

# Qinjie Lin CONTACT

- ✓ ginjielin2018@u.northwestern.edu
- https://qinjielin-nu.github.io/
- linkedin google scholar

## **EDUCATION**

2020 - 2025

**Northwestern University** 

• PhD in Computer Science

2018 - 2020

**Northwestern University** 

- MS in Computer Science
- GPA: 3.87 / 4.0

2014 - 2018

South China University of Technology

- Bachelor in Computer Science
- GPA: 3.74 / 4.0, TOP 10%

## FOCUS & SKILLS

- Sequence Modeling
- · Reinforcement Learning
- Robot Planning
- python, c, c++, pytorch,
- ray, docker, kubernetes
- aws, slurm
- ros, gazebo

#### **WORK EXPERIENCE**

**Meta** 05/2024 - 08/2024

Machine Learning Engineer Intern

• RecGPT modelling at Ranking & Foundational AI

Meta 06/2023 - 10/2023

Al Research Scientist Intern

• Temporal Hierarchical Planning at Reality Lab

**Zebra Tech** 09/2021 - 12/2021

Machine Learning Engineer Intern

• Sequence Modeling for Reinforcement Learning

Inmotion Robotics

06/2018 - 07/2018

Robotics SLAM Intern

• Sequence Modeling for Reinforcement Learning

# **RESEARCH PUBLICATIONS**

#### **Robotics**

 DecisionPilot: A Grammar-aware Framework to Enhance LLM-based Embodied Decision Making
Q Lin, H Liu

- (ICLR 2020) Learning to Plan in High Dimensions via Neural Exploration-Exploitation Trees
  - B Chen, B Dai, Q Lin, G Ye, H Liu, L Song
- (ICRA 2020) Collision-free Navigation of Human-centered Robots via Markov Games

G Ye \*, Q Lin \*, T Juang, H Liu

- (ICRA 2024) DOS®: A Deployment Operating System for Robots G Ye, Q Lin, Z Luo, H Liu
- (ICRA 2023) EMS<sup>®</sup>: A Massive Computational Experiment Management System towards Data-driven Robotics Q Lin, G Ye, H Liu
- (CoRL 2021) RoboFlow: a Data-centric Workflow Management System for Developing Al-enhanced Robots
  Q Lin\*, G Ye\*, J Wang, H Liu

#### LLMs & Foundational Model

- Switch Trajectory Transformer with Distributional Value Approximation for Multi-Task Reinforcement Learning Q Lin, H Liu, B Sengupta
- AURORA: A Time Series Foundational Model for Astrophysics W Li, Q Lin, H Liu ...
- (CVPR 2025) Free-viewpoint Human Animation with Pose-correlated Reference Selection

F Hong, ZXu, H Liu, Q Lin, ...

 GenomeAl: Integrated Fine-Tuning, Inference, and Benchmarking for Genomic Foundation Models
W We, X Song, Q Lin, H Liu