

Near-Isometric Properties of Kronecker-Structured Random Tensor Embeddings

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Abstract

We give uniform concentration inequality for random tensor acting on rank-1 Kronecker structured signals, which parallels a Gordon-type inequality for this class of tensor structured data. Two variants of the random embedding are considered, where the embedding dimension depends on explicit quantities characterizing the complexity of the signal. To appreciate the tools developed herein, we illuminate with two applications from signal recovery and optimization.

Keywords: Structured Non-symmetric Tensor; Uniform Deviation Bound; Generic Chaining

1. Introduction

It is hardly an overstatement to proclaim that underpins most of the analysis for high dimensional statistics and structured signal recovery is the heavy hammer made possible by the machinery of Gaussian process, and in particular Gordon-type inequality that gives tight characterization bounding the suprema of the empirical process with geometric properties of the underlying index set. In this paper, we put Kronecker-structured random tensors into scrutiny and ask for analog of Gordon's inequality for correspondingly tensor-structured signals. We embark with a brief reminder of the classics.

1.1. Gordon's inequality for Gaussian random matrix

For signal $u \in T \subset \mathbb{R}^n$ a vector, we know for $S \in \mathbb{R}^{m \times n}$ random i.i.d standard Gaussian matrix,

$$\mathbb{E}[\min_{u \in T} \|Su\|] \geq a_m - w(T) \quad \text{and} \quad \mathbb{E}[\max_{u \in T} \|Su\|] \leq a_m + w(T)$$

for $a_m = \mathbb{E}[\|g_m\|] \approx \sqrt{m}$ where $g_m \sim \mathcal{N}(0, I_m)$ and $w(T) = \mathbb{E}[\max_{x \in T} g^\top x]$ the Gaussian width for set $T \subset \mathcal{S}^{n-1}$, a subset of the unit sphere. This statement hinges on the Gaussian min-max comparison lemma (i.e., Fernique-Slepian theorem), which implies for g, h independent standard Gaussian vectors,

$$\mathbb{E}_{g,h}[\min_{u \in T} \max_{v \in \mathcal{S}^{m-1}} g^\top v + h^\top u] \leq \mathbb{E}_S[\min_{u \in T} \max_{v \in \mathcal{S}^{m-1}} v^\top Su], \quad (1)$$

from which one can see that the LHS evaluates to the first part of the previous display. The other side is essentially similar. For this expectation bound to justify the attention it deserves, one needs to recognize that $\min_{u \in T} \|Su\|$ (analogously for max) is a Lipschitz function in the Gaussian random matrix S , from which (dimension-free) concentration inequality, alongside the bound on the expectation derived above, conspire to deliver a uniform concentration bound as stated below.

Theorem 1 (*Gordon, 1988*) For all $u \in T \subset \mathbb{R}^n$, where T is a (not necessarily convex) cone, with probability at least $1 - 2 \exp(-\delta^2/2)$ for S entrywise i.i.d standard Gaussian,

$$(1 - \epsilon)\|u\| \leq \frac{1}{a_m}\|Su\| \leq (1 + \epsilon)\|u\|$$

when $m \geq \frac{(w(T)+\delta)^2}{\epsilon^2}$.

This analysis, unfortunately, doesn't have a life beyond the Gaussian case due to the lack of comparison lemma (1) (even for subgaussian), but gives that for example, the extreme singular values of a Gaussian random matrix $1/\sqrt{m} \cdot S$ scales as $1 \pm \sqrt{n/m}$ by picking $T = \mathcal{S}^{n-1}$. It also recovers the familiar Johnson-Lindenstrauss lemma for distance-preserving random projection for finite point set where $w = \sqrt{\log(|T|)}$.

Seemingly a natural obsession for probabilists, results of this flavor have found unexpectedly number of applications across many other areas in numerical linear algebra, signal processing, theoretical computer science, among others. Such uniform convergence result is frequently encountered for deriving tight sample complexity bounds for recovery problems, where the problem boils down to characterizing the probability that a random subspace (i.e., null space of Gaussian measurement matrix) distributed uniformly misses the tangent cone of a regularizer. Nonconvex gradient-based optimization heavily leans on these tools for characterizing restricted singular value for deriving convergence with ERM. Sketching-based least-squares optimization also crucially rely on such results, where $w(U \cap \mathcal{S}^{n-1}) = \sqrt{\dim(U)}$ for $U = \text{colspan}([A, b])$ for subspace embedding property.

1.2. Contributions

We aim to generalize Gordon's uniform concentration result for tensor-structured signal $x = u^1 \otimes \dots \otimes u^d$ while insisting on efficient computation of the embedding operation. More concretely, we consider Kronecker-structured random rank-1 tensor, which when acting on rank-1 tensor-structured signals, can be performed without explicitly forming the $n \times n \times \dots \times n$ tensor since it can be done factor-by-factor effortlessly. Formally we set out our roadmap to address the following questions:

1. For (1) structured and fast tensored embedding (e.g., Tensor-SRHT as defined in Definition 2 below); and (2) Tensor-Subgaussian introduced in Definition 3, what is dictated from the embedding dimension m for the following guarantee to hold w.h.p

$$\left| \frac{1}{m} \sum_{i=1}^m \prod_{j=1}^d \langle v_i^j, u^j \rangle^2 - \|x\|^2 \right| \leq \max(\epsilon, \epsilon^2) \cdot \|x\|^2, \quad (2)$$

for all $x = u^1 \otimes \dots \otimes u^d \in T^1 \times \dots \times T^d$ (Cartesian product of d not necessarily convex cones), as a function of the geometric properties of the *individual* sets T^1, \dots, T^d . This is a generalization of RIP to (1) higher order tensored signals; (2) general cones beyond sparsity. We are interested in the regime $m \ll n^d$ and instantiate the embedding result for this sketch from Section 4 to bound the restricted singular value as required by a tensor signal recovery problem in Section 6.1.

2. To improve the dependence of m on the degree d (while maintaining computation efficiency), we consider a recursive embedding in Section 5 which repeatedly calls a degree-2 Tensor-SRHT $S^j \in \mathbb{R}^{m \times nm}$ as a subroutine as follows: $S(u^1 \otimes u^2 \otimes u^3 \dots) := S^1(u^1 \otimes S^2(u^2 \otimes$

$S^3(u^3 \otimes \dots)$). Similar uniform concentration is derived on the scaling of m with geometric properties of the individual sets for this alternative embedding, which is in turn called upon to speed up solving for optimization problem in Section 6.2.

3. Our technique is based on generic chaining - we include comparison with results one would get from more naive method in Section 3 and part with some discussions of lower bound on the embedding dimension in Section 7.

We emphasize it is the dependency/correlation in the tensor structure that introduces difficulty for tight concentration – result for general random tensor with i.i.d entries is less challenging to obtain.

Definition 2 (Tensor-SRHT) A random matrix constructed as $S = \frac{1}{\sqrt{m}} P_1 H_n D_1 \circ \dots \circ P_d H_n D_d \in \mathbb{R}^{m \times n^d}$ is called a *Tensor-SRHT (Subsampled Randomized Hadamard Transform)*, if when acting on a rank-1 degree- d tensor, takes the form $S(u^1 \otimes \dots \otimes u^d) = \frac{1}{\sqrt{m}} P' H_{n^d} D' \text{vec}(u^1 \otimes \dots \otimes u^d) := \frac{1}{\sqrt{m}} P_1 H_n D_1 u^1 \odot \dots \odot P_d H_n D_d u^d$, where D' is a $n^d \times n^d$ diagonal matrix with entries $D_1 \otimes \dots \otimes D_d$ (i.e., tensor product of independent Rademachers) and P' is a $m \times n^d$ subsampling matrix with a single 1 in each (independent) row and $H_{n^d} = H_n \otimes \dots \otimes H_n$ where n is a power of 2 is the Hadamard matrix of size $n^d \times n^d$. Here \odot denotes Hadamard product and \circ denotes the transposed Khatri-Rao product. Moreover, such embedding can be carried out in time $\mathcal{O}(d(n \log n + m))$.

Definition 3 (Tensor-Subgaussian) We call $S \in \mathbb{R}^{m \times n^d}$ a *Tensor-Subgaussian embedding* if every row $S_i = \text{vec}(v_i^1 \otimes \dots \otimes v_i^d)$ is constructed where each factor is an independent σ -subgaussian isotropic random vector, i.e., (1) $\mathbb{E}[\langle v_i^j, u^j \rangle^2] = \|u^j\|_2^2$; (2) $\mathbb{E}[|\langle v_i^j, u^j \rangle|^p]^{1/p} \leq \sqrt{\sigma p} \|u^j\|_2$ for all $p \geq 2$, $i \in [m]$, $j \in [d]$ and any $u^j \in \mathbb{R}^n$.

2. Related Work

In the case of vector-valued signal ($d = 1$), embedding analysis for infinite sets using structured matrices requires ingenuity and is significantly more involved in general. Notable extensions include (Bourgain et al., 2015; Dirksen, 2016; Bartl and Mendelson, 2021). The work of Oymak et al. (2018) offered a unifying theme - the important message behind is that one can have a reduction from RIP based result to Gordon-type inequality by invoking it at different sparsity levels with various distortions à la Talagrand’s multi-resolution generic chaining. An orthogonal thread for generalizing to heavier-tail distribution involves small-ball technique which gives an one-sided bound for nonnegative empirical process - such undertaking is present in e.g., Koltchinskii and Mendelson (2015).

Previous work on tensor concentration are mostly preoccupied with operator norm bounds for symmetric subgaussian and/or log-concave (potentially non-isotropic) factors (Even and Massoulié, 2021; Zivotovskiy, 2021), where for symmetric forms $\|S\|_{op}$ is maximized by a single vector $u \in \mathcal{S}^{n-1}$ therefore for this we only need to content ourselves with a single index set and look at moment deviations of type: $\sup_{u \in \mathcal{S}^{n-1}} \left| \frac{1}{m} \sum_{i=1}^m \langle S_i, u \rangle^d - \mathbb{E}[\langle S, u \rangle^d] \right|$, an arguably simpler task.

The case of non-symmetric factors warrant more care. Both Vershynin (2020); Bamberger et al. (2021a) studied *pointwise tail bound* of the form $\mathbb{P}(\|Sx\|_2 - \|S\|_F \geq t)$ for $S \in \mathbb{R}^{m \times n^d}$ a linear mapping, $x = u^1 \otimes \dots \otimes u^d \in \mathbb{R}^{n^d}$, where u^k ’s are independent factors each with independent, mean 0, unit variance, subgaussian coordinates – this can in turn be used for deriving a high-probability

lower bound on $\sigma_{\min}(X)$ for the $n^d \times m$ random matrix X where each column is formed by the aforementioned tensor x . Uniform results for general sets on tensors include 2nd-order chaos with mixed tails (Talagrand, 2014), for example in the case of subgaussian-subexponential increments (as is the case when $d = 2$ for Tensor-Subgaussian), i.e., $\forall u > 0, s, t \in T$,

$$\mathbb{P}(\|X_t - X_s\| \geq \sqrt{u}d_2(t, s) + ud_1(t, s)) \leq 2e^{-u},$$

the result of Dirksen (2015) gave a uniform deviation for $\sup_{t \in T} \|X_t\|$ as a combination of $\gamma_2(T, d_2)$ and $\gamma_1(T, d_1)$ but crucially these quantities are tied to the metric complexity of the *product index set* $T := T^1 \times T^2$ – something that is hard to compute by and large.

3. Discrete JL and a Single-scale Approach

At the heart of the following result is a generalized Khinchine inequality (Ahle and Knudsen, 2019) which says if $\mathbb{E}[|\langle v^k, a \rangle|^p]^{1/p} \leq C_p \|a\|_2$ for any vector $a \in \mathbb{R}^n$ and all independent $\{v^k\}_{k=1}^d$, then $\mathbb{E}[|\langle v^1 \otimes \dots \otimes v^d, a \rangle|^p]^{1/p} \leq C_p^d \|a\|_2$ for any tensor $a \in \mathbb{R}^{n^d}$. This is closely related to earlier results from Latała (2006) on the concentration of Gaussian chaos. We establish the finite-set embedding property for the row-wise-tensored embedding matrices below, building upon previous work. This serves as the stepping stone for embedding of general sets.

Lemma 4 (Discrete-JL property for Tensor-SRHT and Tensor-Subgaussian) *For a set of cardinality p that the rank-1 tensor $x \in \mathbb{R}^{n^d}$ belongs, with probability at least $1 - e^{-\eta}$ for any $\eta > 0$ and $\epsilon > 0$, Tensor-SRHT as defined in Definition 2 satisfies $|\|Sx\|_2^2 - \|x\|_2^2| \leq \max(\epsilon, \epsilon^2) \|x\|_2^2$ simultaneously for all p points provided $m = \mathcal{O}(C^d \frac{1}{\epsilon^2} (\log^d(p) + (1 + \eta)^d))$. The same guarantee holds for Tensor-Subgaussian in Definition 3 with $m = \mathcal{O}(C^d \sigma^{2d} \frac{1}{\epsilon^2} (\log^d(p) + (1 + \eta)^d))$ for some universal constant C .*

Proof Tracing the footsteps for the proof of Theorem 3 in Ahle and Knudsen (2019), one could check that we can smuggle in the term $\max(\epsilon, \epsilon^2)$ replacing $\epsilon \in (0, 1)$ for the following guarantee: with

$$m = \mathcal{O}\left(C^d \frac{1}{\epsilon^2} \log\left(\frac{1}{\delta}\right) \log^d\left(\frac{1}{\delta}\right)\right),$$

the resulting Tensor SRHT matrix $S \in \mathbb{R}^{m \times n^d}$ constructed as in Definition 2 satisfies (1) $\mathbb{E}[\|Sx\|_2^2] = 1$ for all $\|x\| = 1$; (2) $\mathbb{E}[|\|Sx\|_2^2 - 1|^{\log(1/\delta)}] \leq (\frac{1}{\epsilon} \max(\epsilon, \epsilon^2))^{\log(1/\delta)}$. This implies via Markov's inequality,

$$\mathbb{P}(|\|Sx\|_2^2 - 1| \geq \max(\epsilon, \epsilon^2)) \leq \delta$$

for any unit norm x and $\delta \in (0, 1)$. Therefore for a set of cardinality p , we take a union bound to conclude with probability at least $1 - e^{-\eta}$ for any $\eta > 0$,

$$|\|Sx\|_2^2 - 1| \leq \max(\epsilon, \epsilon^2)$$

simultaneously for all p points on the unit sphere in the set provided

$$m = \mathcal{O}\left(C^d \frac{1}{\epsilon^2} (\log^d(p) + \eta^d \vee \eta)\right)$$

for some universal constant C , which renders the advertised bound by recognizing $\eta^d \vee \eta \leq (1 + \eta)^d$. The same argument applies to Tensor-Subgaussian embedding by working with Theorem 2 in Ahle and Knudsen (2019) instead. ■

Remark 5 *Close inspection of the proof for Theorem 3 in Ahle and Knudsen (2019) in fact uncovers that the discrete JL property above holds for more general class of SORS (Subsampled Orthogonal Random Sign) constructions for which $H^*H = n \cdot I_n$ and $\max_{i,j \in [n]} |H_{ij}| \leq c$. In the case $d = 1$, it also recovers the classical Johnson–Lindenstrauss lemma.*

Without taking the multi-scale route, in the case $d = 1$, to guarantee ϵ -distortion over a continuous set, one needs to roughly speaking build a Δ -net for $x \in \mathbb{R}^n$ for $\Delta \lesssim \epsilon \cdot \sqrt{m/n}$ therefore the sample complexity one gets with this approach will scale as $m \gtrsim \frac{\log(|\mathcal{N}^\Delta|)}{\epsilon^2} \gtrsim \frac{nw^2(T)}{m\epsilon^4} \Rightarrow m \gtrsim \frac{\sqrt{nw(T)}}{\epsilon^2}$, where we used Sudakov’s minorization for bounding the size of the covering with Gassuain width of the set and the JL Lemma for SRHT/Subgaussian matrices. This back-of-the-envelope calculation showcases that uniform covering is far from optimal, since in general it could be the case $w(T) \ll \sqrt{n}$ for $T \subset \mathcal{S}^{n-1}$ a subset of the unit sphere – and this is precisely the reason that motivated Oymak et al. (2018) to consider a multi-scale approximation that can establish the $m \asymp w^2(T)/\epsilon^2$ guarantee for wider class of random ensembles beyond the Gaussian case in Theorem 1. To put things in perspective with later sections, we work out the sample complexity required from a naive uniform discretization below.

Lemma 6 (Δ -net Covering) *Using Tensor-SRHT, with a uniformly constructed Δ -net covering of the tensor, one requires $m = \mathcal{O}(C^{\frac{d}{2}}((d^2 \sum_{i=1}^d \gamma_2^2(T^i))^d + (1 + \eta)^d))$ for (2) to hold.*

Proof Let $\Delta < 1/2$, to cast an Δ -net (in Frobenius norm) for the rank-1 tensor, suppose for each of the d factors $u^i \in T^i \subset \mathcal{S}^{n-1}$ we find $v^i \in T^i \cap \mathcal{N}^i$ such that $\|v^i - u^i\|_2 \leq \Delta/d$, then

$$\begin{aligned} \|v^1 \otimes \dots \otimes v^d - u^1 \otimes \dots \otimes u^d\|_F &\leq \sum_{i=1}^d \|v^1\| \dots \|v^{i-1}\| \|v^i - u^i\| \|u^{i+1}\| \dots \|u^d\| \\ &\leq d \times \Delta/d = \Delta. \end{aligned}$$

To extend (2) to hold for all $x \in T$, write $u^i = v^i + l^i$ for $\|l^i\|_2 \leq \Delta/d$, and recall $\|u^1 \otimes \dots \otimes u^d\| = \|v^1 \otimes \dots \otimes v^d\| = 1$,

$$\begin{aligned} &|\text{vec}(u^1 \otimes \dots \otimes u^d)^\top (S^\top S - I) \text{vec}(u^1 \otimes \dots \otimes u^d)| \\ &\leq |\text{vec}(v^1 \otimes \dots \otimes v^d)^\top (S^\top S - I) \text{vec}(v^1 \otimes \dots \otimes v^d)| \\ &\quad + 2|(\text{vec}(u^1 \otimes \dots \otimes u^d) - \text{vec}(v^1 \otimes \dots \otimes v^d))^\top (S^\top S - I) \text{vec}(v^1 \otimes \dots \otimes v^d)| \\ &\leq \max_{v^i \in T^i \cap \mathcal{N}^i} |\text{vec}(v^1 \otimes \dots \otimes v^d)^\top (S^\top S - I) \text{vec}(v^1 \otimes \dots \otimes v^d)| + 2\Delta \|S^\top S - I\|_{op} \end{aligned}$$

so taking sup over $u^i \in T^i$, we have

$$\|S^\top S - I\|_{op} \leq \frac{1}{1 - 2\Delta} \cdot \max_{\tilde{x} \in T \cap \mathcal{N}^\Delta} |\tilde{x}^\top (S^\top S - I) \tilde{x}|.$$

Therefore to have the distortion below order $\max(\epsilon, \epsilon^2)$ for all x , it suffices to cover each factor to accuracy Δ/d and union bound over this finite set to guarantee $\max(\epsilon, \epsilon^2)$ -distortion on it.

Using Sudakov’s minorization, the cardinality of the finite set $p \lesssim \prod_{i=1}^d \exp\left(\frac{d^2}{\Delta^2} w^2(T^i)\right)$. Owing to the existence of Lemma 4 on Discrete-JL for Tensor-SRHT, it suggests the dependence

on $w(T^i)$ (and therefore $\gamma_2(T^i)$) should scale as

$$m = \mathcal{O} \left(C^d \frac{1}{\epsilon^2} \left(\left(d^2 \sum_{i=1}^d \gamma_2^2(T^i) \right)^d + (1 + \eta)^d \right) \right)$$

for such a uniform concentration to hold. ■

Even in the prosaic case of Gaussian process indexed by ellipsoid and/or ℓ_1 ball, it is a well-known and disappointing fact that arguments based on union bound / Dudley integral don't give the optimal bound, whereas method based on generic chaining does (Talagrand, 2014), which we turn to next.

4. A Multi-scale Approach: Generic Chaining for Row-wise Tensorized Embedding

One viable approach is to apply the result of Oymak et al. (2018) naively to $\text{vec}(u^1 \otimes \dots \otimes u^d)$ without taking into consideration the Kronecker structure, but this is somewhat of a futile endeavor if one takes any interest in downstream applications of such bounds. In fact, this was also the impetus for Mendelson's work on product empirical processes (Mendelson, 2016) – it is generally hard to handle geometric properties of process indexed by product classes. We will instead derive results with an eye towards bounds involving *decoupled* geometric complexity measure for each factor that lends itself to explicit computations – this necessarily calls for a more intricate chaining argument. Another possibility is to use contraction inequality if the random factors $\{v_i^j\}_{j=1}^d$ come from bounded class but this will be crude in almost all cases.

Our agenda is to leverage the results on finite set embedding from the previous section, wrap them inside of a chaining argument by exploiting coverings at multiple scales with different distortions/probability tradeoff so each level of approximation demands roughly the same embedding dimension (as we will see, the final m depends on the maximum required across all resolutions).

4.1. Preliminaries

Throughout the paper, we use $\lesssim, \asymp, \gtrsim$ to hide absolute constants. To measure the size of the set $T^i \subset \mathbb{R}^n$, we use Gaussian width defined as for $g \sim \mathcal{N}(0, I_n)$,

$$w(T^i) = \mathbb{E} \left[\sup_{u \in T^i} g^\top u \right].$$

In our context, we define the γ_2^* functional as

$$\gamma_2^*(T^i) := \inf_{\{T_l^i\}} \sup_{u^i \in T^i} \sum_{l=0}^{\infty} 2^{l/2} \text{dist}(u^i, T_l^i)$$

where the infimum is taken over all sequences of nets $\{T_l^i\}_l$ with cardinality $|T_l^i| \leq 2^{2^l} =: N_l \forall i \in [d]$ and $|T_0^i| = 1 =: N_0$. For Gaussian process with canonical metric (i.e., Euclidean norm) on T^i , the expected supremum is completely characterized by $\gamma_2^*(T)$, i.e.,

$$\gamma_2^*(T^i) \asymp w(T^i)$$

where the upper bound is due to Fernique and the (much deeper, specific-to-gaussian-process) lower bound is due to Talagrand's majorizing theorem. A more general definition working with admissible sequences defines

$$\gamma_2(T^i) := \inf_{\{\mathcal{A}_l^i\}} \sup_{u^i \in T^i} \sum_{l=0}^{\infty} 2^{l/2} \text{diam}(\mathcal{A}_l^i(u^i))$$

where the infimum is taken over all admissible sequences (i.e., increasing sequence of partitions of T^i with $|\mathcal{A}_l^i| \leq N_l$ for all $l \geq 0$) and $\mathcal{A}_l^i(u^i)$ denotes the (unique) element of \mathcal{A}_l^i that contains u^i . It is not hard to see that by picking one point arbitrarily from each element of the partition, one can build a net which implies that we always have $\gamma_2^*(T^i) \leq \gamma_2(T^i)$. In fact, the work of [van Handel \(2018\)](#) shows that these two quantities are always of the same order.

It is also an immediate consequence that for an optimal admissible sequence $\{\bar{\mathcal{A}}_l^i\}_l$, picking $\{\bar{T}_l^i\}_l$ as a sequence of nets with cardinality $|\bar{T}_l^i| \leq N_l$ constructed by choosing the center point in every element of the partition set $\{\bar{\mathcal{A}}_l^i\}_l$, we have for all $u^i \in T^i, i \in [d]$,

$$\sum_{l=0}^{\infty} 2^{l/2} \text{dist}(u^i, \bar{T}_l^i) \leq \inf_{\{\mathcal{A}_l^i\}} \sup_{t \in T^i} \sum_{l=0}^{\infty} 2^{l/2} \text{diam}(\mathcal{A}_l^i(t)). \quad (3)$$

Below is an easy observation on the sequence of successive coverings $\{\bar{T}_l^i\}_l$ as defined above.

Lemma 7 (Choice of L) *For all $u^i \in T^i$, $\text{dist}(u^i, \bar{T}_L^i) \lesssim \frac{1}{d}$ for $L \gtrsim \lceil \log_2(nd) \rceil$.*

Proof Since $\gamma_2(T^i) \asymp \gamma_2^*(T^i)$ and (3) shows that

$$\sup_{u^i \in T^i} \sum_{l=0}^{\infty} 2^{l/2} \text{dist}(u^i, \bar{T}_l^i) \leq \gamma_2(T^i),$$

it is necessarily the case that (using the inf in the definition of γ_2^*)

$$\sup_{u^i \in T^i} \sum_{l=0}^{\infty} 2^{l/2} \text{dist}(u^i, \bar{T}_l^i) \asymp \gamma_2^*(T^i),$$

so $\{\bar{T}_l^i\}_l$ is almost optimal, which means that for the classical greedily constructed ϵ_l -net for the unit Euclidean ball with cardinality $(1 + 2/\epsilon_l)^n \leq N_l$ for $\epsilon_l = n/2^{l-2}$, and for any $u^i \in T^i$,

$$\sum_{l=0}^{\infty} 2^{l/2} \text{dist}(u^i, \bar{T}_l^i) \lesssim \sum_{l=0}^{\infty} 2^{l/2} \cdot \epsilon_l = n \cdot \text{const}$$

therefore $\text{dist}(u^i, \bar{T}_L^i) \lesssim \frac{n}{(L+1) \cdot 2^{L/2}}$ with a proof of contradiction, where in the above we pushed sup inside. This in turn indicates that sending $L \gtrsim \lceil \log_2(nd) \rceil$ the distortion for approximating any $u^i \in T^i \subset \mathcal{S}^{n-1}$ with the net $\{\bar{T}_L^i\}$ is below order $1/d$. \blacksquare

For our results, we will find it helpful to adopt the slightly more general γ_α -functional for $\alpha > 0$:

$$\sum_{l=0}^{\infty} 2^{l/\alpha} \text{dist}(u^i, \bar{T}_l^i) \leq \gamma_\alpha(T^i) := \inf_{\{\mathcal{A}_l^i\}} \sup_{u^i \in T^i} \sum_{l=0}^{\infty} 2^{l/\alpha} \text{diam}(\mathcal{A}_l^i(u^i))$$

and the infimum is taken over all admissible sequences in exactly the same way as (3). Moreover, we always have the following Dudley-style metric entropy integral estimate (Talagrand, 2014)

$$\gamma_\alpha(T^i) \lesssim C_\alpha \int_0^1 (\log N(T^i, sB_2^n))^{1/\alpha} ds, \quad (4)$$

but the reverse is generally not true. Here the upper limit of the integral goes up to 1 because $N(T^i, sB_2^n) = 1$ for $s \geq 1$ by simply picking $\{0\}$ as cover. It is known that for random variable with tail decay bounded as $e^{-|x|^\alpha}$, the supremum is upper bounded by the γ_α functional (Dirksen, 2015). Covering number can be bounded with estimates on Gaussian width. In particular, Sudakov minorization asserts

$$\sup_{s>0} s \sqrt{\log N(T^i, sB_2^n)} \lesssim w(T^i),$$

which uses covering number at a single scale. Various alternative options exist for upper bounding the covering number, including Volumetric estimates, Maurey's empirical method etc.

Estimate (4) above has the drawback of not being explicit in constants C_α , if one is keen on explicit dependence on α , the following lemma becomes timely.

Lemma 8 (Relationship between γ_α functionals) *For $\alpha \leq 1$, if set $T^i \subset \mathcal{S}^{n-1}$ has covering number $N(T^i, sB_2^n) \leq (\frac{a}{s})^b$ for some $b \geq 2$, $a \geq 2$, then*

$$\gamma_2(T^i) \leq \gamma_\alpha(T^i) \leq (1 + K \cdot \log_2(b/\alpha) \cdot b/\alpha \cdot \log_2(a))^{\frac{2-\alpha}{2\alpha}} \gamma_2(T^i)$$

for some absolute constant K .

Proof By definition, the γ_α functional is monotonically non-increasing in α . The other side of the inequality involves a careful look into the admissible sequence. Pick a cutoff level l_c to be specified later, for the optimal admissible sequence $\{\bar{\mathcal{A}}_l^i\}_l$ for the γ_2 functional we construct another admissible sequence $\{\mathcal{B}_l^i\}_l$ that coincides with $\{\bar{\mathcal{A}}_l^i\}_l$ for $l \leq l_c$, and observe that

$$\sup_{u^i \in T^i} \sum_{l \leq l_c} 2^{l/\alpha} \text{diam}(\bar{\mathcal{A}}_l^i(u^i)) \leq \sup_{u^i \in T^i} 2^{\frac{(2-\alpha)l_c}{2\alpha}} \sum_{l \leq l_c} 2^{l/2} \text{diam}(\bar{\mathcal{A}}_l^i(u^i)). \quad (5)$$

For the scales $l > l_c$, we aim to pick l_c large enough so that $\sum_{l > l_c} 2^{l/\alpha} \text{diam}(\mathcal{B}_l^i(u^i)) \leq 1$ for $|\mathcal{B}_l^i| \leq 2^{2^l}$ being the tightest covering of elements of $\bar{\mathcal{A}}_l^i$ for each $l > l_c$. Since $N(T^i, sB_2^n) \leq (\frac{a}{s})^b$, we have $s_l = a2^{-2^l/b}$ distortion, which means for $l = l_c + e$ where $e > 0$, and any $u^i \in T^i$,

$$2^{l/\alpha} \text{diam}(\mathcal{B}_l^i(u^i)) \leq a2^{l/\alpha - 2^l/b} = 2^{\log_2(a) + l/\alpha - 2^l/b}.$$

Therefore put $l_c = \log_2(K \cdot \log_2(b/\alpha) \cdot b/\alpha \cdot \log_2(a))$ for a sufficiently large constant K (essentially we need l_c large enough such that $2^{l_c} - b/\alpha \cdot l_c \geq (\log_2(a) + 1)b$),

$$\sum_{l > l_c} 2^{l/\alpha} \text{diam}(\mathcal{B}_l^i(u^i)) \leq \sum_{e \geq 0} \frac{1}{2^{e+1}} \leq 1.$$

Plugging l_c back into (5), altogether this gives (since γ_α takes inf over all admissible sequences, of which $\{\mathcal{B}_l^i\}_l$ is one)

$$\gamma_\alpha(T^i) \leq 1 + (K \cdot \log_2(b/\alpha) \cdot b/\alpha \cdot \log_2(a))^{\frac{2-\alpha}{2\alpha}} \cdot \gamma_2(T^i)$$

$$\leq (1 + K \cdot \log_2(b/\alpha) \cdot b/\alpha \cdot \log_2(a))^{\frac{2-\alpha}{2\alpha}} \cdot \gamma_2(T^i)$$

where we used $\gamma_2(T^i) \geq \text{diam}(T^i)/2 = 1$. ■

Remark 9 *The polynomial covering number assumption is a natural one: For VC class with VC dimension v , we have the covering number bound $N(T^i) \leq Kv(4e)^v(\frac{1}{s})^{2(v-1)}$ for some universal constant K . (cf. Theorem 2.6.4 of [Van Der Vaart and Wellner \(1996\)](#))*

4.2. Multi-resolution embedding property

Instead of going through the multi-scale RIP (followed by column sign randomization) as done in [Oymak et al. \(2018\)](#) we will give ourselves more wiggle room by working with a multi-scale embedding property for finite sets. Definition 10 below will be featured prominently in subsequent sections and make the successive construction of approximations less mysterious than it may otherwise seem. We will invoke it for Tensor-SRHT and Tensor-Subgaussian in this section – both taking the form where each row $S_i = \text{vec}(v_i^1 \otimes \cdots \otimes v_i^d)$.

Definition 10 (Multi-resolution Embedding Property) *A mapping $S : \mathbb{R}^{n^d} \mapsto \mathbb{R}^m$ fulfills the (ϵ, η, α) -Multi-resolution Embedding Property if for an increasing sequence of successive coverings $\{\bar{T}_l^i\}_l$ of $T^i \subset \mathcal{S}^{n-1}$ such that $|\bar{T}_l^i| \leq 2^{2^l}$ and $|\bar{T}_0^i| = 1 \forall i \in [d]$ defined in (3) for tensor $x := u^1 \otimes \cdots \otimes u^d$, the following holds simultaneously for all $1 \leq l \leq L \asymp \lceil \log_2(nd) \rceil$ with probability at least $1 - \exp(-\eta)$:*

- For all $k \in [d]$ and $l \in [L]$,

$$\begin{aligned} & \left| \|S(u_l^1 \otimes \cdots \otimes u_l^k \otimes \cdots \otimes u_{l-1}^d) - S(u_l^1 \otimes \cdots \otimes u_{l-1}^k \otimes \cdots \otimes u_{l-1}^d)\|_2^2 \right. \\ & \quad \left. - \|u_l^1 \otimes \cdots \otimes (u_l^k - u_{l-1}^k) \otimes \cdots \otimes u_{l-1}^d\|_F^2 \right| \\ & \leq \max(2^{l/\alpha}\epsilon, 2^{2l/\alpha}\epsilon^2) \cdot \|u_l^1\|_2^2 \cdots \|u_l^k - u_{l-1}^k\|_2^2 \cdots \|u_{l-1}^d\|_2^2 \end{aligned}$$

- For all $k \in [d]$ and $l \in [L]$,

$$\begin{aligned} & \left| \|S(u_l^1 \otimes \cdots \otimes u_l^k \otimes \cdots \otimes u_{l-1}^d)\|_2^2 - \|u_l^1 \otimes \cdots \otimes u_l^k \otimes \cdots \otimes u_{l-1}^d\|_F^2 \right| \\ & \leq \max(2^{l/\alpha}\epsilon, 2^{2l/\alpha}\epsilon^2) \cdot \|u_l^1\|_2^2 \cdots \|u_l^k\|_2^2 \cdots \|u_{l-1}^d\|_2^2 \end{aligned}$$

- For all $k \in [d]$ and $l \in [L]$,

$$\begin{aligned} & \left\| \left\| S \left(u_l^1 \otimes \cdots \otimes \left(\frac{u_l^k - u_{l-1}^k}{\|u_l^k - u_{l-1}^k\|_2} \right) \otimes \cdots \otimes u_{l-1}^d \right) \pm S(u_l^1 \otimes \cdots \otimes u_{l-1}^k \otimes \cdots \otimes u_{l-1}^d) \right\|_2^2 \right. \\ & \quad \left. - \left\| u_l^1 \otimes \cdots \otimes \left(\frac{u_l^k - u_{l-1}^k}{\|u_l^k - u_{l-1}^k\|_2} \pm u_{l-1}^k \right) \otimes \cdots \otimes u_{l-1}^d \right\|_F^2 \right| \\ & \leq \max(2^{l/\alpha}\epsilon, 2^{2l/\alpha}\epsilon^2) \cdot \left\| \frac{u_l^k - u_{l-1}^k}{\|u_l^k - u_{l-1}^k\|_2} \pm u_{l-1}^k \right\|_2^2 \cdot \|u_l^1\|_2^2 \cdots \|u_{l-1}^d\|_2^2 \end{aligned}$$

where tensor Frobenius norm $\|x\|_F := \prod_{k=1}^d \|u^k\|_2$.

For the desired accuracy $\epsilon > 0$ in the final guarantee (2), in what follows we correspondingly define a sequence of distortion levels $\epsilon_0 = \epsilon, \epsilon_1 = 2^{1/\alpha}\epsilon, \dots, \epsilon_L = 2^{L/\alpha}\epsilon$ for $L \asymp \lceil \log_2(nd) \rceil$ levels and let $\tilde{L} = \max(0, \lfloor \alpha \log_2(1/\epsilon) \rfloor)$ such that for $l \leq \tilde{L}$, $\epsilon_l \leq 1$ therefore $\max(\epsilon_l, \epsilon_l^2) = \epsilon_l$. Additionally, we define $x = u_{L+1}^1 \otimes \dots \otimes u_{L+1}^d$ being the finest level of approximation. Give ϵ, n, d , we will pick $L = C \lceil \log_2(nd) \rceil$ for a constant C and work under the assumption that $\tilde{L} \leq L$ in the main text – the case when $\tilde{L} > L$ allows us to draw the same conclusion and is deferred to the Appendix. Here the constant C is independent from all problem parameters.

The corollary below illustrates that with the choice of L above, together with the embedding property, we have control on the distortion of S acting on all tensors in \mathbb{R}^{n^d} .

Corollary 11 (Approximation at the L -th level) *For all $x \in \mathbb{R}^{n^d}$, with $L \asymp \lceil \log_2(nd) \rceil$ and the net $\{\tilde{T}_l^i\}_l$ constructed from an optimal admissible sequence as in (3) for each set T^i ,*

$$\|Sx\|_2^2 - \|x\|_2^2 \lesssim \max(2^{L/\alpha}\epsilon, 2^{2L/\alpha}\epsilon^2) \|x\|_2^2.$$

Proof Since $L \asymp \lceil \log_2(nd) \rceil$, which ensures $\text{dist}(u^i, \tilde{T}_L^i) \lesssim \frac{1}{d}$ using Lemma 7 for all $u^i \in T^i$. Derivation in Lemma 6 gives that for $\tilde{x} = u_L^1 \otimes \dots \otimes u_L^d \in \tilde{T}_L^1 \times \dots \times \tilde{T}_L^d$ with $\|\tilde{x}\|_2 = 1$,

$$\|S^\top S - I\|_{op} \leq \frac{1}{1 - 2d \cdot \text{dist}(u^i, \tilde{T}_L^i)} \cdot \max_{\tilde{x}} |\tilde{x}^\top (S^\top S - I) \tilde{x}| \lesssim \max(2^{L/\alpha}\epsilon, 2^{2L/\alpha}\epsilon^2) \cdot \|\tilde{x}\|_2^2,$$

where we used the multi-resolution embedding property Definition 10 for the last step. \blacksquare

Definition 10 takes center stage in the following lemma. The trade-off of η_l, ϵ_l and p_l specified below ensures that there's no occurrence of l in the final stated m . The $\{\epsilon_l\}$ plays the role of multi-level approximation close in spirit to what the γ -functional attempts to capture. The super-exponential factor of d^d also made an appearance in earlier work on embedding of finite set using Tensor-SRHT (Bamberger et al., 2021b).

Lemma 12 (Multi-resolution embedding property of row-wise tensored sketches) *With $m = \mathcal{O}(C^d(d^d + (1 + \eta)^d)/\epsilon^2)$, Tensor SRHT defined in Definition 2 satisfies Definition 10 for $\alpha = 2/d$. The same property also holds for Tensor Subgaussian defined in Definition 3 for $m = \mathcal{O}(C^d \sigma^{2d}(d^d + (1 + \eta)^d)/\epsilon^2)$ and $\alpha = 2/d$.*

Proof The requirement entails that the cardinality of the set $p_l \leq 5d \cdot (2^{2^l})^{d-1} \cdot (2^{2^l})^2$ for each level of distortion $1 \leq l \leq L$ with $\epsilon_l = 2^{ld/2}\epsilon$ and $\eta_l = l(\eta + 1) \geq 1$ (i.e., we only look at points belonging to neighboring scales). Union bounding over $L \asymp \lceil \log_2(nd) \rceil$ levels, using Lemma 4, we get with

$$m = \mathcal{O}\left(C^d \frac{1}{\epsilon_l^2} (\log^d(p_l) + \eta_l^d \vee \eta_l)\right)$$

which is $\mathcal{O}(C^d(d^d + (1 + \eta)^d)/\epsilon^2)$ hiding poly-logs that all events as required in Definition 10 holds with probability at least

$$1 - \sum_{l=1}^L \exp(-\eta_l) \geq 1 - \sum_{l=1}^{\infty} \exp(-l(\eta + 1)) \geq 1 - \exp(-\eta),$$

as claimed. For the Tensor-Subgaussian sketch, this becomes $\mathcal{O}(C^d \sigma^{2d}(d^d + (1 + \eta)^d)/\epsilon^2)$ using again Lemma 4. \blacksquare

4.3. Embedding of general sets with row-wise tensored sketches

Now we embark on our journey for the proof of our main result on row-wise Kronecker-structured sketches where Definition 10 and Lemma 12 will reveal their power.

Theorem 13 (Gordon-type Inequality for Tensor-SRHT and Tensor-Subgaussian) *Tensor-SRHT with $m = \mathcal{O}(C^d \epsilon^{-2} (\sum_{i=1}^d \gamma_{2/d}(T^i))^2 d^d)$ satisfies uniform concentration (2). The same guarantee carries over to Tensor-Subgaussian with $m = \mathcal{O}(C^d \sigma^{2d} \epsilon^{-2} (\sum_{i=1}^d \gamma_{2/d}(T^i))^2 d^d)$.*

This recovers the result of Oymak et al. (2018) for $d = 1$ (ignoring poly-logs). In light of the tail bound Theorem 2.1 in Bamberger et al. (2021a), it is also natural that $\gamma_{2/d}$ functional shows up.

Remark 14 *This concentration result can also be easily converted to be on $\|Sx\|_2 - 1$ using basic inequality $\frac{1}{3} \min\{|a^2 - 1|, \sqrt{|a^2 - 1|}\} \leq |a - 1| \leq \min\{|a^2 - 1|, \sqrt{|a^2 - 1|}\}$ for $a \geq 0$.*

Proof Throughout the section, we work with the net $\{\bar{T}_l^k\}_{l \in [\tilde{L}]}$ constructed from (3) for each $k \in [d]$. Using triangle inequality, forming a telescoping sum and let $\tilde{x}_l = u_l^1 \otimes \cdots \otimes u_l^d$ for each $l \in [\tilde{L}]$ where $\max(\epsilon_l, \epsilon_l^2) = \epsilon_l$, and on the event $\tilde{L} < L$,

$$\begin{aligned}
& \left| \|Sx\|_2^2 - \|x\|_2^2 \right| \\
& \leq \left| \sum_{l=1}^{\tilde{L}} \sum_{i=1}^m \left(\prod_{k=1}^d \langle v_i^k, u_l^k \rangle^2 - \prod_{k=1}^d \langle v_i^k, u_{l-1}^k \rangle^2 \right) - \left(\prod_{k=1}^d \|u_l^k\|_2^2 - \prod_{k=1}^d \|u_{l-1}^k\|_2^2 \right) \right| \\
& + \left| \|Sx\|_2^2 - \|S\tilde{x}_{\tilde{L}}\|_2^2 \right| + \left| \|x\|_2^2 - \|\tilde{x}_{\tilde{L}}\|_2^2 \right| + \left| \|S\tilde{x}_0\|_2^2 - \|\tilde{x}_0\|_2^2 \right| \\
& \leq \sum_{l=1}^{\tilde{L}} \sum_{k=1}^d \left| \sum_{i=1}^m \left(\langle v_i^k, u_l^k \rangle^2 - \langle v_i^k, u_{l-1}^k \rangle^2 \right) \times \prod_{s=1}^{k-1} \langle v_i^s, u_l^s \rangle^2 \times \prod_{s=k+1}^d \langle v_i^s, u_{l-1}^s \rangle^2 \right. \\
& \quad \left. - \left(\|u_l^k\|_2^2 - \|u_{l-1}^k\|_2^2 \right) \times \prod_{s=1}^{k-1} \|u_l^s\|_2^2 \times \prod_{s=k+1}^d \|u_{l-1}^s\|_2^2 \right| \\
& + \left| \|Sx\|_2^2 - \|S\tilde{x}_{\tilde{L}}\|_2^2 \right| + \left| \|x\|_2^2 - \|\tilde{x}_{\tilde{L}}\|_2^2 \right| + \left| \|S\tilde{x}_0\|_2^2 - \|\tilde{x}_0\|_2^2 \right| \\
& \leq \sum_{l=1}^{\tilde{L}} \sum_{k=1}^d \left| \sum_{i=1}^m \left(\langle v_i^k, u_l^k - u_{l-1}^k \rangle^2 + 2\langle v_i^k, u_l^k - u_{l-1}^k \rangle \langle v_i^k, u_{l-1}^k \rangle \right) \times \prod_{s=1}^{k-1} \langle v_i^s, u_l^s \rangle^2 \times \prod_{s=k+1}^d \langle v_i^s, u_{l-1}^s \rangle^2 \right. \\
& \quad \left. - \left(\|u_l^k - u_{l-1}^k\|_2^2 + 2\langle u_{l-1}^k, u_l^k - u_{l-1}^k \rangle \right) \times \prod_{s=1}^{k-1} \|u_l^s\|_2^2 \times \prod_{s=k+1}^d \|u_{l-1}^s\|_2^2 \right| \\
& + \left| \|Sx\|_2^2 - \|S\tilde{x}_{\tilde{L}}\|_2^2 \right| + \left| \|x\|_2^2 - \|\tilde{x}_{\tilde{L}}\|_2^2 \right| + \left| \|S\tilde{x}_0\|_2^2 - \|\tilde{x}_0\|_2^2 \right| \\
& \leq \sum_{k=1}^d \sum_{l=1}^{\tilde{L}} \left| \sum_{i=1}^m \langle v_i^k, u_l^k - u_{l-1}^k \rangle^2 \prod_{s=1}^{k-1} \langle v_i^s, u_l^s \rangle^2 \prod_{s=k+1}^d \langle v_i^s, u_{l-1}^s \rangle^2 - \|u_l^k - u_{l-1}^k\|_2^2 \prod_{s=1}^{k-1} \|u_l^s\|_2^2 \prod_{s=k+1}^d \|u_{l-1}^s\|_2^2 \right| \\
& + 2 \sum_{k=1}^d \sum_{l=1}^{\tilde{L}} \left| \sum_{i=1}^m \langle v_i^k, u_l^k - u_{l-1}^k \rangle \langle v_i^k, u_{l-1}^k \rangle \prod_{s=1}^{k-1} \langle v_i^s, u_l^s \rangle^2 \prod_{s=k+1}^d \langle v_i^s, u_{l-1}^s \rangle^2 \right. \\
& \quad \left. - \langle u_{l-1}^k, u_l^k - u_{l-1}^k \rangle \prod_{s=1}^{k-1} \|u_l^s\|_2^2 \prod_{s=k+1}^d \|u_{l-1}^s\|_2^2 \right|
\end{aligned}$$

$$+ \left| \|Sx\|_2^2 - \|S\tilde{x}_{\tilde{L}}\|_2^2 \right| + \left| \|x\|_2^2 - \|\tilde{x}_{\tilde{L}}\|_2^2 \right| + \left| \|S\tilde{x}_0\|_2^2 - \|\tilde{x}_0\|_2^2 \right|$$

and we attend to each of the 5 terms above in turn.

Term 1: Fixing a $k \in [d]$ and $l \in [\tilde{L}]$, invoking Definition 10, the first term can be written as for $S \in \mathbb{R}^{m \times n^d}$ (recall u_l^k is the closet point to $u^k \in T^k \subset \mathcal{S}^{n-1}$ in the l -th level covering of T^k therefore $\|u_l^k\|_2 = 1$)

$$\begin{aligned} & \left| \|S \cdot \text{vec}(u_l^1 \otimes \cdots \otimes (u_l^k - u_{l-1}^k) \otimes \cdots \otimes u_{l-1}^d)\|_2^2 - \|\text{vec}(u_l^1 \otimes \cdots \otimes (u_l^k - u_{l-1}^k) \otimes \cdots \otimes u_{l-1}^d)\|_2^2 \right| \\ & \leq \max(2^{ld/2}\epsilon, 2^{ld}\epsilon^2) \cdot \|u_l^1\|_2^2 \cdots \|u_l^k - u_{l-1}^k\|_2^2 \cdots \|u_{l-1}^d\|_2^2 \\ & \leq \max(2^{ld/2}\epsilon, 2^{ld}\epsilon^2) \cdot (\|u_l^k - u^k\|_2 + \|u^k - u_{l-1}^k\|_2)^2 \\ & \leq 2^{ld/2}\epsilon \cdot 4 \cdot \text{dist}(u^k, \bar{T}_{l-1}^k) \leq 2^{ld/2}\epsilon \cdot 8 \cdot \text{dist}(u^k, \bar{T}_{l-1}^k) \end{aligned}$$

Summing over l and d gives Term 1 is upper bounded by

$$8\sqrt{2}\epsilon \sum_{k=1}^d \sum_{l=0}^{\tilde{L}-1} 2^{ld/2} \text{dist}(u^k, \bar{T}_l^k) \leq 8\sqrt{2}\epsilon \cdot \sum_{k=1}^d \gamma_{2/d}(T^k).$$

Term 2: The second term is

$$\begin{aligned} & 2 \left| \text{vec}(u_l^1 \otimes \cdots \otimes u_{l-1}^k \otimes \cdots \otimes u_{l-1}^d) \cdot (S^\top S - I) \cdot \text{vec}(u_l^1 \otimes \cdots \otimes (u_l^k - u_{l-1}^k) \otimes \cdots \otimes u_{l-1}^d) \right| \\ & \leq \max(2^{ld/2}\epsilon, 2^{ld}\epsilon^2) \cdot 2 \cdot \|u_l^k - u_{l-1}^k\|_2 \leq 2^{ld/2}\epsilon \cdot 4 \cdot \text{dist}(u^k, \bar{T}_{l-1}^k), \end{aligned}$$

where we used that part 3 of Definition 10 implies that since S is linear on rank-1 tensors, therefore

$$\begin{aligned} & \left| \text{vec}(u_l^1 \otimes \cdots \otimes \frac{u_l^k - u_{l-1}^k}{\|u_l^k - u_{l-1}^k\|_2} \otimes \cdots \otimes u_{l-1}^d) \cdot (S^\top S - I) \cdot \text{vec}(u_l^1 \otimes \cdots \otimes u_{l-1}^k \otimes \cdots \otimes u_{l-1}^d) \right| \\ & \leq \frac{1}{4} \left\{ \left| \text{vec}(u_l^1 \otimes \cdots \otimes \left(\frac{u_l^k - u_{l-1}^k}{\|u_l^k - u_{l-1}^k\|_2} + u_{l-1}^k \right) \otimes \cdots \otimes u_{l-1}^d) \cdot (S^\top S - I) \right. \right. \\ & \quad \cdot \text{vec}(u_l^1 \otimes \cdots \otimes \left(\frac{u_l^k - u_{l-1}^k}{\|u_l^k - u_{l-1}^k\|_2} + u_{l-1}^k \right) \otimes \cdots \otimes u_{l-1}^d) \Big| \\ & \quad + \left| \text{vec}(u_l^1 \otimes \cdots \otimes \left(\frac{u_l^k - u_{l-1}^k}{\|u_l^k - u_{l-1}^k\|_2} - u_{l-1}^k \right) \otimes \cdots \otimes u_{l-1}^d) \cdot (S^\top S - I) \right. \\ & \quad \cdot \text{vec}(u_l^1 \otimes \cdots \otimes \left(\frac{u_l^k - u_{l-1}^k}{\|u_l^k - u_{l-1}^k\|_2} - u_{l-1}^k \right) \otimes \cdots \otimes u_{l-1}^d) \Big| \Big\} \\ & \leq \max(2^{ld/2}\epsilon, 2^{ld}\epsilon^2) \cdot \frac{1}{4} \cdot \left(2 + 2 \left(\frac{u_l^k - u_{l-1}^k}{\|u_l^k - u_{l-1}^k\|_2} \right)^\top u_{l-1}^k + 2 - 2 \left(\frac{u_l^k - u_{l-1}^k}{\|u_l^k - u_{l-1}^k\|_2} \right)^\top u_{l-1}^k \right) \\ & = \max(2^{ld/2}\epsilon, 2^{ld}\epsilon^2). \end{aligned}$$

Summing over l and d , the second term is upper bounded by

$$4\sqrt{2}\epsilon \sum_{k=1}^d \sum_{l=0}^{\tilde{L}-1} 2^{ld/2} \text{dist}(u^k, \bar{T}_l^k) \leq 4\sqrt{2}\epsilon \cdot \sum_{k=1}^d \gamma_{2/d}(T^k).$$

Term 3: For the third term, we begin by noting that since from Corollary 11, we have for all $x \in \mathbb{R}^{n^d}$

$$|\|Sx\|_2^2 - \|x\|_2^2| \lesssim \max(2^{Ld/2}\epsilon, 2^{Ld}\epsilon^2) \|x\|_2^2$$

this gives that $\|S\|_{op}^2 \lesssim 1 + \max(2^{Ld/2}\epsilon, 2^{Ld}\epsilon^2) \lesssim (1 + 2^{Ld/2}\epsilon)^2$. Now

$$\begin{aligned} |\|Sx\|_2^2 - \|S\tilde{x}_{\tilde{L}}\|_2^2| &\leq |\|Sx\|_2 - \|S\tilde{x}_{\tilde{L}}\|_2| \cdot [\|Sx\|_2 + \|S\tilde{x}_{\tilde{L}}\|_2] \\ &\leq |\|Sx\|_2 - \|S\tilde{x}_{\tilde{L}}\|_2|^2 + 2 \cdot |\|Sx\|_2 - \|S\tilde{x}_{\tilde{L}}\|_2| \cdot \|S\tilde{x}_{\tilde{L}}\|_2, \end{aligned}$$

therefore we are left to wrestle with

$$\begin{aligned} |\|Sx\|_2 - \|S\tilde{x}_{\tilde{L}}\|_2| &\leq \|S(x - \tilde{x}_L)\| + \|S(\tilde{x}_L - \tilde{x}_{\tilde{L}})\| \\ &\leq \|S\|_{op} \|x - \tilde{x}_L\|_2 + \sum_{l=\tilde{L}+1}^L \|S(\tilde{x}_l - \tilde{x}_{l-1})\|_2 \\ &\lesssim (1 + 2^{Ld/2}\epsilon) \cdot \sum_{k=1}^d \|u^1\| \cdots \|u^{k-1}\| \|u^k - u_L^k\| \|u_L^{k+1}\| \cdots \|u_L^d\| \\ &\quad + \sum_{l=\tilde{L}+1}^L \sum_{k=1}^d \|S \cdot \text{vec}(u_l^1 \otimes \cdots \otimes u_l^{k-1} \otimes (u_l^k - u_{l-1}^k) \otimes u_{l-1}^{k+1} \otimes \cdots \otimes u_{l-1}^d)\|_2 \\ &\lesssim (1 + 2^{Ld/2}\epsilon) \cdot \sum_{k=1}^d \text{dist}(u^k, \bar{T}_L^k) + \sum_{l=\tilde{L}+1}^L \sum_{k=1}^d (1 + 2^{ld/2}\epsilon) \cdot \|u_l^k - u_{l-1}^k\|_2 \\ &\lesssim \sum_{k=1}^d \left\{ 2 \cdot 2^{Ld/2}\epsilon \cdot \text{dist}(u^k, \bar{T}_L^k) + \sum_{l=\tilde{L}+1}^L 2 \cdot 2^{ld/2}\epsilon \cdot 2 \cdot \text{dist}(u^k, \bar{T}_{l-1}^k) \right\} \\ &\lesssim \sum_{k=1}^d \left\{ 2 \cdot 2^{Ld/2}\epsilon \cdot \text{dist}(u^k, \bar{T}_L^k) + 4 \cdot 2^{d/2} \cdot \sum_{l=\tilde{L}+1}^L 2^{(l-1)d/2}\epsilon \cdot \text{dist}(u^k, \bar{T}_{l-1}^k) \right\} \\ &\lesssim 4 \cdot 2^{d/2}\epsilon \cdot \sum_{k=1}^d \gamma_{2/d}(T^k) \end{aligned}$$

where we used Definition 10 and that $\epsilon_l \geq 1$ for $l \geq \tilde{L}$. It remains to bound $\|S\tilde{x}_{\tilde{L}}\|_2$, for this,

$$\|S\tilde{x}_{\tilde{L}}\|_2 \leq 2^{\tilde{L}d/2}\epsilon + 1 \leq 2$$

where we again used $1 + \max(\epsilon_{\tilde{L}}, \epsilon_{\tilde{L}}^2) \leq (1 + \epsilon_{\tilde{L}})^2$ and $\epsilon_{\tilde{L}} \leq 1$. Altogether this yields

$$|\|Sx\|_2^2 - \|S\tilde{x}_{\tilde{L}}\|_2^2| \lesssim 16 \cdot 2^d \epsilon^2 \cdot \left(\sum_{k=1}^d \gamma_{2/d}(T^k) \right)^2 + 16 \cdot 2^{d/2} \epsilon \cdot \sum_{k=1}^d \gamma_{2/d}(T^k).$$

Term 4: Analogous to the previous part, we have

$$|\|x\|_2^2 - \|\tilde{x}_{\tilde{L}}\|_2^2| \leq |\|x\|_2 - \|\tilde{x}_{\tilde{L}}\|_2| \cdot [\|x\|_2 + \|\tilde{x}_{\tilde{L}}\|_2]$$

$$\leq \left| \|x\|_2 - \|\tilde{x}_{\tilde{L}}\|_2 \right|^2 + 2 \cdot \left| \|x\|_2 - \|\tilde{x}_{\tilde{L}}\|_2 \right| \cdot \|\tilde{x}_{\tilde{L}}\|_2,$$

where

$$\begin{aligned} \left| \|x\|_2 - \|\tilde{x}_{\tilde{L}}\|_2 \right| &\leq \sum_{l=\tilde{L}}^L \|\tilde{x}_{l+1} - \tilde{x}_l\|_2 \leq \sum_{l=\tilde{L}}^L \sum_{k=1}^d \|u_{l+1}^1\| \cdots \|u_{l+1}^{k-1}\| \|u_{l+1}^k - u_l^k\| \|u_l^{k+1}\| \cdots \|u_l^d\| \\ &\leq \sum_{l=\tilde{L}}^L \sum_{k=1}^d 2 \cdot \text{dist}(u^k, \bar{T}_l^k) \leq \sum_{l=\tilde{L}}^L \sum_{k=1}^d 2 \cdot 2^{ld/2} \epsilon \cdot \text{dist}(u^k, \bar{T}_l^k) \\ &\leq 2\epsilon \sum_{k=1}^d \gamma_{2/d}(T^k) \end{aligned}$$

using $\epsilon_l \geq 1$ for $l \geq \tilde{L}$. Therefore since $\|\tilde{x}_{\tilde{L}}\|_2 = 1$,

$$\left| \|x\|_2^2 - \|\tilde{x}_{\tilde{L}}\|_2^2 \right| \leq 4\epsilon^2 \left(\sum_{k=1}^d \gamma_{2/d}(T^k) \right)^2 + 4\epsilon \sum_{k=1}^d \gamma_{2/d}(T^k).$$

Term 5: The last missing piece directly follows from part 2 of Definition 10:

$$\left| \|S\tilde{x}_0\|_2^2 - \|\tilde{x}_0\|_2^2 \right| \leq \max(\epsilon, \epsilon^2).$$

Now to finish the train of thought, we collect the results and use the definition of the γ_α -functional

$$2^{d/2} \sum_{k=1}^d \gamma_{2/d}(T^k) \geq 2^{d/2} \sum_{k=1}^d \gamma_2(T^k) \geq 2^{d/2} \sum_{k=1}^d \text{diam}(T^k)/2 = 2^{d/2} d > 1$$

since $T^k \subset \mathcal{S}^{n-1}$, to reach

$$\begin{aligned} \left| \|Sx\|_2^2 - \|x\|_2^2 \right| &\lesssim 2^d \epsilon^2 \cdot \left(\sum_{k=1}^d \gamma_{2/d}(T^k) \right)^2 + 2^{d/2} \epsilon \cdot \sum_{k=1}^d \gamma_{2/d}(T^k) + \max(\epsilon, \epsilon^2) \\ &\lesssim \max \left\{ 2^{d/2} \epsilon \cdot \sum_{k=1}^d \gamma_{2/d}(T^k), 2^d \epsilon^2 \cdot \left(\sum_{k=1}^d \gamma_{2/d}(T^k) \right)^2 \right\} + \max(\epsilon, \epsilon^2) \\ &\lesssim \max \left\{ 2^{d/2} \epsilon \cdot \sum_{k=1}^d \gamma_{2/d}(T^k), 2^d \epsilon^2 \cdot \left(\sum_{k=1}^d \gamma_{2/d}(T^k) \right)^2 \right\} \end{aligned}$$

hence a re-scaling $\epsilon \mapsto \frac{\epsilon}{2^{d/2} \sum_{k=1}^d \gamma_{2/d}(T^k)}$ will deliver the desired embedding property. Putting together with Lemma 12 we have the sample complexity

$$m = \mathcal{O} \left(C^d \frac{(\sum_{i=1}^d \gamma_{2/d}(T^i))^2 \cdot (d^d + (1 + \eta)^d)}{\epsilon^2} \right)$$

for Tensor-SRHT. The claim for Tensor-Subgaussian also follows modulo notation adjustments. \blacksquare

It is worth noting that the above argument will generalize to other random ensembles satisfying such multi-resolution embedding property (e.g., partial circulant matrix with random signs). To put things in context, we compare this bound with what we got from Lemma 6. Using Lemma 8,

$$\gamma_{2/d}(T^i) \leq (1 + K \cdot \log_2(b/\alpha) \cdot b/\alpha \cdot \log_2(a))^{\frac{d-1}{2}} \gamma_2(T^i),$$

which means substituting into Theorem 13, assuming for the sake of argument all the T^i are the same, focusing on the dependence on ϵ and γ_2 , this approach gives

$$m = \mathcal{O} \left(\left(\sum_{i=1}^d \gamma_{2/d}(T^i) \right)^2 \epsilon^{-2} \right) = \mathcal{O} \left((b \log_2(a))^{d-1} \cdot \gamma_2(T^i)^2 \epsilon^{-2} \right).$$

if ignoring poly-logs. Compared to Lemma 6 where we used a single-scale discretization $m = \mathcal{O}(\gamma_2(T^i)^{2d} \epsilon^{-2})$, Sudakov informs us

$$\sqrt{b \log(a)} \leq \sup_{\epsilon \in (0,1]} \epsilon \sqrt{b \log(a/\epsilon)} \lesssim \gamma_2(T^i).$$

Therefore in the case of low complexity set and the degree d of the tensor is large, the multi-resolution approach pays off.

Remark 15 *It is likely that one would be able to handle more general concentration of Lipschitz nonlinearities using modification of the same technique, but the expectation will quite possibly become hard to compute. By reckoning that $\mathbb{E}_{s \sim \mathcal{N}(0, I)}[(s^\top x)^2 (s^\top y)^2] = \|x\|_2^2 \cdot \|y\|_2^2 + 2(x^\top y)^2$, for $d = 2$ and orthogonal factors, one could also save randomness by potentially using a symmetric order-2 sketch and appeal to Mendelson (2016)’s result on product processes for near-isometric embedding of arbitrary sets, with dependence on geometric properties of individual sets T^1 and T^2 .*

5. Recursive Kronecker Embedding

The row-wise-tensored mapping from the previous section, despite its simplicity, gives exponential dependency on the degree d (and necessarily so, as a preview for Section 7), suggesting it is ideal for low-degree tensor. In this section, we analyze the “sketch and reduce” approach proposed by Ahle and Knudsen (2019), which composes degree-2 sketches from the previous section in the following way: we define the operation S acting on rank-1 e.g., degree-3 tensor as

$$S(x \otimes y \otimes z) := S^1(x \otimes S^2(y \otimes S^3 z)). \quad (6)$$

The prominent feature of the design is that at each layer, the Kronecker-structured sketch only acts on degree-2, reduced-dimensional tensor – something it excels at. It is an easy exercise that the matrix $S \in \mathbb{R}^{m \times n^d}$, when acting on rank-1 degree- d tensor, can be deemed as $S = Q^0$ for

$$Q^d = 1 \text{ and } Q^{k-1} = S^k(Q^k \otimes I_n) \in \mathbb{R}^{m \times n^{d-k+1}} \text{ for } k = d, \dots, 1,$$

where each $S^k \in \mathbb{R}^{m \times nm}$ for $k \in [d-1]$ and $S^d \in \mathbb{R}^{m \times n}$.

5.1. Building blocks for multi-resolution covering

The analysis follows the same template once we know how the JL moment property is preserved under matrix direct sum and multiplication, which was investigated in previous work. We have the following discrete JL property for the embedding matrix S introduced above.

Lemma 16 (Finite Set Embedding Property) *The recursive embedding (6) satisfies $|||Sx||_2^2 - 1| \leq \max(\epsilon, \epsilon^2)$ for all unit-norm, rank-1 tensors $x \in \mathbb{R}^{n^d}$ belonging to a finite set of cardinality p with probability at least $1 - e^{-\eta}$ for any $\eta > 0$ with $m = \mathcal{O}\left(\frac{d}{\epsilon^2}(\log^2(p) + \eta^2 \vee \eta)\right)$. Moreover, such operation can be conducted in time $\mathcal{O}(d(n \log n + m))$ when each S^i is constructed from an order-2 Tensor-SRHT sketch.*

Proof Invoking the JL moment condition for order-2 Kronecker embedding $S^t \in \mathbb{R}^{m \times nm}$, for Tensor-SRHT matrix constructed from $S_i^t = v_i^{(1)} \otimes v_i^{(2)}$ at each level $t \in [d]$, with

$$m = \mathcal{O}\left(\frac{1}{\epsilon^2} \log\left(\frac{1}{\delta}\right) \log^2\left(\frac{1}{\epsilon\delta}\right)\right)$$

the resulting compositional matrix $S \in \mathbb{R}^{m \times n^d}$ exhibits (1) $\mathbb{E}[|||Sx||_2^2] = 1$ for all $\|x\| = 1$; (2) $\mathbb{E}[(|||Sx||_2^2 - 1)^{\log(1/\delta)}] \leq (\frac{1}{\epsilon} \max(\epsilon/\sqrt{d}, \epsilon^2/d))^{\log(1/\delta)}$ using Theorem 1 of [Ahle and Knudsen \(2019\)](#). This implies via Markov's inequality, $\delta \in (0, 1)$,

$$\mathbb{P}(||||Sx||_2^2 - 1| \geq \max(\epsilon/\sqrt{d}, \epsilon^2/d)) \leq \delta$$

for any unit norm x . So for a set of cardinality p , taking a union bound we reach with probability at least $1 - e^{-\eta}$ for any $\eta > 0$, $|||Sx||_2^2 - 1| \leq \max(\epsilon, \epsilon^2)$ simultaneously for all p points on the unit sphere in the set provided (tilde hides poly-logs in $1/\epsilon$ and d)

$$m = \tilde{\mathcal{O}}\left(\frac{d}{\epsilon^2}(\log^2(p) + \eta^2 \vee \eta)\right).$$

This reduces the dependency on d from exponential to linear. ■

The ensuing lemma makes it clear that we should be grateful for the result stated above.

Lemma 17 (Multi-resolution embedding property of Recursive Tensor SRHT) *With $m = \mathcal{O}(d(d^2 + (1 + \eta)^2)/\epsilon^2)$, Recursive Tensor SRHT satisfies the (ϵ, η, α) -Multi-resolution Embedding Property in Definition 10 with $\alpha = 1$.*

Proof The requirement entails that $p_l \leq 5d \cdot (2^{2^l})^{d-1} \cdot (2^{2^l})^2$ for each level of distortion $1 \leq l \leq L$ with $\epsilon_l = 2^l \epsilon$ and $\eta_l = l(\eta + 1) \geq 1$ (i.e., we only look at points engaging in neighboring scales). Union bounding over $L \asymp \lceil \log_2(nd) \rceil$ levels, using Lemma 16, we get with

$$m = \tilde{\mathcal{O}}\left(\frac{d}{\epsilon_l^2}(\log^2(p_l) + \eta_l^2 \vee \eta_l)\right)$$

which is $\tilde{\mathcal{O}}(d(d^2 + (1 + \eta)^2)/\epsilon^2)$ that all events required in Definition 10 hold with probability at least $1 - \sum_{l=1}^L \exp(-\eta_l) \geq 1 - \sum_{l=1}^{\infty} \exp(-l(\eta + 1)) \geq 1 - \exp(-\eta)$, as promised. ■

5.2. Embedding of general set using recursive sketch

We will employ a slightly different decomposition of the chain for this construction and dedicate the section to prove the following theorem. At a high level, the observation is that the sketch, albeit taking complicated hierarchical form, happens to be linear when acting on rank-1 tensor. Therefore the strategy is to have all the terms in the chain we need to control in the rank-1 form that only involves difference in one factor, after which the multi-resolution embedding property can be repeatedly instantiated as before.

Theorem 18 (Gordon-type Inequality for Recursive Kronecker Embedding) *The Recursive Tensor SRHT with $m = \mathcal{O}(d\epsilon^{-2}(\sum_{i=1}^d \gamma_1(T^i))^2 \cdot (d^2 + (1 + \eta)^2))$ satisfies $|\|Sx\|_2^2 - 1| \leq \max(\epsilon, \epsilon^2)$ for all $x = u^1 \otimes \dots \otimes u^d \in T^1 \times \dots \times T^d$ with probability at least $1 - \exp(-\eta)$ for $d \geq 2$.*

Proof Let \odot denote elementwise product and $\bar{x}_l^t := S^t(u_l^t \otimes \dots \otimes S^d u_l^d) \in \mathbb{R}^m$ for each $l \in [L]$ and $t \in [d]$. Denote S_1^t and S_2^t the two $m \times n$ and $m \times m$ independent sketches at each level $t \in [d-1]$ and $S^d \in \mathbb{R}^{m \times n}$. Note that \bar{x}_l^t is a recursive sketch of degree $d - t + 1$ tensor with all factors i belonging to l -th level approximation in $\{\bar{T}_l^i\}$. Furthermore, let $\tilde{L} = \max(0, \lfloor \log_2(1/\epsilon) \rfloor)$ such that for $l \leq \tilde{L}$, $\epsilon_l \leq 1$. Forming a telescoping sum and keeping in mind we are working under $\tilde{L} < L$,

$$\begin{aligned}
& |\|Sx\|_2^2 - \|x\|_2^2| \\
& \leq \sum_{l=1}^{\tilde{L}} \sum_{i=1}^m \langle S_{1,i}^1, u_l^1 \rangle^2 \langle S_{2,i}^1, \bar{x}_l^2 \rangle^2 - \langle S_{1,i}^1, u_{l-1}^1 \rangle^2 \langle S_{2,i}^1, \bar{x}_{l-1}^2 \rangle^2 - \sum_{k=1}^d \left(\|u_l^k\|_2^2 - \|u_{l-1}^k\|_2^2 \right) \prod_{s=1}^{k-1} \|u_l^s\|_2^2 \prod_{s=k+1}^d \|u_{l-1}^s\|_2^2 \\
& + |\|Sx\|_2^2 - \|S\tilde{x}_{\tilde{L}}\|_2^2| + |\|x\|_2^2 - \|\tilde{x}_{\tilde{L}}\|_2^2| + |\|S\tilde{x}_0\|_2^2 - \|\tilde{x}_0\|_2^2| \\
& \leq \sum_{l=1}^{\tilde{L}} \left(\sum_{i=1}^m (\langle S_{1,i}^1, u_l^1 \rangle^2 - \langle S_{1,i}^1, u_{l-1}^1 \rangle^2) \cdot \langle S_{2,i}^1, \bar{x}_{l-1}^2 \rangle^2 - (\|u_l^1\|_2^2 - \|u_{l-1}^1\|_2^2) \times \prod_{s=2}^d \|u_{l-1}^s\|_2^2 \right) \quad (*) \\
& + \sum_{l=1}^{\tilde{L}} \left(\sum_{i=1}^m (\langle S_{2,i}^1, \bar{x}_l^2 \rangle^2 - \langle S_{2,i}^1, \bar{x}_{l-1}^2 \rangle^2) \langle S_{1,i}^1, u_l^1 \rangle^2 - \sum_{k=2}^d (\|u_l^k\|_2^2 - \|u_{l-1}^k\|_2^2) \times \prod_{s=1}^{k-1} \|u_l^s\|_2^2 \times \prod_{s=k+1}^d \|u_{l-1}^s\|_2^2 \right) \\
& + |\|Sx\|_2^2 - \|S\tilde{x}_{\tilde{L}}\|_2^2| + |\|x\|_2^2 - \|\tilde{x}_{\tilde{L}}\|_2^2| + |\|S\tilde{x}_0\|_2^2 - \|\tilde{x}_0\|_2^2|
\end{aligned}$$

Term 1 + 2: Expand the second line above using $\bar{x}_l^2 = \langle S_1^2, u_l^2 \rangle \odot \langle S_2^2, \bar{x}_l^3 \rangle$ as

$$\leq \sum_{l=1}^{\tilde{L}} \left(\sum_{i=1}^m \left(\langle S_{2,i}^1, \langle S_1^2, u_l^2 \rangle \odot \langle S_2^2, \bar{x}_l^3 \rangle \rangle^2 - \langle S_{2,i}^1, \langle S_1^2, u_{l-1}^2 \rangle \odot \langle S_2^2, \bar{x}_{l-1}^3 \rangle \rangle^2 \right) \langle S_{1,i}^1, u_l^1 \rangle^2 \right) \quad (7)$$

$$- \sum_{k=2}^d \left(\|u_l^k\|_2^2 - \|u_{l-1}^k\|_2^2 \right) \times \prod_{s=1}^{k-1} \|u_l^s\|_2^2 \times \prod_{s=k+1}^d \|u_{l-1}^s\|_2^2 \quad (8)$$

$$\leq \sum_{l=1}^{\tilde{L}} \sum_{i=1}^m \left(\langle S_{2,i}^1, \langle S_2^2, \bar{x}_{l-1}^3 \rangle \odot \langle S_1^2, u_l^2 \rangle \rangle^2 - \langle S_{2,i}^1, \langle S_2^2, \bar{x}_{l-1}^3 \rangle \odot \langle S_1^2, u_{l-1}^2 \rangle \rangle^2 \right) \langle S_{1,i}^1, u_l^1 \rangle^2 \quad (9)$$

$$- (\|u_l^2\|_2^2 - \|u_{l-1}^2\|_2^2) \times \|u_l^1\|_2^2 \times \prod_{s=3}^d \|u_{l-1}^s\|_2^2 \quad (10)$$

$$+ \sum_{l=1}^{\tilde{L}} \sum_{i=1}^m \left(\langle \langle S_1^2, u_l^2 \rangle \odot \langle S_2^2, \bar{x}_l^3 \rangle, S_{2,i}^1 \rangle^2 - \langle \langle S_1^2, u_l^2 \rangle \odot \langle S_2^2, \bar{x}_{l-1}^3 \rangle, S_{2,i}^1 \rangle^2 \right) \langle S_{1,i}^1, u_l^1 \rangle^2 \quad (11)$$

$$- \sum_{k=3}^d \left(\|u_l^k\|_2^2 - \|u_{l-1}^k\|_2^2 \right) \times \prod_{s=1}^{k-1} \|u_l^s\|_2^2 \times \prod_{s=k+1}^d \|u_{l-1}^s\|_2^2 \quad (12)$$

where we used the fact that for vectors a, b, c of same length, $\langle a, b \odot c \rangle = \langle a \odot c, b \rangle$. Notice that for a fixed l , (9) above is nothing but a recursive sketch on tensor

$$\|S(u_l^1 \otimes u_l^2 \otimes u_{l-1}^3 \otimes \cdots \otimes u_{l-1}^d)\|_2^2 - \|S(u_l^1 \otimes u_{l-1}^2 \otimes u_{l-1}^3 \otimes \cdots \otimes u_{l-1}^d)\|_2^2$$

therefore both (*) and (9)-(10) above involve bounding distortion of the form below for which we can invoke Definition 10 and follow similar steps as the previous section to reach

$$\begin{aligned} & \left| \|S(u_l^1 \otimes \cdots \otimes u_l^k \otimes \cdots \otimes u_{l-1}^d)\|_2^2 - \|S(u_l^1 \otimes \cdots \otimes u_{l-1}^k \otimes \cdots \otimes u_{l-1}^d)\|_2^2 \right. \\ & \quad \left. - \|\text{vec}(u_l^1 \otimes \cdots \otimes u_l^k \otimes \cdots \otimes u_{l-1}^d)\|_2^2 + \|\text{vec}(u_l^1 \otimes \cdots \otimes u_{l-1}^k \otimes \cdots \otimes u_{l-1}^d)\|_2^2 \right| \\ & \leq \left| \|S(u_l^1 \otimes \cdots \otimes u_l^k - u_{l-1}^k \otimes \cdots \otimes u_{l-1}^d)\|_2^2 - \|u_l^1 \otimes \cdots \otimes u_l^k - u_{l-1}^k \otimes \cdots \otimes u_{l-1}^d\|_2^2 \right| \\ & \quad + 2 \left| (u_l^1 \otimes \cdots \otimes u_l^k - u_{l-1}^k \otimes \cdots \otimes u_{l-1}^d)^\top (S^\top S - I)(u_l^1 \otimes \cdots \otimes u_{l-1}^k \otimes \cdots \otimes u_{l-1}^d) \right| \\ & \leq 2^l \epsilon \cdot 8 \cdot \text{dist}(u^k, \bar{T}_{l-1}^k) + 2^l \epsilon \cdot 4 \cdot \text{dist}(u^k, \bar{T}_{l-1}^k). \end{aligned}$$

Proceeding by unfolding (11)-(12) above in a similar fashion, and summing over $l \in [\tilde{L}]$ gives

$$12\sqrt{2}\epsilon \sum_{k=1}^d \sum_{l=0}^{\tilde{L}-1} 2^l \text{dist}(u^k, \bar{T}_l^k) \leq 12\sqrt{2}\epsilon \cdot \sum_{k=1}^d \gamma_1(T^k).$$

The derivation for the rest terms mirrors that from the previous section so we will be terse.

Term 3: For the third term, we note that $\|Sx\|^2 \lesssim (1 + \max(2^L \epsilon, 2^{2L} \epsilon^2)) \|x\|^2 \lesssim (1 + 2^L \epsilon)^2 \|x\|^2$ for any tensor $x \in \mathbb{R}^{n^d}$. Now recall $\tilde{x}_{\tilde{L}} = \bar{x}_{\tilde{L}}^1$ in our notation,

$$\begin{aligned} & \left| \|Sx\|_2^2 - \|S\tilde{x}_{\tilde{L}}\|_2^2 \right| \leq \left| \|Sx\|_2 - \|S\tilde{x}_{\tilde{L}}\|_2 \right|^2 + 2 \cdot \left| \|Sx\|_2 - \|S\tilde{x}_{\tilde{L}}\|_2 \right| \cdot \|S\tilde{x}_{\tilde{L}}\|_2 \\ & \lesssim 64\epsilon^2 \cdot \left(\sum_{k=1}^d \gamma_1(T^k) \right)^2 + 32\epsilon \cdot \sum_{k=1}^d \gamma_1(T^k). \end{aligned}$$

Term 4: Analogous to the previous part, we have

$$\begin{aligned} & \left| \|x\|_2^2 - \|\tilde{x}_{\tilde{L}}\|_2^2 \right| \leq \left| \|x\|_2 - \|\tilde{x}_{\tilde{L}}\|_2 \right|^2 + 2 \cdot \left| \|x\|_2 - \|\tilde{x}_{\tilde{L}}\|_2 \right| \cdot \|\tilde{x}_{\tilde{L}}\|_2 \\ & \lesssim 4\epsilon^2 \cdot \left(\sum_{k=1}^d \gamma_1(T^k) \right)^2 + 4\epsilon \cdot \sum_{k=1}^d \gamma_1(T^k). \end{aligned}$$

Term 5: Directly invoking part 2 of Definition 10 gives

$$\left| \|S\tilde{x}_0\|_2^2 - \|\tilde{x}_0\|_2^2 \right| \leq \max(\epsilon, \epsilon^2).$$

The finishing touch is done by noting $\sum_{k=1}^d \gamma_1(T^k) \geq d \geq 1$, assembling the pieces,

$$\begin{aligned} ||Sx||_2^2 - \|x\|_2^2 &\lesssim \epsilon^2 \cdot \left(\sum_{k=1}^d \gamma_1(T^k) \right)^2 + \epsilon \cdot \sum_{k=1}^d \gamma_1(T^k) + \max(\epsilon, \epsilon^2) \\ &\lesssim \max \left\{ \epsilon \cdot \sum_{k=1}^d \gamma_1(T^k), \epsilon^2 \cdot \left(\sum_{k=1}^d \gamma_1(T^k) \right)^2 \right\} + \max(\epsilon, \epsilon^2) \end{aligned}$$

hence a change of variable $\epsilon \mapsto \frac{\epsilon}{\sum_{k=1}^d \gamma_1(T^k)}$ will make the stars align. Invoking Lemma 17 we end up with the sample complexity

$$m = \tilde{O} \left(d \frac{(\sum_{k=1}^d \gamma_1(T^k))^2 \cdot (d^2 + (1 + \eta)^2)}{\epsilon^2} \right)$$

for tensors with degree $d \geq 2$. ■

It is enlightening to compare with the previous embedding bounds, assuming again the covering number admits $N(T^i, sB_2^n) \leq (\frac{a}{s})^b$ for all $i \in [d]$,

$$\gamma_1(T^i) \leq C_1 \int_0^1 \log N(T^i, sB_2^n) ds \leq C_1 \int_0^1 b \log(a/s) ds \leq C'_1 \cdot b \log(a)$$

which means using Theorem 18 that $m = \mathcal{O}(\frac{d^5 b^2 \log^2(a)}{\epsilon^2})$. This is favorable as the dependence on d has been reduced from exponential to polynomial. For example we can see that when T^i is composed of a set of p points on the unit sphere, $b = o(1)$ and $a = p$ we get $\log^2(p)/\epsilon^2$ as opposed to $\log^d(p)/\epsilon^2$ from the previous section when focusing on the scaling of p .

6. Applications

In this section, we deliberate on applications of our result in two settings, deploying one type of random embedding for each, where we see how these bounds can take advantage of the low complexity structure to move away from the (much larger) ambient dimension. We note that these applications crucially exploit the fact that the object in \mathbb{R}^{n^d} being acted upon has Kronecker structure – this departs from e.g., oblivious subspace embedding (OSE) result from Ahle and Knudsen (2019) where column span of *any* $n^d \times p$ matrix is preserved.

6.1. Signal Recovery

Inspired by compressed sensing, suppose we are given independent random (linear) 1-subgaussian measurements on Kronecker-structured rank-1 signal x of type

$$y_i = \langle S_i, x \rangle = \prod_{j=1}^d \langle v_i^j, u^j \rangle, \quad i \in [m] \tag{13}$$

for $x = u^1 \otimes \cdots \otimes u^d$, $u^i \in T^i \subset \mathcal{S}^{n-1}$, and would like to know when does performing

$$\min_{\{z^j\}_{j=1}^d \in \mathcal{S}^{n-1}} \sum_{j=1}^d f_j(z^j) \quad \text{subject to } S(z^1 \otimes \cdots \otimes z^d) = y, f_j(z^j) \leq R_j \quad \forall j \in [d] \tag{14}$$

uniquely reconstruct x , where f_j above is convex and $R_j := f_j(u^j)$ encodes the prior knowledge we have so that $\{u^j\}$ is feasible. In the case when such information is not available, the constraint can simply read as $\|z^j\|_2 \leq 1$, for example. Notice that the decision variable lives in a lower dimensional space (nd as opposed to n^d if we naively vectorize the signal) and one candidate could be alternating projected gradient descent over each factor. Computation aside on which algorithm to enlist for solving (14), the analysis below gives an information-theoretic lower bound on the sample complexity for successful recovery. The following quantities facilitate the analysis.

Definition 19 (Descent Cone and Restricted Singular Value) We use $\mathcal{D}(f_j, u^j)$ to denote the descent cone of a convex function f_j at point $u^j \in \mathbb{R}^n$, that is, $\mathcal{D}(f_j, u^j) := \cup_{\tau > 0} \{t \in \mathbb{R}^n : f_j(u^j + \tau t) \leq f_j(u^j)\}$. The correspondingly normalized descent cone is denoted as $\bar{\mathcal{D}}(f_j, u^j) := \mathcal{D}(f_j, u^j) \cap \mathcal{S}^{n-1}$. Let $\sigma_{\min}(S; \mathcal{C})$ be the minimum singular value of a matrix S restricted to set \mathcal{C} , i.e., $\sigma_{\min}(S; \mathcal{C}) := \min_{x \in \mathcal{C} \cap \mathcal{S}^{n-1}} \|Sx\|$. Furthermore, the descent cone of a proper convex function is always convex.

We take hints from (Chandrasekaran et al., 2012; Tropp, 2015) for the lemma below.

Lemma 20 (Recovery Guarantee) If $\|Sw\| \geq (1 - \epsilon)\|w\|$ for all $w = (u^1 + t^1) \cap \mathcal{S}^{n-1} \otimes \dots \otimes (u^d + t^d) \cap \mathcal{S}^{n-1}$ for which $t^j \in \mathcal{D}(f_j, u^j)$ where $\epsilon < 1$, the optimizer $\{z_*^j\}_{j=1}^d$ returned by (14) satisfies $z_*^1 \otimes \dots \otimes z_*^d = u^1 \otimes \dots \otimes u^d$ for the measurement model (13).

Proof Denote $t^j = z^j - u^j$ as the error from the true unknown, and let the optimizer of (14) be $z_*^j = t_*^j + u^j$ for all $j \in [d]$. The constraint entails that t_*^j verifies the following condition:

$$t_*^j \in \mathcal{D}(f_j, u^j) \forall j \in [d] \text{ and } S(u^1 + t_*^1 \otimes \dots \otimes u^d + t_*^d) = y, \|u^j + t_*^j\|_2 = 1.$$

Introduce the shorthand $\mathcal{W}^j := (u^j + \mathcal{D}(f_j, u^j)) \cap \mathcal{S}^{n-1}$. Using the definition of restricted singular value and the stated assumption,

$$\sigma_{\min}(S; \mathcal{W}^1 \times \dots \times \mathcal{W}^d) \geq 1 - \epsilon > 0.$$

Identifying $z_*^1 \otimes \dots \otimes z_*^d$ as belonging to the set $\mathcal{W}^1 \times \dots \times \mathcal{W}^d$, the restricted strong convexity condition allows us to finish the proof for the uniqueness claim. \blacksquare

Using Theorem 13 with Tensor-Subgaussian, for $\epsilon \in (0, 1)$, $\forall w \in \mathcal{W}^1 \times \dots \times \mathcal{W}^d$,

$$|\|Sw\| - 1| \leq \min\{|\|Sw\|_2^2 - 1|, |\|Sw\|_2^2 - 1|^{1/2}\} \leq \epsilon$$

if picking

$$m = \mathcal{O} \left(C^d \frac{(\sum_{i=1}^d \gamma_{2/d}(\mathcal{W}^i))^2 \cdot (d^d + (1 + \eta)^d)}{\epsilon^2} \right), \quad (15)$$

which means $\sigma_{\min}(S; \mathcal{W}^1 \times \dots \times \mathcal{W}^d) \geq 1 - \epsilon > 0$ as needed by Lemma 20. Since γ -functionals are translation-invariant, this is the same as $m = \mathcal{O}(C^d (\sum_{i=1}^d \gamma_{2/d}(\bar{\mathcal{D}}(f_i, u^i)))^2 \cdot (d^d + (1 + \eta)^d))$. Now thanks to the decoupling, it reduces to d descent cone vector Gaussian width type calculation.

We start with an example where each of the d factors is k -sparse, i.e., $T^i = \{u^i \in \mathbb{R}^n : \|u^i\|_0 \leq k, \|u^i\|_2 = 1\}$, it is classical that the normalized descent cone for ℓ_1 norm at k -sparse vector is $\bar{\mathcal{D}}(f_i, u^i) = \{s : \|s\|_1 \leq 2\sqrt{k}\|s\|_2, \|s\|_2 = 1\}$. Since $\text{conv}(kB_0^n \cap B_2^n) \subset \sqrt{k}B_1^n \cap B_2^n \subset$

$C \cdot \text{conv}(kB_0^n \cap B_2^n)$ for an absolute constant C , from known result one can deduce that the covering number and Gaussian width scale as

$$\begin{aligned} w(\bar{\mathcal{D}}(\|\cdot\|_1, u^j)) &\asymp \sqrt{k \log(en/k)} \\ \log(|\mathcal{N}^\Delta(\bar{\mathcal{D}}(\|\cdot\|_1, u^j))|) &\asymp k \log(en/\Delta k), \end{aligned}$$

consequently

$$\gamma_{2/d}^2(\mathcal{D}(\|\cdot\|_1, u^j)) \lesssim (kd \log(n/k) \log(kd))^{d-1} \cdot k \log(n/k).$$

This gives assuming $\log(n/k) \ll k$ (not worrying about the d^d factor, assuming d is small for this application) with $m = \mathcal{O}(k^d(1+\eta)^d)$, the recovery is successful with probability at least $1 - \exp(-\eta)$ when omitting poly-logs. It should be clarified that the minimizer of (14) may not be unique (as in the case with $f_i = \|\cdot\|_1$ up to sign ambiguity – which is the only possible one for rank-1 tensor), but this sample complexity suffices for recovering any of the equivalent representations of the rank-1 signal under consideration.

Another example comes from signals taking quantized values (e.g, binary vectors). In this case, we may choose the regularizer $f_j = \|\cdot\|_\infty$ when $u^j \in \{\pm 1\}^n / \sqrt{n}$. Since $\bar{\mathcal{D}}(\|\cdot\|_\infty, u^j) = \{s: s_i \cdot u_i^j \leq 0 \ \forall i \in [n], \|s\|_2 = 1\}$ for a binary vector u^j , and the cone can be confirmed to be self-dual, the calculation in (Chandrasekaran et al., 2012) suggests

$$w^2(\bar{\mathcal{D}}(\|\cdot\|_\infty, u^j)) \leq n/2.$$

Moreover the covering number is that of $1/2^n$ of the unit sphere, using $N(\mathcal{S}^{n-1}, sB_2^n) \leq (3/s)^n$,

$$\begin{aligned} \gamma_{2/d}(\bar{\mathcal{D}}(\|\cdot\|_\infty, u^j)) &\lesssim \int_0^1 (\log N(\bar{\mathcal{D}}(\|\cdot\|_\infty, u^j), sB_2^n))^{d/2} ds \\ &\lesssim C_{2/d} \int_0^1 (n \log(1/s))^{d/2} ds \leq C'_{2/d} \cdot n^{d/2}. \end{aligned}$$

Therefore with sample complexity (not concerned about the d^d factor) $m = \mathcal{O}(n^d(1+\eta)^d)$, one would be able to recover with high probability. In general, the work of (Chandrasekaran et al., 2012; Tropp, 2015) provide powerful recipe for bounding the Gaussian width of a descent cone based on duality and polar cones: for f_i a convex function, and $u^i \in \mathbb{R}^n$ a fixed point, $g \sim \mathcal{N}(0, I_n)$,

$$w^2(\mathcal{D}(f_i, u^i)) \leq \mathbb{E} \inf_{\tau \geq 0} \text{dist}^2(g, \tau \cdot \partial f_i(u^i)),$$

which cries out for more opportunities on application of (15). If one is interested in optimizing (14) using gradient information, the prescribed concentration in Theorem 13 will come in handy as well. The sampling matrix S , of course, can come from more structured random ensembles apart from subgaussian factors.

6.2. Optimization

Consider an optimization problem, where for given signal $x = u^1 \otimes \cdots \otimes u^d \in T^1 \times \cdots \times T^d$ taking Kronecker structure, we wish to solve for

$$\min_{z^i \in T^i \ \forall i \in [d]} \|u^1 \otimes \cdots \otimes u^d - z^1 \otimes \cdots \otimes z^d\|_F^2. \quad (16)$$

In general, one could also consider the denoising version where there is noise $x + e$, but we will focus on the noiseless case. With the hope of saving storage and speeding up, we apply sketching before solving a lower m -dimensional problem:

$$\min_{z^i \in T^i \forall i \in [d]} \|S(u^1 \otimes \cdots \otimes u^d) - S(z^1 \otimes \cdots \otimes z^d)\|_2^2 =: g(z^1, \dots, z^d). \quad (17)$$

Let S be the recursive sketch from Section 5 and denote the optimizer of (17) as $\{z_*^i\}$. It is not hard to see that since $g(z_*^1, \dots, z_*^d) \leq g(u^1, \dots, u^d) = 0$, we must have $S(z_*^1 \otimes \cdots \otimes z_*^d) = S(u^1 \otimes \cdots \otimes u^d)$, which means that S restricted to set $T^1 \times \cdots \times T^d$ must have the smallest singular value bounded away from 0 for us to uniquely identify the rank-1 signal. Note again this doesn't resolve the inherent ambiguity between the factors such as sign flips but the resulting sample complexity is sufficient to recover any such signal consistent with the measurement (i.e., the returned rank-1 solution obeys $z_*^1 \otimes \cdots \otimes z_*^d = u^1 \otimes \cdots \otimes u^d$ hence in x space it is unique).

For a concrete example, suppose we have a-priori knowledge that the factors are smooth ($\|Du^i\|_0 \leq k, \|u^i\|_2 = 1$), in which case picking $T^i = \{s^i : \|Ds^i\|_1 \leq 4\sqrt{k}, \|s^i\|_2 \leq 1\}$ for

$$D = \begin{bmatrix} -1 & 1 & 0 & \cdots & 0 & 0 \\ 0 & -1 & 1 & \cdots & 0 & 0 \\ 0 & 0 & -1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -1 & 1 \\ 0 & 0 & 0 & \cdots & 0 & -1 \end{bmatrix} \in \mathbb{R}^{n \times n}$$

the 1D total variation regularization becomes a natural choice. To carry out the program, it remains to bound the covering number of this set. For this, the work of (Cai and Xu, 2015) showed that

$$w_2(T^i) \asymp \gamma_2(T^i) \asymp (nk)^{1/4} \sqrt{\log(n)}.$$

A short calculation together with Theorem 18 allow us to reach that $m = \tilde{O}(d^5 nk)$ ensures the solution to (17) will identify the correct factors. Other examples could be signals taking block sparse structure where a $\|\cdot\|_{\ell_1/\ell_2}$ may be appropriate – the possibilities seem endless.

7. Tightness of Embedding Dimension

We contemplate on lower bounds for the embedding dimension and provide evidence for the row-wise-tensored sketch considered in Section 4 in this section.

In the case of finite set, Ahle and Knudsen (2019) used the key ingredient of tight moment bound from Latała (1997) which states for mean-0 i.i.d random variables where $\|X_i\|_p \asymp p^\alpha$, it holds that $\|\sum_{i=1}^n X_i\|_p \asymp \max\{2^\alpha \sqrt{pn}, (n/p)^{1/p} p^\alpha\}$ for all $2 \leq p \leq 2n$ – this can be turned into tail bounds. With minor massaging, one can extract from their result that for Tensor-Rademacher, the embedding dimension has to scale as $m \gtrsim (\log p)^d$ for simultaneously preserving the norms of p^d points. Close examination of their proof in fact reveals that the only critical assumptions responsible for such scaling are (1) each factor is independent; and (2) has $\|\langle v_i^k, h \rangle\|_p \asymp \sqrt{p}$ for any $\|h\|_2 = 1$, therefore similar conclusion holds for e.g., independent Gaussian factors. In the case of Tensor-SRHT, Bamberger et al. (2021b) showed that one needs at least $m \gtrsim (\log p)^d$ as well. Compared with our Theorem 13, this is tight, since we will have each factor belonging to a

set of cardinality p , therefore $\gamma_2(T^i)^2 = \log(p)$, $a = p$, $b = o(1)$, manifesting the inevitability of exponential dependence on d for this sketch.

On the occasion of unit sphere ($T^i = \mathcal{S}^{n-1}$), consider the case when each $\{v_i^k\}_{i \in [m], k \in [d]}$ is independent random vector uniform on the sphere of radius \sqrt{n} . This closely resembles an n -dimensional standard Gaussian in high dimension ($\sigma = 1$). Now let every $u^k = v_1^k / \sqrt{n} \in \mathcal{S}^{n-1}$ for $k \in [d]$. Since random vectors on unit sphere are almost orthogonal to each other (i.e., $\langle v_i^k, u^k \rangle = o(1)$ for $i \neq 1$),

$$\frac{1}{m} \sum_{i=1}^m \prod_{k=1}^d \langle v_i^k, u^k \rangle^2 \approx \frac{1}{m} \left(\frac{n^2}{n} \right)^d.$$

Therefore for this particular example, for the quantity to be $o(1)$, we need $m \gtrsim n^d$. Putting side-by-side with our Theorem 13, the sample complexity $m = \mathcal{O}(n^d)$ is sharp as $\gamma_2(\mathcal{S}^{n-1})^2 = n$, $b = n$, $a = o(1)$ in this case.

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Appendix A. Embedding Distortion when $\tilde{L} > L$

We will only use the Multi-resolution Embedding Property Definition 10 in the argument below, making it valid extension for both Theorem 13 and Theorem 18. We decompose:

$$\begin{aligned} \left| \|Sx\|_2^2 - \|x\|_2^2 \right| &\leq \sum_{l=1}^L \left| \|S\tilde{x}_l\|_2^2 - \|\tilde{x}_l\|_2^2 \right| - \left| \|S\tilde{x}_{l-1}\|_2^2 - \|\tilde{x}_{l-1}\|_2^2 \right| \\ &+ \left| \|Sx\|_2^2 - \|x\|_2^2 \right| - \left| \|S\tilde{x}_L\|_2^2 - \|\tilde{x}_L\|_2^2 \right| + \left| \|S\tilde{x}_0\|_2^2 - \|\tilde{x}_0\|_2^2 \right|. \end{aligned}$$

The proofs in the main text have already taught us that the first term is $\lesssim \epsilon \cdot \sum_{k=1}^d \gamma_\alpha(T^k)$ by simply recalling that Definition 10 holds up until level L and since $L < \tilde{L}$, all the distortion take the first term ϵ_l instead of ϵ_l^2 for $l \in [L]$. The last term is also easily bounded by $\max(\epsilon, \epsilon^2)$ as before. This

leaves us with the middle two terms. For this, note that both x and \tilde{x}_L are rank-1 tensors, the inner product $x^\top \tilde{x}_L$ denotes $\prod_{k=1}^d \langle u^k, u_L^k \rangle$ here,

$$\begin{aligned} & \left| \|Sx\|_2^2 - \|x\|_2^2 \right| - \left| \|S\tilde{x}_L\|_2^2 - \|\tilde{x}_L\|_2^2 \right| \leq |(\|Sx\|_2^2 - \|x\|_2^2) - (\|S\tilde{x}_L\|_2^2 - \|\tilde{x}_L\|_2^2)| \\ & \leq \|Sx - S\tilde{x}_L\|_2^2 - \|x - \tilde{x}_L\|_2^2 + 2|(Sx - S\tilde{x}_L)^\top S\tilde{x}_L - (x^\top \tilde{x}_L - \tilde{x}_L^\top \tilde{x}_L)|. \quad (*) \end{aligned}$$

We only sketch the calculation and omit the details below as it is largely similar to earlier ones. Using polarization identity for the second term and telescoping over the degree, it amounts to looking at the distortion of S acting on $\cdots \otimes u^k - u_L^k \otimes \cdots$, $\cdots \otimes \frac{u^k - u_L^k}{\|u^k - u_L^k\|_2} + u_L^k \otimes \cdots$ and $\cdots \otimes \frac{u^k - u_L^k}{\|u^k - u_L^k\|_2} - u_L^k \otimes \cdots$, for which we can simply delegate Corollary 11 at level L with the first term in the max for the job (since $L < \tilde{L}$). After some simplification, one would reach that $(*) \lesssim \epsilon \cdot \sum_{k=1}^d 2^{L/\alpha} \text{dist}(u^k, \tilde{T}_L^k) \lesssim \epsilon \cdot \sum_{k=1}^d \gamma_\alpha(T^k)$. Merging with other pieces,

$$\left| \|Sx\|_2^2 - \|x\|_2^2 \right| \lesssim \epsilon \cdot \sum_{k=1}^d \gamma_\alpha(T^k) + \max(\epsilon, \epsilon^2),$$

from which it should become evident that the same distortion conclusion holds in this case as well.