Lab 5 Exercise - A little Linear Regression

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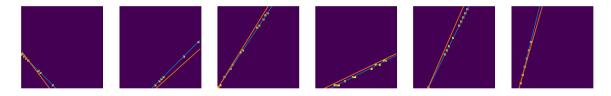
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This is the exercise that you need to work through **on your own** after completing the forth lab session. You'll need to write up your results/answers/findings and submit this to ECS handin as a PDF document along with the other lab exercises near the end of the module (1 pdf document per lab).

We expect that you will use no more than one side of A4 to cover your responses to *this* exercise. This exercise is worth 5% of your overall module grade.

1 An initial attempt

In the lab exercise you built and trained a couple of CNNs for image classification. Your now going to try something different and build some CNNs for image-to-vector regression task - in particular you're going to implement a network that takes an image of a scatter plot, and predicts the parameters of the line of best fit.



The following code is used to generate the datasets for this task (get it in a useable form here: https://gist.github.com/jonhare/73a59dcc5416729548a086a983e81f07):

```
import torch
from torchvision import transforms
from torch.utils.data import Dataset
class MyDataset(Dataset):
  def __init__(self, size=5000, dim=40, random_offset=0):
        super(MyDataset, self).__init__()
        self.size = size
        self.dim = dim
        self.random\_offset = random\_offset
  def __getitem__(self , index):
      if index >= len(self):
          raise IndexError('{}_index_out_of_range'.format(self.__class__._name__))
      rng_state = torch.get_rng_state()
      torch.manual_seed(index + self.random_offset)
      while True:
        img = torch.zeros(self.dim, self.dim)
        dx = torch.randint(-10,10,(1,),dtype=torch.float)
        dy = torch.randint(-10,10,(1,),dtype=torch.float)
        c = torch.randint(-20,20,(1,), dtype=torch.float)
        params = torch.cat((dy/dx, c))
        xy = torch.randint(0,img.shape[1], (20, 2), dtype=torch.float)
```

```
xy[:,1] = xy[:,0] * params[0] + params[1]
       xy.round_()
       xy = xy[xy[:,1] > 0]
       xy = xy[xy[:,1] < self.dim]
       xy = xy[xy[:,0] < self.dim]
        for i in range (xy.shape[0]):
          x, y = xy[i][0], self.dim - xy[i][1]
          img[int(y), int(x)]=1
        if img.sum() > 2:
          break
      torch.set_rng_state(rng_state)
      return img.unsqueeze(0), params
 \mathbf{def} __len__(self):
      return self.size
train_data = MyDataset()
val_data = MyDataset(size=500, random_offset=33333)
test_data = MyDataset(size=500, random_offset=99999)
```

1.1 A simple CNN baseline (2 marks)

Implement the following CNN model, and train it using Adam (default parameters) for 100 epochs (use a GPU and be prepared to wait 6 or 7 minutes!). State the loss function you're using. **Comment** on the performance of the model.

```
\label{eq:convolution2D} Convolution2D \,, \ channels=48, \ size=3x3 \,, \ stride=1, \ padding=1 \\ ReLU \\ Linear \,, \ 128 \ outputs \\ ReLU \\ Linear \,, \ 2 \ outputs \\
```

2 A second attempt

Clearly the CNN implemented in Section 1 has many parameters in its final hidden layers. One common way of reducing this is to use Global Max Pooling to flatten the feature maps into a vector (called AdaptiveMaxPool2d in PyTorch).

2.1 A simple CNN with global pooling (1 mark)

Implement the following CNN model, and train it using Adam (default parameters) for 100 epochs. **Comment** on the model performance.

```
Convolution2D, channels=48, size=3x3, stride=1, padding=1
ReLU
Convolution2D, channels=48, size=3x3, stride=1, padding=1
ReLU
Global Max Pool
Linear, 128 outputs
ReLU
Linear, 2 outputs
```

3 Something that actually works?

The two models so far likely have a few issues. We're now going to try and fix this.

3.1 Let's regress (2 marks)

Modify the model from Section 2 as follows:

- 1. Modify the number of input channels to the first convolutional layer to be 3 instead of 1
- 2. In the forward pass, before the first convolution, modify the input, x, using the following code:

```
 \begin{array}{l} idxx = torch.repeat\_interleave (\\ torch.arange (-20,20,\ dtype=torch.float).unsqueeze (0) \ / \ 40.0\,,\\ repeats=40,\ dim=0).to (x.device)\\ idxy = idxx.clone ().t ()\\ idx = torch.stack ([idxx,\ idxy]).unsqueeze (0)\\ idx = torch.repeat\_interleave (idx,\ repeats=x.shape [0],\ dim=0)\\ x = torch.cat ([x,\ idx],\ dim=1) \end{array}
```

Train the modified model using Adam (default parameters) for 100 epochs. **Comment** on the model performance. **Describe** the rationale for the modification that was made.