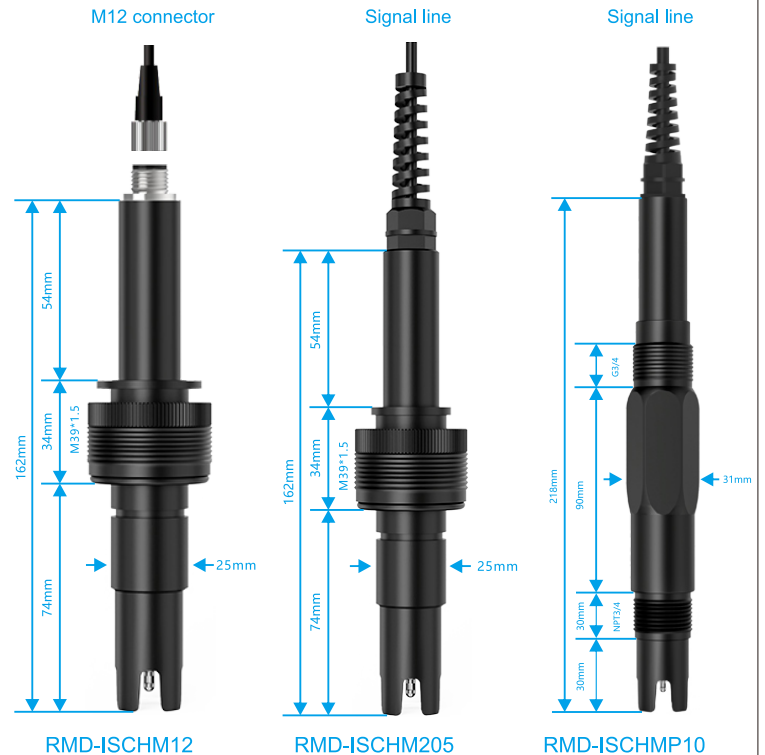


1. Technical data

Measuring range	0...2; 0....20mg/l(ppm)
Principle	Constant voltage principle
Accuracy	2% or ± 10 ppb HOCl
Temperature range	0.0...60.0°C
Response time	90% < 90 seconds
Pressure range	< 1bar
Calibration method	Laboratory comparison method
Calibration point	2-point calibration
Flow rate	15...30L/H(flow cell install)
Shell material	ABS, PPS
PH range	5-9pH
Thread	M39*1.5, 3/4
Sensor top material	Two platinum rings
Power supply	DC9...30V (recommend DC12V)
Output signal	RS485(MODBUS-RTU), 4-20mA
Cable length	5 m,10m or customize
Electrical connection	pin type
Protection grade	Ip68

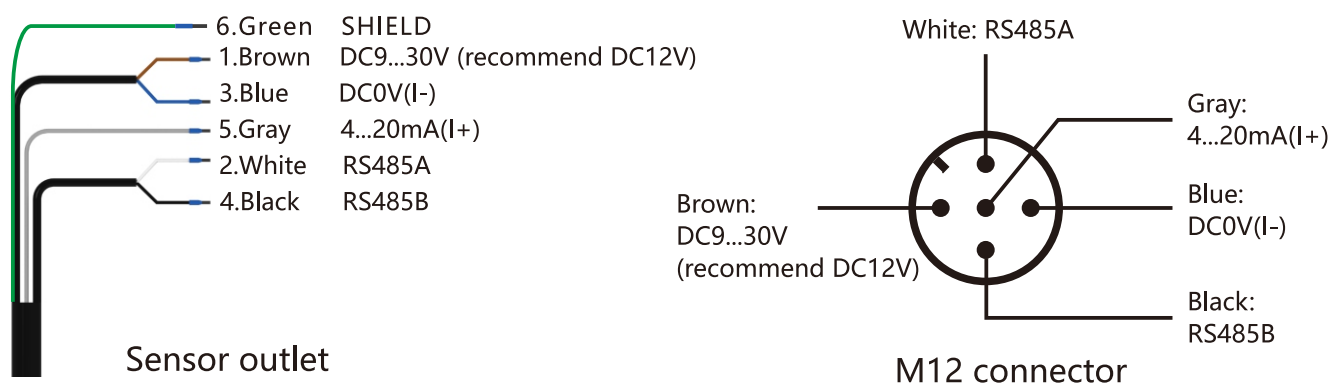


2. Before use

- 2.1 Please read this instruction carefully before use.
- 2.2 The platinum ring of the sensor is a vulnerable item, it cannot be repaired if it is damaged.
- 2.3 Before using the sensor, the protective cover should be gently removed.
- 2.4 In the measurement process, if there is dirt, adhesive or encrust on the probe , the measured value would be inaccurate or fluctuate. The sensor should be cleaned and calibrated in time.
- 2.5 If there are bubbles at the platinum ring sensing point, it will cause inaccurate or fluctuate measurement value.

3. Sensor wiring

- 3.1 Please follow the instructions carefully, the wrong wiring will damage the product completely.
- 3.2 Please carefully check all the wiring in the system and confirm that the wiring is complete right before switch on the power.
- 3.3 Note: RS485A line and RS485B line are strictly forbidden to contact with the power supply line, otherwise the communication of the sensor will be permanently damaged.



4. Sensor activation

4.1 The sensor needs to be activated in 3 M KCL solution.

5. Sensor calibration

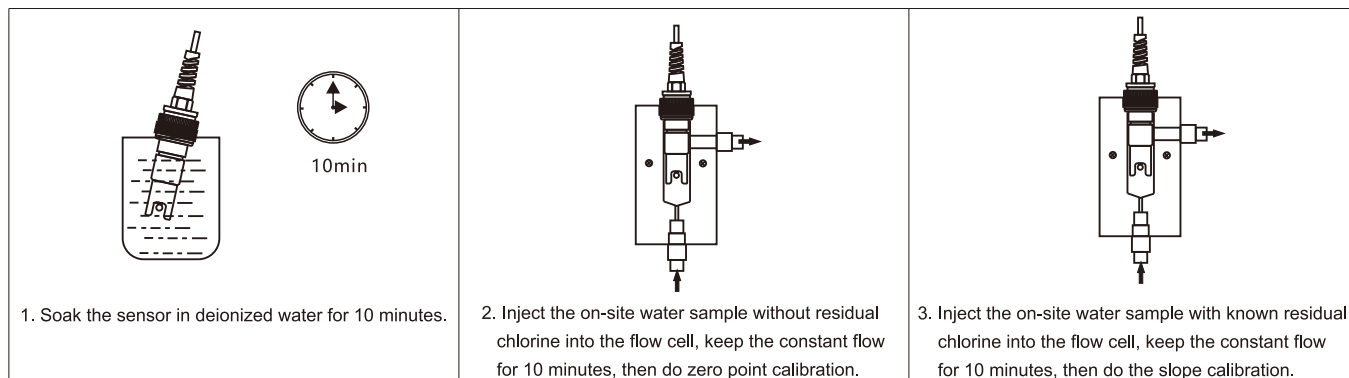
5.1 It is recommended that users be put into use after calibration.

5.2 It is recommended to use the laboratory comparison method for calibration when calibrating.

5.3 The sensor should be calibrated in the actual water sample.

5.4 It is recommended that users calibrate once every 1 to 2 months.

5.5 The calibration steps are shown in the figure.

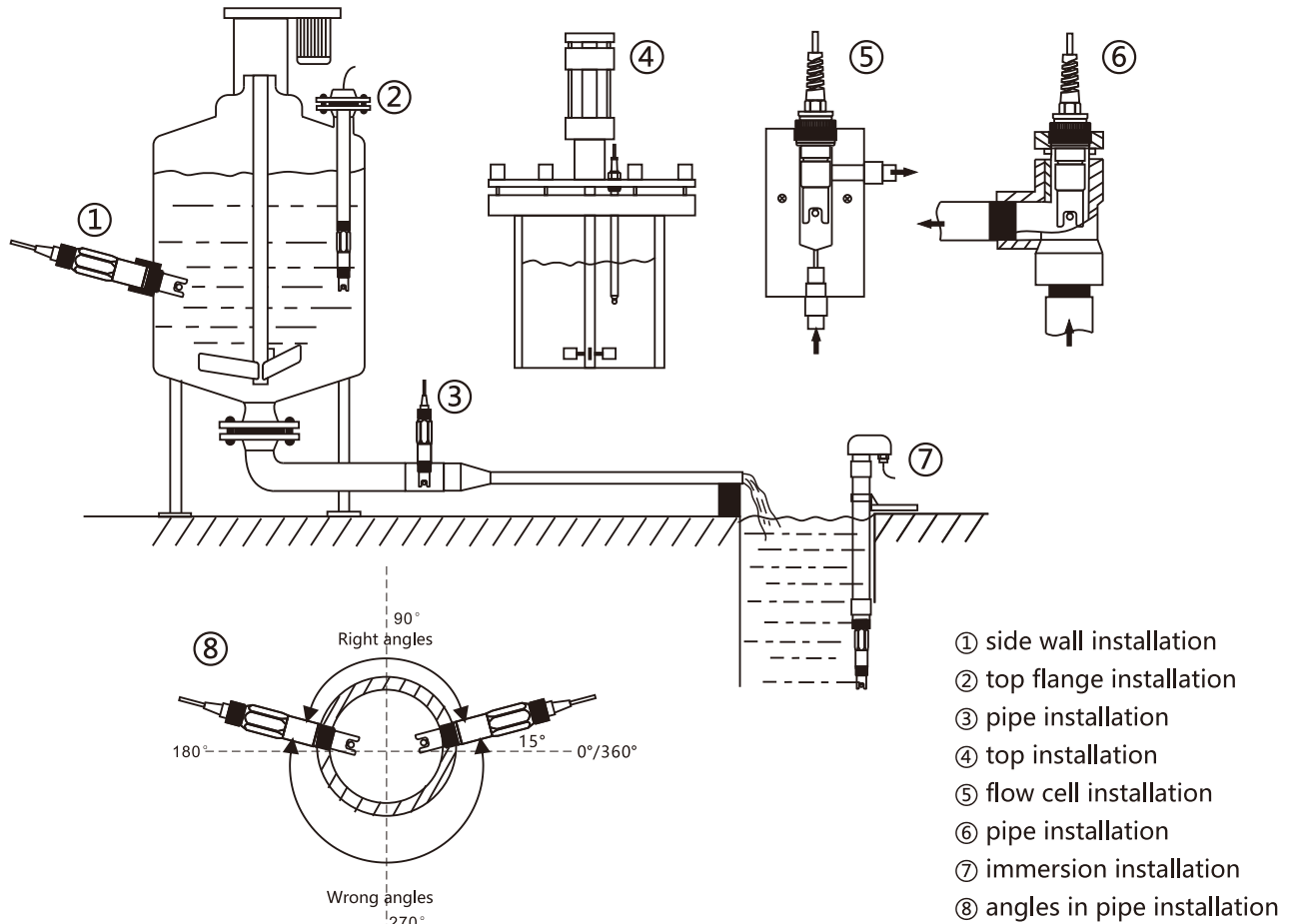


6. Sensor installation

6.1 The chlorine sensor is recommended to be installed in the flow cell for more stable and accurate measurement.

6.2 If installing sensor in the pipe, the right angle should be $15^{\circ}\sim 165^{\circ}$.

6.3 Installation method.



Pay attention to the immersion installation:

1. In this installation, there will be dirt on the sensor frequently, it needs to be cleaned regularly.
2. Measuring value is not stable.
3. Different insertion depths will affect the measured value.
4. The position of the sensor must be above the sediment.

7. Sensor communication

7.0 Default communication instructions:

- Note: 1. Data starting at 0x represents hexadecimal;
 2. The check code is 16CRC, the low byte is in the front and the high byte is in the back;
 3. Floating point number occupy four bytes;

7.1 Communication description (factory default):

Factory default	
Baud rate	9600 (default)
Data bit	8
Stop bit	1
Check bit	no
Address	1 (default)

7.2 Host computer transmission format:

	Data type	Description	Remarks
Integer	16 bit integer	The high and low bytes of the word component are not reversed	Example: 0x 0032 to decimal number is 50
Floating point number	(CDAB) 3412	The high-low word of the double-byte component is reversed, but the high-low byte of the word is not reversed.	Example: 72 37 41 DB transfer to floating point number, CDAB change order is ABCD, ie 41 DB 72 37 transfer to floating point is 27.4

7.3 Function code description

7.3.1 This product supports 03,06,16 and other common function codes

7.3.2 The output register uses 16 function codes when writing double word data or writing multiple data in batches

03	Read single or multiple registers
06	Write single register
16	Write multiple registers

7.4 Read floating point number

7.4.1 Host computer transmission format:

	ID address	Function code	Register start address		Qty of registers		CRC16	
			High byte	Low byte	High byte	Low byte	Low byte	High byte
Example 1 Read measured value	0x 01	0x 03	0x 00	0x 01	0x 00	0x 02	0x 95	0x CB
Example 2 Read Temp value	0x 01	0x 03	0x 00	0x 03	0x 00	0x 02	0x 34	0x 0B

7.4.2 Slave computer response format:

	ID address	Function code	Qty of registers	Read register data in hexadecimal floating point number				CRC16	
				C	D	A	B	Low byte	High byte
Example 1 Measured value return	0x 01	0x 03	0x 04	0x 2C	0x 81	0x 40	0x 91	0x 52	0x E7
Example 2 Temp value return	0x 01	0x 03	0x 04	0x 72	0x 37	0x 41	0x DB	0x 20	0x 8E

Note: 72 37 41 DB transfer to floating point number, CDAB change order is ABCD, ie 41 DB 72 37 transfer to floating point is 27.4.

7.5 Read integer

7.5.1 Host computer transmission format:

	ID address	Function code	Register start address		Qty of registers		CRC16	
			High byte	Low byte	High byte	Low byte	Low byte	High byte
Example 1 Read warning status	0x 01	0x 03	0x 00	0x 07	0x 00	0x 01	0x 35	0x CB

7.5.2 Slave computer response format:

	ID address	Function code	Qty of registers	Read register data in hexadecimal integer		CRC16	
				A	B	Low byte	High byte
Example 1 Warning status return	0x 01	0x 03	0x 02	0x 00	0x 00	0x B8	0x 44

7.6 Write floating point number

7.6.1 Host computer transmission format:

	ID address	Function code	Register start address		Qty of registers		Qty of bytes	Write register data in hexadecimal floating point number				CRC16	
			High byte	Low byte	High byte	Low byte		C	D	A	B	Low byte	High byte
Example 1 Write Measured value offset	0x 01	0x 10	0x 00	0x 12	0x 00	0x 02	0x 04	0x 00	0x 00	0x 3F	0x 80	0x 63	0x 2A

7.6.2 Slave computer response format:

	ID address	Function code	Register start address		Qty of registers		CRC16	
			High byte	Low byte	High byte	Low byte	Low byte	High byte
Example 1 Measured value offset return	0x 01	0x 10	0x 00	0x 12	0x 00	0x 02	0x E1	0x CD

Note: the measured value is offset by 1.00, floating point number 1.00 converts to hexadecimal 0X3F800000, transpose the high and low positions 0X00003F80 and write 0X0012.

7.7 Write integer

7.7.1 Host computer transmission format:

	ID address	Function code	Register start address		Write register data in hexadecimal integer		CRC16	
			High byte	Low byte	A	B	Low byte	High byte
Example 1 Write device address	0x 01	0x 06	0x 00	0x 19	0x 00	0x 02	0x D9	0x CC

7.7.2 Slave computer response format:

	ID address	Function code	Register start address		Write register data in hexadecimal integer		CRC16	
			High byte	Low byte	A	B	Low byte	High byte
Example 1 Device address return	0x 01	0x 06	0x 00	0x 19	0x 00	0x 02	0x D9	0x CC

Note: change the local computer address 1 to address 2 and write the hexadecimal number 0x 00 02 into register 0x 00 19.

7.8 Calibrating instructions

7.8.1 Before calibration

Write the free chlorine calibration value to the sensor before calibration;

If the calibration is 1.0mg/L, write the current data to the 0x24 register;

(Floating point 1.0 to hexadecimal number is 3F800000, high and low transposition is 00003F80);

Send command : 01 10 00 24 00 02 04 00 00 3F 80 E0 14.

7.8.2 The first point Zero calibration:

The sensor is cleaned and dried and put into the free chlorine 0mg/L solution;

Send command : 01 03 00 66 00 01 64 15;

After the measured AD value is stable, read the AD value in the 0x66 register;

Write the instruction to confirm the calibration to the 0x 3E register;

Send command: 01 06 00 3E 00 FF A8 46.

7.8.3 The second point High point standard calibration:

The sensor is cleaned and dried and put into the free chlorine 1.0mg/L solution;

Send command : 01 03 00 66 00 01 64 15;

After the measured AD value is stable, read the AD value in the 0x66 register;

Write the instruction to confirm the calibration to the 0x 3F register;

Send command : 01 06 00 3F 00 FF F9 86;

The free chlorine sensor generally only needs to calibrate the high point, and may also calibrate both of the high and low points.

End of calibration

7.9 Address description

Name	Hosting number	Data type	Length	Read/write	Description
Measurements	0X 00 01	floating point	2	read	Storage location for measured value
Temperature measurement	0X 00 03	floating point	2	read	Storage location for measured temperature
Current output value	0X 00 05	floating point	2	read	Output current based on FCL measurements
Warning	0X 00 07	Integer	1	read	01: Measurement exceeds the upper limit; 02: Measurement exceeds the lower limit 03: Temperature exceeds the upper limit; 04: Temperature exceeds the lower limit
Upper limit of measurement	0X 00 0A	floating point	2	read/write	Upper limit of measured value (20mA corresponding value)
Lower limit of measurement	0X 00 0C	floating point	2	read/write	Lower limit of measurement value (4mA corresponding value)
Upper temperature limit	0X 00 0E	floating point	2	read/write	Upper temperature limit
Lower temperature limit	0X 00 10	floating point	2	read/write	Lower temperature limit
Measured value offset	0X 00 12	floating point	2	read/write	Adjust measurement
Temperature offset	0X 00 14	floating point	2	read/write	Adjust temperature value
Damping coefficient	0X 00 16	Integer	1	read/write	0-10
Device address	0X 00 19	Integer	1	read/write	1-255
Baud rate	0X 00 1A	Integer	1	read/write	0=2400, 1=4800, 2=9600 3=19200, 4=38400
Restore default	0X 00 1B	Integer	1	write	
Standard solution value	0X 00 24	floating point	2	read/write	
PH compensation	0X 00 26	floating point	2	read/write	
Manual temperature	0X 00 3A	floating point	2	read/write	25°C
Zero calibration	0X 00 3E	Integer	1	write	
Slope calibration	0X 00 3F	Integer	1	write	
Measured AD	0X 00 66	Integer	1	read	

Note: When reading register data, do not continuously read more than 20 registers, the address register that does not list prohibits read and write data.

7.10 Common instruction examples

	Function	Send command	Return command	Remarks
1	Read measured value	01 03 00 01 00 02 95 CB	01 03 04 2C 81 40 91 52 E7	The 2C814091 change order to 40912C81 and its floating point is 4.53
2	Read temperature measurement	01 03 00 03 00 02 34 0B	01 03 04 72 37 41 DB 20 8E	The 723741DB change order to 41DB7237 and its floating point is 27.4
3	Read current output value	01 03 00 05 00 02 D4 0A	01 03 04 00 00 41 40 CB 93	The 00004140 change order to 41400000 and its floating point is 12.00
4	Read warning	01 03 00 07 00 01 35 CB	01 03 02 00 00 B8 44	0000 is the current normal state
5	Write measurement mode	01 06 00 08 00 01 C9 C8	01 06 00 08 00 01 C9 C8	Set to residual chlorine mode
6	Write upper limit of measurement	01 10 00 0A 00 02 04 00 00 41 20 42 58	01 10 00 0A 00 02 61 CA	The upper measurement limit is set to 10.00
7	Write lower limit of measurement	01 10 00 0C 00 02 04 00 00 3F 80 E3 AA	01 10 00 0C 00 02 81 CB	The lower measurement limit is set to 1.00
8	Write upper temperature limit	01 10 00 0E 00 02 04 00 00 42 C8 43 15	01 10 00 0E 00 02 20 0B	The upper temperature limit is set to 100.00
9	Write lower temperature limit	01 10 00 10 00 02 04 00 00 40 A0 C3 1B	01 10 00 10 00 02 40 0D	The lower temperature limit is set to 5.00
10	Write measured value offset	01 10 00 12 00 02 04 00 00 3F 80 63 2A	01 10 00 12 00 02 E1 CD	Set to 1.00
11	Write temperature offset	01 10 00 14 00 02 04 00 00 3F 80 E3 00	01 10 00 14 00 02 01 CC	Set to 1.00
12	Write damping coefficient	01 06 00 16 00 01 A9 CE	01 06 00 16 00 01 A9 CE	Set to 1
13	Write device address	01 06 00 19 00 02 D9 CC	01 06 00 19 00 02 D9 CC	Set to 2
14	Write baud rate	01 06 00 1A 00 00 A8 0D	01 06 00 1A 00 00 A8 0D	Set to 2400
15	Write restore default	01 06 00 1B 00 FF B9 8D	01 06 00 1B 00 FF B9 8D	Factory default values are restored after sent
16	Write manual temperature	01 10 00 3A 00 02 04 00 00 41 A0 40 EC	01 10 00 3A 00 02 61 C5	Set to 20.0
17	Write zero calibration	01 06 00 3E 00 FF A8 46	01 06 00 3E 00 FF A8 46	Confirm to calibration zero
18	Write slope calibration	01 06 00 3F 00 FF F9 86	01 06 00 3F 00 FF F9 86	Confirm to calibration slope
19	Read measured AD	01 03 00 66 00 01 64 15	01 03 02 2E E0 A4 6C	2EE0 turns to integer 12000

8. Maintenance and storage

- 8.1 The sensor should be cleaned regularly. The metal ring should not be damaged when disassembling and washing the sensor, the metal ring on the sensor should not be wiped with filter paper or sandpaper.
- 8.2 When the metal ring is fouled, fouled or contaminated, stop using it , remove and clean the metal ring or replace the sensor .
- 8.3 After cleaning the sensor, after long-term storage, it needs to be calibrated before use.
- 8.4 The cable connector must be kept clean, dry, free from moisture, water etc.
- 8.5 When the sensor is not used for a long time, it needs to be stored for a long time. clean it and put on a protective cover containing soaking liquid, and store it in a dry place at room temperature.
- 8.6 Electrochemical sensors will naturally age and fail after long-term storage, it is recommended to use it as soon as possible after purchasing.

9. Troubleshooting

- 9.1 If the measurement is not accurate, mostly because the condition of free chlorine sensor has changed, so it is necessary to check whether the free chlorine sensor is in good condition. The free chlorine sensor is not easy to damage, generally the platinum ring needs to be cleaned due to scaling or contamination.
- 9.2 Modbus troubleshooting:

Problem	Possible reason	Solution
Modbus no response	The baud rate, or stop bit does not match the Modbus master settings	Verify that the settings match the Modbus master device settings, and verify that the Modbus master device parity check is set to None
	Rs232 or RS485 cable is faulty	Replace/repair cables
	No network offsets and terminations, or network offsets and terminations are not suitable	Check the termination or offset Settings for all network devices. Only the endpoints of the network should be turned on and terminated, and there should be only a point on the network to provide an offset
	The slave address is incorrect, or the slave address is the same as the address of another bus device	Verify that all addresses are unique and are between 1 and 247
Modbus abnormal response	Register not supported	Verify that the register is supported
	Incorrect data type	Verify that the requested register data type matches the Modbus master device request; for example, you cannot access a floating point data using 2-byte integer data. When a floating point data (2 registers / 4 bytes) is requested, two registers must be requested at the same time

10. Warranty

The sensor has a one year warranty period. As long as the damage is caused by improper use of non-human within the warranty period, please prepaid freight, pack the sensor and ship it back, we will repair it for you free of charge. We will analyze the reasons for the damage of the sensor, if the damage exceeds the warranty conditions, we need to charge the repair fee.