

APPENDIX A  
PROOF OF LEMMA 1

*Proof.* Since  $G(V, E, F)$  is modeled as the realistic road map, the feasible paths to reach the target position must be found.

Therefore, we denote the paths from the source  $s$  to the destination  $d$  as:

$$L_{sd} = \{l_{sd}^1, l_{sd}^2, \dots, l_{sd}^n\}, \quad n > 0 \quad (1)$$

where  $n$  represents the number of paths. As for  $L_{sd}$  we have:

$$l_{max} = \max(l_{sd}^k), \quad k = 1 \dots n \quad (2)$$

since the condition  $n > 0$  is always valid. Hence for any path from  $s$  to  $d$  has the longest length  $l_{max}$ .  $\square$

APPENDIX B  
PROOF OF LEMMA 2

*Proof.* According to the principle of relax operation, we can learn: only when  $N_Q(x) \cdot \text{dist} + w(x, v) < N_Q(v) \cdot \text{dist}$ , for  $x \in v$  .preds  $Q_R$  will update  $N_Q(v) \cdot \text{dist}$  and  $N_Q(v) \cdot s \cdot p$ . Based on this equation, we prove:

Case 1  $\Delta w(u, v) > 0$

Since  $w(u, v)$  is increased, Eq.(B) is certainly not satisfied. Thus  $Q_R$  remains self-ordered and no changes will occur in  $Q$ , only  $w(u, v)$  will update to  $w'(u, v)$ .

Case 2  $\Delta w(u, v) < 0$

If  $w'(u, v)$  cannot satisfy Eq.(B), it is the same situation with Case 1. Else, if satisfying, through  $w'(u, v)$  we can obtain the updated value:

$$N_Q(v) \cdot \text{dist} = N_Q(u) \cdot \text{dist} + w'(u, v) \quad \square$$

APPENDIX C  
PROOF OF LEMMA 3

*Proof.* We use  $\text{dist}_{\min}(v)$  to denote the minimum value currently calculated from  $V_s$  to  $v$ . According to the meaning of  $N_T(v) \cdot \text{dist}$ , the value is always keep in accordance with  $\text{dist}_{\min}(v)$ . Based on these characteristics, we prove:

$N_T(v) \cdot \text{dist}$ . Therefore:

$$\begin{aligned} \text{dist}_{\min}(v) &= N_T(v) \cdot \text{dist} \\ &\leq N_T(u) \cdot \text{dist} + w(u, v) \end{aligned}$$

Assume that we update  $\text{dist}_{\min}(v)$  to  $\text{dist}'_{\min}(v)$  instead of doing nothing:  $\text{dist}'_{\min}(v) = N_T(u) \cdot \text{dist} + w'(u, v)$  However,  $\text{dist}'_{\min}(v) > N_T(u) \cdot \text{dist} + w(u, v)$

currently  $\text{dist}_{\min}(v) > \text{dist}'_{\min}(v)$ , there is no need to update the value, hence violating our assumption. Case &  $\Delta w(u, v) < 0$ : When  $N_T(u) \cdot \text{dist} + w'(u, v) < N_T(v) \cdot \text{dist}$ , it will trigger rollback operation, modifying relevant values to maintain  $\text{dist}_{\min}(v) = N_T(v) \cdot \text{dist}$ .

Therefore, there has  $N'_T(v) \cdot \text{dist} = N_T(u) \cdot \text{dist} + w'(u, v)$ . Assume the current time  $t_c$ ,  $t_e > N_T(v) \cdot t$ . Hence:  $T = T + v \cdot \text{succes}$ , for  $t \in [N_T(v) \cdot t, t_e]$  At  $t_c$ ,  $N_T(v) \cdot \text{dist}$  has updated to  $N'_T(v) \cdot \text{dist}$ .  $x \in v \cdot \text{succes}$  satisfies the relax condition Eq.(30), the rollback operation will be performed as follows:

$$N_T(x) \cdot \text{dist} \leftarrow N'_T(x) \cdot \text{dist}, \quad \text{for } x \in v \cdot \text{succes}$$

Hence the proof is complete.  $\square$