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2017 – present	 Laboratory: Institute of Movement Sciences, Bio-robotics team, France; Topic: Design and development of a camera based soft tactile sensor for measuring the frictional information and 3d interaction forces of the contact. MASTER - Advanced System and Robotics University of Pierre and Marie Curie, France 		
2014 - 2016			
2013 - 2014			
2011 - 2013	DUT - Mechanical and Production Engineering+ IUT of Cachan - University of Paris Sud, France		
EXPERENCE			
2016	INTERNSHIP - The Laboratory LIRMM - 6 months - France + Implementation of a force and vision based augmented reality system in trans-oral robot assisted surgery of tongue base cancer.		
2014	 INTERNSHIP - The Institute of Industrial Internet of Things - 12 weeks - China Development of intelligent vision of a welding robot; programming of the robot by language C# and teach pendant. 		
2013	 INTERNSHIP - Freyssinet Products Company - 10 weeks - France + Establishment of a production schedule; production tracking of the pavement joints for a monorail. 		
PROJECTS			
2016 2015	MASTER PROJECT - Computer assisted design of a haptic device + Computer assisted design and analysis of a haptic interface based on control momer gyroscope by ADAMS MASTER PROJECT - Digital modeling of a mobile robot		
SKILLS	+ Computer assisted modeling and simulation of a mobile robot with two wheels by Python and Blender.		
	LANGUAGES + French: Current + English: Current + Chinese: Native language		

+ Chinese: Native language

TECHNICAL SKILLS

- + **Software**: Matlab; Solidworks; SolidEdge; Comsol; Python; Adams; Blender.
- + **Scientific knowledge**: Tactile sensor; Haptics; Image processing; Computer assisted design; Analysis and Control of Robotic and Mechanical Systems; Kinematics and Dynamics in robotic systems; Structural Mechanics.