitly index quantities that depend on the distribution P , we use a zero subscript to denote a quantity evaluated at the true distribution $P = P_0$, we use a ε subscript to denote a quantity evaluated at the parametric submodel $P = P_\varepsilon$. We will show that $\varphi(O; \theta_P, \eta_P)$ is equal to the efficient influence function by showing that it is the canonical gradient of the pathwise derivative of θ_P , i.e., [5]

$$\left. \frac{\partial \theta_\varepsilon}{\partial \varepsilon} \right|_{\varepsilon=0} = E_0\{\text{EIF}(O; \theta_P, \eta_P) s_0(O)\}, \quad (\text{S2})$$

where $\theta_\varepsilon = \theta_{P_\varepsilon}$, $s_\varepsilon(O) = \partial \log dP_\varepsilon(O) / \partial \varepsilon$ denotes the parameter submodel score, which can be decomposed as $s_\varepsilon(Y | S, A, X) + s_\varepsilon(A | S, X) + s_\varepsilon(S | X) + s_\varepsilon(X)$ or $s_\varepsilon(X | Y, S, A) + s_\varepsilon(Y | S, A) + s_\varepsilon(S, A)$.

By the equality in Proposition 1 (a), we have

$$\begin{aligned}
\left. \frac{\partial}{\partial \varepsilon} \theta_\varepsilon \right|_{\varepsilon=0} &= \frac{\partial}{\partial \varepsilon} E_\varepsilon(Y | S = 1, A = 1) |_{\varepsilon=0} \\
&\quad - \frac{\partial}{\partial \varepsilon} E_\varepsilon\{E_\varepsilon(Y | S = 1, A = 0, X) | S = 1, A = 1\} |_{\varepsilon=0} \\
&\quad - \frac{\partial}{\partial \varepsilon} E_\varepsilon\{E_\varepsilon(Y | S = 0, A = 1, X) | S = 1, A = 1\} |_{\varepsilon=0} \\
&\quad + \frac{\partial}{\partial \varepsilon} E_\varepsilon\{E_\varepsilon(Y | S = 0, A = 0, X) | S = 1, A = 1\} |_{\varepsilon=0} \\
&=: M_1 - M_2 - M_3 + M_4.
\end{aligned} \quad (\text{S3})$$

In what follows, we use the following identities repeatedly:

$$E_\varepsilon\{b(O_1) s_\varepsilon(O_2 | O_1)\} = 0, \quad (\text{S4})$$

$$E_\varepsilon\{b(O_1)(O_2 - E_\varepsilon(O_2 | O_1))\} = 0, \quad (\text{S5})$$

for any b and any $(O_1, O_2) \subset O$.

Consider each term M_1, M_2, M_3, M_4 separately:

$$\begin{aligned}
 M_1 &= E_0\{Ys_0(Y|S, A)|S = 1, A = 1\} \\
 &= E_0\left[\frac{SA}{E_0(SA)}Ys_0(Y|S, A)\right] \\
 &= E_0\left[\frac{SA}{E_0(SA)}\{Y - E_0(Y|S, A)\}s_0(Y|S, A)\right] \quad (S4) \\
 &= E_0\left[\frac{SA}{E_0(SA)}\{Y - E_0(Y|S, A)\}\{s_0(Y|S, A) + s_0(S, A)\}\right] \quad (S5) \\
 &= E_0\left[\frac{SA}{E_0(SA)}\{Y - E_0(Y|S, A)\}\{s_0(Y|S, A) + s_0(S, A) + s_0(X|Y, S, A)\}\right] \quad (S4) \\
 &= E_0\left[\frac{SA}{E_0(SA)}\{Y - E_0(Y|S, A)\}s_0(O)\right]
 \end{aligned}$$

$$\begin{aligned}
 M_2 &= E_0\{E_0(Ys_0(Y|S, A, X)|S = 1, A = 0, X)|S = 1, A = 1\} \\
 &\quad + E_0\{E_0(Y|S = 1, A = 0, X)s_0(X|S, A)|S = 1, A = 1\} \\
 &= E_0\left\{\frac{SA}{E_0(SA)}E_0\left(\frac{S(1-A)}{P_0(S = 1, A = 0|X)}Ys_0(Y|S, A, X)|X\right)\right\} \\
 &\quad + E_0\left\{\frac{SA}{E_0(SA)}E_0(Y|S = 1, A = 0, X)s_0(X|S, A)\right\} \\
 &= E_0\left\{\frac{E_0(SA|X)}{E_0(SA)}\frac{S(1-A)}{E_0(S(1-A)|X)}Ys_0(Y|S, A, X)\right\} \\
 &\quad + E_0\left\{\frac{SA}{E_0(SA)}E_0(Y|S = 1, A = 0, X)s_0(X|S, A)\right\} \\
 &= E_0\left\{\frac{E_0(SA|X)}{E_0(SA)}\frac{S(1-A)}{E_0(S(1-A)|X)}Ys_0(Y|S, A, X)\right\} \\
 &\quad + E_0\left\{\frac{SA}{E_0(SA)}E_0(Y|S = 1, A = 0, X)s_0(X|S, A)\right\} \\
 &= E_0\left\{\frac{E_0(SA|X)}{E_0(SA)}\frac{S(1-A)}{E_0(S(1-A)|X)}\{Y - \mu_{Y0}(S, A, X)\}s_0(Y|S, A, X)\right\} \quad (S4) \\
 &\quad + E_0\left\{\frac{SA}{E_0(SA)}\{\mu_{Y0}(1, 0, X) - E_0(\mu_{Y0}(1, 0, X)|S, A)\}s_0(X|S, A)\right\} \quad (S4) \\
 &= E_0\left\{\frac{E_0(SA|X)}{E_0(SA)}\frac{S(1-A)}{E_0(S(1-A)|X)}\{Y - \mu_{Y0}(S, A, X)\}\{s_0(Y|S, A, X) + s_0(S, A, X)\}\right\} \quad (S5) \\
 &\quad + E_0\left\{\frac{SA}{E_0(SA)}\{\mu_{Y0}(1, 0, X) - E_0(\mu_{Y0}(1, 0, X)|S, A)\}\{s_0(X|S, A) + s_0(S, A)\}\right\} \quad (S5) \\
 &= E_0\left\{\frac{E_0(SA|X)}{E_0(SA)}\frac{S(1-A)}{E_0(S(1-A)|X)}\{Y - \mu_{Y0}(S, A, X)\}s_0(O)\right\} \\
 &\quad + E_0\left\{\frac{SA}{E_0(SA)}\{\mu_{Y0}(1, 0, X) - E_0(\mu_{Y0}(1, 0, X)|S, A)\}s_0(O)\right\} \quad (S4)
 \end{aligned}$$

$$\begin{aligned}
M_3 &= E_0 \left\{ \frac{E_0(SA|X)}{E_0(SA)} \frac{(1-S)A}{E((1-S)A|X)} Y s_0(Y|S, A, X) \right\} \\
&\quad + E_0 \left\{ \frac{SA}{E_0(SA)} E_0(Y|S=0, A=1, X) s_0(X|S, A) \right\} \\
&= E_0 \left\{ \frac{E_0(SA|X)}{E_0(SA)} \frac{(1-S)A}{E_0((1-S)A|X)} \{Y - \mu_{Y0}(S, A, X)\} s_0(O) \right\} \\
&\quad + E_0 \left\{ \frac{SA}{E_0(SA)} \{\mu_{Y0}(0, 1, X) - E_0(\mu_{Y0}(0, 1, X)|S, A)\} s_0(O) \right\} \\
M_4 &= E_0 \left\{ \frac{E_0(SA|X)}{E_0(SA)} \frac{(1-S)(1-A)}{E_0((1-S)(1-A)|X)} Y s_0(Y|S, A, X) \right\} \\
&\quad + E_0 \left\{ \frac{SA}{E_0(SA)} E_0(Y|S=0, A=0, X) s_0(X|S, A) \right\} \\
&= E_0 \left\{ \frac{E_0(SA|X)}{E_0(SA)} \frac{(1-S)(1-A)}{E_0((1-S)(1-A)|X)} \{Y - \mu_{Y0}(S, A, X)\} s_0(O) \right\} \\
&\quad + E_0 \left\{ \frac{SA}{E_0(SA)} \{\mu_{Y0}(0, 0, X) - E_0(\mu_{Y0}(0, 0, X)|S, A)\} s_0(O) \right\}.
\end{aligned}$$

Combining the above derivations, we have

$$\left. \frac{\partial \theta_\varepsilon}{\partial \varepsilon} \right|_{\varepsilon=0} = E_0\{\text{EIF}(O; \theta_P, \eta_P) s_0(O)\}, \quad (\text{S6})$$

with $\text{EIF}(O; \theta_P, \eta_P)$ being the efficient influence function.

S2.3 Proof of double robustness

Let $\bar{\eta} = (\bar{\mu}_Y, \bar{\pi}_S, \bar{\pi}_A)$ be the limit of $\hat{\eta}$. Here we will show that $E[\text{EIF}(O, \theta_0; \bar{\eta})] = 0$ as long as either $\bar{\mu}_Y = \mu_{Y0}$ or $(\bar{\pi}_S, \bar{\pi}_A) = (\pi_{S0}, \pi_{A0})$. In this section, expectations $E = E_0$ are evaluated under P_0 , but we drop the subscript for notational convenience.

When μ_Y is correctly specified, we have $\bar{\mu}_Y = \mu_{Y0}$. Then, by iterative expectation,

$$\begin{aligned}
E[\text{EIF}(O, \theta_0; \bar{\eta})] &= E \left[\frac{SA}{E(SA)} \{Y - \mu_{Y0}(1, 0, X) - \mu_{Y0}(0, 1, X) + \mu_{Y0}(0, 0, X) - \theta_0\} \right. \\
&\quad - \frac{S(1-A) \frac{\bar{\pi}_A(X, 1)}{1 - \bar{\pi}_A(X, 1)}}{E \left[S(1-A) \frac{\bar{\pi}_A(X, 1)}{1 - \bar{\pi}_A(X, 1)} \right]} \{Y - \mu_{Y0}(1, 0, X)\} \\
&\quad - \frac{(1-S)A \frac{\bar{\pi}_A(X, 1)}{\bar{\pi}_A(X, 0)} \frac{\bar{\pi}_S(X)}{1 - \bar{\pi}_S(X)}}{E \left[(1-S)A \frac{\bar{\pi}_A(X, 1)}{\bar{\pi}_A(X, 0)} \frac{\bar{\pi}_S(X)}{1 - \bar{\pi}_S(X)} \right]} \{Y - \mu_{Y0}(0, 1, X)\} \\
&\quad \left. + \frac{(1-S)(1-A) \frac{\bar{\pi}_A(X, 1)}{1 - \bar{\pi}_A(X, 0)} \frac{\bar{\pi}_S(X)}{1 - \bar{\pi}_S(X)}}{E \left[(1-S)(1-A) \frac{\bar{\pi}_A(X, 1)}{1 - \bar{\pi}_A(X, 0)} \frac{\bar{\pi}_S(X)}{1 - \bar{\pi}_S(X)} \right]} \{Y - \mu_{Y0}(0, 0, X)\} \right] \\
&= E[Y - \mu_{Y0}(1, 0, X) - \mu_{Y0}(0, 1, X) + \mu_{Y0}(0, 0, X) - \theta_0 | S=1, A=1] \\
&= 0.
\end{aligned}$$

When π_A, π_S are correctly specified, we have $\bar{\pi}_S = \pi_{S0}$ and $\bar{\pi}_A = \pi_{A0}$. Then, by iterative expectation,

$$E[\text{EIF}(O, \theta_0; \bar{\eta})] = E \left[\frac{SA}{E(SA)} \{Y - \bar{\mu}_Y(1, 0, X) - \bar{\mu}_Y(0, 1, X) + \bar{\mu}_Y(0, 0, X) - \theta_0\} \right]$$

$$\begin{aligned}
& - \frac{S(1-A) \frac{\pi_{A0}(X,1)}{1-\pi_{A0}(X,1)}}{E\left[S(1-A) \frac{\pi_{A0}(X,1)}{1-\pi_{A0}(X,1)}\right]} \{Y - \bar{\mu}_Y(1, 0, X)\} \\
& - \frac{(1-S)A \frac{\pi_{A0}(X,1)}{\pi_{A0}(X,0)} \frac{\pi_{S0}(X)}{1-\pi_{S0}(X)}}{E\left[(1-S)A \frac{\pi_{A0}(X,1)}{\pi_{A0}(X,0)} \frac{\pi_{S0}(X)}{1-\pi_{S0}(X)}\right]} \{Y - \bar{\mu}_Y(0, 1, X)\} \\
& + \frac{(1-S)(1-A) \frac{\pi_{A0}(X,1)}{1-\pi_{A0}(X,0)} \frac{\pi_{S0}(X)}{1-\pi_{S0}(X)}}{E\left[(1-S)(1-A) \frac{\pi_{A0}(X,1)}{1-\pi_{A0}(X,0)} \frac{\pi_{S0}(X)}{1-\pi_{S0}(X)}\right]} \{Y - \bar{\mu}_Y(0, 0, X)\} \Bigg] \\
& = E[Y|S=1, A=1] - E\{\bar{\mu}_Y(1, 0, X)|S=1, A=1\} \\
& \quad - E\{\bar{\mu}_Y(0, 1, X)|S=1, A=1\} + E\{\bar{\mu}_Y(0, 0, X)|S=1, A=1\} - \theta_0 \\
& \quad - E\{E(Y|S=1, A=0, X) - \bar{\mu}_Y(1, 0, X)|S=1, A=1\} \\
& \quad - E\{E(Y|S=0, A=1, X) - \bar{\mu}_Y(0, 1, X)|S=1, A=1\} \\
& \quad + E\{E(Y|S=0, A=0, X) - \bar{\mu}_Y(0, 0, X)|S=1, A=1\} \\
& = 0.
\end{aligned}$$

S2.4 Proof of Theorem 2

In what follows, we will use $P\{f(O)\} = \int f(O)dP$ to denote expectation treating the function f as fixed; thus $P\{f(O)\}$ is random when f is random, and is different from the fixed quantity $E\{f(O)\}$ which averages over randomness in both f and O .

Since $\hat{\theta}$ is a Z-estimator, using Theorem 5.31 of [6], we have that

$$\sqrt{n}(\hat{\theta} - \theta_0) = \sqrt{n}P\{\text{EIF}(O; \theta_0, \hat{\eta})\} + n^{-1/2} \sum_{i=1}^n [\text{EIF}(O_i; \theta_0, \bar{\eta}) - E\{\text{EIF}(O_i; \theta_0, \bar{\eta})\}] + o_p(1 + \sqrt{n}P\{\text{EIF}(O; \theta_0, \hat{\eta})\}).$$

Using standard central limit theorem, the second term is asymptotically normal, and is $O_p(1)$. Hence, the consistency and rate of convergence of $\hat{\theta}$ depend on the property of the first term. We analyze $\sqrt{n}P\{\text{EIF}(O; \theta_0, \hat{\eta})\}$ in the following.

Define $\eta = (\mu_Y, \pi_A, \pi_S, \lambda)$, $\hat{\eta} = (\hat{\mu}_Y, \hat{\pi}_A, \hat{\pi}_S, \hat{\lambda})$, $\tilde{\eta} = (\hat{\mu}_Y, \hat{\pi}_A, \hat{\pi}_S, \lambda_0)$, and $\eta_0 = (\pi_{S0}, \pi_{A0}, \mu_{Y0}, \lambda_0)$. From

$$\theta_0 = P\left[\frac{SA}{E(SA)}\{\mu_{Y0}(1, 1, X) - \mu_{Y0}(1, 0, X) - \mu_{Y0}(0, 1, X) + \mu_{Y0}(0, 0, X)\}\right],$$

we can write $P\{\text{EIF}(O; \theta_0, \tilde{\eta})\}$ as

$$\begin{aligned}
P\{\text{EIF}(O; \theta_0, \tilde{\eta})\} &= P\left[\frac{SA}{E(SA)}\{Y - \hat{\mu}_Y(1, 0, X) - \hat{\mu}_Y(0, 1, X) + \hat{\mu}_Y(0, 0, X) - \theta_0\}\right. \\
&\quad - \frac{S(1-A) \frac{\hat{\pi}_A(X,1)}{1-\hat{\pi}_A(X,1)}}{E(SA)}\{Y - \hat{\mu}_Y(1, 0, X)\} - \frac{(1-S)A \frac{\hat{\pi}_A(X,1)}{\hat{\pi}_A(X,0)} \frac{\hat{\pi}_S(X)}{1-\hat{\pi}_S(X)}}{E(SA)}\{Y - \hat{\mu}_Y(0, 1, X)\} \\
&\quad \left. + \frac{(1-S)(1-A) \frac{\hat{\pi}_A(X,1)}{1-\hat{\pi}_A(X,0)} \frac{\hat{\pi}_S(X)}{1-\hat{\pi}_S(X)}}{E(SA)}\{Y - \hat{\mu}_Y(0, 0, X)\}\right] \\
&= P\left[\frac{SA}{E(SA)}\{-\{\hat{\mu}_Y(1, 0, X) - \mu_{Y0}(1, 0, X)\} - \{\hat{\mu}_Y(0, 1, X) - \mu_{Y0}(0, 1, X)\}\}\right. \\
&\quad \left. + \frac{SA}{E(SA)}\{\hat{\mu}_Y(0, 0, X) - \mu_{Y0}(0, 0, X)\}\right] - \frac{S(1-A) \frac{\hat{\pi}_A(X,1)}{1-\hat{\pi}_A(X,1)}}{E(SA)}\{\mu_{Y0}(1, 0, X) - \hat{\mu}_Y(1, 0, X)\} \\
&\quad - \frac{(1-S)A \frac{\hat{\pi}_A(X,1)}{\hat{\pi}_A(X,0)} \frac{\hat{\pi}_S(X)}{1-\hat{\pi}_S(X)}}{E(SA)}\{\mu_{Y0}(0, 1, X) - \hat{\mu}_Y(0, 1, X)\} \\
&\quad + \frac{(1-S)(1-A) \frac{\hat{\pi}_A(X,1)}{1-\hat{\pi}_A(X,0)} \frac{\hat{\pi}_S(X)}{1-\hat{\pi}_S(X)}}{E(SA)}\{\mu_{Y0}(0, 0, X) - \hat{\mu}_Y(0, 0, X)\}
\end{aligned}$$

$$\begin{aligned}
& - \frac{(1-S)A \frac{\hat{\pi}_A(X,1)}{\hat{\pi}_A(X,0)} \frac{\hat{\pi}_S(X)}{1-\hat{\pi}_S(X)}}{E(SA)} \{\mu_{Y0}(0,1,X) - \hat{\mu}_Y(0,1,X)\} \\
& + \frac{(1-S)(1-A) \frac{\hat{\pi}_A(X,1)}{1-\hat{\pi}_A(X,0)} \frac{\hat{\pi}_S(X)}{1-\hat{\pi}_S(X)}}{E(SA)} \{\mu_{Y0}(0,0,X) - \hat{\mu}_Y(0,0,X)\} \Big] \\
& = P \left[\left[\frac{SA}{E(SA)} - \frac{S(1-A) \frac{\hat{\pi}_A(X,1)}{1-\hat{\pi}_A(X,1)}}{E(SA)} \right] \{\mu_{Y0}(1,0,X) - \hat{\mu}_Y(1,0,X)\} \right] \\
& + P \left[\left[\frac{SA}{E(SA)} - \frac{(1-S)A \frac{\hat{\pi}_A(X,1)}{\hat{\pi}_A(X,0)} \frac{\hat{\pi}_S(X)}{1-\hat{\pi}_S(X)}}{E(SA)} \right] \{\mu_{Y0}(0,1,X) - \hat{\mu}_Y(0,1,X)\} \right] \\
& + P \left[\left[-\frac{SA}{E(SA)} + \frac{(1-S)(1-A) \frac{\hat{\pi}_A(X,1)}{1-\hat{\pi}_A(X,0)} \frac{\hat{\pi}_S(X)}{1-\hat{\pi}_S(X)}}{E(SA)} \right] \{\mu_{Y0}(0,0,X) - \hat{\mu}_Y(0,0,X)\} \right] \\
& = T_1 + T_2 + T_3.
\end{aligned}$$

From the facts that

$$\begin{aligned}
& \|\hat{\pi}_A(X, S) - \pi_{A0}(X, S)\|_2^2 \\
& = \|\{\hat{\pi}_A(X, 1) - \pi_{A0}(X, 1)\}\pi_{S0}(X)^{1/2}\|_2^2 + \|\{\hat{\pi}_A(X, 0) - \pi_{A0}(X, 0)\}\{1 - \pi_{S0}(X)\}^{1/2}\|_2^2 \\
& \|\hat{\mu}_Y(S, A, X) - \mu_{Y0}(S, A, X)\|_2^2 \\
& = \|\{\hat{\mu}_Y(1, 1, X) - \mu_{Y0}(1, 1, X)\}\pi_{S0}(X)^{1/2}\pi_{A0}(X, 1)^{1/2}\|_2^2 \\
& + \|\{\hat{\mu}_Y(1, 0, X) - \mu_{Y0}(1, 0, X)\}\pi_{S0}(X)^{1/2}(1 - \pi_{A0}(X, 1))^{1/2}\|_2^2 \\
& + \|\{\hat{\mu}_Y(0, 1, X) - \mu_{Y0}(0, 1, X)\}(1 - \pi_{S0}(X))^{1/2}\pi_{A0}(X, 1)^{1/2}\|_2^2 \\
& + \|\{\hat{\mu}_Y(0, 0, X) - \mu_{Y0}(0, 0, X)\}(1 - \pi_{S0}(X))^{1/2}(1 - \pi_{A0}(X, 1))^{1/2}\|_2^2,
\end{aligned}$$

we have that every term on the right-hand side of the equations are bounded by the term on the left-hand side, e.g.,

$$\|\{\hat{\pi}_A(X, 1) - \pi_{A0}(X, 1)\}\pi_{S0}(X)^{1/2}\|_2 \leq \|\hat{\pi}_A(X, S) - \pi_{A0}(X, S)\|_2.$$

Hence, from Cauchy-Schwarz inequality, boundedness of $1/\hat{\pi}_A(X, 0)$, $1/\{1 - \hat{\pi}_A(X, 0)\}$, $1/\{1 - \hat{\pi}_A(X, 1)\}$, $1/\{1 - \hat{\pi}_S(X)\}$, and the triangle inequality, the first term satisfies

$$\begin{aligned}
T_1 & = P \left[\frac{\pi_{S0}(X)^{1/2}\{\pi_{A0}(X, 1) - \hat{\pi}_A(X, 1)\}}{E(SA)\{1 - \hat{\pi}_A(X, 1)\}} \frac{\pi_{S0}(X)^{1/2}(1 - \pi_{A0}(X, 1))^{1/2}}{(1 - \pi_{A0}(X, 1))^{1/2}} \{\mu_{Y0}(1, 0, X) - \hat{\mu}_Y(1, 0, X)\} \right] \\
& \leq C \|\pi_{S0}(X)^{1/2}\{\pi_{A0}(X, 1) - \hat{\pi}_A(X, 1)\}\|_2 \|\pi_{S0}(X)^{1/2}(1 - \pi_{A0}(X, 1))^{1/2}\{\mu_{Y0}(1, 0, X) - \hat{\mu}_Y(1, 0, X)\}\|_2 \\
& = O_p(\|\hat{\pi}_A(X, S) - \pi_{A0}(X, S)\|_2 \|\hat{\mu}_Y(S, A, X) - \mu_{Y0}(S, A, X)\|_2).
\end{aligned}$$

Similarly, for the second and third terms, we have

$$\begin{aligned}
T_2 & = P \left[\frac{\pi_{A0}(X, 1)\pi_{S0}(X)\hat{\pi}_A(X, 0)(1 - \hat{\pi}_S(X)) - \pi_{A0}(X, 0)(1 - \pi_{S0}(X))\hat{\pi}_A(X, 1)\hat{\pi}_S(X)}{E(SA)\hat{\pi}_A(X, 0)(1 - \hat{\pi}_S(X))} \{\mu_{Y0}(0, 1, X) - \hat{\mu}_Y(0, 1, X)\} \right] \\
& = O_p(\{\|\hat{\pi}_S(X) - \pi_{S0}(X)\|_2 + \|\hat{\pi}_A(X, S) - \pi_{A0}(X, S)\|_2\} \|\hat{\mu}_Y(S, A, X) - \mu_{Y0}(S, A, X)\|_2) \\
T_3 & = - \frac{\pi_A(X, 1)\pi_{S0}(X)(1 - \hat{\pi}_A(X, 0))(1 - \hat{\pi}_S(X)) - (1 - \pi_{A0}(X, 0))(1 - \pi_{S0}(X))\hat{\pi}_A(X, 1)\hat{\pi}_S(X)}{E(SA)(1 - \hat{\pi}_A(X, 0))(1 - \hat{\pi}_S(X))} \{\mu_{Y0}(0, 0, X) \\
& \quad - \hat{\mu}_Y(0, 0, X)\} \Big] \\
& = O_p(\{\|\hat{\pi}_S(X) - \pi_{S0}(X)\|_2 + \|\hat{\pi}_A(X, S) - \pi_{A0}(X, S)\|_2\} \|\hat{\mu}_Y(S, A, X) - \mu_{Y0}(S, A, X)\|_2).
\end{aligned}$$

Therefore,

$$P\{\text{EIF}(O; \theta_0, \tilde{\eta})\} = O_p(\{\|\hat{\pi}_S - \pi_{S0}\|_2 + \|\hat{\pi}_A - \pi_{A0}\|_2\} \|\hat{\mu}_Y - \mu_{Y0}\|_2)$$

Similarly, we can show that

$$P\{\varphi(O; \theta_0, \tilde{\eta})\} - P\{\varphi(O; \theta_0, \hat{\eta})\} = O_p(\{\|\hat{\pi}_S - \pi_{S0}\|_2 + \|\hat{\pi}_A - \pi_{A0}\|_2\} \|\hat{\mu}_Y - \mu_{Y0}\|_2 |\hat{\lambda} - \lambda_0|).$$

Again applying the triangle inequality and because $\hat{\lambda} - \lambda_0 = o_p(1)$, we arrive at

$$P\{\varphi(O; \theta_0, \hat{\eta})\} = O_p(\{\|\hat{\pi}_A - \pi_{A0}\|_2 + \|\hat{\pi}_S - \pi_{S0}\|_2\} \|\hat{\mu}_Y - \mu_{Y0}\|_2).$$

S2.5 Proof of bounds on $V(X)$

Recall the definition $V(X) = E\{Y^{(0)}|S = 1, A = 1, X\} - E\{Y^{(0)}|S = 1, A = 0, X\} - [E\{Y^{(0)}|S = 0, A = 1, X\} - E\{Y^{(0)}|S = 0, A = 0, X\}]$.

The bounds on $V(X)$, that is,

$$\begin{aligned} E[Y|S = 0, A = 1, X](\Gamma^{-1} - 1) - E[Y|S = 0, A = 0, X](\Gamma - 1) \\ \leq V(X) \leq E[Y|S = 0, A = 1, X](\Gamma - 1) - E[Y|S = 0, A = 0, X](\Gamma^{-1} - 1), \end{aligned}$$

follows from the result that

$$V(X) = E[E\{Y|S = 0, U, X\}r(1, U, X) - 1|S = 0, A = 1, X] - E[E\{Y|S = 0, U, X\}r(0, U, X) - 1|S = 0, A = 0, X].$$

S3 Variance estimator

S3.1 Constructing a consistent variance estimator

A general recipe for constructing a consistent variance estimator under the M-estimation framework (see, e.g., tutorials by Stefanski and Boos [7] and Saul and Hudgens [8]) can be applied to our proposed estimators as follows. Let $\text{IF}(O; \theta, \eta)$ denote the efficient influence function corresponding to $\hat{\theta}_{\text{reg}}$, $\hat{\theta}_{\text{IPW}}$, or $\hat{\theta}_{\text{dr}}$. Nuisance parameters η are estimated by $\hat{\eta}$ via solving their corresponding estimating equations $\sum_{i=1}^n \phi(O_i; \hat{\eta}) = 0$, and the target parameter θ is estimated by $\hat{\theta}$ via solving $\sum_{i=1}^n \text{IF}(O_i; \hat{\theta}, \hat{\eta}) = 0$. Write $\gamma = (\theta, \eta)$ for simplicity. To estimate γ , it suffices to stack estimating equations $\phi(O_i; \eta)$ and $\text{IF}(O_i; \theta, \eta)$, and find $\gamma = \hat{\gamma}$ that solves

$$\sum_{i=1}^n \psi(O_i; \hat{\gamma}) = \begin{pmatrix} \sum_{i=1}^n \phi(O_i; \hat{\eta}) \\ \sum_{i=1}^n \text{IF}(O_i; \hat{\theta}, \hat{\eta}) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}. \quad (\text{S7})$$

Define $A(\gamma) = \mathbb{E}\{-\partial\psi(O; \gamma)/\partial\gamma\}$ and $B(\gamma) = \mathbb{E}\{\psi(O; \gamma)\psi(O; \gamma)^T\}$. A consistent estimator of the variance-covariance matrix of $\hat{\gamma}$ can then be obtained using

$$\hat{V}(\hat{\gamma}) = (1/n) \cdot A(\hat{\gamma})^{-1} B(\hat{\gamma}) \{A(\hat{\gamma})^{-1}\}^T. \quad (\text{S8})$$

A consistent variance estimator of the target parameter θ is then obtained as the (1, 1)-th element of $\hat{V}(\hat{\gamma})$.

S3.2 Implementation in R using the geex package

The R package geex is a general purpose software to find roots and compute the empirical sandwich estimator for a set of user-supplied, unbiased estimating equations ([8]). Below, we provide an implementation of the sandwich variance estimator via the geex package.

```
#####
# Estimating equation
dr_est_func <- function(data, models){
  A = data$A
  S = data$S
  Y = data$Y
  Xs <- grab_design_matrix(data = data,
    rhs_formula = grab_fixed_formula(models$S_md))
  Xa = grab_design_matrix(data = data,
    rhs_formula = grab_fixed_formula(models$A_md))
  Xmu <- grab_design_matrix(data = data,
    rhs_formula = grab_fixed_formula(models$mu_md))
  Xa_S1 = Xa
  Xa_S1[, 'S'] = 1
  Xa_S0 = Xa
  Xa_S0[, 'S'] = 0
  Xmu_S1_A0 = Xmu
  Xmu_S1_A0[, 'S'] = 1
  Xmu_S1_A0[, 'A'] = 0
  Xmu_S1_A0[, 'S:A'] = 0
  Xmu_S0_A1 = Xmu
  Xmu_S0_A1[, 'S'] = 0
  Xmu_S0_A1[, 'A'] = 1
  Xmu_S0_A1[, 'S:A'] = 0
  Xmu_S0_A0 = Xmu
  Xmu_S0_A0[, 'S'] = 0
  Xmu_S0_A0[, 'A'] = 0
  Xmu_S0_A0[, 'S:A'] = 0
  S_md_pos = 1:length(coef(models$S_md))
  S_scores <- grab_psiFUN(models$S_md, data = data)
  A_md_pos = (length(coef(models$S_md))+1):(length(coef(models$S_md)) +
    length(coef(models$A_md)))
  A_scores <- grab_psiFUN(models$A_md, data = data)
  mu_md_pos = (length(coef(models$S_md)) + length(coef(models$A_md)) + 1):
    (length(coef(models$S_md)) + length(coef(models$A_md)) +
    length(coef(models$mu_md)))
  mu_scores <- grab_psiFUN(models$mu_md, data = data)
  function(theta, n, n_11) {
    pi_s = plogis(Xs %*% theta [S_md_pos ])
    pi_a_s_1 = plogis(Xa_S1 %*% theta [A_md_pos ])
    pi_a_s_0 = plogis(Xa_S0 %*% theta [A_md_pos ])
    mu_s_1_a_0 = Xmu_S1_A0 %*% theta [mu_md_pos ]
    mu_s_0_a_1 = Xmu_S0_A1 %*% theta [mu_md_pos ]
    mu_s_0_a_0 = Xmu_S0_A0 %*% theta [mu_md_pos ]
  }
}
```

```

beta = S * A * (n/n_11) * (Y - mu_s_1_a_0 - mu_s_0_a_1 +
mu_s_0_a_0 - theta[length(theta)]) -
(n/n_11) * S * (1 - A) * (pi_a_s_1/(1-pi_a_s_1)) *
(Y - mu_s_1_a_0) - (n/n_11) * (1 - S) * A *
(pi_a_s_1/pi_a_s_0) * (pi_s/(1-pi_s)) *
(Y - mu_s_0_a_1) + (n/n_11) * (1 - S) * (1 - A) *
(pi_a_s_1/(1-pi_a_s_0)) * (pi_s/(1-pi_s)) * (Y - mu_s_0_a_0)
c(S_scores(theta[S_md_pos]),
A_scores(theta[A_md_pos]),
mu_scores(theta[mu_md_pos]),
beta)
}
}

```

```
#####
```

```
# Solve the estimating equation and compute the empirical
```

```
# sandwich estimator. The function returns the point
```

```
# estimator and the estimated standard error.
```

```

estimate_aipw <- function(data, models){
n_11 = length(which(data$S == 1 & data$A == 1))
n = dim(data)[1]
res = m_estimate(estFUN = dr_est_func,
data = data,
root_control = setup_root_control(start =
c(unlist(lapply(models, function(x) coef(x))), 0)),
outer_args = list(models = models),
inner_args = list(n = n, n_11 = n_11))
nparam = length(roots(res))
point_est = roots(res)[nparam]
se = sqrt(vcov(res)[nparam, nparam])
return(c(point_est, se))
}

```

```
#####
```

```
# Run the code
```

```

res = estimate_aipw(data = data,
models = list(S_md = S_md,
A_md = A_md,
mu_md = mu_md))

```

S4 Additional simulation results

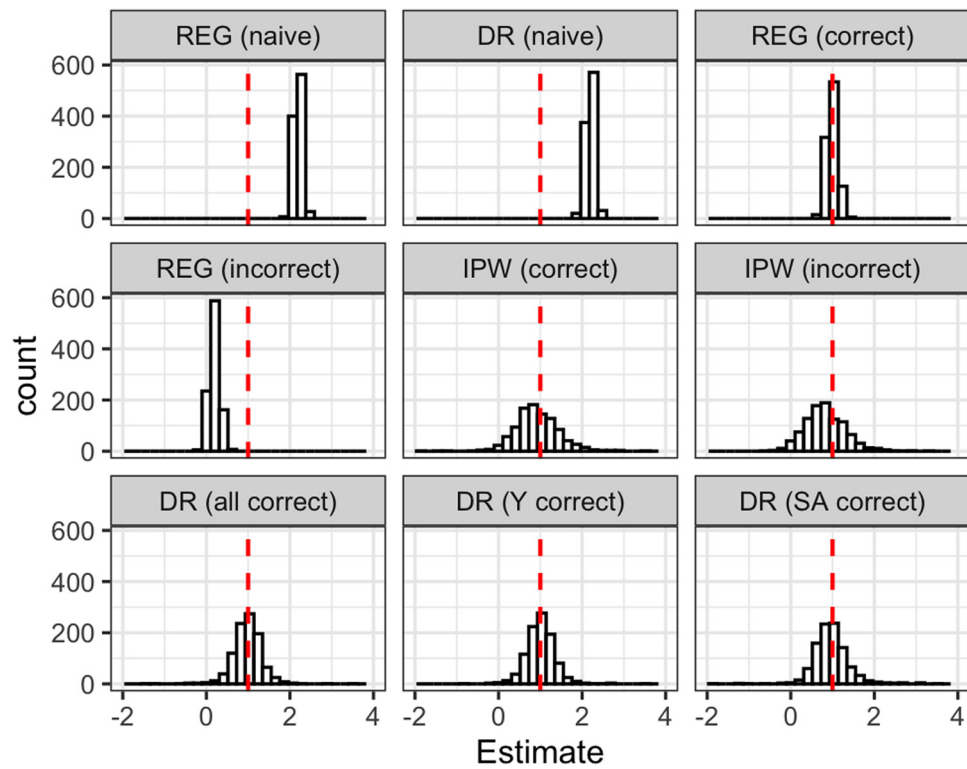


Figure S3: Sampling distribution of nine estimators under Scenario 1.

Table 1: Simulation results for four scenarios. Scenario 5: $b = (b1)$, $d = (d1)$, $e = (e)$, $f = (f1)$. Scenario 6: $b = (b1)$, $d = (d1)$, $e = (e)$, $f = (f2)$. Scenario 7: $b = (b1)$, $d = (d2)$, $e = (e)$, $f = (f1)$. Scenario 8: $b = (b1)$, $d = (d2)$, $e = (e)$, $f = (f2)$. $\theta_0 = 1$ in all four scenarios

Sample size	Estimator	Model Spec.	Bias	Median Est. SE	95% CI Cov. (%)	Bias	Median Est. SE	95% CI Cov. (%)	Bias	Median Est. SE	95% CI Cov. (%)
Scenario 5											
1,000	$\hat{\theta}_{reg,naive}$		1.19	0.13	0.00	1.19	0.13	0.00	1.19	0.13	0.00
2,000	$\hat{\theta}_{reg,naive}$		1.19	0.09	0.00	1.19	0.09	0.00	1.19	0.09	0.00
5,000	$\hat{\theta}_{reg,naive}$		1.19	0.06	0.00	1.19	0.06	0.00	1.19	0.06	0.00
1,000	$\hat{\theta}_{dr,naive}$		1.19	0.14	0.20	1.19	0.14	0.20	1.20	0.13	0.40
2,000	$\hat{\theta}_{dr,naive}$		1.20	0.10	0.00	1.20	0.10	0.00	1.20	0.09	0.20
5,000	$\hat{\theta}_{dr,naive}$		1.19	0.07	0.00	1.19	0.07	0.00	1.20	0.06	0.00
1,000	$\hat{\theta}_{reg}$	μ_Y correct	-0.01	0.19	95.97	-0.02	0.20	93.85	-0.01	0.19	95.36
2,000	$\hat{\theta}_{reg}$	μ_Y correct	-0.01	0.14	95.99	-0.01	0.14	96.29	-0.01	0.13	95.59
5,000	$\hat{\theta}_{reg}$	μ_Y correct	-0.01	0.09	95.06	-0.01	0.09	94.63	-0.01	0.08	93.45
1,000	$\hat{\theta}_{reg}$	μ_Y incorrect	-0.81	0.18	0.50	-0.82	0.19	1.11	-0.83	0.18	0.40
2,000	$\hat{\theta}_{reg}$	μ_Y incorrect	-0.81	0.13	0.00	-0.81	0.13	0.00	-0.82	0.13	0.00
5,000	$\hat{\theta}_{reg}$	μ_Y incorrect	-0.81	0.08	0.00	-0.81	0.08	0.00	-0.82	0.08	0.00
1,000	$\hat{\theta}_{pw}$	(π_S, π_A) correct	-0.10	0.49	92.54	-0.12	0.48	88.61	-0.09	0.42	92.04
2,000	$\hat{\theta}_{pw}$	(π_S, π_A) correct	-0.07	0.38	90.97	-0.03	0.37	91.17	-0.06	0.33	89.97
5,000	$\hat{\theta}_{pw}$	(π_S, π_A) correct	-0.03	0.26	89.90	-0.06	0.26	89.15	-0.03	0.23	92.37
1,000	$\hat{\theta}_{pw}$	(π_S, π_A) incorrect	-0.21	0.49	89.21	-0.22	0.49	87.60	-0.18	0.43	89.42
2,000	$\hat{\theta}_{pw}$	(π_S, π_A) incorrect	-0.17	0.38	87.56	-0.13	0.38	87.56	-0.15	0.33	86.66

(Continued)

Table 1: *Continued*

Sample size	Estimator	Model Spec.	Bias	Median	95% CI	Bias	Median	95% CI	Bias	Median	95% CI	95% CI
				Est. SE	Cov. (%)		Est. SE	Cov. (%)		Est. SE	Cov. (%)	Cov. (%)
5,000	$\hat{\theta}_{\text{pw}}$	(π_S, π_A) incorrect	−0.14	0.26	82.92	−0.16	0.27	83.57	−0.13	0.23	86.14	85.18
1,000	$\hat{\theta}_{\text{dr}}$	All correct	−0.04	0.32	93.85	−0.03	0.33	93.65	−0.01	0.31	95.56	95.06
2,000	$\hat{\theta}_{\text{dr}}$	All correct	−0.01	0.25	94.88	0.01	0.25	94.38	0.00	0.23	94.68	94.08
5,000	$\hat{\theta}_{\text{dr}}$	All correct	−0.01	0.17	93.34	−0.02	0.18	93.56	0.01	0.16	94.84	94.63
1,000	$\hat{\theta}_{\text{dr}}$	μ_Y correct	−0.01	0.36	93.45	−0.02	0.36	93.75	−0.03	0.31	94.96	93.65
2,000	$\hat{\theta}_{\text{dr}}$	μ_Y correct	0.01	0.27	95.09	0.03	0.27	94.88	−0.02	0.24	94.98	94.98
5,000	$\hat{\theta}_{\text{dr}}$	μ_Y correct	0.00	0.18	93.66	−0.01	0.19	92.59	−0.01	0.16	93.23	93.56
1,000	$\hat{\theta}_{\text{dr}}$	(π_S, π_A) correct	−0.03	0.36	90.83	−0.02	0.36	90.12	−0.01	0.34	92.64	90.73
2,000	$\hat{\theta}_{\text{dr}}$	(π_S, π_A) correct	−0.01	0.28	92.28	0.05	0.28	92.68	−0.02	0.26	91.88	91.98
5,000	$\hat{\theta}_{\text{dr}}$	(π_S, π_A) correct	0.00	0.19	90.87	−0.02	0.19	92.70	0.02	0.18	92.16	93.23

Table 2: Simulation results for four scenarios. Scenario 9: $b = (b2)$, $d = (d1)$, $e = (e)$, $f = (f1)$. Scenario 10: $b = (b2)$, $d = (d1)$, $e = (e)$, $f = (f2)$. Scenario 11: $b = (b2)$, $d = (d2)$, $e = (e)$, $f = (f1)$. Scenario 12: $b = (b2)$, $d = (d2)$, $e = (e)$, $f = (f2)$. $\theta_0 = 1$ in all four scenarios

Sample size	Estimator	Model Spec.	Bias	Median Est. SE	95% CI Cov. (%)	Bias	Median Est. SE	95% CI Cov. (%)	Bias	Median Est. SE	95% CI Cov. (%)
Scenario 9											
1,000	$\hat{\theta}_{reg,naive}$		1.20	0.14	0.00	1.19	0.15	0.00	1.18	0.15	0.00
2,000	$\hat{\theta}_{reg,naive}$		1.20	0.10	0.00	1.20	0.10	0.00	1.19	0.10	0.00
5,000	$\hat{\theta}_{reg,naive}$		1.19	0.06	0.00	1.19	0.07	0.00	1.18	0.07	0.00
1,000	$\hat{\theta}_{dr,naive}$		1.20	0.15	0.20	1.19	0.16	0.20	1.19	0.14	0.10
2,000	$\hat{\theta}_{dr,naive}$		1.20	0.11	0.10	1.19	0.11	0.10	1.20	0.10	0.00
5,000	$\hat{\theta}_{dr,naive}$		1.19	0.07	0.32	1.19	0.07	0.00	1.19	0.06	0.00
1,000	$\hat{\theta}_{reg}$	μ_Y correct	-0.01	0.19	94.35	-0.02	0.19	94.76	-0.01	0.19	94.05
2,000	$\hat{\theta}_{reg}$	μ_Y correct	0.00	0.14	95.89	0.00	0.14	94.08	-0.01	0.13	94.48
5,000	$\hat{\theta}_{reg}$	μ_Y correct	-0.01	0.09	94.41	-0.01	0.09	95.38	-0.01	0.08	95.27
1,000	$\hat{\theta}_{reg}$	μ_Y incorrect	-0.78	0.19	1.81	-0.78	0.19	1.21	-0.78	0.18	1.11
2,000	$\hat{\theta}_{reg}$	μ_Y incorrect	-0.77	0.13	0.00	-0.77	0.13	0.00	-0.78	0.13	0.00
5,000	$\hat{\theta}_{reg}$	μ_Y incorrect	-0.77	0.08	0.00	-0.77	0.08	0.00	-0.78	0.08	0.00
1,000	$\hat{\theta}_{ppw}$	(π_S, π_A) correct	-0.07	0.48	91.83	-0.09	0.48	90.02	-0.05	0.42	90.62
2,000	$\hat{\theta}_{ppw}$	(π_S, π_A) correct	-0.06	0.36	92.38	-0.05	0.37	92.58	-0.05	0.32	92.58
5,000	$\hat{\theta}_{ppw}$	(π_S, π_A) correct	-0.05	0.26	89.47	-0.03	0.25	91.62	-0.04	0.23	90.01
1,000	$\hat{\theta}_{ppw}$	(π_S, π_A) incorrect	-0.15	0.49	90.22	-0.19	0.49	89.31	-0.13	0.43	91.13
2,000	$\hat{\theta}_{ppw}$	(π_S, π_A) incorrect	-0.15	0.38	89.37	-0.13	0.38	89.67	-0.10	0.33	89.77
Scenario 10											
Scenario 11											
Scenario 12											

(Continued)

Table 2: *Continued*

Sample size	Estimator	Model Spec.	Bias	Median Est. SE	95% CI Cov. (%)	Bias	Median Est. SE	95% CI Cov. (%)	Bias	MedianEst. SE	95% CI Cov. (%)	
5,000	$\hat{\theta}_{\text{IPW}}$	(π_S, π_A) incorrect	−0.14	0.26	87.00	−0.11	0.26	88.08	−0.11	0.23	87.22	87.86
1,000	$\hat{\theta}_{\text{dr}}$	All correct	0.00	0.33	94.66	0.00	0.32	92.84	0.00	0.29	94.76	94.35
2,000	$\hat{\theta}_{\text{dr}}$	All correct	0.00	0.24	95.09	0.01	0.25	94.18	−0.01	0.22	94.98	93.58
5,000	$\hat{\theta}_{\text{dr}}$	All correct	−0.01	0.17	94.31	−0.01	0.17	95.06	−0.02	0.15	93.88	95.06
1,000	$\hat{\theta}_{\text{dr}}$	μ_Y correct	0.01	0.37	93.25	0.00	0.36	93.85	−0.01	0.32	94.96	94.25
2,000	$\hat{\theta}_{\text{dr}}$	μ_Y correct	0.01	0.28	93.78	0.01	0.28	94.68	−0.01	0.24	94.68	93.28
5,000	$\hat{\theta}_{\text{dr}}$	μ_Y correct	0.00	0.19	93.88	0.01	0.19	93.88	−0.02	0.16	93.56	95.38
1,000	$\hat{\theta}_{\text{dr}}$	(π_S, π_A) correct	0.01	0.36	91.43	0.00	0.36	92.04	0.00	0.32	92.14	91.94
2,000	$\hat{\theta}_{\text{dr}}$	(π_S, π_A) correct	0.02	0.27	93.38	0.01	0.27	93.28	0.00	0.25	92.88	92.78
5,000	$\hat{\theta}_{\text{dr}}$	(π_S, π_A) correct	−0.01	0.19	93.02	0.00	0.18	93.13	−0.01	0.17	92.16	93.77

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