COMP 3331/9331: Computer Networks and Applications

Week 8

Control Plane (Routing)

Chapter 5: Section 5.1 - 5.2, 5.6

Network layer, control plane: outline

5.1 introduction

- 5.2 routing protocols
- link state
- distance vector
- Hierarchical routing (NOT ON EXAM)

5.6 ICMP: The Internet Control Message Protocol

Network-layer functions

- forwarding: move packets from router's input to appropriate router output
- routing: determine route taken by packets from source to destination

data plane

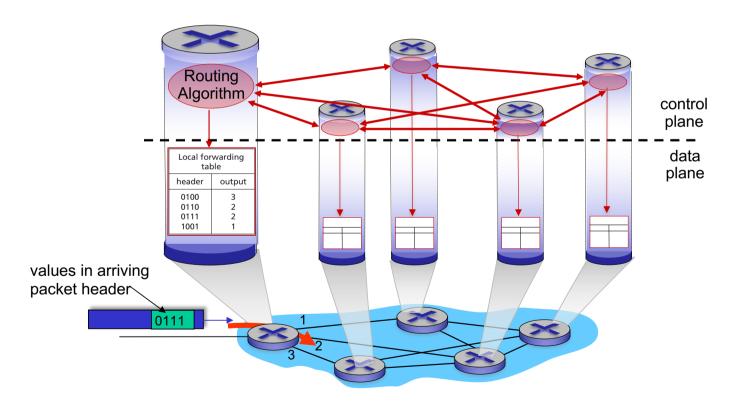
control plane

Two approaches to structuring network control plane:

- per-router control (traditional)
- logically centralized control (software defined networking)

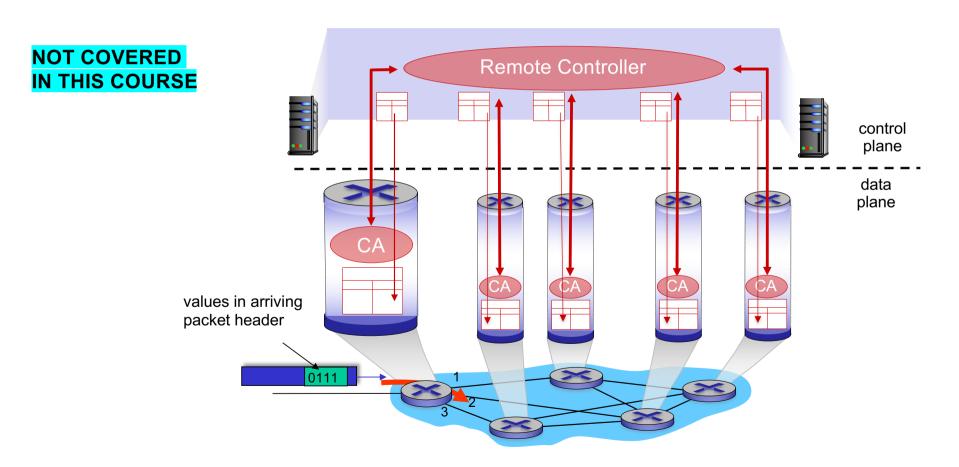
Per-router control plane

Individual routing algorithm components *in each and every* router interact in the control plane



Software-Defined Networking (SDN) control plane

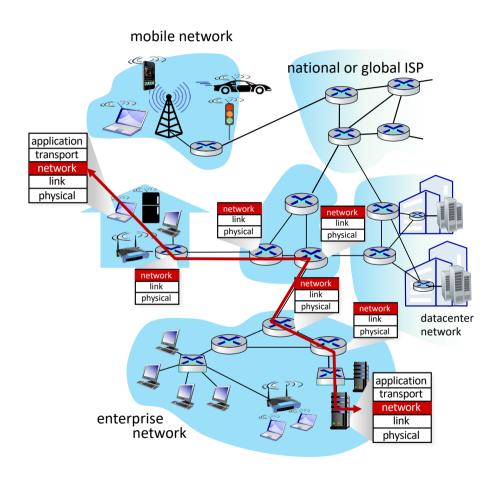
Remote controller computes, installs forwarding tables in routers

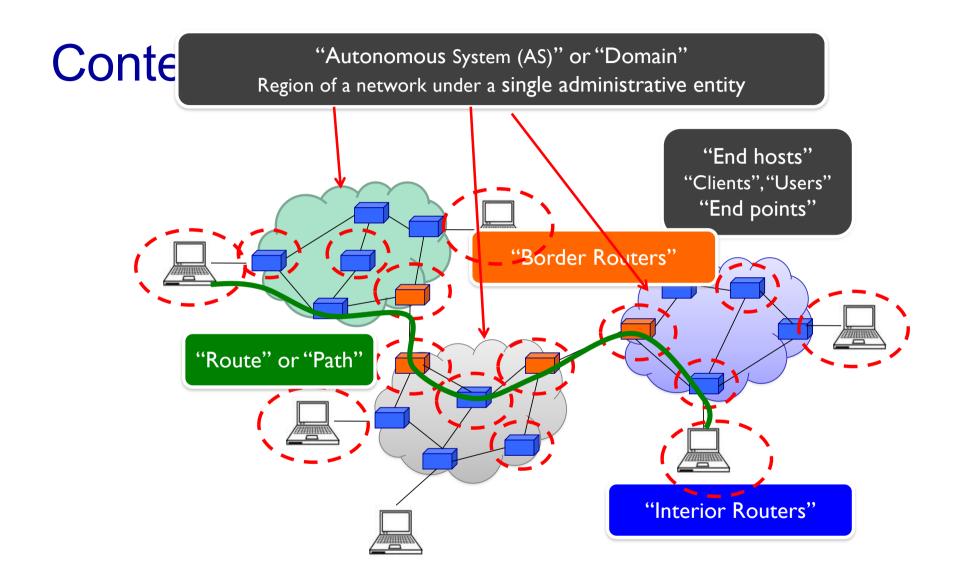


Routing protocols

Routing protocol goal: determine "good" paths (equivalently, routes), from sending hosts to receiving host, through network of routers

- path: sequence of routers packets traverse from given initial source host to final destination host
- * "good": least "cost", "fastest", "least congested"
- routing: a "top-10" networking challenge!

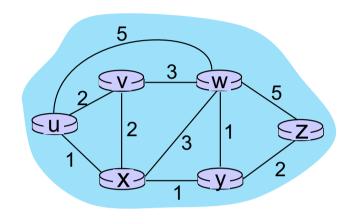




Internet Routing

- Internet Routing works at two levels
- Each AS runs an intra-domain routing protocol that establishes routes within its domain
 - AS -- region of network under a single administrative entity
 - Link State, e.g., Open Shortest Path First (OSPF)
 - Distance Vector, e.g., Routing Information Protocol (RIP)
- ASes participate in an inter-domain routing protocol that establishes routes between domains
 - Path Vector, e.g., Border Gateway Protocol (BGP)

Graph abstraction: link costs



 $c_{a,b}$: cost of *direct* link connecting a and b e.g., $c_{w,z} = 5$, $c_{u,z} = \infty$

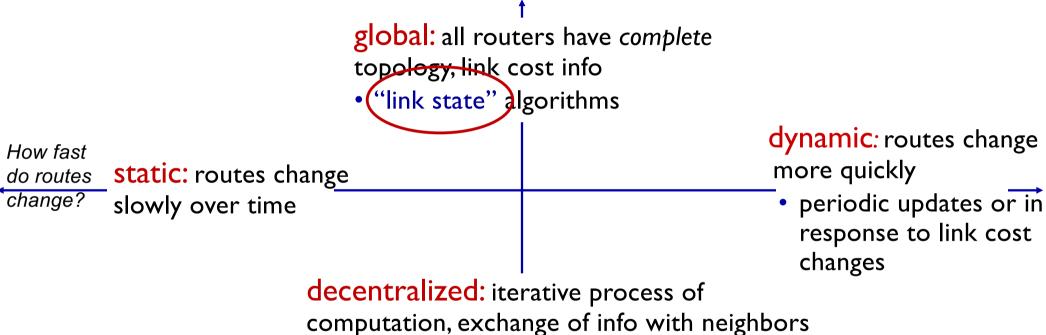
cost defined by network operator: could always be 1, or inversely related to bandwidth, or inversely related to congestion

graph: G = (N,E)

N: set of routers = { u, v, w, x, y, z }

E: set of links = $\{ (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) \}$

Routing algorithm classification



 routers initially only know link costs to attached neighbors

• "distance vector" algorithms

global or decentralized information?

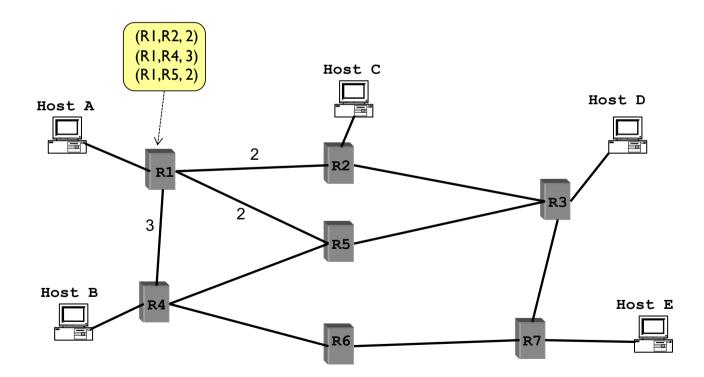
Network layer, control plane: outline

- 5.1 introduction
- 5.2 routing protocols
- link state
- distance vector
- hierarchical routing

5.6 ICMP: The Internet Control Message Protocol

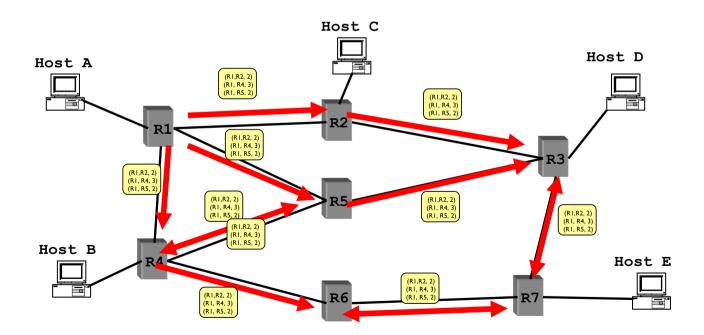
Link State Routing

- Each node maintains its local "link state" (LS)
 - i.e., a list of its directly attached links and their costs



Link State Routing

- Each node maintains its local "link state" (LS)
- Each node floods its local link state
 - on receiving a new LS message, a router forwards the message to all its neighbors other than the one it received the message from

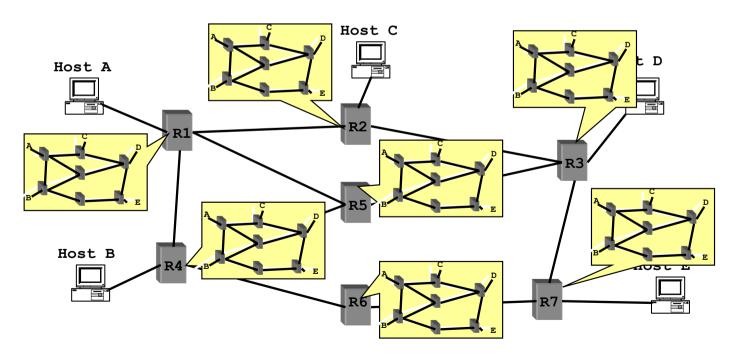


Flooding LSAs

- Routers transmit Link State Advertisement (LSA) on links
 - A neighbouring router forwards out on all links except incoming
 - Keep a copy locally; don't forward previously-seen LSAs
- Challenges
 - Packet loss
 - Out of order arrival
- Solutions
 - Acknowledgements and retransmissions
 - Sequence numbers
 - Time-to-live for each packet

Link State Routing

- Each node maintains its local "link state" (LS)
- * Each node floods its local link state
- Eventually, each node learns the entire network topology
 - Can use Dijkstra's to compute the shortest paths between nodes



Dijkstra's link-state routing algorithm

- centralized: network topology, link costs known to all nodes
 - accomplished via "link state broadcast"
 - all nodes have same info
- computes least cost paths from one node ("source") to all other nodes
 - gives forwarding table for that node
- iterative: after k iterations, know
 least cost path to k destinations

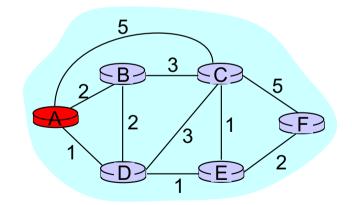
notation

- $C_{x,y}$: direct link cost from node x to y; = ∞ if not direct neighbors
- D(v): current estimate of cost of least-cost-path from source to destination v
- p(v): predecessor node along path from source to v
- N': set of nodes whose leastcost-path definitively known

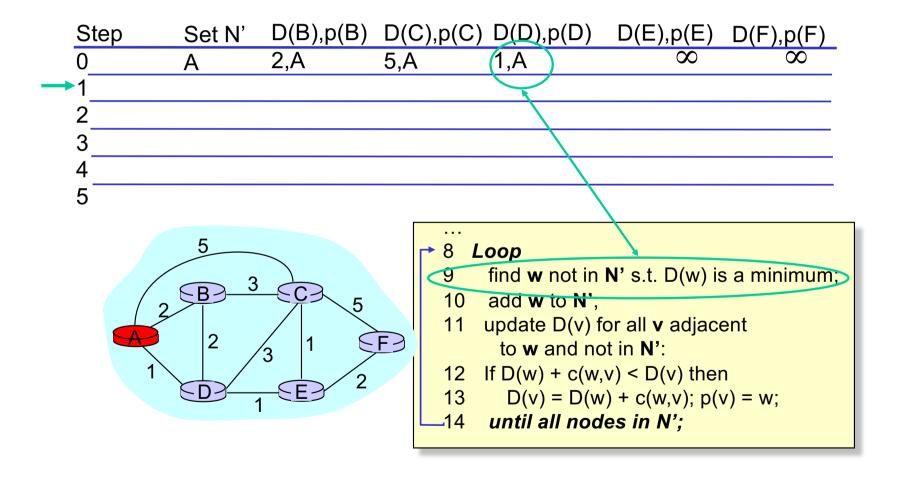
Dijkstra's link-state routing algorithm

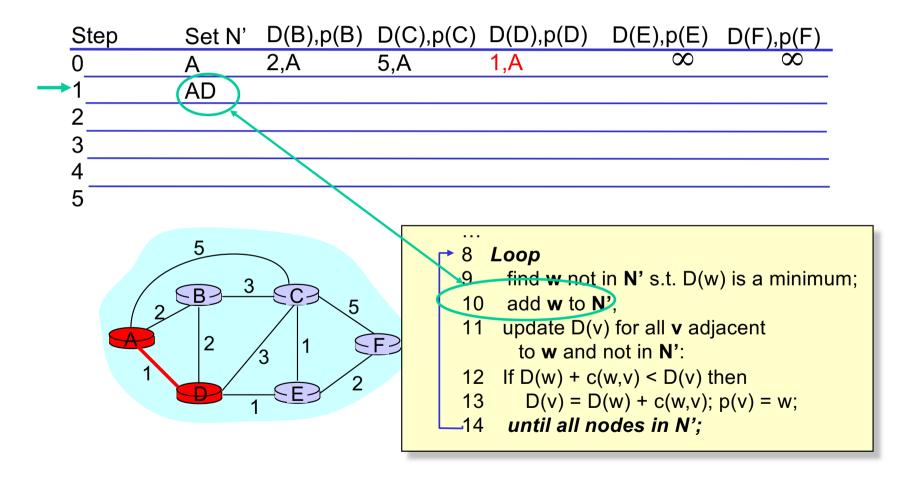
```
Initialization:
    N' = \{u\}
                                      /* compute least cost path from u to all other nodes */
    for all nodes v
     if v adjacent to u
                                   /* u initially knows direct-path-cost only to direct neighbors
         then D(v) = c_{u,v}
                                   /* but may not be minimum cost!
     else D(v) = \infty
   Loop
      find w not in N' such that D(w) is a minimum
      add w to N'
      update D(v) for all v adjacent to w and not in N':
          D(v) = \min (D(v), D(w) + c_{w,v})
      /* new least-path-cost to v is either old least-cost-path to v or known
13
      least-cost-path to w plus direct-cost from w to v */
    until all nodes in N'
```

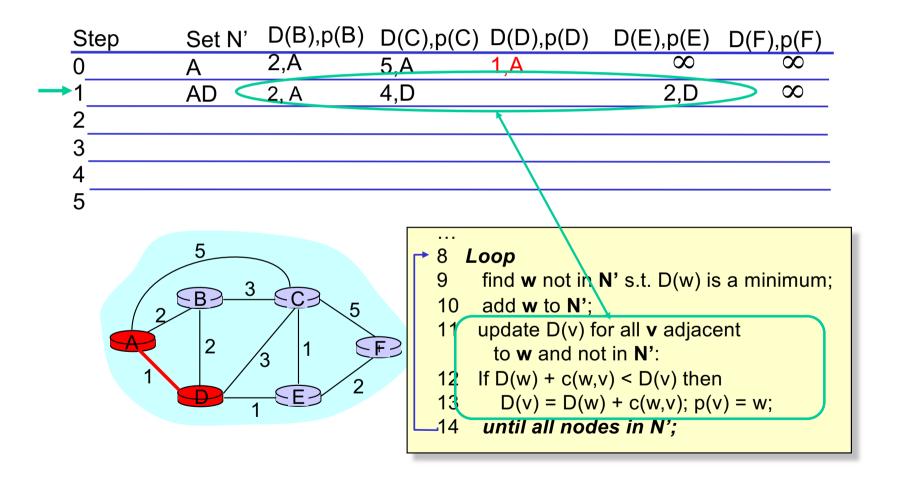
Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
-0	Α	2,A	5,A	1,A	∞	∞
1						
2						
3						
4						
5						



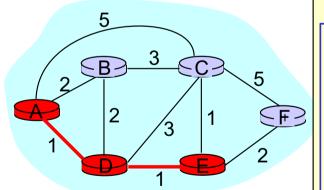
```
    1 Initialization:
    2 N' = {A};
    3 for all nodes v
    4 if v adjacent to A
    5 then D(v) = c(A,v);
    6 else D(v) = ∞;
    ...
```





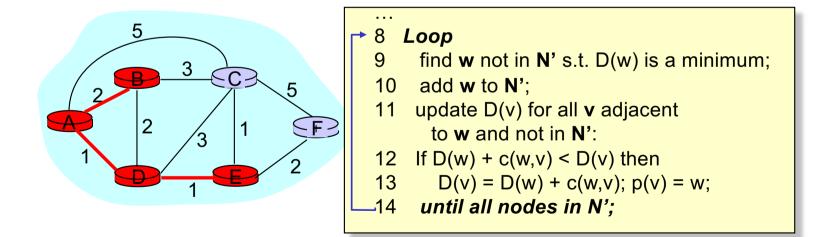


Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	Α	2,A	5,A	1,A	∞	∞
1	AD	2, A	4,D		2,D	∞
	ADE	2, A	3,E			4,E
3						
4						
5						

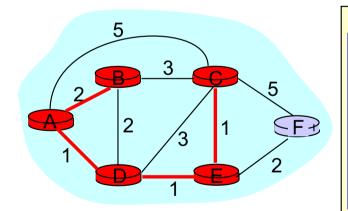


```
    8 Loop
    9 find w not in N' s.t. D(w) is a minimum;
    10 add w to N';
    11 update D(v) for all v adjacent to w and not in N':
    12 If D(w) + c(w,v) < D(v) then</li>
    13 D(v) = D(w) + c(w,v); p(v) = w;
    14 until all nodes in N';
```

Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	Α	2,A	5,A	1,A	∞	∞
1	AD	2,A	4,D		2,D	
2	ADE	2,A	3,E			4,E
→ 3	ADEB		3,E			4,E
4						
5						

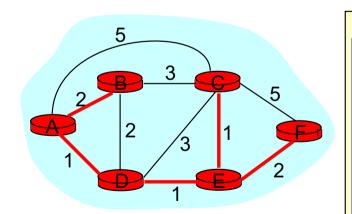


S	tep	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0		Α	2,A	5,A	1,A	∞	∞
1		AD	2,A	4,D		2,D	
2		ADE	2,A	3,E			4,E
3		ADEB		3,E			4,E
 4		ADEBC					4,E
5							



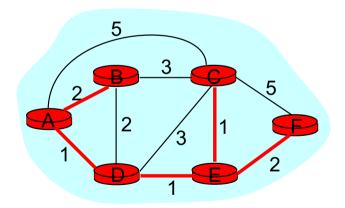
```
    Noop
    find w not in N' s.t. D(w) is a minimum;
    add w to N';
    update D(v) for all v adjacent to w and not in N':
    If D(w) + c(w,v) < D(v) then</li>
    D(v) = D(w) + c(w,v); p(v) = w;
    until all nodes in N';
```

Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	Α	2,A	5,A	1,A	∞	∞
1	AD	2,A	4,D		2,D	
2	ADE	2,A	3,E			4,E
3	ADEB		3,E			4,E
4	ADEBC					4,E
→ 5	ADEBCF					

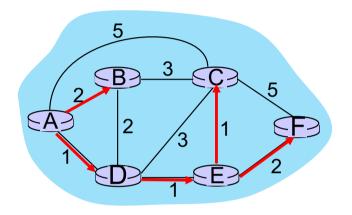


```
    Noop
    find w not in N' s.t. D(w) is a minimum;
    add w to N';
    update D(v) for all v adjacent to w and not in N':
    If D(w) + c(w,v) < D(v) then</li>
    D(v) = D(w) + c(w,v); p(v) = w;
    until all nodes in N';
```

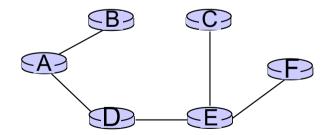
Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	Α	2,A	5,A	(1,A)	∞	∞
1	AD		4,D		(2,D)	
2	ADE		(3,E)			4,E
3	ADEB					
4	ADEBC					
5	ADEBCE					



To determine path $A \rightarrow C$ (say), work backward from C via p(v)



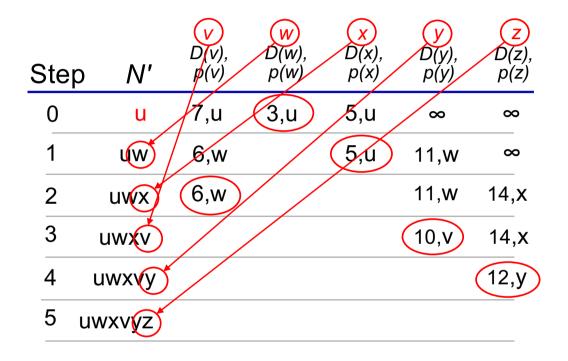
resulting least-cost-path tree from A:

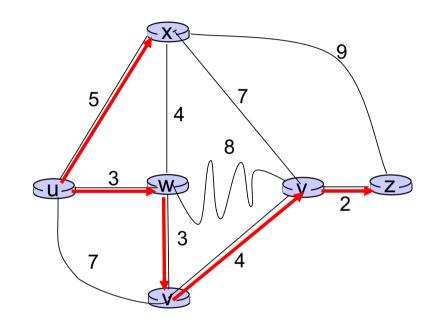


resulting forwarding table in A:

destination	outgoing link	
В	(A,B)-	route from A to B directly
С	(A,D)	
D	(A,D)	route from A to all
E	(A,D)	other destinations
F	(A,D)	via D

Dijkstra's algorithm: another example





notes:

- construct least-cost-path tree by tracing predecessor nodes
- ties can exist (can be broken arbitrarily)

Dijkstra's algorithm: discussion

algorithm complexity: n nodes

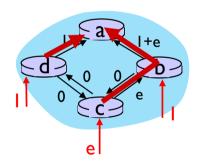
- each of n iteration: need to check all nodes, w, not in N
- n(n+1)/2 comparisons: $O(n^2)$ complexity
- more efficient implementations possible: O(nlogn)

message complexity:

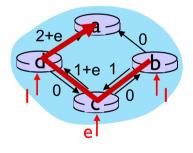
- each router must broadcast its link state information to other n routers
- efficient (and interesting!) broadcast algorithms: O(n) link crossings to disseminate a broadcast message from one source
- each router's message crosses O(n) links: overall message complexity: $O(n^2)$

Dijkstra's algorithm: oscillations possible

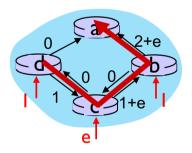
- when link costs depend on traffic volume, route oscillations possible
- sample scenario:
 - routing to destination a, traffic entering at d, c, e with rates I, e (< I), I
 - link costs are directional, and volume-dependent



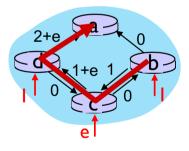
initially



given these costs, find new routing.... resulting in new costs



given these costs, find new routing.... resulting in new costs



given these costs, find new routing.... resulting in new costs

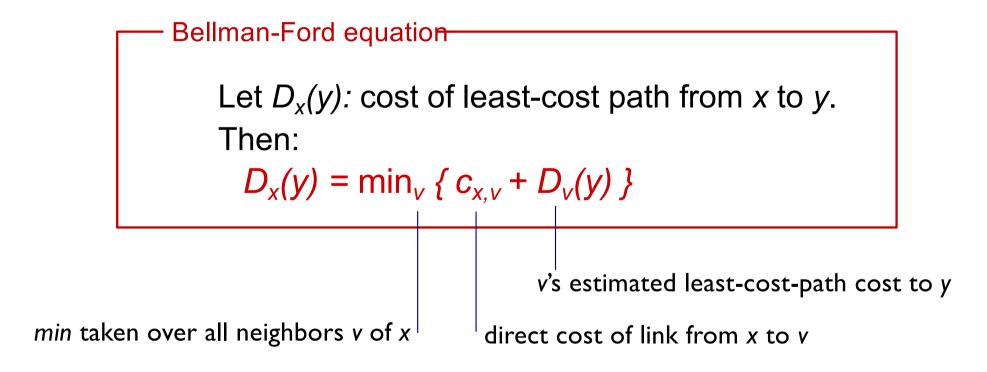
Network layer, control plane: outline

- 5.1 introduction
- 5.2 routing protocols
- link state
- distance vector
- hierarchical routing

5.6 ICMP: The Internet Control Message Protocol

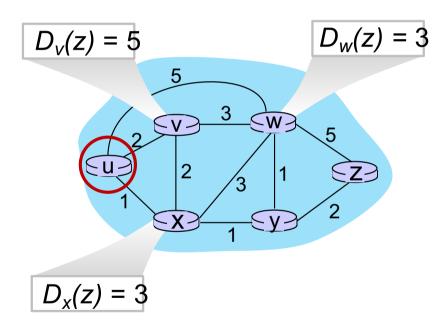
Distance vector algorithm

Based on Bellman-Ford (BF) equation (dynamic programming):



Bellman-Ford Example

Suppose that u's neighboring nodes, x,v,w, know that for destination z:



Bellman-Ford equation says:

$$D_{u}(z) = \min \{ c_{u,v} + D_{v}(z), c_{u,x} + D_{x}(z), c_{u,w} + D_{w}(z) \}$$

$$= \min \{ 2 + 5, 1 + 3, 5 + 3 \} = 4$$

node achieving minimum (x) is next hop on estimated least-cost path to destination (z)

Distance vector algorithm

key idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when x receives new DV estimate from any neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_{v} \{c_{x,v} + D_v(y)\}\$$
 for each node $y \in N$

 under minor, natural conditions, the estimate D_x(y) converge to the actual least cost d_x(y)

Distance vector algorithm:

each node:

wait for (change in local link cost or DV from neighbor)

recompute DV estimates using DV received from neighbor if DV to any destination has changed, notify neighbors

iterative, asynchronous: each local iteration caused by:

- local link cost change
- DV update message from neighbor

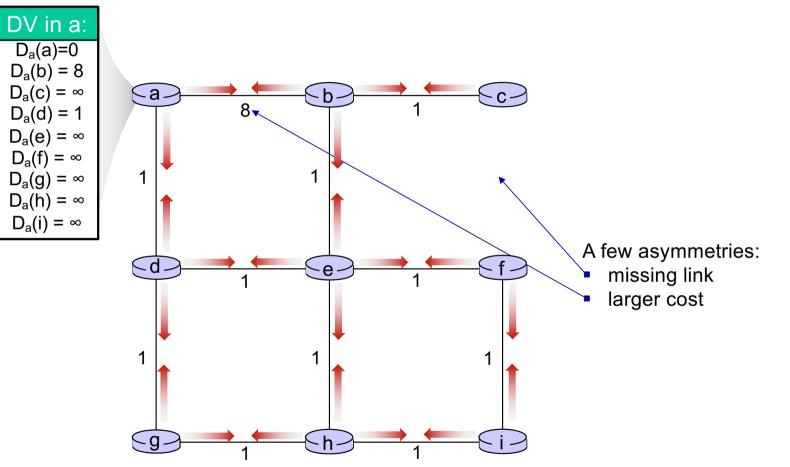
distributed, self-stopping: each node notifies neighbors only when its DV changes

- neighbors then notify their neighbors – only if necessary
- no notification received; no actions taken!

Distance vector: example

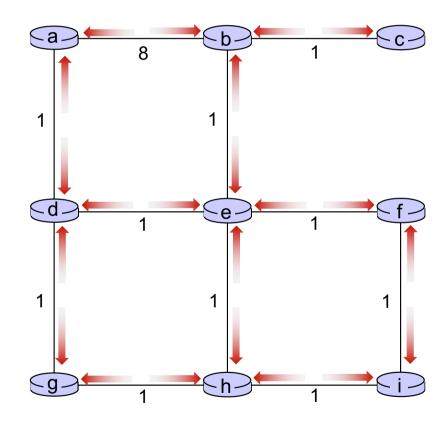


- All nodes have distance estimates to nearest neighbors (only)
- All nodes send their local distance vector to their neighbors



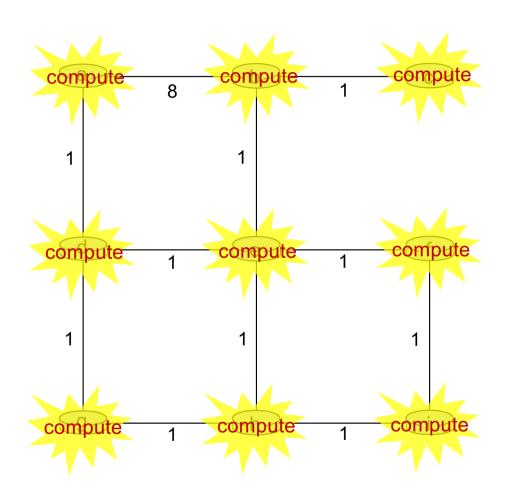


- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



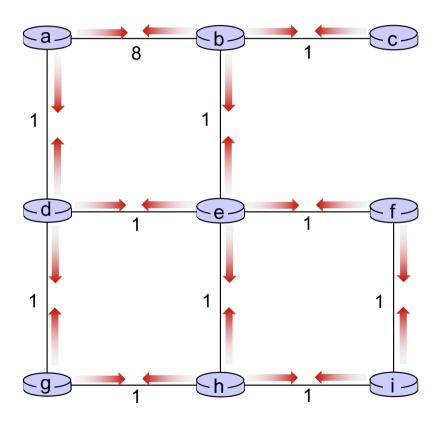


- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



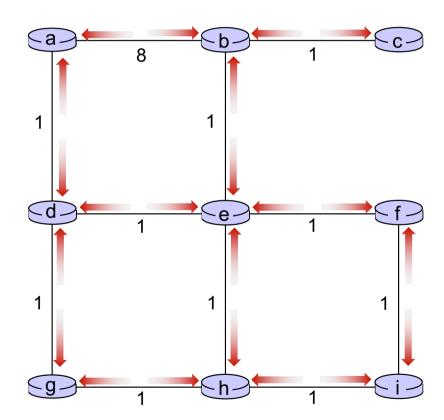


- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



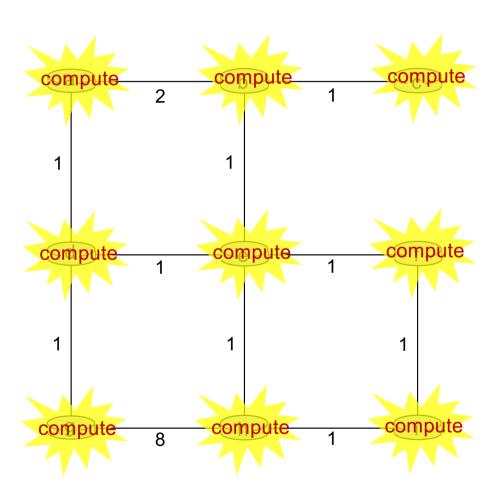


- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



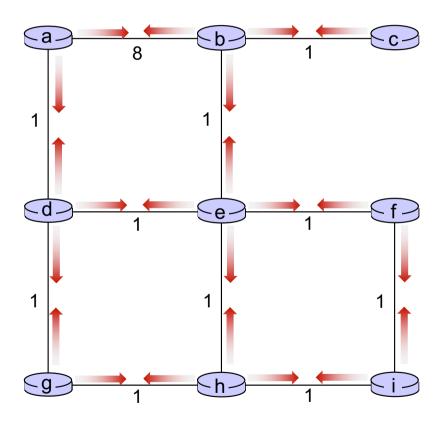


- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors





- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



.... and so on

Let's next take a look at the iterative computations at nodes

DV in a:

 $D_a(a)=0$ $D_a(b) = 8$ $D_a(c) = \infty$ $D_a(d) = 1$ $D_a(e) = \infty$

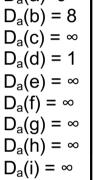
 $D_a(f) = \infty$

 $D_a(h) = \infty$

b receives DVs

from a, c, e

 $D_a(i) = \infty$



<a-

⊆g.

DV in b:

 $D_b(f) = \infty$ $D_{b}(a) = 8$ $D_b(c) = 1$ $D_b(g) = \infty$ $D_b(h) = \infty$ $D_b(d) = \infty$ $D_{b}(e) = 1$ $D_b(i)' = \infty$

-b-

DV in c:

 $D_c(a) = \infty$

 $D_{c}(b) = 1$

 $D_c(c) = 0$

 $D_c(d) = \infty$

 $D_c(e) = \infty$

 $D_c(f) = \infty$

 $D_c(g) = \infty$

 $D_c(h) = \infty$

 $D_c(i) = \infty$

DV in e:

 $D_e(a) = \infty$

 $D_{e}(b) = 1$

 $D_e(c) = \infty$

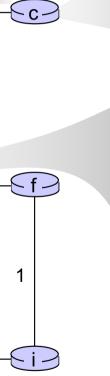
 $D_e(d) = 1$

 $D_{e}(e) = 0$ $D_e(f) = 1$

 $D_{e}(g) = \infty$

 $D_{e}(h) = 1$

 $D_e(i) = \infty$



1-1

b receives DVs from a, c, e, computes:



 $D_{a}(b) = 8$ $D_{a}(c) = \infty$ $D_{a}(d) = 1$ $D_{a}(e) = \infty$ $D_{a}(f) = \infty$

⊂a.

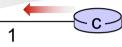
$$D_{a}(g) = \infty$$

$$D_{a}(h) = \infty$$

$$D_{a}(i) = \infty$$

DV in b:

$$\begin{array}{ll} D_b(a) = 8 & D_b(f) = \infty \\ D_b(c) = 1 & D_b(g) = \infty \\ D_b(d) = \infty & D_b(h) = \infty \\ D_b(e) = 1 & D_b(i) = \infty \end{array}$$



$D_b(e) = 1$ $D_b(i) =$

compute

DV in e:

DV in c:

 $D_c(a) = \infty$

 $D_{c}(b) = 1$

 $D_c(c) = 0$

 $D_c(d) = \infty$

 $D_c(e) = \infty$

 $D_c(f) = \infty$

 $D_c(g) = \infty$

 $D_c(h) = \infty$

 $D_c(i) = \infty$

$$D_e(a) = \infty$$

 $D_e(b) = 1$

$$D_{e}(c) = \infty$$

$$D_{e}(d) = 1$$

$$D_e(e) = 0$$

$$D_e(f) = 1$$

 $D_e(g) = \infty$

$$D_{e}(h) = 1$$

$$D_{e}(i) = \infty$$

$D_b(a) = \min\{C_{b,a} + D_a(a), C_{b,c} + D_c(a), C_{b,e} + D_e(a)\} = \min\{8, \infty, \infty\} = 8$
$D_b(c) = min\{c_{b,a} + D_a(c), c_{b,c} + D_c(c), c_{b,e} + D_e(c)\} = min\{\infty, 1, \infty\} = 1$
$D_b(d) = min\{c_{b,a} + D_a(d), c_{b,c} + D_c(d), c_{b,e} + D_e(d)\} = min\{9,2,\infty\} = 2$
$D_b(e) = min\{c_{b,a} + D_a(e), c_{b,c} + D_c(e), c_{b,e} + D_e(e)\} = min\{\infty, \infty, 1\} = 1$
$D_b(f) = \min\{c_{b,a} + D_a(f), c_{b,c} + D_c(f), c_{b,e} + D_e(f)\} = \min\{\infty, \infty, 2\} = 2$
$D_{b}(g) = \min\{c_{b,a} + D_{a}(g), c_{b,c} + D_{c}(g), c_{b,e} + D_{e}(g)\} = \min\{\infty, \infty, \infty\} = \infty$
$D_b(h) = min\{c_{b,a} + D_a(h), c_{b,c} + D_c(h), c_{b,e} + D_e(h)\} = min\{\infty, \infty, 2\} = 2$

 $D_b(i) = min\{c_{b,a} + D_a(i), c_{b,c} + D_c(i), c_{b,e} + D_e(i)\} = min\{\infty, \infty, \infty\} = \infty$

DV in b:

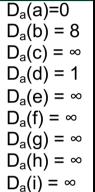
$$D_b(a) = 8$$
 $D_b(f) = 2$
 $D_b(c) = 1$ $D_b(g) = \infty$
 $D_b(d) = 2$ $D_b(h) = 2$
 $D_b(e) = 1$ $D_b(i) = \infty$

DV in b:

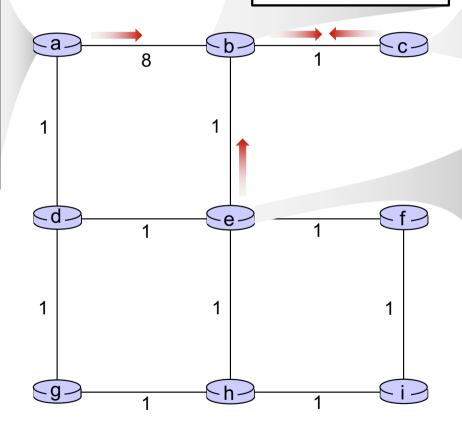
 $\begin{array}{ll} D_b(a)=8 & D_b(f)=\infty \\ D_b(c)=1 & D_b(g)=\infty \\ D_b(d)=\infty & D_b(h)=\infty \\ D_b(e)=1 & D_b(i)=\infty \end{array}$



c receives DVs from b



DV in a:



DV in c:

$$D_c(a) = \infty$$

$$D_{c}(b) = 1$$

$$D_c(c) = 0$$

$$D_c(d) = \infty$$

$$D_c(e) = \infty$$

$$D_c(f) = \infty$$

$$D_c(g) = \infty$$

$$D_c(h) = \infty$$

 $D_c(i) = \infty$

DV in e:

$$D_e(a) = \infty$$

$$D_{e}(b) = 1$$

$$D_e(c) = \infty$$

$$D_{e}(d) = 1$$

$$D_e(e) = 0$$

$$D_{e}(f) = 1$$

$$D_e(g) = \infty$$

$$D_{e}(h) = 1$$

$$D_e(i) = \infty$$

DV in b:

$D_{b}(a) = 8$	$D_b(f) = \infty$
$D_b(c) = 1$	$D_b(g) = \infty$
$D_b(d) = \infty$	$D_b(h) = \infty$
$D_{b}(e) = 1$	$D_b(i) = \infty$

compute

DV in c:

 $D_{c}(a) = \infty$ $D_{c}(b) = 1$

 $D_c(c) = 0$

 $D_c(d) = \infty$

 $D_c(e) = \infty$

 $D_c(f) = \infty$

 $D_c(g) = \infty$

 $D_c(h) = \infty$

 $D_c(i) = \infty$



c receives DVs from b computes:

$$D_c(a) = min\{c_{c,b}+D_b(a)\} = 1 + 8 = 9$$

$$D_c(b) = min\{c_{c,b}+D_b(b)\} = 1 + 0 = 1$$

$$D_c(d) = \min\{c_{c,b} + D_b(d)\} = 1 + \infty = \infty$$

$$D_c(e) = min\{c_{c,b}+D_b(e)\} = 1 + 1 = 2$$

$$D_c(f) = \min\{c_{c,b} + D_b(f)\} = 1 + \infty = \infty$$

$$D_c(g) = \min\{c_{c,b} + D_b(g)\} = 1 + \infty = \infty$$

$$D_c(h) = \min\{c_{bc,b} + D_b(h)\} = 1 + \infty = \infty$$

$$D_c(i) = \min\{c_{c,b} + D_b(i)\} = 1 + \infty = \infty$$

DV in c:

$$D_c(a) = 9$$

 $D_c(b) = 1$

$$D_{c}(c) = 0$$

$$D_c(d) = \infty$$

$$D_{c}(e) = 2$$

$$D_c(f) = \infty$$

 $D_c(g) = \infty$

$$D_c(g) = \infty$$

$$D_c(i) = \infty$$

⊂a-

DV in b:

$$\begin{array}{ll} D_b(a)=8 & D_b(f)=\infty \\ D_b(c)=1 & D_b(g)=\infty \\ D_b(d)=\infty & D_b(h)=\infty \\ D_b(e)=1 & D_b(i)=\infty \end{array}$$

- C -

DV in e:



$$D_{e}(c) = \infty$$

$$D_{e}(d) = 1$$

$$D_e(e) = 0$$

$$D_e(f) = 1$$

 $D_e(g) = \infty$

$$D_{e}(h) = 1$$

$$D_{e}(i) = \infty$$

DV in d:

$$D_{c}(a) = 1$$

$$D_c(b) = \infty$$

$$D_c(c) = \infty$$

$$D_c(d) = 0$$

$$D_{c}(e) = 1$$

$$D_c(f) = \infty$$

$$D_c(g) = 1$$

e receives DVs

from b, d, f, h

$$D_c(h) = \infty$$

$$D_c(i) = \infty$$

DV in h:

$$D_{c}(d) = \infty$$

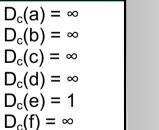
$$D_{c}(e) = 1$$

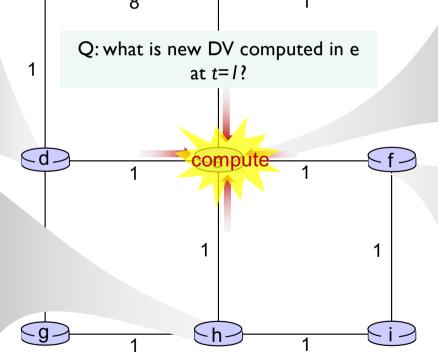
$$D_{c}(f) = \infty$$

$$D_c(g) = 1$$

$$D_{c}(h) = 0$$

 $D_{c}(i) = 1$





-b-

DV in f:

$$D_c(a) = \infty$$

$$D_c(b) = \infty$$

$$D_c(c) = \infty$$

$$D_c(d) = \infty$$

 $D_c(e) = 1$

$$D_{c}(e) = 1$$

 $D_{c}(f) = 0$

$$D_c(1) = 0$$

 $D_c(g) = \infty$

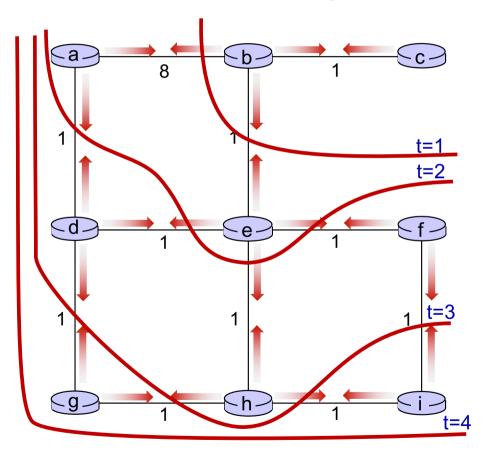
$$D_c(g)$$
 $D_c(h) = \infty$

$$D_c(i) = 1$$

Distance vector: state information diffusion

Iterative communication, computation steps diffuses information through network:

- t=0 c's state at t=0 is at c only
- c's state at t=0 has propagated to b, and may influence distance vector computations up to 1 hop away, i.e., at b
- c's state at t=0 may now influence distance vector computations up to **2** hops away, i.e., at b and now at a, e as well
- c's state at t=0 may influence distance vector computations up to **3** hops away, i.e., at b,a,e and now at c,f,h as well
- c's state at t=0 may influence distance vector computations up to **4** hops away, i.e., at b,a,e, c, f, h and now at g,i as well



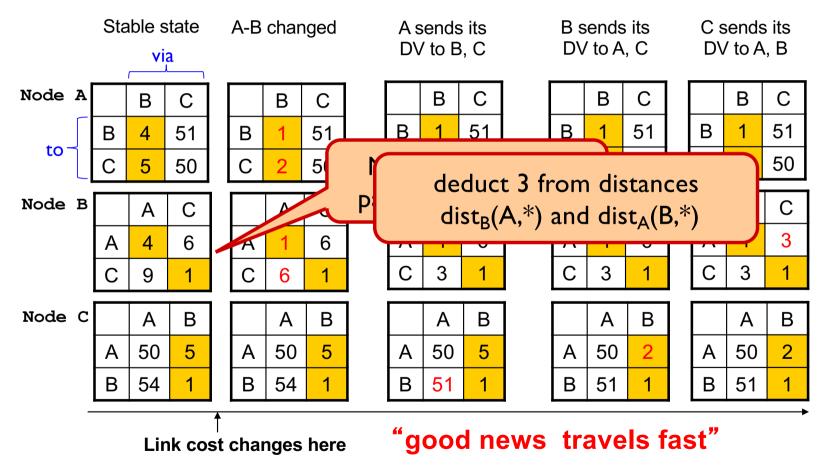
Problems with Distance Vector

- A number of problems can occur in a network using distance vector algorithm
- Most of these problems are caused by slow convergence or routers converging on incorrect information
- Convergence is the time during which all routers come to an agreement about the best paths through the internetwork
 - whenever topology changes there is a period of instability in the network as the routers converge
- Reacts rapidly to good news, but leisurely to bad news

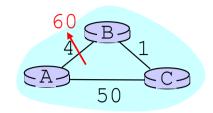
DV: Link Cost Changes

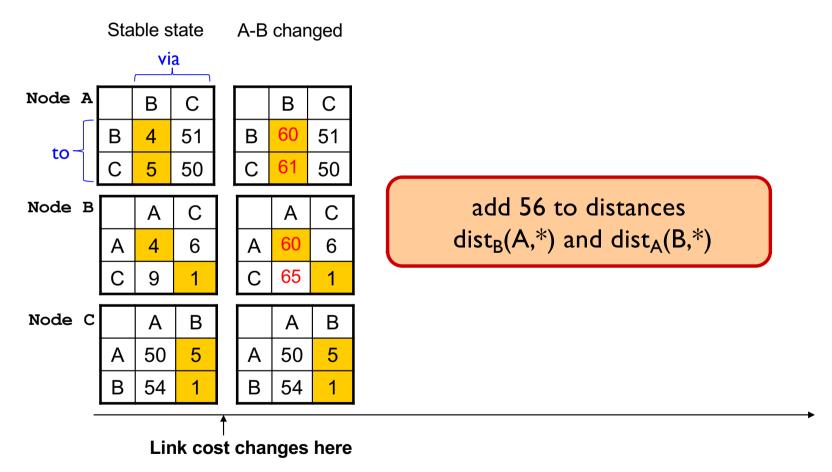
1 B 50

NOTE: DIFFERENT REPRESENTATION FROM BEFORE. YELLOW ENTRIES ARE THE DV

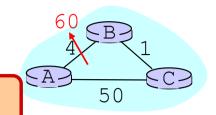


DV: Link Cost Changes

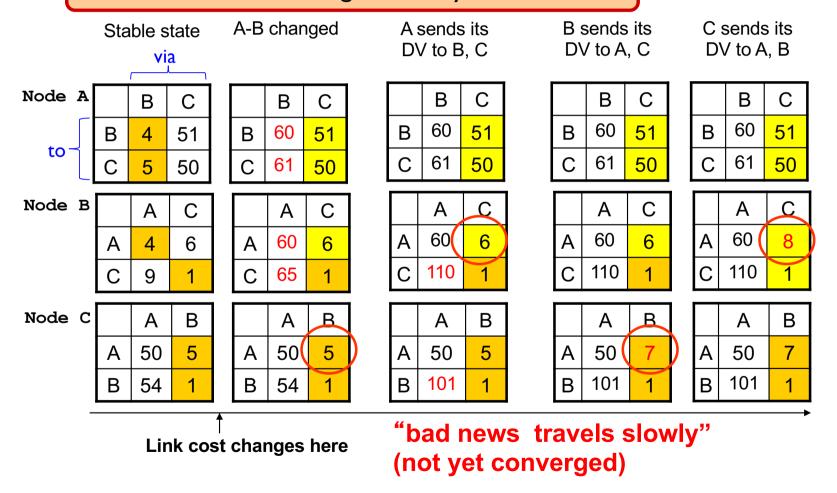




DV: Link Cost Changes

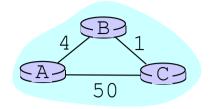


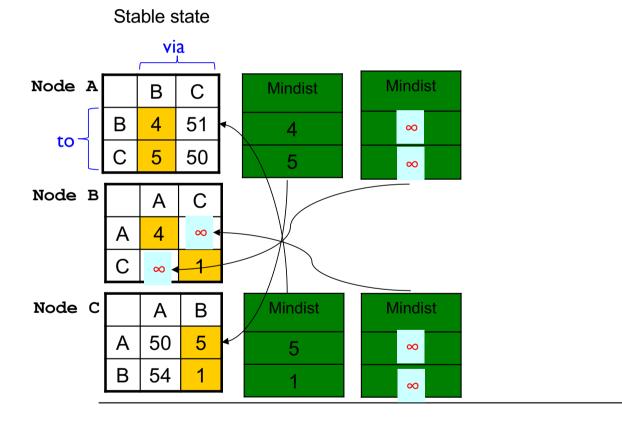
This is the "Counting to Infinity" Problem

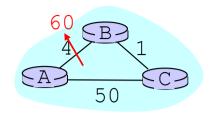


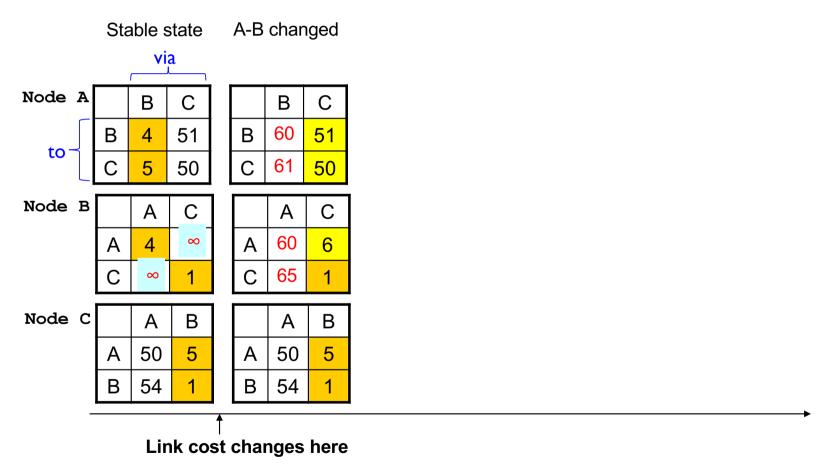
The "Poisoned Reverse" Rule

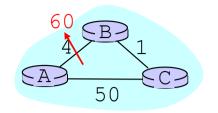
- Heuristic to avoid count-to-infinity
- If B routes via C to get to A:
 - B tells C its (B's) distance to A is infinite (so C won't route to A via B)

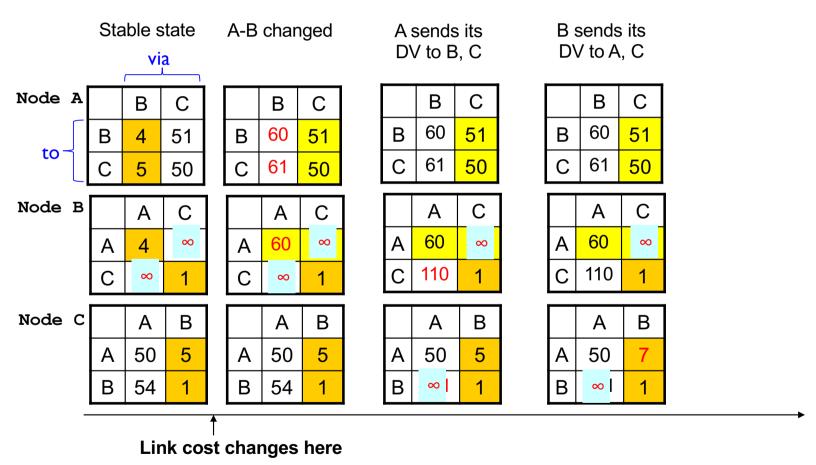


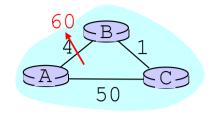


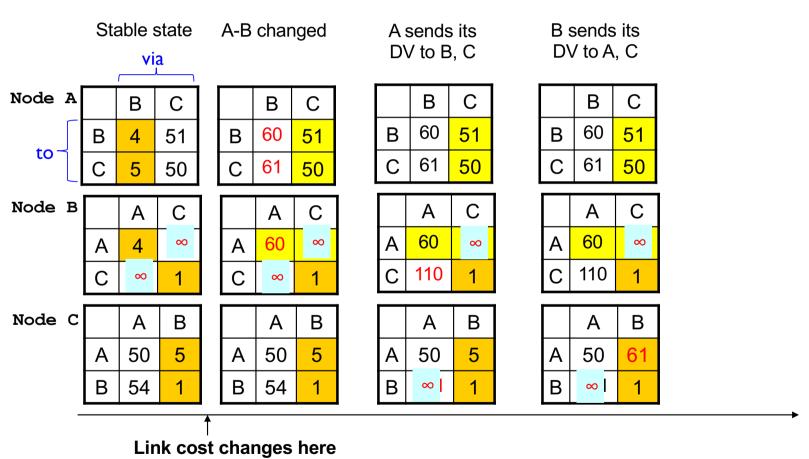


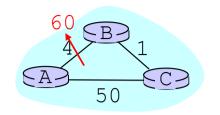


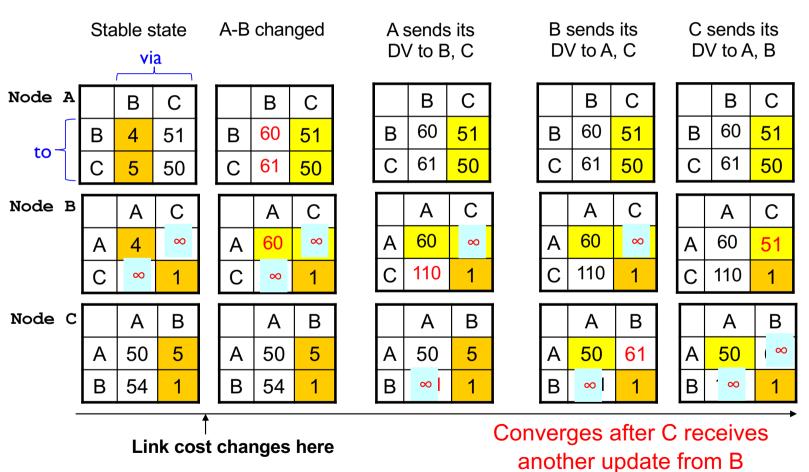




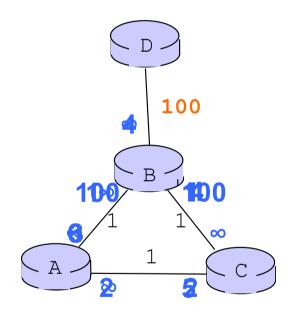








Will Poison-Reverse Completely Solve the Count-to-Infinity Problem?



Numbers in blue denote the best cost to destination D advertised along the link

Comparison of LS and DV algorithms

message complexity

LS: n routers, $O(n^2)$ messages sent

DV: exchange between neighbors; convergence time varies

speed of convergence

LS: $O(n^2)$ algorithm, $O(n^2)$ messages

may have oscillations

DV: convergence time varies

- may have routing loops
- count-to-infinity problem

robustness: what happens if router malfunctions, or is compromised?

LS:

- router can advertise incorrect link cost
- each router computes only its own table

DV:

- DV router can advertise incorrect path cost ("I have a really low cost path to everywhere"): black-holing
- each router's table used by others:
 error propagate thru network

Real Protocols

Link State

Open Shortest Path First (OSPF)

Intermediate system to intermediate system (IS-IS)

Distance Vector

Routing Information Protocol (RIP)

Interior Gateway Routing Protocol (IGRP-Cisco)

Border Gateway Protocol (BGP) - variant

Quiz: Link-state routing

- In link state routing, each node sends information of its direct links (i.e., link state) to ______?
- A. Immediate neighbours
- B. All nodes in the network
- C. Any one neighbor
- D. No one

www.pollev.com/salil

Quiz: Distance-vector routing

- In distance vector routing, each node shares its distance table with ?
- A. All Immediate neighbours
- B. All nodes in the network
- C. Any one neighbor
- D. No one

www.pollev.com/salil

Quiz: Distance-vector routing

- Which of the following is true of distance vector routing?
- A. Convergence delay depends on the topology (nodes and links) and link weights
- B. Convergence delay depends on the number of nodes and links
- C. Each node knows the entire topology
- D. A and C
- E. B and C

www.pollev.com/salil

Network layer, control plane: outline

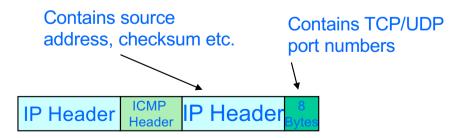
- 5.1 introduction
- 5.2 routing protocols
- link state
- distance vector
- hierarchical routing

5.6 ICMP: The Internet Control Message Protocol

Self study (not on exam)

ICMP: Internet Control Message Protocol

- Used by hosts & routers to communicate network level infromation
 - Error reporting: unreachable host, network, port
 - Echo request/reply (used by ping)
- Works above IP layer
 - ICMP messages carried in IP datagrams
- ICMP message: type, code plus IP header and first 8 bytes of IP datagram payload causing error



ICMP: Internet Control Message Protocol

Туре	Code	Description
0	0	echo reply(ping)
3	0	dest. network unreachable
3	1	dest host unreachable
3	3	dest port unreachable
3	4	frag needed; DF set
8	0	echo request(ping)
П	0	TTL expired
П	1	frag reassembly time exceeded
12	0	bad IP header

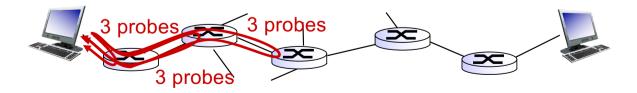
Traceroute and ICMP

- Source sends series of UDP segments to dest
 - first set has TTL = I
 - second set has TTL=2, etc.
 - unlikely port number
- When nth set of datagrams arrives to nth router:
 - router discards datagrams
 - and sends source ICMP messages (type II, code 0)
 - ICMP messages includes IP address of router

when ICMP messages arrives, source records RTTs

stopping criteria:

- UDP segment eventually arrives at destination host
- destination returns ICMP "port unreachable" message (type 3, code 3)
- source stops



Summary

- Network Layer: Data Plane
 - Overview
 - IP

- Network Layer: Control Plane
 - Routing Protocols
 - Link—state
 - Distance Vector
 - ICMP