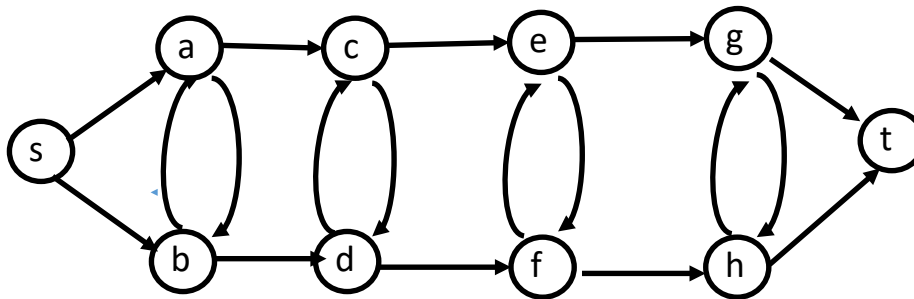


(1) **Finding minimum cut closest to t** Consider a maximum flow problem with directed graph $G = (V, E)$ with m edges and $n < m$ nodes, a source $s \in V$, a sink $t \in V$ and integer capacities $c_e \geq 0$ on each edge. We note that some graphs have many minimum capacity (s, t) -cuts. For example, in the graph below, if all edge capacities are $c_e = 1$, this graph has lots of minimum capacity cuts: any of $\{s\}$, $\{s, a, b\}$, $\{s, a, b, c, d\}$, etc. are all s -sides of minimum capacity cuts (cuts of capacity 2).



Assume that you are given a maximum value flow f that was already computed. Give an $O(m)$ time algorithm that finds a minimum capacity (s, t) -cut, (A, B) with $s \in A$ and $t \in B$, with as many nodes in A as possible. In the example above, this would be the cut $A = \{s, a, b, c, d, e, f, g, h\}$ and $B = \{t\}$.

(2) Scheduling Interviews

You are scheduling initial phone interviews for n job candidates that have applied to different jobs at the same company (each candidate has applied to just one job). The company has $k \leq n$ recruiters, and each recruiter is qualified to interview candidates only for some of the jobs. Each candidate needs to be assigned to a recruiter to be interviewed.

Candidates will be labeled $0, 1, \dots, n-1$, and recruiters will be labeled $n, n+1, \dots, n+k-1$. We will let `neighbors` hold the adjacency lists of the bipartite graph representing compatible candidate-recruiter pairs. That is, for each candidate i , `neighbors[i]` holds the recruiters that they can be interviewed by. For each recruiter j , `neighbors[j]` holds the candidates that recruiter j can interview. You also want to make sure that recruiters are not overloaded: so, we have an array `recruiter_capacities` where `recruiter_capacities[j]` is the maximum number of interviews that recruiter j can do (note that because of our indexing scheme, entries 0 through $n-1$ of this array are empty).

Someone has already tried to find an assignment of candidates to interviewers, but they are having trouble. They have an array `preliminary_assignment` that assigns each candidate i to recruiter `preliminary_assignment[i]` (without overloading any recruiter). Unfortunately, `preliminary_assignment[n-1]` is blank, and they are having trouble filling this last entry.

You must code an efficient algorithm that has the following behavior:

- If there exists a valid assignment that assigns all job candidates to recruiters, output it. Note that **there may be more than one such valid assignment**. We will accept any, as long as it is assigns all job candidates to recruiters in a valid way (i.e., no recruiter is overbooked).
- If no such assignment exists, you plan to ask one of the recruiters j to increase their capacity `recruiter_capacities[j]`. Output the list of recruiters j such that if their capacity is increased by 1 (while the other capacities remain the same), then a solution will exist.

Your algorithm must run in $O(m)$ time, where $m = \sum_{i=0}^{n-1} |\text{neighbors}[i]|$ is the number of edges in the graph. Solutions that take longer (e.g., $O(nk)$) will only get partial credit.

We illustrate the problem with the following **example**:

- Suppose we have $n = 3$ candidates, $k = 2$ recruiters, candidate neighbors `neighbors[0] = (3, 4)`, `neighbors[1] = (3)`, and `neighbors[2] = (3)` (the rest of the array can be inferred from these entries), and recruiter capacities `recruiter_capacities[3] = 2`, `recruiter_capacities[4] = 1`. If we are given `preliminary_assignment = (3, 3, ·)`, then a fully satisfying assignment does exist: it is `valid_assignment = (4, 3, 3)`.
- For the (otherwise) same input, if `recruiter_capacities[3] = 1`, `recruiter_capacities[4] = 2`, and `preliminary_assignment = (4, 3, ·)`, then no fully satisfying assignment exists, and the only way to create one is to increase `recruiter_capacities[3]`.