

\* Time complexity: quantifies the time taken by an algorithm,  
as a function of the length of the string representation  
of the input

eps

Formally, we can write  $T = f(n)$ , where  $T$  is the time, and  $f(n)$  is the time-complexity function

$f(n) = \underbrace{C_2 n^2}_{\text{input}} + \underbrace{C_1 n}_{\text{input}} + C_0$

$C_2 n^2 \geq C_1 n + C_0$  when  $n$  is "large"

$n^2 \geq \frac{C_1}{C_2} n + C_0$

$n \geq \frac{\frac{C_1}{C_2} n + C_0}{n}$

$n \geq \frac{C_1}{C_2} + \frac{C_0}{n}$

$n \geq \frac{C_1}{C_2} + \frac{C_0}{\text{constant}}$



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### Time analysis

- focus on the fastest-growing term
- focus on large input size

Bounds: Let  $f(n)$  be the time-complexity function of an algorithm, and  $f'(n)$  be its fastest-growing term.

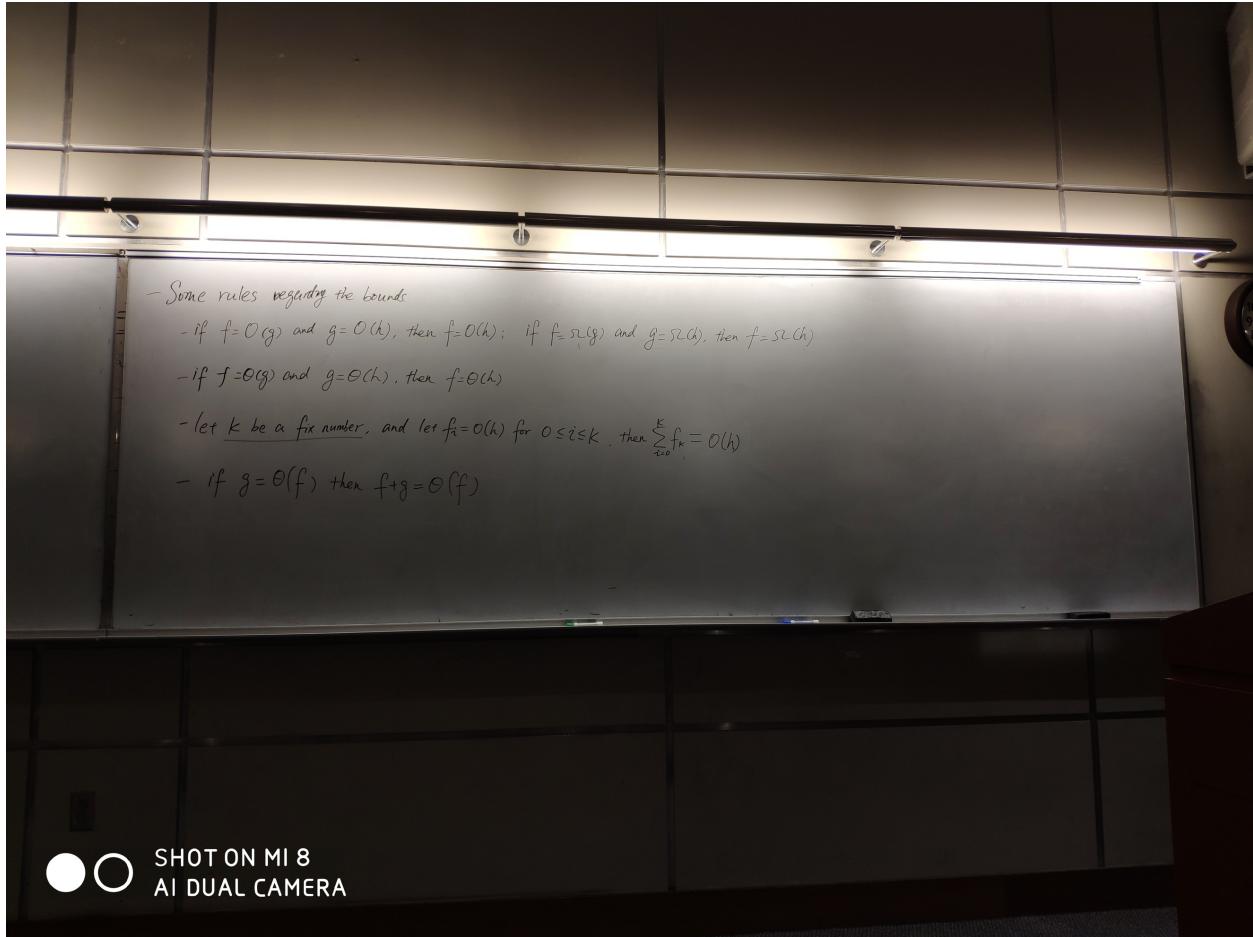
- upper bound:  $T \leq c f(n) \Rightarrow T = O(f'(n))$  the big-O notation. (e.g.  $T \leq 2n^2 \Rightarrow T = O(n^2)$ )

- lower bound:  $T \geq c f(n) \Rightarrow T = \Omega(f'(n))$  the big- $\Omega$  notation

- tight bound: if  $T = O(f(n))$  and  $T = \Omega(f(n))$  the big- $\Theta$  notation.  $T(n) = \Theta(f'(n))$



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- Major classes of complexity functions

logarithm < polynomial

$$\lim_{n \rightarrow \infty} \frac{\log n}{n^k} = \lim_{n \rightarrow \infty} \frac{d(\log n)}{d(n^k)} = \lim_{n \rightarrow \infty} \frac{1/n}{kn^{k-1}} = \lim_{n \rightarrow \infty} \frac{1}{kn^k} = 0$$

$$\log(n) < n^k < e^n$$

"efficient"      "infeasible"

polynomial < exponential

$$\lim_{n \rightarrow \infty} \frac{n^k}{e^n} = \lim_{n \rightarrow \infty} \frac{d(n^k)}{d(e^n)} = \lim_{n \rightarrow \infty} \frac{kn^{k-1}}{e^n} = \lim_{n \rightarrow \infty} \frac{d(kn^{k-1})}{d(e^n)} \cdots = \lim_{n \rightarrow \infty} \frac{k!}{e^n} = 0$$



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## Analysis of Merge Sort.

MergeSort ( $R$ )

If  $|R| \leq 1$ ; return  $R$ .

Split  $R$  into two equal-size sets  $R_1$  and  $R_2$ .

MergeSort ( $R_1$ ); MergeSort ( $R_2$ )

$R' = \emptyset$ ;  $i = 0$ ;  $j = 0$ ;

while ( $i < |R_1|$  and  $j < |R_2|$ ) do.

    if ( $R_1[i] \leq R_2[j]$ ): { insert  $R_1[i]$  to  $R'$ ;  $++i$ ; $j$ }

    else: { insert  $R_2[j]$  to  $R'$ ;  $++j$ ; $i$ }

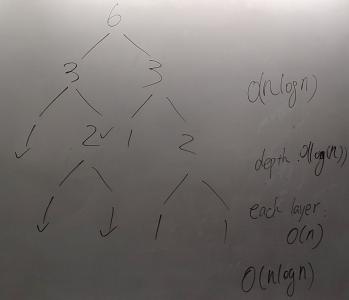
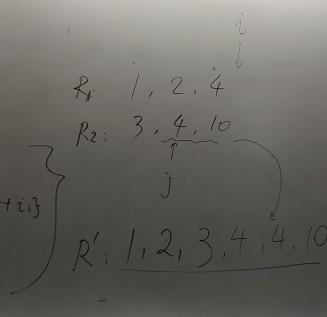
endif

endwhile.

if ( $i < |R_1|-1$ ): insert  $R_1[i+1:|R_1|-1]$  to  $R'$

if ( $j < |R_2|-1$ ): insert  $R_2[j+1:|R_2|-1]$  to  $R'$

endif; return  $R'$



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