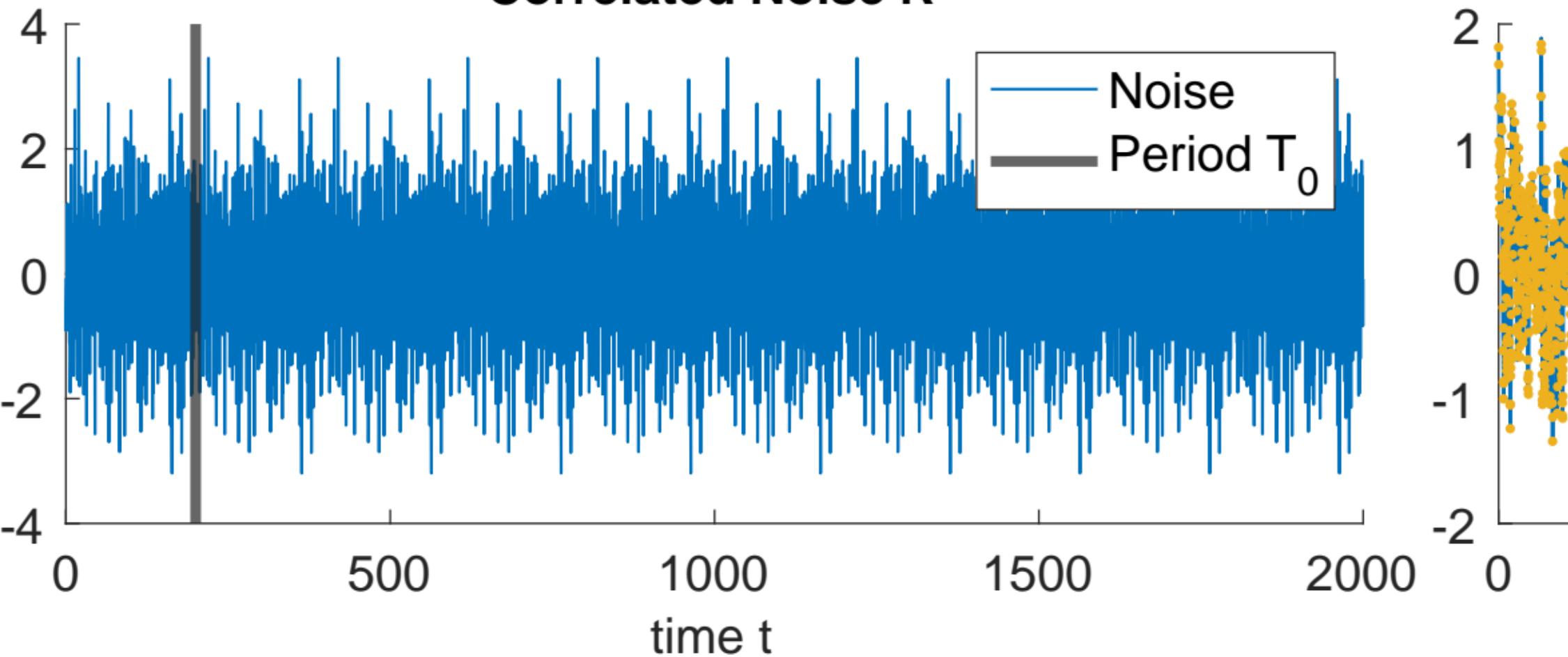


Correlated Noise R



Trajectory v

