

Codes of gamepad controller for teleoperate

```
import ipywidgets.widgets as widgets

controller = widgets.Controller(index=1) # replace with index of your controller

display(controller)


from jetbot import Robot
import traitlets

robot = Robot()

left_link = traitlets.dlink((controller.buttons[3], 'value'), (robot.left_motor,
'value'), transform=lambda x: -x/2)
right_link = traitlets.dlink((controller.buttons[1], 'value'), (robot.right_motor,
'value'), transform=lambda x: -x/2)
forward_link = traitlets.dlink((controller.buttons[0], 'value'), (robot.left_motor,
'value'), transform=lambda x: x/2)
forward_link = traitlets.dlink((controller.buttons[0], 'value'), (robot.right_motor,
'value'), transform=lambda x: x/2)
backward_link = traitlets.dlink((controller.buttons[2], 'value'), (robot.left_motor,
'value'), transform=lambda x: -x/2)
backward_link = traitlets.dlink((controller.buttons[2], 'value'), (robot.right_motor,
'value'), transform=lambda x: -x/2)
```