Derivation on discretized differential operators on (ir)regular grids with boundary conditions

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1 Setup

- Define an irregular grid $\{x_i\}_{i=1}^M$ with $x_1 = x_{\min}$ and $x_M = x_{\max}$. Denote the grid with the variable name, i.e. $x \equiv \{x_i\}_{i=1}^M$.
- Denote the distance between the grid points as the backwards difference

$$\Delta_{i,-} \equiv x_i - x_{i-1}, \text{ for } i = 2, \dots, M$$

$$\Delta_{i,+} \equiv x_{i+1} - x_i, \text{ for } i = 1, \dots, M - 1$$
 (2)

• Assume $\Delta_{1,-} = \Delta_{1,+}$ and $\Delta_{M,+} = \Delta_{M,-}$, due to ghost points, x_0 and x_{M+1} on both boundaries. (i.e.he distance to the ghost nodes are the same as the distance to the closest nodes). Then define the vector of backwards and forwards first differences as

$$\Delta_{-} \equiv \begin{bmatrix} x_2 - x_1 \\ \text{diff}(x) \end{bmatrix} \tag{3}$$

$$\Delta_{+} \equiv \begin{bmatrix} \operatorname{diff}(x) \\ x_{M} - x_{M-1} \end{bmatrix} \tag{4}$$

• Reflecting barrier conditions:

$$\xi v(x_{\min}) + \partial_x v(x_{\min}) = 0 \tag{5}$$

$$\overline{\xi}v(x_{\text{max}}) + \partial_x v(x_{\text{max}}) = 0 \tag{6}$$

Let L_1^- be the discretized backwards first differences and L_2 be the discretized central differences subject to the Neumann boundary conditions in (5) and (6) such that $L_1^-v(x)$ and $L_2v(x)$ represent the first and second derivatives of v(x) respectively at x. For second derivatives, we use the following numerical scheme from Achdou et al. (2017):

$$v''(x_i) \approx \frac{\Delta_{i,-}v(x_i + \Delta_{i,+}) - (\Delta_{i,+} + \Delta_{i,-})v(x_i) + \Delta_{i,+}v(x_i - \Delta_{i,-})}{\frac{1}{2}(\Delta_{i,+} + \Delta_{i,-})\Delta_{i,+}\Delta_{i,-}}, \text{ for } i = 1,\dots, M$$
 (7)

1.1 Regular grids

Suppose that the grids are regular, i.e., elements of diff(x) are all identical with Δ for some $\Delta > 0$. Using the backwards first-order difference, (5) implies

$$\frac{v(x_{\min}) - v(x_{\min} - \Delta)}{\Delta} = -\underline{\xi}v(x_{\min}) \tag{8}$$

at the lower bound.

Likewise, (6) under the forwards first-order difference yields

$$\frac{v(x_{\text{max}} + \Delta) - v(x_{\text{max}})}{\Delta} = -\overline{\xi}v(x_{\text{max}}) \tag{9}$$

at the upper bound.

The discretized central difference of second order under (5) at the lower bound is

$$\frac{v(x_{\min} + \Delta) - 2v(x_{\min}) + v(x_{\min} - \Delta)}{\Delta^2} = \frac{v(x_{\min} + \Delta) - v(x_{\min})}{\Delta^2} - \frac{1}{\Delta} \frac{v(x_{\min}) - v(x_{\min} - \Delta)}{\Delta}$$
(10)

$$= \frac{v(x_{\min} + \Delta) - v(x_{\min})}{\Delta^2} + \frac{1}{\Delta} \underline{\xi} v(x_{\min})$$
 (11)

$$= \frac{1}{\Delta^2} (-1 + \Delta \underline{\xi}) v(x_{\min}) + \frac{1}{\Delta^2} v(x_{\min} + \Delta)$$
 (12)

Similarly, by (6), we have

$$\frac{v(x_{\text{max}} + \Delta) - 2v(x_{\text{max}}) + v(x_{\text{max}} - \Delta)}{\Delta^2} = \frac{v(x_{\text{max}} - \Delta) - v(x_{\text{max}})}{\Delta^2} + \frac{1}{\Delta} \frac{v(x_{\text{max}} + \Delta) - v(x_{\text{max}})}{\Delta}$$
(13)

$$= \frac{v(x_{\text{max}} - \Delta) - v(x_{\text{max}})}{\Delta^2} - \frac{1}{\Delta} \overline{\xi} v(x_{\text{max}})$$
 (14)

$$= \frac{1}{\Lambda^2} (-1 - \Delta \overline{\xi}) v(x_{\text{max}}) + \frac{1}{\Lambda^2} v(x_{\text{max}} - \Delta)$$
 (15)

at the upper bound.

Thus, the corresponding discretized differential operator L_1^- , L_1^+ , and L_2 are defined as

$$L_{1}^{-} \equiv \frac{1}{\Delta} \begin{pmatrix} 1 - (1 + \underline{\xi}\Delta) & 0 & 0 & \dots & 0 & 0 & 0 \\ -1 & 1 & 0 & \dots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & -1 & 1 & 0 \\ 0 & 0 & 0 & \dots & 0 & -1 & 1 \end{pmatrix}_{M \times M}$$

$$(16)$$

$$L_{1}^{+} \equiv \frac{1}{\Delta} \begin{pmatrix} -1 & 1 & 0 & \dots & 0 & 0 & 0 \\ 0 & -1 & 1 & \dots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & & \vdots \\ 0 & 0 & 0 & \dots & 0 & -1 & 1 \\ 0 & 0 & 0 & \dots & 0 & 0 & -1 + (1 - \overline{\xi}\Delta) \end{pmatrix}_{M \times M}$$

$$(17)$$

$$L_{2} \equiv \frac{1}{\Delta^{2}} \begin{pmatrix} 0 & 0 & \cdots & 0 & 0 & -1 + (1 - \xi \Delta) \end{pmatrix}_{M \times M}$$

$$L_{2} \equiv \frac{1}{\Delta^{2}} \begin{pmatrix} -2 + (1 + \underline{\xi}\Delta) & 1 & 0 & \dots & 0 & 0 & 0 \\ 1 & -2 & 1 & \dots & 0 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 1 & -2 & 1 & 0 \\ 0 & 0 & 0 & \cdots & 0 & 1 & -2 + (1 - \overline{\xi}\Delta) \end{pmatrix}_{M \times M}$$

$$(18)$$

1.2 Irregular grids

Using the backwards first-order difference, (5) implies

$$\frac{v(x_{\min}) - v(x_{\min} - \Delta_{1,-})}{\Delta_{1,-}} = -\underline{\xi}v(x_{\min})$$
 (19)

at the lower bound. Likewise, the forwards first-order difference under (6) yields

$$\frac{v(x_{\text{max}} + \Delta_{M,+}) - v(x_{\text{max}})}{\Delta_{M,+}} = -\overline{\xi}v(x_{\text{max}})$$
(20)

at the upper bound.

Note that we have assumed that $\Delta_{1,-} = \Delta_{1,+}$ and $\Delta_{M,+} = \Delta_{M,-}$ for the ghost notes. The discretized central difference of second order scheme at the lower bound under (5) is

$$\frac{\Delta_{1,-}v(x_{\min} + \Delta_{1,+}) - (\Delta_{1,+} + \Delta_{1,-})v(x_{\min}) + \Delta_{1,+}v(x_{\min} - \Delta_{1,-})}{\frac{1}{2}(\Delta_{1,+} + \Delta_{1,-})\Delta_{1,+}\Delta_{1,-}}$$
(21)

$$= \frac{v(x_{\min} + \Delta_{1,+}) - 2v(x_{\min}) + v(x_{\min} - \Delta_{1,+})}{\Delta_{1,+}^2}$$
(22)

$$= \frac{v(x_{\min} + \Delta_{1,+}) - v(x_{\min})}{\Delta_{1,+}^2} - \frac{1}{\Delta_{1,+}} \frac{v(x_{\min}) - v(x_{\min} - \Delta_{1,+})}{\Delta_{1,+}}$$
(23)

$$= \frac{v(x_{\min} + \Delta_{1,+}) - v(x_{\min})}{\Delta_{1,+}^2} + \frac{1}{\Delta_{i,+}} \underline{\xi} v(x_{\min})$$
 (24)

$$= \frac{1}{\Delta_{1,+}^2} (-1 + \Delta_{1,+} \underline{\xi}) v(x_{\min}) + \frac{1}{\Delta_{1,+}^2} v(x_{\min} + \Delta_{1,+})$$
 (25)

Similarly, by (6), we have

$$\frac{\Delta_{M,-}v(x_{\max} + \Delta_{M,+}) - (\Delta_{M,+} + \Delta_{M,-})v(x_{\max}) + \Delta_{M,+}v(x_{\max} - \Delta_{M,-})}{\frac{1}{2}(\Delta_{M,+} + \Delta_{M,-})\Delta_{M,+}\Delta_{M,-}}$$
(26)

$$= \frac{v(x_{\text{max}} + \Delta_{M,-}) - 2v(x_{\text{max}}) + v(x_{\text{max}} - \Delta_{M,-})}{\Delta_{M,-}^2}$$
(27)

$$= \frac{v(x_{\text{max}} - \Delta_{M,-}) - v(x_{\text{max}})}{\Delta_{M,-}^2} + \frac{1}{\Delta_{M,-}} \frac{v(x_{\text{max}} + \Delta_{M,-}) - v(x_{\text{max}})}{\Delta_{M,-}}$$
(28)

$$= \frac{v(x_{\text{max}} - \Delta_{M,-}) - v(x_{\text{max}})}{\Delta_{M,-}^2} - \frac{1}{\Delta_{M,-}} \overline{\xi} v(x_{\text{max}})$$
(29)

$$= \frac{1}{\Delta_{M,-}^2} (-1 - \Delta_{M,-} \bar{\xi}) v(x_{\text{max}}) + \frac{1}{\Delta_{M,-}^2} v(x_{\text{max}} - \Delta_{M,-})$$
(30)

at the upper bound.

Thus, the corresponding discretized differential operator L_1^- , L_1^+ , and L_2 are defined as

$$L_{1}^{-} \equiv \begin{pmatrix} \Delta_{1,-}^{-1}[1 - (1 + \underline{\xi}\Delta_{1,-})] & 0 & 0 & \dots & 0 & 0 & 0 \\ -\Delta_{2,-}^{-1} & \Delta_{2,-}^{-1} & 0 & \dots & 0 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & -\Delta_{M-1,-}^{-1} & \Delta_{M-1,-}^{-1} & 0 & 0 \\ 0 & 0 & 0 & \dots & 0 & -\Delta_{M,-}^{-1} & \Delta_{M,-}^{-1} & \Delta_{M,-}^{-1} \end{pmatrix}_{M \times M}$$

$$L_{1}^{-} \equiv \begin{pmatrix} -\Delta_{1,+}^{-1} & \Delta_{1,+}^{-1} & 0 & \dots & 0 & 0 & 0 & 0 \\ 0 & -\Delta_{2,+}^{-1} & \Delta_{2,+}^{-1} & \dots & 0 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & -\Delta_{M-1,+}^{-1} & \Delta_{M-1,+}^{-1} & 0 & 0 & 0 \\ 0 & 0 & 0 & \dots & 0 & 0 & \Delta_{M,+}^{-1}[-1 + (1 - \overline{\xi}\Delta_{M,+})] \end{pmatrix}_{M \times M}$$

$$L_{2} \equiv \begin{pmatrix} \Delta_{1,+}^{-2}[-2 + (1 + \underline{\xi}\Delta_{1,+})] \Delta_{1,+}^{-2} & 0 & \dots & 0 & 0 & 0 & 0 \\ \vdots & \vdots & \ddots & \ddots & \ddots & \ddots & \vdots & \vdots \\ 0 & \dots & 2(\Delta_{i,+} + \Delta_{i,-})^{-1}\Delta_{i,-}^{-1} & 2(\Delta_{i,+} + \Delta_{i,-})^{-1}\Delta_{i,+}^{-1} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 0 & \Delta_{M,-}^{-2} & \Delta_{M,-}^{-2}[-2 + (1 - \overline{\xi}\Delta_{M,-})] \end{pmatrix}_{M \times M}$$

$$(33)$$

1.3 Differential operators by basis

Define the following basis matrices:

$$U_{1}^{-} \equiv \begin{pmatrix} 1 & 0 & 0 & \dots & 0 & 0 & 0 \\ -1 & 1 & 0 & \dots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & -1 & 1 & 0 \\ 0 & 0 & 0 & \dots & 0 & -1 & 1 \end{pmatrix}_{M \times M}$$

$$(34)$$

$$U_1^+ \equiv \begin{pmatrix} -1 & 1 & 0 & \dots & 0 & 0 & 0 \\ 0 & -1 & 1 & \dots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & -1 & 1 \\ 0 & 0 & 0 & \dots & 0 & 0 & -1 \end{pmatrix}_{M \times M}$$

$$(35)$$

(36)

and the boundary conditions for the reflecting conditions:

$$B_{1} \equiv \begin{pmatrix} (1 + \underline{\xi} \Delta_{1,-}^{-1}) & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 0 \end{pmatrix}_{M \times M}$$

$$(37)$$

$$B_{M} \equiv \begin{pmatrix} 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & (1 - \overline{\xi} \Delta_{M+}^{-1}) \end{pmatrix}_{M \times M}$$

$$(38)$$

1.3.1 Regular grids

For regular grids with the uniform distance of $\Delta > 0$, (16) and (18) can be represented by

$$L_1^- = \frac{1}{\Lambda} U_1^- - B_1 \tag{39}$$

$$L_1^+ = \frac{1}{\Lambda} U_1^+ + B_M \tag{40}$$

$$L_2 = \frac{1}{\Delta^2} (U_1^+ - U_1^-) + B_1 + B_M \tag{41}$$

1.3.2 Irregular grids

For notational brevity, for vectors with the same size, x_1, x_2 , define x_1x_2 as the elementwise-multiplied vector. Then, we have

$$L_1^- = \operatorname{diag}(\Delta_-)^{-1}U_1^- - B_1 \tag{42}$$

$$L_1^+ = \operatorname{diag}(\Delta_+)^{-1}U_1^+ + B_M \tag{43}$$

$$L_2 = \operatorname{diag} \left[\frac{1}{2} (\Delta_+ + \Delta_-) \Delta_+ \right]^{-1} U_1^+ - \operatorname{diag} \left[\frac{1}{2} (\Delta_+ + \Delta_-) \Delta_- \right]^{-1} U_1^- + B_1 + B_M$$
 (44)

We can simplify this expression further by introducing a new notation. Let x^{-1} be defined as the elementwise inverse of a vector x that contains no zero element. Then, L_2 can be represented as

$$L_2 = 2 \left[\operatorname{diag} \left((\Delta_+ + \Delta_-)^{-1} \Delta_+^{-1} \right) U_1^+ - \operatorname{diag} \left((\Delta_+ + \Delta_-)^{-1} \Delta_-^{-1} \right) U_1^- \right] + B_1 + B_M$$
 (45)

$$= 2\operatorname{diag}\left((\Delta_{+} + \Delta_{-})^{-1}\right) \left[\operatorname{diag}\left(\Delta_{+}^{-1}\right)U_{1}^{+} - \operatorname{diag}\left(\Delta_{-}^{-1}\right)U_{1}^{-}\right] + B_{1} + B_{M}$$
(46)

The diagonal elements of (46) are also identical with the one provided in (33) – to see this, note that the diagonal elements of (46), modulo B_1 and B_M , are

$$-2\left[(\Delta_{+} + \Delta_{-})^{-1}\Delta_{+}^{-1} + (\Delta_{+} + \Delta_{-})^{-1}\Delta_{-}^{-1}\right] = -2(\Delta_{+} + \Delta_{-})^{-1}(\Delta_{+}^{-1} + \Delta_{-}^{-1}) \tag{47}$$

$$= -2(\Delta_{+} + \Delta_{-})^{-1}(\Delta_{+}^{-1}\Delta_{-}^{-1})(\Delta_{+} + \Delta_{-})$$
 (48)

$$= -2(\Delta_{+}^{-1}\Delta_{-}^{-1}) \tag{49}$$

which is identical with $\operatorname{diag}(L_2)$ with L_2 from (33) except the first row and last row that are affected by B_1 and B_M .

References

Achdou Y., Han J., Lasry J.-M., Lions P.-L., Moll B., 2017, Technical report, Income and wealth distribution in macroeconomics: A continuous-time approach. National Bureau of Economic Research