Dynamic Programming with Google JAX CEF 2024

John Stachurski

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Slides, code:

https://github.com/QuantEcon/cef_2024_singapore

Quick poll:

- Python programmers?
 - NumPy? Numba? PyTorch? JAX?
- Julia?
- MATLAB?
- C?
- Fortran?

Regular GPU users?

Topics

- Types of programming languages
- Vectorization vs JIT compilers
- Motivation for JAX

Old school: static types & AOT compilers

Typical languages: Fortran / C / C++

Example. Suppose we want to compute the sequence

$$k_{t+1} = sk_t^\alpha + (1-\delta)k_t$$

from some given k_0

Let's write a function that returns the last \boldsymbol{k}_t

```
#include <stdio.h>
#include <math.h>
int main() {
    double k = 0.2:
    double alpha = 0.4;
    double s = 0.3;
    double delta = 0.1;
    int i:
    int n = 1000;
    for (i = 0; i < n; i++) {
        k = s * pow(k, alpha) + (1 - delta) * k;
    printf("k = %f \setminus n", k);
```

```
program main
 implicit none
 integer, parameter :: dp=kind(0.d0)
 integer :: n=1000
 real(dp) :: s=0.3 dp
 real(dp) :: a=1.0 dp
 real(dp) :: delta=0.1 dp
 real(dp) :: alpha=0.4_dp
 real(dp) :: k=0.2 dp
 integer :: i
 do i = 1, n - 1
  k = a * s * k**alpha + (1 - delta) * k
 end do
 print *,'k = ', k
end program main
```

Pros of low-level languages

fast loops / arithmetic

Cons

- low interactivity
- time consuming to write / read / debug
- hard to parallelize

For comparison, the same operation in Python:

```
α = 0.4
s = 0.3
δ = 0.1
n = 1_000
k = 0.2

for i in range(n):
    k = s * k**α + (1 - δ) * k

print(k)
```

Pros

- high interactivity
- easy to write / read / debug

Cons

• slow loops / arithmetic

Why is pure Python slow?

Pros

- high interactivity
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Cons

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Why is pure Python slow?

Problem 1: Type checking

```
# Ints
x, y = 1, 2
z = x + y # z = 3
# Floats
x, y = 1.0, 2.0
z = x + y # z = 3.0
# Strings
x, y = 'foo', 'bar'
z = x + y # z = 'foobar'
```

How does Python know which operation to perform?

Answer: Python checks the type of the objects first

```
>> x = 1
>> type(x)
int
```

```
>> x = 'foo'
>> type(x)
str
```

In a large loop, this type checking generates massive overhead

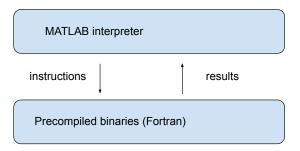
Problem 2: Memory management

```
>>> import sys
>>> x = [2.56, 3.21]
>>> sys.getsizeof(x) * 8  # number of bits
576  # whaaaat???
```

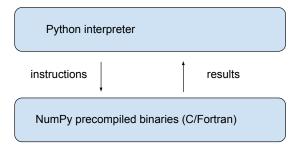
So how can we get

good execution speeds and high productivity / interactivity?

MATLAB's vectorization trick



Python + NumPy - stealing MATLAB's idea



Vectorization: pros and cons

Pros

high interactivity

Cons

- some tasks cannot be efficiently vectorized
- cannot adapt flexibly to function arguments / hardware

Julia — rise of the JIT compilers

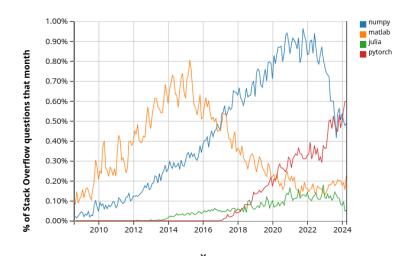
```
function solow(k0, α=0.4, δ=0.1, n=1_000)
    k = k0
    for i in 1:(n-1)
        k = s * k^α + (1 - δ) * k
    end
    return k
end
solow(0.2)
```

Python + Numba copy Julia

```
from numba import jit
@jit
def solow(k0, \alpha=0.4, \delta=0.1, n=1_000):
    k = k0
    for i in range(n-1):
         k = s * k**\alpha + (1 - \delta) * k
     return k
solow(0.2)
```

Runs at same speed as Julia / C / Fortran

Some trends:



So where does JAX fit in?

Let's start with some motivation and background

Al-driven scientific computing

Al is changing the world

- image processing / computer vision
- speech recognition, translation
- scientific knowledge discovery
- forecasting and prediction
- generative AI

Plus killer drones, skynet, etc...

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Projected spending on AI in 2024:

Google: \$48 billion

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etc.

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Platforms / libraries

- PyTorch (ChatGPT, LLaMA 3, Github Copilot)
- Google JAX (Gemini)
- Tensorflow?
- Mojo (by Modular)?

Deep learning in two slides

Supervised deep learning: find a good approximation to an unknown functional relationship

$$y = f(x)$$
 $(x \in \mathbb{R}^d, y \in \mathbb{R})$

Examples.

- x = sequence of words, y = next word
- $ullet x = {\sf weather \ sensor \ data}, \ y = {\sf max \ temp \ tomorrow}$

Problem:

• observe $(x_i,y_i)_{i=1}^n$ and seek f such that $y_{n+1}\approx f(x_{n+1})$

Training: minimize the empirical loss

$$\ell(\theta) := \sum_{i=1}^n (y_i - f_{\theta}(x_i))^2 \quad \text{ s.t. } \quad \theta \in \Theta$$

But what is $\{f_{\theta}\}_{\theta \in \Theta}$?

In the case of ANNs, we consider all f_{θ} having the form

$$f_\theta = \sigma \circ A_1 \circ \cdots \circ \sigma \circ A_{k-1} \circ \sigma \circ A_k$$

where

- $\bullet \ A_i x = W_i x + b_i \ \text{is an affine map}$
- σ is a nonlinear "activation" function

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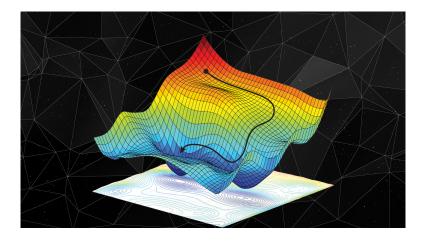
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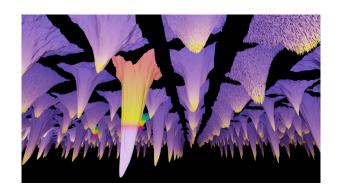
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Minimizing a smooth loss functions – what algorithm?



Source: https://danielkhv.com/

Deep learning: $\theta \in \mathbb{R}^d$ where d = ?



Source: https://losslandscape.com/gallery/

Hardware



"NVIDIA supercomputers are the factories of the AI industrial revolution." – Jensen Huang

Software

Core elements

- automatic differentiation (for gradient descent)
- parallelization (GPUs! how many?)
- Compilers / JIT-compilers

Crucially, these components must be well integrated



```
import jax.numpy as jnp
from jax import grad, jit
def f(\theta, x):
  for W, b in \theta:
    W = W \otimes X + b
    x = jnp.tanh(w)
  return x
def loss(\theta, x, y):
  return jnp.sum((y - f(\theta, x))**2)
grad loss = jit(grad(loss)) # Now use gradient descent
```

Source: JAX readthedocs

What I need: software that will parallelize for me

- automated intelligent parallelization
- JIT compiled flexible
- integrated autodiff
- automatically supports most CPUs / GPUs / TPUs / etc.

JAX ticks these boxes