

# Analysis of Algorithms - CS 323

## Lecture #12 – May 18, 2016

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### Announcements:

1. Five more points on test two (bringing us up to +10 so far)
2. From Spring 2016, Announcements #56 - Contacting the Instructor Please email the instructor at [LT.CS320@Yahoo.com](mailto:LT.CS320@Yahoo.com)

### Homework:

1. Watch a simple proof for the halting problem <https://www.youtube.com/watch?v=92WHN-pAFCs>

### P = NP

Probably the biggest problem is  $P \stackrel{?}{=} NP$ . We can make an analogy to people who can compose quality music vs people who can appreciate quality music.

There is a huge number of possible permutations of musical notes to create a composition but not all of those permutations results in quality music. Many if not most people can tell whether a given permutation makes a good musical composition. We can compare this to verifying a solution to the travelling salesman problem. The verification of a solution is one level of complexity. However, writing a musical composition from the many possible permutations that results in a good musical composition is a different task.

#### Countably infinite

A set is countably infinite if its elements can be put in one-to-one correspondence with the set of natural numbers. In other words, one can count off all elements in the set in such a way that, even though the counting will take forever, you will get to any particular element in a finite amount of time.<sup>1</sup>

#### Uncountably infinite

A uncountable set<sup>2</sup> is an infinite set that contains too many elements to be countable.

#### How many programs are out there?

A program can be considered as a sequence of characters. A program can be arbitrarily long (from zero instructions to an arbitrarily long  $n$  instructions). This means that there are infinitely many programs out there.

We can do better though. Let us say that there is a finite pool of instructions. Therefore, for any given position in our program, there is a finite set of instructions available per position. Thus, we can say that the number of programs out there is countably infinite.

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<sup>1</sup> [http://mathinsight.org/definition/countably\\_infinite](http://mathinsight.org/definition/countably_infinite)

<sup>2</sup> [https://en.wikipedia.org/wiki/Uncountable\\_set](https://en.wikipedia.org/wiki/Uncountable_set)

However, we can prove that the number of functions possible is not countably infinite. The set of all possible functions is uncountably infinite. See Cantor's diagonal argument<sup>3</sup> which proves that there are infinite sets which cannot be put into one-to-one correspondence with the infinite set of natural numbers.

The proof shows there is no [total computable function](#) that decides whether an arbitrary program  $i$  halts on arbitrary input  $x$ ; that is, the following function  $h$  is not computable (Penrose 1990, p. 57–63):

$$h(i, x) = \begin{cases} 1 & \text{if program } i \text{ halts on input } x, \\ 0 & \text{otherwise.} \end{cases}$$

Here *program*  $i$  refers to the  $i$ th program in an [enumeration](#) of all the programs of a fixed [Turing-complete](#) model of computation.

$f(i,j)$		$i$					
		1	2	3	4	5	6
$j$	1	1	0	0	1	0	1
	2	0	0	0	1	0	0
	3	0	1	0	1	0	1
	4	1	0	0	1	0	0
	5	0	0	0	1	1	1
	6	1	1	0	0	1	0

$f(i,i)$	1	0	0	1	1	0
$g(i)$	U	0	0	U	U	0

Possible values for a total computable function  $f$  arranged in a 2D array. The orange cells are the diagonal. The values of  $f(i,i)$  and  $g(i)$  are shown at the bottom;  $U$  indicates that the function  $g$  is undefined for a particular input value.

The proof proceeds by directly establishing that every total computable function with two arguments differs from the required function  $h$ . To this end, given any total computable binary function  $f$ , the following [partial function](#)  $g$  is also computable by some program  $e$ :

$$g(i) = \begin{cases} 0 & \text{if } f(i, i) = 0, \\ \text{undefined} & \text{otherwise.} \end{cases}$$

<sup>3</sup> [https://en.wikipedia.org/wiki/Cantor%27s\\_diagonal\\_argument](https://en.wikipedia.org/wiki/Cantor%27s_diagonal_argument)

The verification that  $g$  is computable relies on the following constructs (or their equivalents):

- computable subprograms (the program that computes  $f$  is a subprogram in program  $e$ ),
- duplication of values (program  $e$  computes the inputs  $i, i$  for  $f$  from the input  $i$  for  $g$ ),
- conditional branching (program  $e$  selects between two results depending on the value it computes for  $f(i, i)$ ),
- not producing a defined result (for example, by looping forever),
- returning a value of 0.

The following [pseudocode](#) illustrates a straightforward way to compute  $g$ :

```
procedure compute_g(i):  
  if f(i, i) == 0 then  
    return 0  
  else  
    loop forever
```

Because  $g$  is partial computable, there must be a program  $e$  that computes  $g$ , by the assumption that the model of computation is Turing-complete. This program is one of all the programs on which the halting function  $h$  is defined. The next step of the proof shows that  $h(e, e)$  will not have the same value as  $f(e, e)$ .

It follows from the definition of  $g$  that exactly one of the following two cases must hold:

- $f(e, e) = 0$  and so  $g(e) = 0$ . In this case  $h(e, e) = 1$ , because program  $e$  halts on input  $e$ .
- $f(e, e) \neq 0$  and so  $g(e)$  is undefined. In this case  $h(e, e) = 0$ , because program  $e$  does not halt on input  $e$ .

In either case,  $f$  cannot be the same function as  $h$ . Because  $f$  was an *arbitrary* total computable function with two arguments, all such functions must differ from  $h$ .

This proof is analogous to [Cantor's diagonal argument](#). One may visualize a two-dimensional array with one column and one row for each natural number, as indicated in the table above. The value of  $f(i, j)$  is placed at column  $i$ , row  $j$ . Because  $f$  is assumed to be a total computable function, any element of the array can be calculated using  $f$ . The construction of the function  $g$  can be visualized using the main diagonal of this array. If the array has a 0 at position  $(i, i)$ , then  $g(i)$  is 0. Otherwise,  $g(i)$  is undefined. The contradiction comes from the fact that there is some column  $e$  of the array corresponding to  $g$  itself. Now assume  $f$  was the halting function  $h$ , if  $g(e)$  is defined (  $g(e) = 0$  in this case ),  $g(e)$  halts so  $f(e, e) = 1$ . But  $g(e) = 0$  only when  $f(e, e) = 0$ , contradicting  $f(e, e) = 1$ . Similarly, if  $g(e)$  is not defined, then halting function  $f(e, e) = 0$ , which leads to  $g(e) = 0$  under  $g$ 's construction. This contradicts the assumption that  $g(e)$  not being defined. In both cases contradiction arises. Therefore any arbitrary computable function  $f$  cannot be the halting function  $h$ .

five more points on test two to +10

Probably the biggest problem is  $P = NP$ ? watch the video.

The real life difference between  $P$  and  $NP$   
Proposed solution to travelling salesman problem (we can verify the solution in a deterministic polynomial time)

People who can appreciate music and people who compose quality music  
One level of complexity to read a work and say that's cool but to be able to come up with it is difference between  $P$  and  $NP$

Boring proof of Halting Problem  
Approximately in 1930s Alan Turing proved the halting problem is unsolvable.

COUNTABLE

UNCOUNTABLE  $\mathbb{R}$  diagonalization arg

Cantor's diagonalization argument to prove  $\mathbb{R}$  real numbers are irrational (binary)

$[0, 1)$  Real numbers including 0 and up to but not including 1.  $0, b_{1,1}, b_{1,2}, b_{1,3}, b_{1,4}, \dots$

$0, b_{2,1}, b_{2,2}, b_{2,3}, b_{2,4}, b_{2,5}, \dots$

$0, b_{3,1}, b_{3,2}, b_{3,3}, b_{3,4}, \dots$

$0, b_{4,1}, b_{4,2}, b_{4,3}, b_{4,4}, \dots$

$\overline{b_{i,j}}$  = inverse of  $b_{i,j}$   $0 \rightarrow 1$   $1 \rightarrow 0$

$r^* = 0, \overline{b_{1,1}}, \overline{b_{2,2}}, \overline{b_{3,3}}, \overline{b_{4,4}}, \dots$

is not on the list. so the premise is wrong  
we can find a number NOT on the list.

How many programs are out there?  
 There are infinitely many programs but  
 countably infinite in any given model.  
 How many functions are out there?

$$f(x) \rightarrow y \quad x \in \mathbb{N} \quad y \in \mathbb{N}$$

$x$	$f_1(x)$	$f_2(x)$	$f_3(x)$	$f_4(x)$	$f^*(x)$
0	$f_1(0)$	$f_2(0)$	$f_3(0)$	$f_4(0)$	$f_0(0) + 1$
1	$f_1(1)$	$f_2(1)$	$f_3(1)$	$f_4(1)$	$f_1(0) + 1$
2	$f_1(2)$	$f_2(2)$	$f_3(2)$	$f_4(2)$	$f_2(0)$
3	$f_1(3)$	$f_2(3)$	$f_3(3)$	$f_4(3)$	$f_i(i) + 1$
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$

$f^*$  is a new function where  $f_i(i) + 1$   
 Countably infinite programs  
 Uncountably infinite simple integer functions  
 Uncountably infinite functions can't be solved

We have a program  $(x)$  if  $\text{Halt}(x, x)$   
 then loop forever else halt

NP completeness making a problem look like  
 another (where have I seen this before?)

Median of five to find median of unsorted  
 Hamiltonian circuit  $\rightarrow$  Travelling Salesman

IS (independent set problem)  
 subgraph  $S$  such that no edges in  $V_s$  are  
 adjacent

Vertex Cover problem VC problem  
 Subgraph  $S$  that is complete such that  
 each  $v \in V_s$  is adjacent to another vertex  
 (These two problems complement)  
 Clique problem (Polynomial time reduction)  
 NP complete problems



One question from stuff from exam 1

One q from stuff from exam 2

Part 2 → part 1 is short answers

E.g. what is the worst case time complexity

If quick sort  $n^2$  average case  $n \log n$

Best case of bubble sort  $\log(n^2)$  insertion

sort best case is  $O(n)$  Time complexity of

binary search  $O(\log n)$  Minimum time to sort

$O(n \log n)$  Names of main algorithm why

$1+2+\dots+n = n(n+1)/2$   $r+r^2+r^3+\dots+\frac{r^{n+1}-1}{r-1}$

$f(n) = f(n/2) + f(n-2) \rightarrow f(n) - f(n-1) - f(n-2) \geq 0$

$x^2 - x - 1 = 0$  master theory don't have

to invoke it but  $T(n) = T(\frac{n}{2}) + f(n)$

$S(k) = S(k-1)$   $n = 2^k$  domain

transformation. what result helps

to explain the time complexity?

$T(n) = 2T(\frac{n}{2}) + f(n)$  Domain

transformation is where we rethink the

input. The range transformation is

where we change the output.

Exam 1 question will probably have to

do with sorting (so a linear time sort)

A decision problem will have a yes or no

answer. An optimization problem asks what

is the minimum/maximum we can do?

Dynamic programming → Floyd's

Dijkstra's, Prim's algorithm (keep adding one

more element to sets) will not ask dynamic

programming for triangulation. Big integer

multiplication. Bellman Ford SSSP that

handles negative  $W(V, E)$  time complexity

Knapsack problem is NP complete  $O(K \times K)$  where

$K$  is the upper bound capacity on knapsack

we incremented by 1, 2, finite precision vs

③

8 Bucket sort, Radix sort  $\leftarrow$  if I describe it then you should be able to say that's a Radix sort.

0-1 knapsack problem is NP complete.  
0-1 knapsack problem with integer capacity  $\Theta(nk)$  where  $k$  is capacity of knapsack.  
 $k$  could be much bigger than  $n$  so not really linear.  
fractional knapsack once you sort by non-increasing order (value per weight) it takes  $O(n)$  with greedy approach.

matrix multiplication algorithm Divide and Conquer Sort of like big integer multiplication in two dimensions ~~For~~  $n$  is number of rows number of columns

$$T(n) = 8 T\left(\frac{n}{2}\right) + \Theta(n^2)$$
$$T(n) = \Theta(n^3)$$

Using an algorithm  $T(n) = 7 T\left(\frac{n}{2}\right) + \Theta(n^2)$

Strauss's algorithm  $T(n) = \Theta(n^{\log_2 7})$

focus on the graphs

Chapter 17, there is another version of knapsack problem called knapsack problem

Also pg 511