

# QIUSHI (MAX) LIN

<https://qiushi-lin.github.io>

qiushi\_lin@sfu.ca

## RESEARCH INTERESTS

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Developing theoretically principled machine learning algorithms, with a focus on reinforcement learning.

## EDUCATION

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**Simon Fraser University (SFU)**, Burnaby, Canada  
M.Sc. in Computing Science (Thesis-Based Program)

*2021 - 2023*

GPA: 4.06/4.33

- Advisor: Hang Ma
- Courses: Theoretical Foundations of Reinforcement Learning [Ongoing], Optimization for Machine Learning [A], Statistical Machine Learning [A], Graph Representation Learning [A], (Multi-Agent) Intelligent Systems [A+], Data Mining [A]
- Thesis: Learning Cooperation for Partially Observable Multi-Agent Path Finding [pdf]

**Southern University of Science and Technology (SUSTech)**, Shenzhen, China  
B.Eng. in Computer Science and Technology

*2016 - 2020*

GPA: 3.75/4.00

- Graduation with Departmental Highest Honors

## RESEARCH EXPERIENCES

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**Research Assistant**, AIRob Lab (SFU Robotics Research Group)

*2021- 2023*

- supervised by Prof. Hang Ma
- focusing on reinforcement learning and multi-agent systems

**Research Intern**, Illinois Institute of Technology

*2019*

- supervised by Prof. Xin Chen
- focusing on semantic segmentation of 3D point clouds for LiDAR sensor data

## PUBLICATIONS AND PREPRINTS

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### [2] **Mean Field Control with Envelope $Q$ -learning for Moving Agents in Formation**

Qiushi Lin and Hang Ma.

Preprint (In Submission) [pdf] [code]

Short Abstract: We proposed an adaptable multi-objective multi-agent reinforcement learning algorithm that combines mean field control and envelop  $Q$ -learning for moving agents in formation, and provided theoretical analysis and empirical evaluation.

### [1] **SACHA: Soft Actor-Critic with Heuristic-Based Attention for Partially Observable Multi-Agent Path Finding**

In IEEE Robotics and Automation Letters (RA-L) 2023 [pdf] [code]

Qiushi Lin and Hang Ma.

Short Abstract: We designed a novel multi-agent actor-critic reinforcement framework for partially observable multi-agent path finding. We integrated the heuristic-based attention mechanisms to enable the learned model to generalize among multiple instances on a large scale.

## AWARDS AND HONORS

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- Westak International Sales, Inc. Graduate Scholarship, SFU 2023
- Departmental Highest Honors of Graduation, SUSTech 2020

## TEACHING EXPERIENCES

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**Teaching Assistant, SFU**

- CMPT 310: Introduction to Artificial Intelligence
- CMPT 417/827: (Multi-Agent) Intelligent Systems
- MACM 101: Discrete Mathematics

## TECHNICAL SKILLS

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**Programming Languages:** Python, C/C++, Matlab, SQL

**Frameworks and Tools:** Pytorch, Tensorflow, Linux, GitHub, LaTeX