

MACHINE LEARNING.

Assignment 3.

Due: November 10, 2017.

1. [20 points] **A midterm preparation question**

For each of the learning problems outlined below, specify what is the best learning algorithm to use and why. Note that you should give *one* algorithm for each problem, even if there are several correct answers.

- (a) You have about 1000 training examples in a 6-dimensional continuous feature space. You only expect to be asked to classify 100 test examples.
- (b) You are going to develop a classifier to recommend which children should be assigned to special education classes in kindergarten. The classifier has to be justified to the board of education before it is implemented.
- (c) You are working for a huge retailing company. You are trying to predict whether customer X will like a particular item, as a function of the input which is a vector of 1 million bits specifying whether each of the other customers liked the item. You will train a classifier on a very large data set of items, where the inputs are everyone else preferences for that item, and the output is customer X 's preference for that item. The classifier will have to be updated frequently and efficiently as new data comes in.
- (d) You are working for an oil company which is trying to decide where to drill. You have 40 attributes, both discrete and continuous, that describe a plot of land. Some of these attributes are noisy. For previous sites, you know whether they contained oil or not, but you only have data about 50 such sites.

2. [20 points] **Properties of entropy**

- (a) Define joint probability mass function for random variables X, Y as follows

$$p(0, 0) = 1/3, p(0, 1) = 1/3, p(1, 0) = 0, p(1, 1) = 1/3.$$

Evaluate the following quantities

- i. $H[x]$ (entropy)
 - ii. $H[y]$
 - iii. $H[y|x]$ (conditional entropy)
 - iv. $H[x|y]$
 - v. $H[x, y]$
 - vi. $I[x, y]$ (mutual information).
- (b) Prove that maximum entropy of a discrete probability distribution is achieved for a uniform distribution.

- (c) Prove that maximum entropy of a continuous distribution with a given mean and variance is achieved for Gaussian distribution.
- (d) Prove rigorously using information gain that test T1 wins (see Lecture 4, slide 90).

3. [25 points] **Kernels**

In this problem, we consider constructing new kernels by combining existing kernels. Recall that for some function $K(\mathbf{x}, \mathbf{z})$ to be a kernel, we need to be able to write it as a dot product of vectors from some high-dimensional feature space:

$$K(x, z) = \phi(\mathbf{x})^T \phi(\mathbf{z})$$

Mercer's theorem gives a necessary and sufficient condition for a function K to be a kernel: its corresponding kernel matrix has to be symmetric and positive semi-definite.

Suppose that $K_1(\mathbf{x}, \mathbf{z})$ and $K_2(\mathbf{x}, \mathbf{z})$ are kernels over $\mathfrak{R}^n \times \mathfrak{R}^n$. For each of the cases below, state whether K is also a kernel. If it is, prove it. If it is not, give a counterexample. You can use either Mercer's theorem, or the definition of a kernel as needed

- (a) $K(\mathbf{x}, \mathbf{z}) = aK_1(\mathbf{x}, \mathbf{z}) + bK_2(\mathbf{x}, \mathbf{z})$, where $a, b > 0$ are real numbers
- (b) $K(\mathbf{x}, \mathbf{z}) = aK_1(\mathbf{x}, \mathbf{z}) - bK_2(\mathbf{x}, \mathbf{z})$, where $a, b > 0$ are real numbers
- (c) $K(\mathbf{x}, \mathbf{z}) = K_1(\mathbf{x}, \mathbf{z})K_2(\mathbf{x}, \mathbf{z})$
- (d) $K(\mathbf{x}, \mathbf{z}) = f(\mathbf{x})f(\mathbf{z})$ where $f : \mathfrak{R}^n \rightarrow \mathfrak{R}$ is a real-valued function
- (e) $K(\mathbf{x}, \mathbf{z}) = p(\mathbf{x})p(\mathbf{z})$ where p is a probability density function.

4. [5 points] **Nearest neighbor vs decision trees**

Consider a classification problem with instances consisting of two real-valued attributes. Do the decision boundaries that are possible for 1-nearest neighbor classification rule and decision trees coincide, or are they different? Justify your answer.

5. [10 marks] It is easy to see that the nearest-neighbor error rate P can equal the Bayes rate P^* . if $P^* = 0$ (the best possibility) or if $P^* = (c-1)/c$ (the worst possibility). One might ask whether or not there are problems for which $P = P^*$ when P^* is between these extremes.

- (a) Show that the Bayes rate for the one-dimensional case where $P(\omega_i) = 1/c$ and

$$p(x|\omega_i) = \begin{cases} 1 & 0 \leq x \leq \frac{cr}{c-1} \\ 1 & i \leq x \leq i+1 - \frac{cr}{c-1} \\ 0 & \text{elsewhere} \end{cases}$$

is $P^* = r$, where $P^* = 1 - \int \max_{1 \leq i \leq c} P(\omega_i|x)p(x)dx$
(see Duda, Hart, Stork, *Pattern Classification*, Wiley, 2000, p. 68, ex. 12).

- (b) Show that for this case that the nearest-neighbor rate is $P = P^*$.

Hint: Use the formula for the asymptotic error rate of the 1-nearest-neighbor rule

$$L_{NN} = \int \left[1 - \sum_{i=1}^c P^2(\omega_i|x) \right] p(x) dx.$$

6. [25 points] **Implementation**

In this problem, you are asked to perform *one* of the implementation and data analysis tasks below (of your choosing). Either one is worth 25 points.

- (a) Implement Adaboost with decision stumps, and run it on the Wisconsin data set, using 10-fold cross-validation. Plot training and testing error curves as a function of the number of training rounds.
- (b) Implement k-nearest neighbor on the Wisconsin data set, using Euclidean distance. Perform cross-validation for different values of k and plot training and testing error curves as a function of k.