Answer Set Programming

(4) ASP as modelling language

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COMP4418

Overview of the Lecture

- Semantics of ASP programs
- Extensions of ASP programs
- Handling of variables in ASP
- ASP as modelling language

ASP Modelling

$$c(r) \cdot c(g) \cdot c(b) \cdot e(1, 2) \cdot e(1, 3) \cdot e(1, 4) \cdot e(2, 4) \cdot e(2, 5) \cdot e(2, 6) \cdot e(4, 1) \cdot e(3, 4) \cdot e(3, 4) \cdot e(3, 4) \cdot e(3, 5) \cdot e(5, 3) \cdot e(5$$

Typical ASP structure:

- e(5,3). e(5,4). e(5,6). e(6,2). e(6,3). e(6,5). Problem instance: a set of facts
- Problem class: a set of rules.
 - Generator rules: often choice rules ${}^1\{m(X,C):c(C)\}$ ${}^1:=\nu(X)$.

:-e(X, Y), m(X, C), m(Y, C).

Ideal modeling is **uniform**: problem class encoding fits all instances

Semantically equivalent encodings may differ immensely in performance!

Tweety the penguin:

- (Normal) Birds fly.
- Penguins are abnormal.
- Tweety is a bird. So Tweety flies.
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$$S_1 = \{b(t), f(t)\} \quad \Rightarrow \quad P^{S_1} = \{f(t) \leftarrow b(t), \operatorname{not} a(t). \quad a(t) \leftarrow p(t). \quad b(t).\} \checkmark$$

$$S_2 = \{a(t), b(t), p(t)\} \quad \Rightarrow \quad P^{S_2} = \{f(t) \leftarrow b(t), \operatorname{not} a(t). \quad a(t) \leftarrow p(t). \quad b(t).\} \checkmark$$
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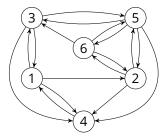
$$\begin{split} U &= \{ f(X) \leftarrow b(X), \text{not} \, a(X). \quad a(X) \leftarrow p(X). \quad b(t). \} \\ P &= \{ f(t) \leftarrow b(t), \text{not} \, a(t). \quad a(t) \leftarrow p(t). \quad b(t). \} \\ S_1 &= \{ b(t), f(t) \} \quad \Rightarrow \quad P^{S_1} = \{ f(t) \leftarrow b(t), \frac{\text{not} \, a(t)}{\text{not} \, a(t)}. \quad a(t) \leftarrow p(t). \quad b(t). \} \, \checkmark \\ S_2 &= \{ a(t), b(t), p(t) \} \quad \Rightarrow \quad P^{S_2} = \{ f(t) \leftarrow b(t), \frac{\text{not} \, a(t)}{\text{not} \, a(t)}. \quad a(t) \leftarrow p(t). \quad b(t). \} \, \checkmark \end{split}$$

$$\begin{array}{lll} S_1 = \{b(t), f(t)\} & \Rightarrow & (P \cup \{p(t).\})^{S_1} = P_2^{S_1} \cup \{p(t).\} & \\ S_2 = \{a(t), b(t), p(t)\} & \Rightarrow & (P \cup \{p(t).\})^{S_2} = P_2^{S_1} \cup \{p(t).\} & \\ & \forall \\ & \text{Tweety doesn't fly.} \end{array}$$

Example: Hamilton Cycle

Definition: Hamilton cycle problem

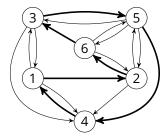
Input: graph with vertex set V and edges $E \subseteq V \times V$. Is there a cycle that visits every vertex exactly once?



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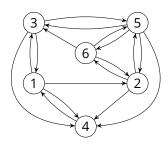
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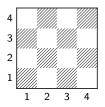


$$\begin{split} &\{p(X,Y)\} \leftarrow e(X,Y).\\ &r(X) \leftarrow p(1,X).\\ &r(Y) \leftarrow r(X), p(X,Y).\\ &\leftarrow 2 \ \{p(X,Y)\} \ , \nu(X).\\ &\leftarrow 2 \ \{p(X,Y)\} \ , \nu(Y).\\ &\leftarrow \operatorname{not} r(X), \nu(X). \end{split}$$

Example: *N*-Queens

Definition: *N*-queens problem

Place N queens on a $N \times N$ chessboard so that they do not attack each other, i.e., share no row, column, or diagonal.

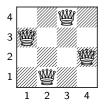


Program on paper

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