

# CSE330(Numerical Methods)

## LECTURE 11 – ROOTS OF EQUATIONS

[OPEN METHODS: SECANT METHOD]

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# Secant Method: Overview

- ❑ **Secant method** is an extension to the **Newton-Raphson method**.
- ❑ The Newton-Raphson formula from lesson 10 is –

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)} \dots\dots\dots(1)$$

The value of derivative  $[f'(x_i)]$  can be determined using **first order backward divided difference formula** from lesson 4 as follows-

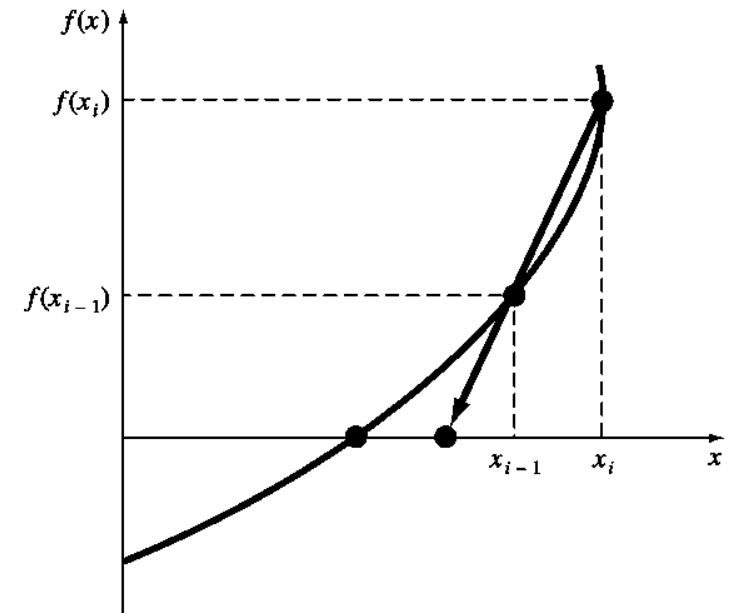
$$f'(x_i) \cong \frac{f(x_{i-1}) - f(x_i)}{x_{i-1} - x_i} \dots\dots\dots(2)$$

Substituting the value from equation (2) into equation (1), we get-

$$x_{i+1} = x_i - \frac{f(x_i)(x_{i-1} - x_i)}{f(x_{i-1}) - f(x_i)} \dots\dots\dots(3)$$

# Secant Method: Overview

- ❑ Equation (3) is referred to as the **Secant Formula**. It is also called **linear interpolation method**.
- ❑ Notice that the approach requires two initial estimates of  $x$ . However, because  $f(x)$  is not required to change signs between the estimates, it is not classified as a bracketing method.
- ❑ The name '**Secant Formula**' is derived from the fact that at the initial starting point( $x_i$ ), we draw a secant through the function. The secant intersects the  $x$ -axis at point ( $x_{i+1}$ ), which is referred to as the next approximation of root. In **Newton-Raphson** formula, this was a tangent line; not a secant line.
- ❑ The Secant formula can be derived using the slope information of the secant line. **Try to derive it.**



# Secant Method: Algorithm

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## □ Step 1:

Take two initial guesses, such as  $x_i$  and  $x_{i-1}$

## □ Step 2:

Find out the new approximation of the root ( $x_{i+1}$ ) with the following formula-

$$x_{i+1} = x_i - \frac{f(x_i)(x_{i-1} - x_i)}{f(x_{i-1}) - f(x_i)}$$

## □ Step 3: Calculate relative percentage error with the formula –

$$\epsilon_a = \left| \frac{x_{i+1} - x_i}{x_{i+1}} \right| \times 100 \%$$

## □ Step 4:

--> If  $\epsilon_a < \epsilon_s$ , terminate the calculation.  $x_{i+1}$  is the estimated root.

--> If  $\epsilon_a > \epsilon_s$ , set  $x_i = x_{i+1}$  and  $x_{i-1} = x_i$ ; go to step 2.



# Secant Method: Example

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## □ Example 1:

Use the Secant method to estimate the root of  $f(x) = e^{-x} - x$ , employing an initial guess of  $x_0=1$  and  $x_{-1} = 0$ .

## Solution:

The solution process is same as that for the Newton-Raphson method, except there are two starting points and the secant formula is used for approximating the root. Try to solve the problem!

**Q:** Although the secant method may be divergent, when it converges it usually does so at a quicker rate than the false-position method. Can you find out the difference between False-Position Method and the Secant method although they both require two starting points?



# Modified Secant Method: Overview

- ❑ Rather than using two arbitrary values to estimate the derivative, an alternative approach involves a fractional perturbation of the independent variable to estimate  $f'(x)$ -

$$f'(x_i) \cong \frac{f(x_i + \delta x_i) - f(x_i)}{\delta x_i} \dots\dots\dots(4)$$

where  $\delta$  = a small perturbation fraction. This approximation can be substituted into Eq. (1) to yield the following iterative equation-

$$x_{i+1} = x_i - \frac{\delta x_i f(x_i)}{f(x_i + \delta x_i) - f(x_i)} \dots\dots\dots(5)$$

- ❑ **Modified Secant Method** is interesting, because now it requires one single starting point, rather than two in the **Original Secant Method**.



# Modified Secant Method: Example

□ Use the modified secant method to estimate the root of  $f(x) = e^{-x} - x$ . Use a value of 0.01 for  $\delta$  and start with  $x_0 = 1.0$ . Recall that the true root is 0.56714329...

□ Solution:

Iteration 1:

Here, we will be using **True Percentage Relative Error** ( $\epsilon_t$ ) since we know the true value of the root.

$$x_0 = 1 \qquad f(x_0) = -0.63212$$

$$x_0 + \delta x_0 = 1.01 \qquad f(x_0 + \delta x_0) = -0.64578$$

$$x_1 = 1 - \frac{0.01(-0.63212)}{-0.64578 - (-0.63212)} = 0.537263 \qquad |\epsilon_t| = 5.3\%$$



# Modified Secant Method: Example

## Iteration 2:

$$x_0 = 0.537263$$

$$f(x_0) = 0.047083$$

$$x_0 + \delta x_0 = 0.542635$$

$$f(x_0 + \delta x_0) = 0.038579$$

$$x_1 = 0.537263 - \frac{0.005373(0.047083)}{0.038579 - 0.047083} = 0.56701 \quad |\epsilon_t| = 0.0236\%$$

## Iteration 3:

$$x_0 = 0.56701$$

$$f(x_0) = 0.000209$$

$$x_0 + \delta x_0 = 0.572680$$

$$f(x_0 + \delta x_0) = -0.00867$$

$$x_1 = 0.56701 - \frac{0.00567(0.000209)}{-0.00867 - 0.000209} = 0.567143 \quad |\epsilon_t| = 2.365 \times 10^{-5}\%$$





# Modified Secant Method: Choosing $\delta$

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- ❑ The choice of a proper value for  $\delta$  is not automatic. If  $\delta$  is too small, the method can be swamped by round-off error caused by subtractive cancellation in the denominator of Eq. (5).
- ❑ If it is too big, the technique can become inefficient and even divergent.
- ❑ However, if chosen correctly, it provides a nice alternative for cases where evaluating the derivative is difficult and developing two initial guesses is inconvenient.



# Conclusion

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- In this lesson, we have
  - learnt **Secant Method**, one of the most widely used root finding method next to Newton-Raphson Method.
  - developed the algorithm for implementing the method.
  - Known about an alternative version of Secant Method, named '**Modified Secant Method**'. The modified version is useful, because it involves single starting point and it does not require calculating complex derivative.
- ❖ Please try out the MATLAB code of Secant method and Modified Secant Method.

**In the next lesson, we will learn about an extension of Secant method, names as “Inverse Quadratic Interpolation Method (IQIM)”**



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# Thank You