#### The Growth Model In Continuous Time

Prof. Lutz Hendricks

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# **Topics**

- ▶ We study the standard growth model in continuous time.
- ► To solve it: Optimal Control
- ► To characterize it: phase diagrams

# Cantinua Tima va Diameta Tima

Continuous Time vs. Discrete Time

[Some of you will find the next several slides obvious.]

#### Continuous time

- So far, time was divided into discrete "periods."
- ▶ It is often more convenient to shrink the length of periods to 0.
- ▶ Difference equations then become differential equations.

#### Continuous time

#### Example: Law of motion for capital

▶ Discrete time:

$$K_{t+1} - K_t = I_t - \delta K_t \tag{1}$$

More generally:

$$K_{t+\Delta t} - K_t = [I_t - \delta K_t] \ \Delta t \tag{2}$$

► Continuous time  $(\Delta t \rightarrow 0)$ :

$$\lim_{\Delta t \to 0} \frac{K_{t+\Delta t} - K_t}{\Delta t} = \dot{K}_t = I_t - \delta K_t \tag{3}$$

Notation:  $\dot{K} = dK/dt$ .

#### Growth rates in continuous time

The growth rate of a variable is defined as

$$g(x) = \frac{\dot{x}}{x} = \frac{d\ln x}{dt} \tag{4}$$

Growth rate rules (easy to prove):

- 1. g(xy) = g(x) + g(y).
- 2. g(x/y) = g(x) g(y).
- 3.  $g(x^{\alpha}) = \alpha g(x)$ .
- 4.  $x(t) = e^{\gamma t} \Longrightarrow g(x) = \gamma$ .

# Differential equations

### Differential equations

Take a function of time:

$$x(t) = a + bt (5)$$

There is another way of describing this function:

► Take the derivative:

$$\dot{x}(t) = dx(t)/dt = b \tag{6}$$

- Fix x(0) = a.
- The two pieces of information (the derivative and x(0)) completely describe x(t).
- ▶ Only one function x(t) satisfies both pieces.
  - But note that infinitely many functions satisfy the derivative!

# Definition: Differential equation

▶ A differential equation (DE) is a function of the form

$$\dot{x}(t) = f(x(t), t) \tag{7}$$

- This is actually a "first-order" DE.
- ▶ **Higher order** DEs contain higher order derivatives of time.
  - ► E.g.: A second order DE

$$d^{2}x(t)/dt^{2} + dx(t)/dt = a + bt$$
 (8)

▶ Together with a boundary condition, the DE can be solved for x(t).

# Solving DEs

- ▶ The bad news: There is no algorithm for solving DEs.
- But one look up solutions in tables.
- ▶ It is also easy to **verify** a solution one may guess.

# Guess + Verify

#### Consider again

$$\dot{x}(t) = b \tag{9}$$

$$x(0) = a \tag{10}$$

#### Guess

$$x(t) = a + bt (11)$$

#### Verify:

- ► Take the time derivative and find that it matches  $\dot{x} = b$ .
- Verify that x(0) = a.

# Example: constant growth

$$\dot{x}(t) = b x(t) \tag{12}$$

$$x(0) = a \tag{13}$$

Guess:

$$x(t) = a e^{bt} (14)$$

Verify: Take the derivative

$$\dot{x}(t) = b \ a \ e^{bt} = b \ x(t) \tag{15}$$

$$x(0) = a e^0 = a (16)$$

# Boundary conditions

#### Boundary conditions can take many forms:

- x(1.7) = 5.
- x(T)-x(T-2)=5.
- etc.

# The Solow Model

#### The Solow Model - Structure

- Modify the discrete time growth model in two ways:
  - 1. Continuous time.
  - 2. Fixed saving rate.
- This is not an equilibrium model, but can be interpreted as one.

#### Model Elements

Demographics: households live forever;

$$L_t = e^{nt} \tag{17}$$

Preferences:

$$\int_{t=0}^{\infty} e^{-(\rho-n)t} u(c_t) dt \tag{18}$$

- Endowments:
  - at each moment, the household has 1 unit of work time
  - ▶ at t = 0 he has  $K_0$  goods

#### Model Elements

#### Technology:

$$F(K_t, L_t) = \dot{K}_t + \delta K_t + L_t c_t \tag{19}$$

F: constant returns to scale

#### Markets:

 competitive markets for goods (numeraire), labor rental, capital rental

#### **Firms**

The firm solves a static problem.

The same as in discrete time.

$$\max F(K,L) - wL - qK \tag{20}$$

**FOC** 

$$q_t = F_K \tag{21}$$

$$w_t = F_L \tag{22}$$

#### Firms: Intensive Form

Define  $k^F = K/L$  and

$$f(k^F) = F(K,L)/L = F(k^F,1)$$
 (23)

The first order conditions are then

$$q = f'(k^F) \tag{24}$$

and

$$w = f(k^F) - f'(k^F)k^F (25)$$

#### Households

Budget constraint

$$\dot{K}_t = w_t L_t + (q_t - \delta) K_t - L_t c_t$$

It is convenient to have everything per capita.

Define k = K/L.

Law of motion for k:

$$\dot{k}/k = \dot{K}/K - n$$
$$= w/k + (q - \delta) - c/k$$

Or

$$\dot{k}_t = w_t + (q_t - \delta - n)k_t - c_t \tag{26}$$

# Constant saving rate

- ► The modern way: Set up an optimization problem and derive the saving function.
- ► The Solow way: Assume that the saving rate is fixed:

$$c = (1-s)(w+qk)$$
 (27)

Therefore:

$$\dot{k} = s(w + qk) - (n + \delta)k \tag{28}$$

# Market Clearing

Capital rental:

$$k = k^F (29)$$

Goods market:

$$F(K_t, L_t) = C_t + \delta K_t + \dot{K}_t$$

or in per capita terms

$$\dot{k} = f(k) - (n+\delta)k - c \tag{30}$$

# Equilibrium

An equilibrium is a collection of functions (of time)

$$c_t, k_t, k_t^F, w_t, q_t$$

that satisfy

- 1. the firm's first order conditions (2)
- 2. the household's budget constraint and the behavioral equation

$$\dot{k} = s(w + qk) - (n + \delta)k$$

3. market clearing (2)

#### Law of Motion

▶ The entire model boils down to to one key equation:

$$\dot{k}_t = sf(k_t) - (n+\delta)k_t \tag{31}$$

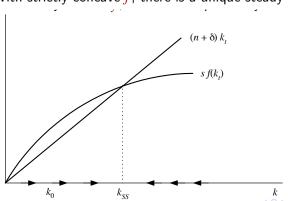
► This is simply the household's behavioral equation after applying f(k) = w + qk.

# Steady state

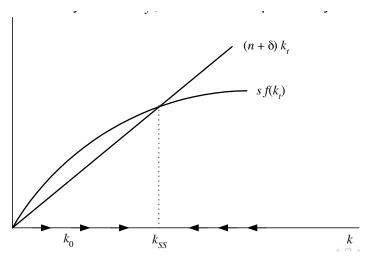
The steady state requires  $\dot{k} = 0$  or

$$sf(k) = (n+\delta)k \tag{32}$$

With strictly concave f, there is a unique steady state with k > 0.



# **Dynamics**



The steady state is *stable*.

Convergence is monotone.

# Adding Technical Change

- ► The model does not have sustained growth in per capita income.
- ► This requires technical change (A grows).
- Assume exogenous growth in A:

$$A(t) = A(0)e^{\gamma t} \tag{33}$$

# Adding Technical Change

► Assume that technical change takes the following form:

$$Y(t) = F(K(t), A(t)L(t))$$
(34)

- This type of technical change is called "labor-augmenting" or "Harrod-neutral."
- ► This is the *only* form of technical change that is consistent with *balanced growth*.

#### Definition

A balanced growth path is a path along which all growth rates are constant.

# How to analyze a growing model?

- Construct a stationary transformation.
- Divide each variable by its balanced growth factor:

$$\tilde{x}(t) = x(t)e^{-g_x t} \tag{35}$$

where  $g_x$  is the balanced growth rate of x.

- Or take ratios of variables that grow at the same rate.
- ▶ The economy in transformed variables  $(\tilde{x})$  has a steady state.

# How to find the balanced growth rates?

For equations that involve sums:

$$Y(t) = C(t) + I(t) + G(t)$$
 (36)

Constant growth (usually) requires that all summands grow at the same rate.

- ► For other equations: Try taking the growth rate of the whole equation.
- Example:

$$Y(t) = K(t)^{\alpha} \left[ A(t)L(t) \right]^{1-\alpha} \tag{37}$$

implies

$$g(Y) = \alpha g(K) + (1 - \alpha)[g(A) + n]$$
(38)

# Balanced growth path: Solow Model

Start from

$$\dot{K}(t) = sF(K(t), A(t)L(t)) - \delta K(t)$$
 (39)

$$g(K(t)) = sF\left(1, \frac{A(t)L(t)}{K(t)}\right) - \delta$$
 (40)

Constant growth requires that

$$\bar{k}(t) = \frac{K(t)}{A(t)L(t)} \tag{41}$$

be constant over time. Thus, on a balanced growth path:

$$g(K) = \gamma + n \tag{42}$$

# Balanced growth path

Production function:

$$\bar{y}(t) = \frac{Y(t)}{A(t)L(t)} = F(\bar{k}(t), 1) \tag{43}$$

must be constant on a balanced growth path.

▶ Thus: The model has a steady state in  $(\bar{k}, \bar{y})$ .

#### Law of motion

$$g(\bar{k}) = g(K) - \gamma - n$$

$$= sF\left(1, \frac{A(t)L(t)}{K(t)}\right) - \delta - \gamma - n$$

$$= sf(\bar{k})/\bar{k} - \delta - \gamma - n$$

Or

$$\dot{\bar{k}}(t) = sf(\bar{k}(t)) - (n + \delta + \gamma)\bar{k}(t)$$
(44)

Nothing changes, except the constant term in the law of motion.

# Reading

- Acemoglu (2009), ch. 2 covers the Solow model and stationary transformations of growing economies.
- Barro and Martin (1995), ch. 1
- Romer (2011), ch. 1
- ▶ Krusell (2014) ch. 2 discusses some insights that might be gained from the Solow model (and its limitations).

#### References I

Acemoglu, D. (2009): *Introduction to modern economic growth*, MIT Press.

Barro, R. and S.-i. Martin (1995): "X., 1995. Economic growth," Boston, MA.

Krusell, P. (2014): "Real Macroeconomic Theory," Unpublished.

Romer, D. (2011): Advanced macroeconomics, McGraw-Hill/Irwin.