

# Weighted Distinct Sampling: Cardinality Estimation for SPJ Queries

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# Select-Project-Join Queries

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- Relational Algebra

- $\pi_A(\sigma_\phi(R_1 \bowtie R_2 \bowtie \dots \bowtie R_m))$

- SQL

- `select (distinct) A`
  - `from R1, R2, ..., Rm`
  - `where Phi`

- Example: Find customers who placed an order after 2020-01-01

- `SELECT (DISTINCT) o_custkey FROM orders`  
`WHERE o_orderdate > 2020-01-01`

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- Relational Algebra

- $\pi_A(\sigma_\phi(R_1 \bowtie R_2 \bowtie \dots \bowtie R_m))$

- SQL

- `select (distinct) A`
  - `from R1, R2, ..., Rm`
  - `where Phi`

- Example: Find customers who placed an order after 2020-01-01

- And the order contains an item of price more than 100
  - `SELECT (DISTINCT) o_custkey FROM orders, lineitem`  
`WHERE o_orderdate > 2020-01-01 AND l_extendedprice > 100`

# Cardinality Estimation for S / P / J Queries

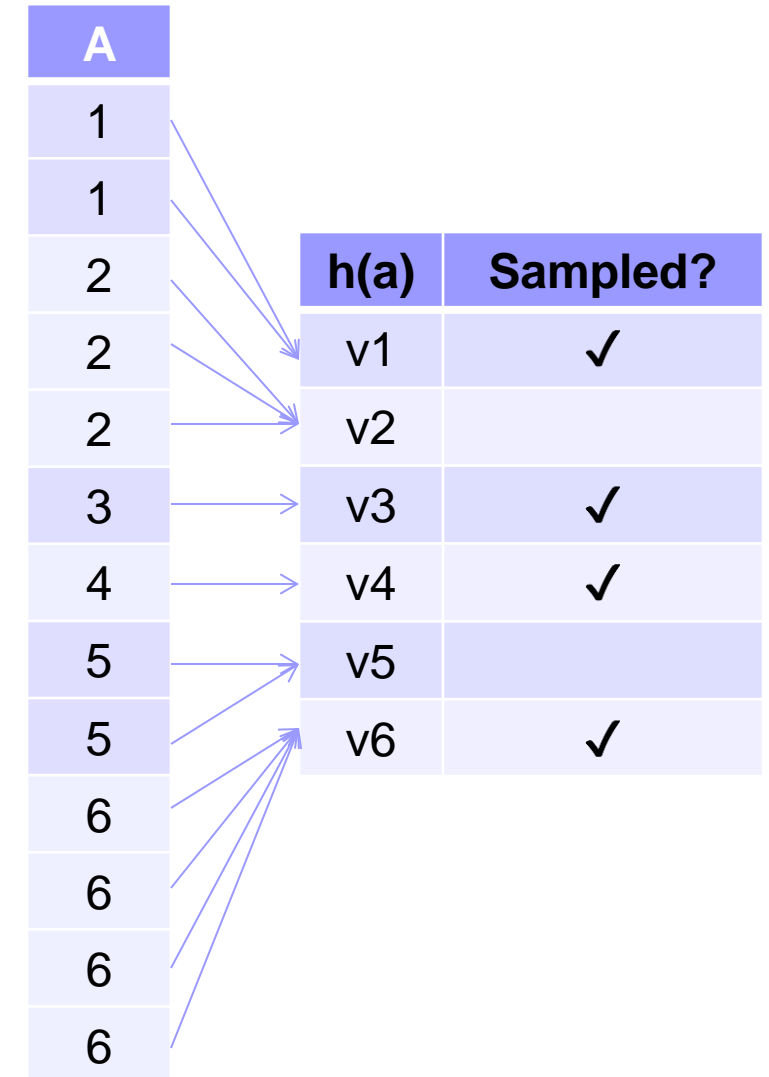
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- Selection ( $\sigma$ )
  - **Selectivity** estimation
  - Sampling, Assumptions (uniform, independent, ...), ...
- Projection ( $\pi$ )
  - If duplicates are not removed, cardinality is not affected (`select A from R`)
  - Otherwise, **distinct count** estimation (`select distinct A ... / select A, agg() ... group by A`)
  - Summary (FM, HyperLogLog, KMV, ...), Sampling (uniform, distinct, ...)
- Join ( $\bowtie$ ) / Selection + Join ( $\bowtie_{\theta}$ )
  - **Join size** estimation
  - Sketch (AMS, Count Sketch, ...), Sampling (Ripple Join, Wander Join, Two-Level Sampling, ...), ...
- What about Selection + Projection (+ Join)?

# Review: Distinct Sampling

## ■ Projection Only:

- Want to estimate  $D = |\pi_A R|$
- Sample each **distinct** value with probability  $p$  into set  $A_s$ 
  - Perform sampling on hash values
- $|A_s|/p$  is a good estimator for  $D$ 
  - Unbiased
  - Variance  $\frac{Dp(1-p)}{p^2} \approx \frac{D}{p}$
- Example:
  - Suppose the sampling rate  $p = 1/2$
  - Our sample is  $A_s = \{1,3,4,6\}$
  - Estimate  $\hat{D} = \frac{4}{1/2} = 8$  (Actual  $D = 6$ )



# Review: Distinct Sampling

## ■ Selection + Projection:

- Want to estimate  $D^\phi = |\pi_A \sigma_\phi R|$
- Augment each sample with  $\tau$  tuples as  $R_s$ 
  - Uniformly taken from all its tuples
- Use  $|\pi_A \sigma_\phi R_s|/p$  as estimator
- Example:
  - Still  $p = 1/2$  and  $A_s = \{1,3,4,6\}$
  - Set  $\tau = 2$ , so each  $a \in A_s$  is augmented by  $\leq 2$  tuples
  - Now our filter is  $\phi := (B < 10 * A)$
  - $\pi_A \sigma_\phi R = \{2,3,4,5,6\}$ , so  $D^\phi = 5$

A	B	sampled?	$\phi$
1	10	✓	
1	20	✓	
2	30		
2	20		
2	10		✓
3	10	✓	✓
4	20	✓	✓
5	60		
5	10		✓
6	80	✓	
6	20		✓
6	60	✓	
6	30		✓

# Review: Distinct Sampling

## ■ Selection + Projection:

- Want to estimate  $D^\phi = |\pi_A \sigma_\phi R|$
- Augment each sample with  $\tau$  tuples as  $R_s$ 
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- Example:
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  - Now our filter is  $\phi := (B < 10 * A)$
  - $\pi_A \sigma_\phi R = \{2,3,4,5,6\}$ , so  $D^\phi = 5$
  - $\pi_A \sigma_\phi R_s = \{3,4\}$ , so  $\widehat{D^\phi} = \frac{2}{1/2} = 4$

A	B	sampled?	$\phi$
1	10	✓	
1	20	✓	
3	10	✓	✓
4	20	✓	✓
6	80	✓	
6	60	✓	

# Uniform Distinct Sampling: Problems

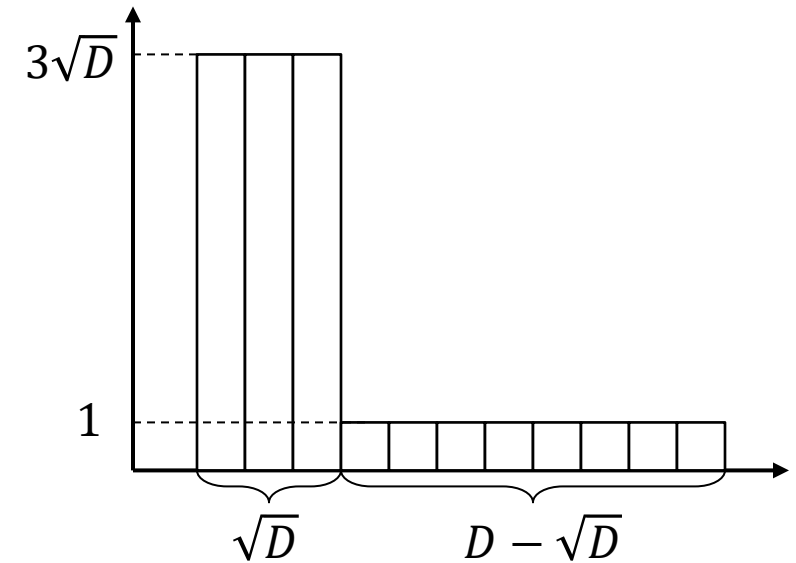
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- If we could augment each value with **ALL** its tuples, the estimator would degenerate to the projection-only case.
  - Unbiased with variance  $\Theta\left(\frac{D}{p}\right)$ .
- However, we only stored  $\tau$  tuples
  - It is possible that we **failed** to sample a passing tuple when there exists
  - This creates a (downward) bias
- The expected sample size is  $Dp\tau$ , so a problem is how to balance
  - The original paper used a heuristic
  - We show next that there are hard inputs where no setting is good



# Uniform vs. Weighted Distinct Sampling

- Hard Input
  - $\sqrt{D}$  **heavy** hitters, each having  $3\sqrt{D}$  tuples
  - $D - \sqrt{D}$  **light** hitters, each having 1 tuple
  - $D$  distinct values,  $\approx 4D$  tuples, use  $2D$  sample budget
- Uniform Distinct Sampling:  $\text{MSE} = \Omega(D)$ 
  - If  $\tau > 2\sqrt{D}$ , variance is  $\Omega(D)$
  - If  $\tau \leq 2\sqrt{D}$ , bias is  $\Omega(\sqrt{D})$
- Weighted Distinct Sampling: A simple configuration can achieve  $O(\sqrt{D})$ 
  - Keep **ALL** **light** values (Sampling with probability  $p_l = 1$ )
  - Sample **heavy** values with  $p_h = 1/3$ , and store **ALL** their tuples if sampled.



# Why Use Weighted Distinct Sampling?

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- In distinct count estimation, **heavy** hitters are not more important.
  - Any distinct value can only contribute 1 to the distinct count post filter  $D^\phi$ .
- However, **heavy** hitters are harder to estimate.
  - For light hitters, we may store all its tuples to remove the bias.
  - This is not possible for heavy hitters.

# Weighted Distinct Sampling: Algorithm

- Parameters: **vectors**  $\{p_i\}, \{\tau_i\}$  defined for  $i \in \text{dom}(A)$
- Algorithm: Sample each distinct value  $i$  with probability  $p_i$ .  
If sampled, augment it with  $\tau_i$  of its tuples.
- Estimation: Let  $n_i^\phi$  denote the number of tuples that passes  $\phi$  among the  $\tau_i$  sampled tuples.  $n_i^\phi = 0$  if  $i$  itself was not sampled at all. Use the following estimator.

$$\widehat{D}^\phi = \sum_{i \in \text{dom}(A)} \frac{I[n_i^\phi \geq 1]}{p_i}$$

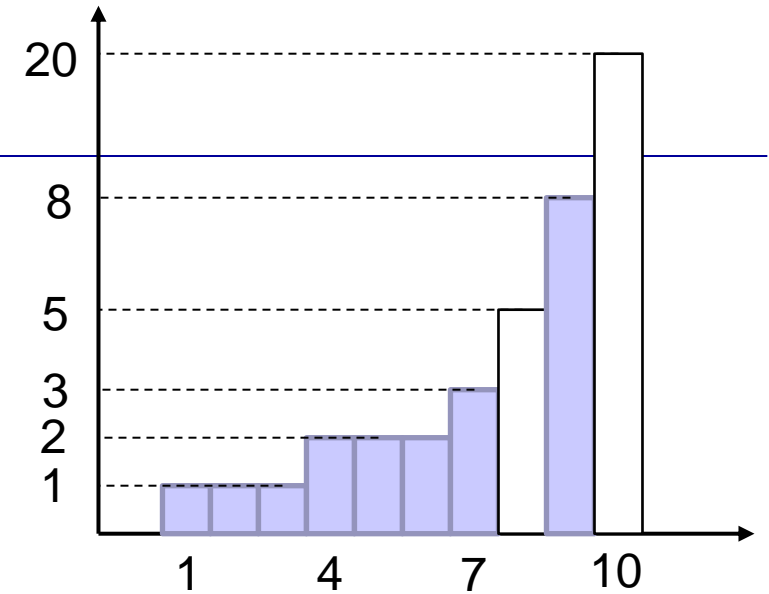
- When  $p_i \equiv p$  and  $\tau_i \equiv \tau$ , it degenerates to uniform distinct sampling.
- What are the best parameters?
  - Solving an optimization problem.

# Near Optimal Solution

- $N_i$ : Frequency of items  $i$ .
- In general,  $p_i \propto \frac{1}{\sqrt{N_i}}$ , and  $\tau_i = N_i$ .
  - When  $N_i$  is too small, we set  $p_i = 1$ .
  - When  $N_i$  is too large, we **never** sample the value.
- Intuition
  - Heavy hitters are harder to estimate, so the sampling probability  $p_i$  **decreases** wrt  $N_i$
  - **Bias** is more important than variance, so we keep all tuples from a value if it is sampled.
  - The **cost** of sample budget for  $i$  is proportional to  $\sqrt{N_i}$ , so for large  $N_i$ , costs outweigh benefits, and we never sample them.

$$\begin{aligned} & \underset{\mathbf{p}, \boldsymbol{\tau}}{\text{minimize}} \max_{\phi} \text{MSE}(\mathbf{p}, \boldsymbol{\tau}, \phi) \\ & \text{subject to} \quad 0 < \mathbf{p} \leq 1, \\ & \quad \quad \quad 0 \leq \boldsymbol{\tau} \leq \mathbf{N}, \\ & \quad \quad \quad \mathbf{p} \cdot \boldsymbol{\tau} \leq n, \end{aligned}$$

# Weighted Distinct Sampling: Example



- Consider a frequency distribution as below.
  - $N_1, N_2, N_3 = 1, N_4, N_5, N_6 = 2$
  - $N_7 = 3, N_8 = 5, N_9 = 8, N_{10} = 20$
- Say our sample budget is  $n = 20$ , then
  - For  $i = 1, \dots, 6$ ,  $p_i = 1$ , we **deterministically** keep them in the sample. (cost = 9)
  - $p_7 = 0.93, p_8 = 0.72, p_9 = 0.57$  is inversely proportional to  $\sqrt{N_i}$ . Once sampled, all their tuples will be maintained. (cost =  $0.93 \cdot 3 + 0.72 \cdot 5 + 0.57 \cdot 8 = 11$ )
  - $N_{10}$  is too large, so we **never** sample value 10. (cost = 0)
- Estimation: Suppose our current sample is  $A_s = \{1, 2, 3, 4, 5, 6, 7, 9\}$ , and the filter passes a tuple for each  $i = 1, \dots, 10$ . Our estimator is

$$\widehat{D^\phi} = 6 + 0.93^{-1} + 0.57^{-1} = 8.82$$

when actual  $D^\phi = 10$ .

# Weighted Distinct Sampling for SPJ queries

- Direct Extension: Join-and-Run
- More efficient approach: using random walks
- View the join as a graph
  - Nodes: **distinct values** + **tuples**
  - Edges: **value**  $\in$  **tuple** + between joining **tuples**
  - Example:  $R(A, \dots) \bowtie S \bowtie T$ 
    - Each length 3 path from  $i \rightarrow t_j$  is a join result
- Start by running WDS on  $R$ 
  - Scale  $\tau$  up by a constant as joins can expand tuples
  - For each sampled value, perform a BFS in the graph while being careful not to break  $\tau$ .
- Estimation time: WDS + Bias Correction

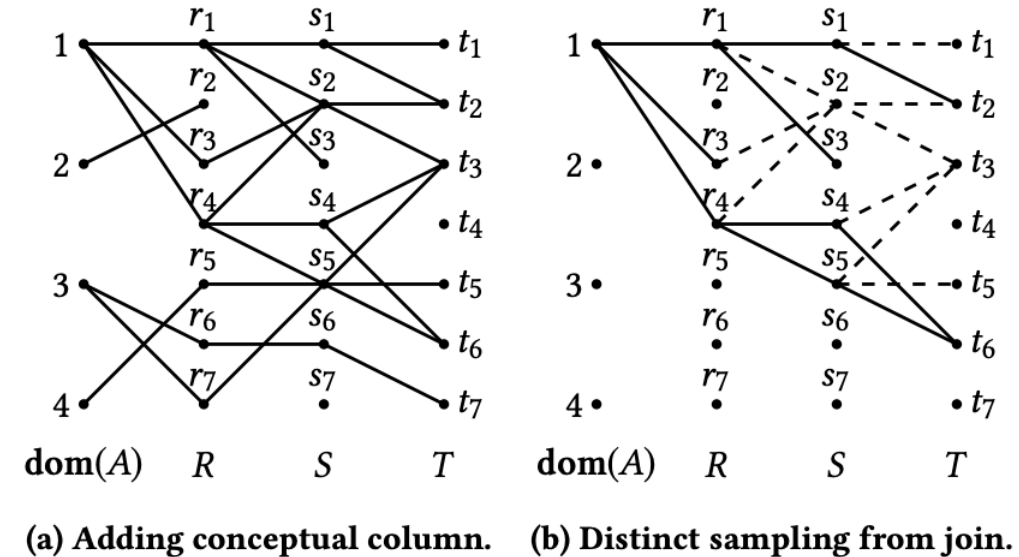


Figure 1: Sampling by random walks.

# Experiment Results (SP, Synthetic)

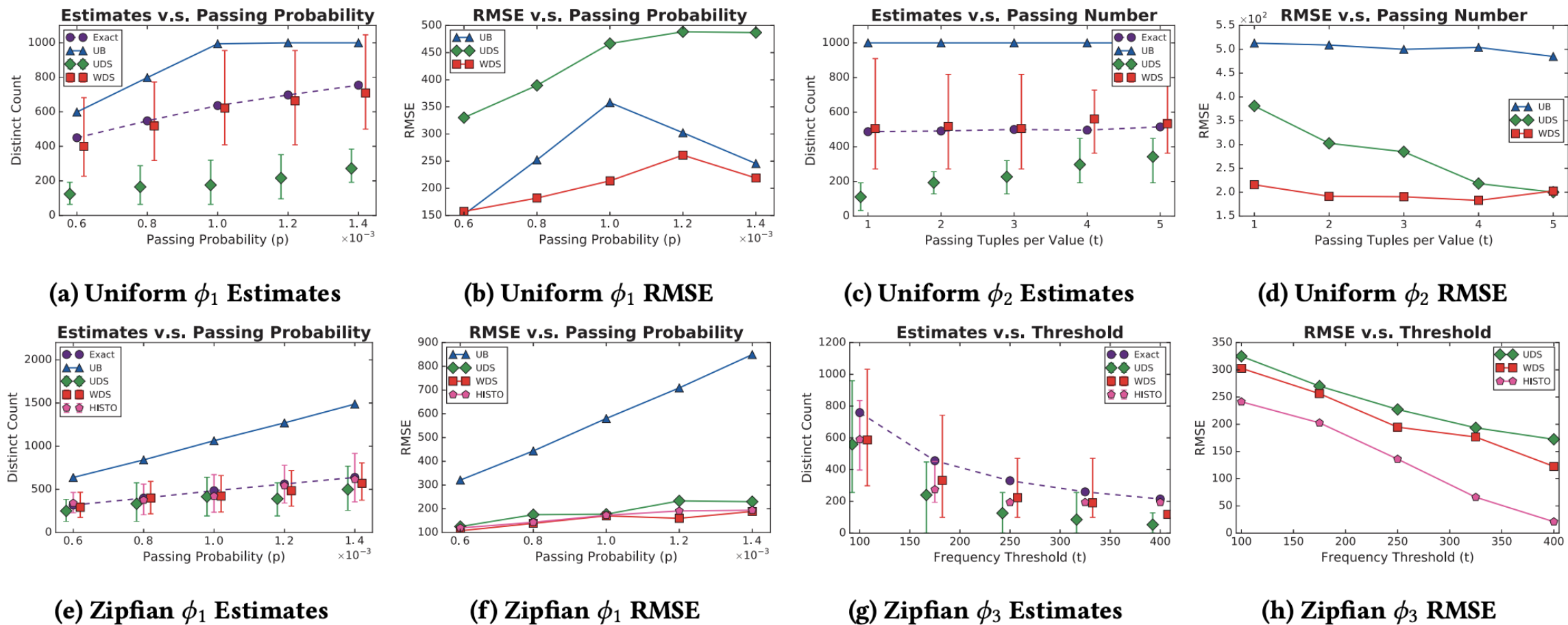
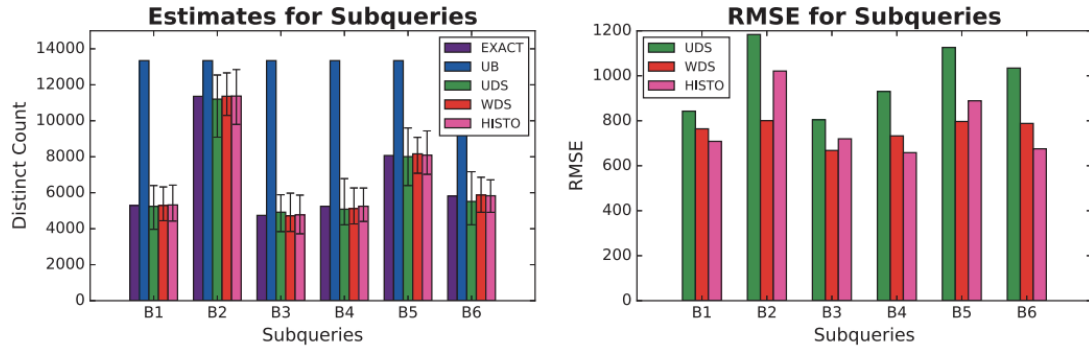


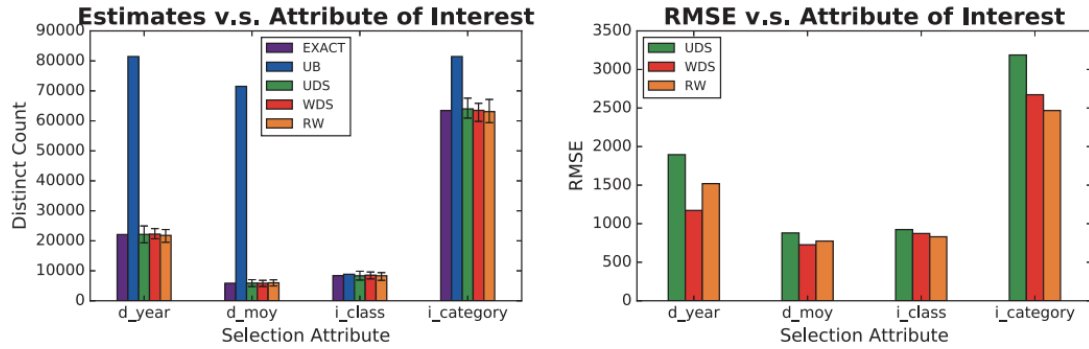
Figure 2: Performance Evaluation for Synthetic Datasets

# Experiment Results (SPJ, Benchmark & Real)



(a) Query 28 Estimates

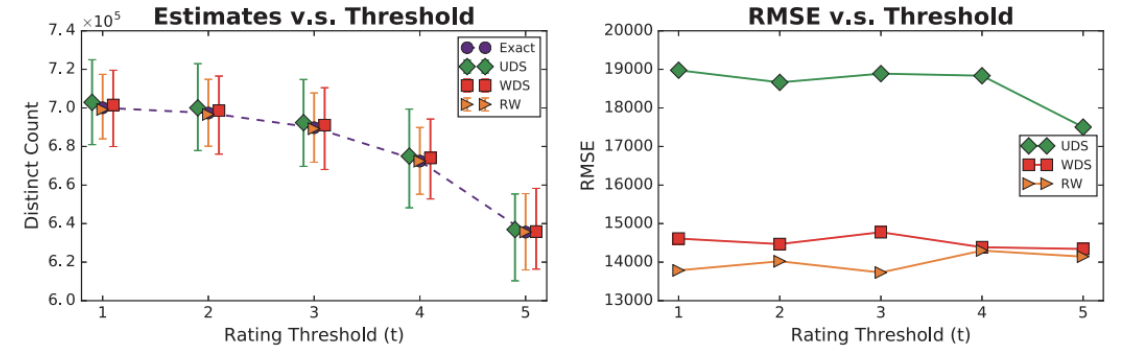
(b) Query 28 RMSE



(c) Query 54 Estimates

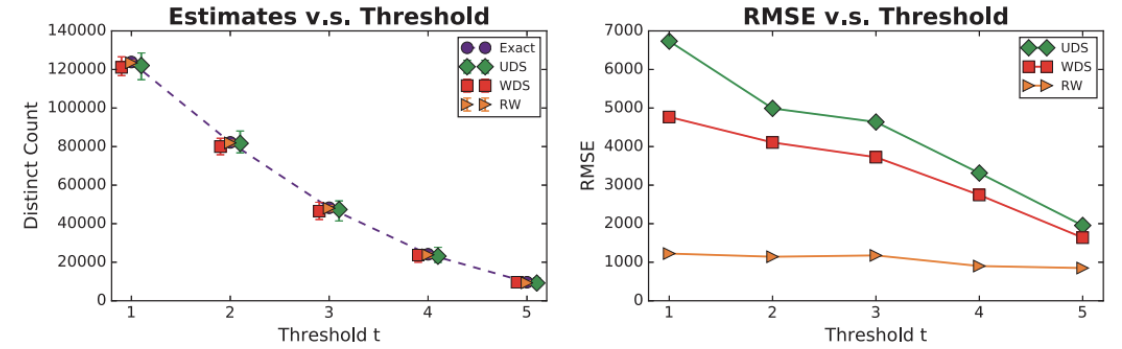
(d) Query 54 RMSE

Figure 3: Performance Evaluation for TPC-DS Benchmark



(a) IMDb Query 1 Estimates

(b) IMDb Query 1 RMSE



(c) IMDb Query 2 Estimates

(d) IMDb Query 2 RMSE

Figure 4: Performances Evaluation of IMDb Data



# Conclusions and Future Directions

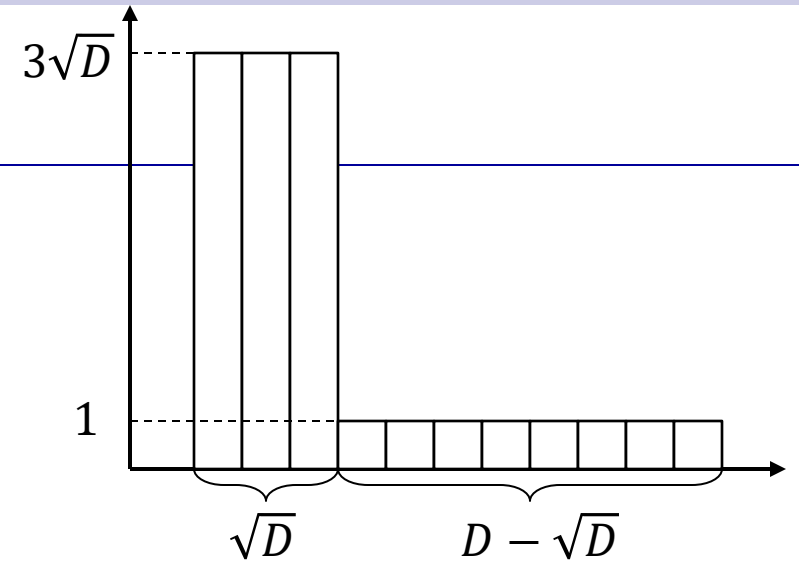
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- We introduced Weighed Distinct Sampling for cardinality estimation of SP(J) queries.
- Implemented in AnalyticDB, product of Alibaba Cloud
- Future Directions
  - Dynamic Maintenance
  - Special Predicates (e.g. ranges)

**Thank you!**

# **BACK-UP SLIDES**

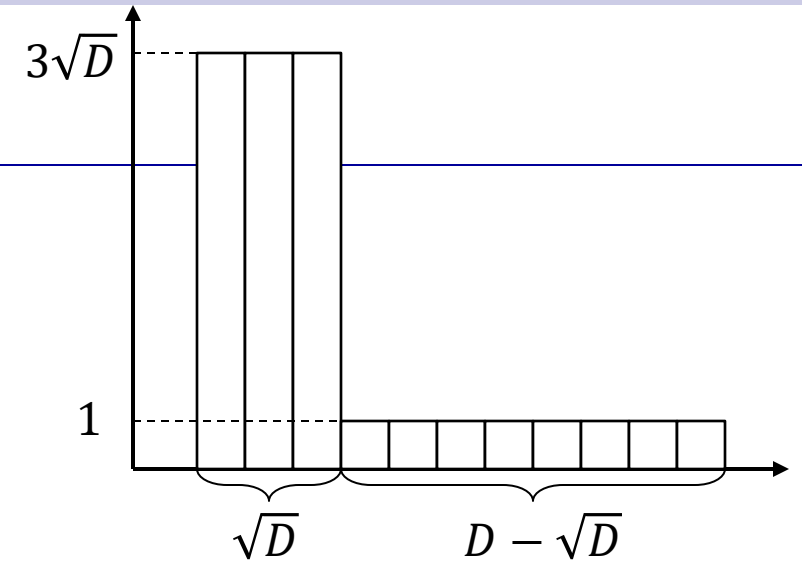
# Uniform Distinct Sampling: Hard Case



- There are  $\sqrt{D}$  **heavy** hitters, each having  $3\sqrt{D}$  tuples
- Remaining  $D - \sqrt{D}$  values are **light**, each having 1 tuple
  - There are  $3D + D - \sqrt{D} \approx 4D$  tuples in total
- Suppose we allow a sample budget of  $2D$ , sampling half the database!
- Intuition: If  $\tau$  is large, then  $p$  must be small, so variance is large. Otherwise  $\tau$  is small, and bias is large.
- If  $\tau > 2\sqrt{D}$ , then  $p \leq 3/4$ . Otherwise the expected sample size is at least
$$\frac{3}{4} \left( \sqrt{D} \cdot 2\sqrt{D} + D - o(D) \right) = \frac{9}{4}D - o(D) > 2D$$
  - Since  $p \leq \frac{3}{4}$ , the variance is  $\Omega\left(\frac{D}{p}\right) = \Omega(D)$

# Uniform Distinct Sampling: Hard Case

- If  $\tau \leq 2\sqrt{D}$ , for simplicity we just consider  $p = 1$ .
- Consider  $\phi_x$  that 1) blocks all **light** value, and
  - 2) passes  $x$  tuples for any **heavy** value
- When  $x$  varies from 1 to  $3\sqrt{D}$ ,  $D^{\phi_x} \equiv \sqrt{D}$
- Our estimator is  $\widehat{D^{\phi_x}} = |\pi_A \sigma_{\phi_x} R_S| = \sum_{i=1}^{\sqrt{D}} I[n_i^{\phi_x} \geq 1]$ , where  $n_i^{\phi_x}$  is the number of passing tuples sampled for value  $i$ . Its expectation is  $E[\widehat{D^{\phi_x}}] = p(x) \cdot \sqrt{D}$ .
- $p(x)$  is the probability of sampling at least one passing tuple for any value.
  - If  $x = 3\sqrt{D}$ , we must sampled passing tuples, thus  $p(x) = 1$
  - If  $x = 1$ ,  $p(x) = \tau/3\sqrt{D} \leq 2/3$ .
- The gap of the estimator is  $\Omega(\sqrt{D})$  when the actual  $D^{\phi_x}$  is fixed. So the bias is  $\Omega(\sqrt{D})$



# Uniform vs. Weighted Distinct Sampling

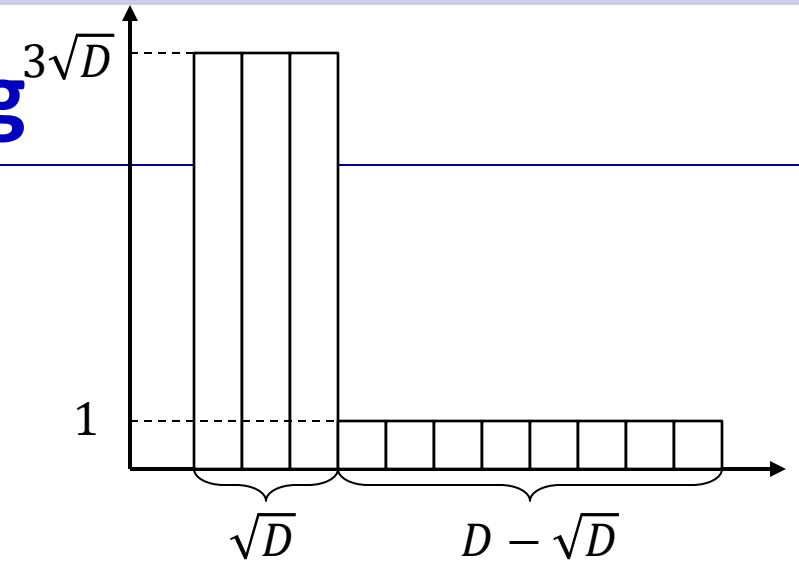
## ■ Uniform Distinct Sampling:

- If  $\tau > 2\sqrt{D}$ , variance is  $\Omega(D)$
- If  $\tau \leq 2\sqrt{D}$ , bias is  $\Omega(\sqrt{D})$
- Either way,  $\text{MSE} = \text{Bias}^2 + \text{Var} = \Omega(D)$

## ■ Can we do better?

## ■ For this specific case:

- Keep all **light** values (Sampling with probability  $p_l = 1$ )
- Sample **heavy** values with  $p_h = 1/3$ , and take ALL their tuples if sampled.
- Expected sample size is  $p_h\sqrt{D} \cdot 3\sqrt{D} + p_l(D - \sqrt{D}) \cdot 1 < 2D$
- There is no bias, and the variance (from heavy values) is  $O(\sqrt{D}/p_h) = O(\sqrt{D})$ .



# WDS for SPJ: Estimation

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- We are no longer able to store **ALL** join results for a distinct value (they are huge!)
- So we want to reduce the bias.
- At estimation time, we check each distinct value in our sample:
  - If **none** of its join results passed the filter, or if it failed to extend to any join result at all, we regard that it **does not appear** in the original (post-filter) join result, and estimate 0.
  - If  $\geq 2$  of its join results passed the filter, we assume there are **many** candidates, so we regard the probability of sampling a passing join result is **high**, and estimate 1.
  - If there is a **single** passing join result, we have sampled it due to luck. And we want to estimate the probability of sampling a passing tuple.
    - Lower bounded by  $p_t$ , the probability of sampling this **exact** tuple; Upper bounded by 1, so we use a scaled up estimator  $\frac{1}{\sqrt{p_t}}$ , and  $p_t$  can be calculated in random walks.
- Finally, scale it up by the inverse of  $p_i$ .