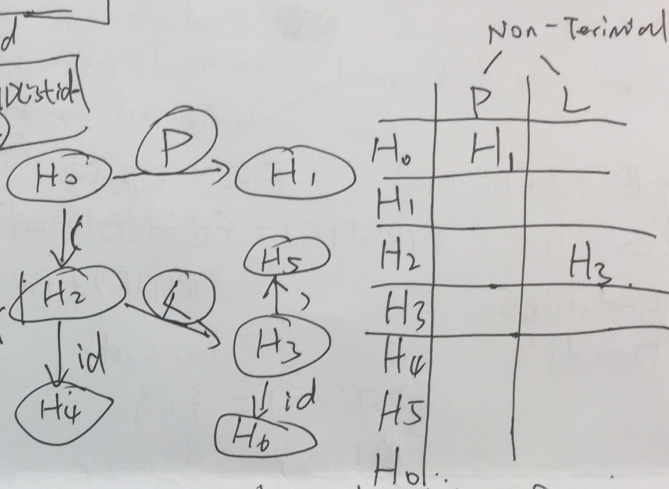


for every nonterminal X
 if there is an $[H_j, H_k]$ edge on X
 Set $\text{GoTo}[H_j, X] = H_k$.



Action Table: {Shift/Reduce/Accept}.

Shift. $A \rightarrow \alpha \cdot t$ (H_0, H_3, H_2)
 t is terminal

Action $[H_j, t] = \text{shift } H_k$.

Reduce. $A \rightarrow \alpha \cdot$ (H_4, H_5, H_6)

A is not s' (start)

for each t is FOLLOW(A)

Action $[H_j, t] \Rightarrow \text{reduce } A \rightarrow \alpha$.

FOLLOW(L) = { }, id

FOLLOW(P) = { eof }

Accept: $s' \rightarrow s$.

$[H_j, eof] = \text{accept!}$

	()	id	eof
H_0	SH ₂			
H_1				✓
H_2			SH ₄	
H_3		SH ₅	SH ₆	
H_4		R(3)	R(3)	
H_5				R(2)
H_6		R(4)	R(4)	