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Pricing and Hedging in Stochastic Volatility Regime Switching Models

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ABSTRACT

We consider general regime switching stochastic volatility models where both the asset and the volatility dynamics depend on the values of a Markov jump process. Due to the stochastic volatility and the Markov regime switching, this financial market is thus incomplete and perfect pricing and hedging of options are not possible. Thus, we are interested in finding formulae to solve the problem of pricing and hedging options in this framework. For this, we use the local risk minimization approach to obtain pricing and hedging formulae based on solving a system of partial differential equations. Then we get also formulae to price volatility and variance swap options on these general regime switching stochastic volatility models.

1. Introduction

In this paper, we consider general regime switching stochastic volatility models where both the asset and the volatility dynamics depend on the values of a Markov jump process. We are interested in finding formulae to solve the problem of pricing and hedging contingent claims in this framework. However, due to the stochastic volatility and the Markov regime switching, the market is incomplete and thus perfect pricing and hedging are not possible. Hence, to hedge derivatives, we adopt firstly the local-risk minimization approach studied by Föllmer and Schweizer in [1]. This approach consists of controlling the hedging errors at each instant $t \in [0,T]$ by minimizing the conditional variances of the instantaneous cost increments. Health *et al*. in [2], provided comparative theoretical and numerical results on risks, values and hedging strategies for this approach versus the mean-variance (see [3] or [4] for more details on this approach), in the specific case of stochastic volatility models. We propose in this paper to apply the local risk minimization approach to a more global class of stochastic volatility models since we will assume in the sequel that all parameters of the model depend on the values of a Markov jump process. Hence, we will work on a global class of regime switching stochastic volatility models. We will obtain formulae to give the price of contingent claims by solving a system of partial differential equations. We will also obtain the optimal strategy which solves the local risk minimization hedging problem.

There has been considerable interest in applications of regime switching models driven by a Markov process to various financial problems. Elliott *et al*. in [5] provided an overview of hidden Markov chain models. Indeed, the use of Markov switching in diffusions allows us to have different levels of drift or volatility during time. Moreover these regime switching activities are a better fit for economic times series data than non regime switching models and also allow us to better capture some market features or economics behaviors such as recession and financial crisis periods (see for example Goutte and Zou in [6]). Thus, Di Masi *et al*. in [7] considered the problem of hedging an European call option for a (non-stochastic volatility) diffusion models where the drift and volatility are functions of a Markov jump process.

Furthermore, we are also interested in pricing volatility derivatives, such as variance and volatility swaps. Broadie *et al.* in [8] studied the pricing and hedging of variance swaps and other volatility derivatives in the classical Heston stochastic volatility model introduced by Heston in [9]. Elliott *et al*. in [10] then developed a model for pricing the same class of derivatives but under a Markov-modulated version of this stochastic volatility model. In their paper, they only considered the case where not all the parameters of the model depend on the state of the Markov process. Moreover, they studied only the Heston stochastic volatility model. Hence, based on these two preceding works, we will extend this methodology to our global class of regime switching stochastic

volatility models. Thus, we will obtain formulae to price options on the stochastic volatility process such as variance and volatility swaps.

This paper is arranged as follows: Section 1 gives the notion of the regime switching framework and presents our regime switching stochastic volatility models. Section 2 solves the problem of pricing and hedging using the local risk minimization approach. Section 3 then gives the formulas to price options on the volatility process.

2. The Stochastic Regime Switching Volatility Model

Let $(\omega, \mathcal{F}, P)$ be a filtered probability space with filtration $\mathbb{F} = (\mathcal{F}_t)_{t \in [0,T]}$ satisfying the usual conditions for some fixed but arbitrary time horizon $T \in (0, \infty)$. We consider a general stochastic volatility model defined by the stochastic differential equations:

$$dS_t = \mu(t, Y_t, X_t) S_t dt + Y_t S_t dW_t^1,$$
$$dY_t = a(t, Y_t, X_t) dt + b(t, Y_t, X_t) dW_t^2, \quad (1.1)$$
$$d\langle W^1, W^2 \rangle_t = \rho dt \text{ with } \rho \in [0,1].$$

where W^1 and W^2 are two correlated Brownian motions. In fact, the process S represents the discounted price process of a tradable asset price process $(\tilde{S})_{t \in [0,T]}$ divided by a Bond price process $(B_t)_{t \in [0,T]}$. The process B represents the savings account in a riskless asset. $(Y_t)_{t \in [0,T]}$ is a real stochastic process which is $\mathcal{F}_t$-adapted and $(X_t)_{t \in [0,T]}$ is a Markov jump process on finite state space $\mathcal{S} := \{1, 2, \cdots, N\}$. It can be viewed as an observable exogenous quantity. We assume that the time invariant matrix Q denotes the infinitesimal generator $(q_{ij})_{i,j=1,\cdots,m}$ of X, where q_{ij} is an infinitesimal intensity of X. This generator is defined as $q_{ij} \geq 0$, for all $i \neq j \in \mathcal{S}$ and $q_{ii} = -\sum_{j \neq i; j \in \mathcal{S}} q_{ij} < 0$ for all $i \in \mathcal{S}$.

Then, the semi-martingale decomposition for X is given by

$$X_t = X_0 + \int_0^t Q X_s ds + M_t^X, \quad t \in [0,T],$$

where $(M_t^X)_{t \in [0,T]}$ is an $\mathbb{R}^N$-valued martingale with respect to $\mathbb{F}^X = (\mathcal{F}_t^X)_{t \in [0,T]} := \sigma(X_t, 0 \leq t \leq T)$, which is the natural filtration generated by the Markov process X under P.

Hence, in our model, there are three sources of randomness: W^1, W^2 and X. We will denote by $\mathbb{G} = (\mathcal{G}_t)_{t \in [0,T]} := \sigma(W_t^1, W_t^2, 0 \leq t \leq T)$ the filtration generated by the two Brownian motions. Finally, we will denote by $\mathbb{F}$ the global filtration $\mathbb{F} := \mathbb{G} \vee \mathbb{F}^X$.

Let T_n be the sequential jump times of X (i.e. $0 = T_0 \leq T_1 \leq \cdots \leq T_n \leq \cdots$) and ν a jump measure of X, i.e. the integer-valued random measure given by

$$\nu([0,t] \times \mathcal{S}) = \sum_{n \geq 1} 1_{\{X_{T_n} \in \mathcal{S}, T_n \leq t\}}. \quad (1.2)$$

Then the $\mathbb{F}$-compensator of ν is given by

$$\bar{\nu}(dt, \{j\}) = \sum_{i \neq j} q_{ij} 1_{\{X_t = j\}} dt. \quad (1.3)$$

Assumption 1.1

1) We assume all the hypothesis to ensure the existences and the regularities of the solutions of our model (1.1) (see for example [11] for more details). Hence, the system of stochastic differential Equations (1.1) admits a unique strong continuous solution for the vector process (S, Y, X) with a strictly positive price process S and a volatility process Y.

2) We assume moreover that the Markov process X is independent to both processes S and Y.

Remark 1.1 *This independence implies that the Markov process X is an exogenous factor of the market information. Thus, it can be viewed as an exogenous factor such as an economic impact factor. An economic interpretation of this is that this Markov process can represent a credit rating of a firm A. Indeed, assume that our stochastic volatility model describes the price of a commodity produced by the firm A, then the Markov process X can represent the credit rating of this firm given by an exogenous rating company as "Standard and Poors". Thus, it is natural to think that the dynamic of the commodity's price, produced by the firm A, depends on the value of this notation X.*

To exclude arbitrage opportunities, we assume that the process S admits an *equivalent local martingale measure* (ELMM) Q. In the sense that it is a probability measure with the same null sets as P and such that the process S is a local martingale under Q. We will denote, in the sequel, by $\mathbb{P}$ the set of all ELMMs Q.

Remark 1.2

1) We can rewrite the Brownian motion W_t^2 as $W_t^2 = \rho W_t^1 + \sqrt{1 - \rho^2} W_t^3$, where the process W^3 is another Brownian motion such that processes W^1 and W^3 are now independent.

2) The condition that S should be a Q-local martingale fixes the effect of the Girsanov transformation of W^1 but allows us for different transformations on the independent Brownian motion W^3 defined in point 1. Consequently, if the correlation factor ρ satisfies $|\rho| < 1$, then the set $\mathbb{P}$ contains more than one element and so the financial market is then incomplete. Moreover, there is an other source of incompleteness of the market which is the dependence of processes S and Y with

respect to the Markov process X.

We give now some examples of classical stochastic volatility models which are contained in our model (1.1).

Example 1.1 Hull-White:

$$\mu(t, Y_t, X_t) = \mu Y_t, \, a(t, Y_t, X_t) = \frac{Y_t}{2}\left(\alpha - \frac{\beta^2}{2}\right)$$

$$\text{and } b(t, Y_t, X_t) = \frac{\beta}{2} Y_t,$$

$$\mathrm{d}S_t = \mu Y_t S_t \mathrm{d}t + Y_t S_t \mathrm{d}W_t^1,$$

$$\mathrm{d}Y_t^2 = \alpha Y_t^2 \mathrm{d}t + \beta Y_t^2 \mathrm{d}W_t^2.$$

Stein-Stein:

$$\mu(t, Y_t, X_t) = \mu Y_t, \, a(t, Y_t, X_t) = \alpha(\omega - Y_t)$$

$$\text{and } b(t, Y_t, X_t) = \beta,$$

$$\mathrm{d}S_t = \mu Y_t S_t \mathrm{d}t + Y_t S_t \mathrm{d}W_t^1,$$

$$\mathrm{d}Y_t = \alpha(\omega - Y_t)\mathrm{d}t + \beta \mathrm{d}W_t^2.$$

Heston:

$$\mu(t, Y_t, X_t) = \mu Y_t, \, a(t, Y_t, X_t) = \frac{4\kappa\theta - \sigma^2}{8Y_t} - \frac{\kappa}{2} Y_t$$

$$\text{and } b(t, Y_t, X_t) = \frac{\sigma}{2},$$

$$\mathrm{d}S_t = \mu Y_t S_t \mathrm{d}t + Y_t S_t \mathrm{d}W_t^1,$$

$$\mathrm{d}Y_t^2 = \kappa(\theta - Y_t^2)\mathrm{d}t + \sigma Y_t \mathrm{d}W_t^2,$$

$$2\kappa\theta \geq \sigma^2.$$

3. Pricing and Hedging via Local Risk Minimization Approach

We are interested, in this section, in the hedging of an European contingent claims with an $\mathcal{F}_T$-measurable squared integrable random variable H based on the dynamics given by (1.1). As an example of this payoff, we can take an European call option:
$H = h(S_T) = (S_T - K)^+$ with maturity T and strike $K > 0$.

We consider here the local risk-minimization approach to hedge in this incomplete market. We recall some definitions of this approach.

Definition 2.1 *An hedging strategy is a pair*
$\varphi = (v, \eta)$ *such that* $v = (v_t)_{t \in [0,T]}$ *is a predictable process which satisfies*

$$\mathbb{E}\left[\int_0^T v_t^2 Y_t^2 S_t^2 \mathrm{d}t\right] + \mathbb{E}\left[\left(\int_0^T |v_t| |\mu(t, Y_t, X_t)|\right)^2\right] < \infty, \quad (2.4)$$

and $\eta = (\eta_t)_{t \in [0,T]}$ *is an adapted process such that*

$$\mathbb{E}\left[\eta_t^2\right] < \infty, \quad \forall t \in [0, T]. \quad (2.5)$$

We will denote by $\mathcal{A}$ the set of strategies which satisfy (2.4) and (2.5).

The hedging strategy φ defines a portfolio where v_t denotes the number of shares of the risky asset S held by the investor at time $t \in [0, T]$ and η_t denotes the amount invested at time t in the bond.

Definition 2.2 *Given a hedging strategy φ, we call the Value process $V(\varphi)$ of this corresponding portfolio the right continuous process given by*

$$V_t(\varphi) = v_t S_t + \eta_t, \quad \forall t \in [0, T]. \quad (2.6)$$

Definition 2.3 *Given a hedging strategy φ, we call the Cost process $C(\varphi)$ of this corresponding portfolio the process given by*

$$C_t(\varphi) = V_t(\varphi) - \int_0^t v_s \mathrm{d}S_s, \quad \forall t \in [0, T]. \quad (2.7)$$

We can see that the quantity $\int_0^t v_s \mathrm{d}S_s$ represents the hedging gains or losses up to time $t \in [0, T]$ following the hedging strategy φ. A hedging strategy φ is called self-financing if its cost process is P-a.s. constant over the time $[0, T]$ and mean self-financing if $C(\varphi)$ is a P-martingale. If $C(\varphi)$ is square integrable, then the risk process of φ is defined by

$$R_t(\varphi) := \mathbb{E}\left[\left(C_T(\varphi) - C_t(\varphi)\right)^2 \big| \mathcal{F}_t\right], \forall t \in [0, T]. \quad (2.8)$$

Remark 2.3 *Since the contingent claim H is $\mathcal{F}_T$-measurable and η is adapted, there always exists a hedging strategy such that $V_T(\varphi) = H$. Indeed, we can take $v \equiv 0$ and $\eta_t = H 1_{\{t=T\}}$ for all $t \in [0, T]$.*

3.1. Local Risk Minimization Approach

We only consider hedging strategies which replicate contingent claim H at time T. This means that we only allow hedging strategies φ such that

$$V_T(\varphi) = H, \quad P - a.s. \quad (2.9)$$

Thus, the hedging problem is so to find the strategy $\varphi \in \mathcal{A}$ which minimizes at time $t \in [0, T]$ the quadratic risk:

$$\min_{\varphi \in \mathcal{A}} R_t(\varphi) := \min_{\varphi \in \mathcal{A}} \mathbb{E}\left[\left(H - \int_0^T v_s \mathrm{d}s - C_t(\varphi)\right)^2 \big| \mathcal{F}_t\right]. \quad (2.10)$$

The idea is so to control the hedging errors at each instant $t \in [0, T]$ by minimizing the conditional variances of the instantaneous cost increments sequentially over time.

Remark 2.4 *An alternative approach to hedge in incomplete market is the mean-variance approach (see [3]). In fact, in this approach, the aim is to minimize the global risk over the entire time $[0, T]$. Hence, it is a different approach than the local risk minimization which focuses on the minimization of the second moments of the infinitesimal cost increments (8).*

Therefore, the study of this minimization problem in a general semimartingale case is due to Schweizer [3] and it requires more assumptions on the asset dynamic S. We assume firstly that S can be decomposed as

$$S_t = S_0 + M_t + A_t,$$

where M is a real valued locally squared integrable local P-martingale null at zero and A is a real valued adapted continuous process of finite variation also null at zero.

We recall now the Definition of the *Structure Condition* (SC). We say that the process S satisfies the (SC) if there exists a predictable process λ such that the process A is absolutely continuous with respect to $\langle M \rangle$ (*i.e.* the oblique bracket). In the sense that

$$A_t = \int_0^t \lambda_s \mathrm{d} \langle M \rangle_s$$

and such that the so called *mean variance tradeoff process* (MVT) K satisfies

$$K_t := \int_0^t \lambda_s^2 \mathrm{d} \langle M \rangle_s < \infty, \quad P-a.s.$$

Lemma 2.1 *Since* $\mathbb{P} \neq \varnothing$, *we have that if the process* S *is continuous then* (SC) *is satisfied.*

Proof. See Theorem 1 of Schweizer [4].

Proposition 2.24 of Föllmer and Schweizer in [1] shows that finding a locally risk minimizing strategy for a given contingent claim $H \in L^2(P)$ is equivalent to finding a decomposition of H of the form:

$$H = H_0^{lr} + \int_0^T \xi_t^{lr} \mathrm{d} S_t + L_T^{lr}, \qquad (2.11)$$

where H_0^{lr} is a constant, ξ^{lr} is a predictable process satisfying Condition (2.4) and L^{lr} is a square integrable P-martingale null at 0 and strongly orthogonal to M (*i.e.* $L^{lr}M$ is a P-martingale). The representation (2.11) is usually referred to as the Föllmer-Schweizer (FS) decomposition of the random variable H. Once we have (2.11), then the desired hedging strategy φ^{lr}, which is locally risk minimizing, is then given, for all $t \in [0,T]$, by

$$v_t^{lr} = \xi_t^{lr} \qquad (2.12)$$

and

$$\eta_t^{lr} = V_t\left(\varphi^{lr}\right) - v_t^{lr} S_t, \qquad (2.13)$$

where

$$V_t\left(\varphi^{lr}\right) = C_t\left(\varphi^{lr}\right) + \int_0^t v_s^{lr} \mathrm{d} S_s \qquad (2.14)$$

with

$$C_t\left(\varphi^{lr}\right) = H_0^{lr} + L_t^{lr}. \qquad (2.15)$$

In view of these results, finding the Föllmer-Schweizer decomposition (2.11) of a given contingent claim H is

important because it allows us to obtain the locally risk minimizing strategy. Monat and Sticker in [12] and Pham *et al.* in [13] give sufficient conditions to prove the existence of this decomposition. We therefore explain how one can often obtain this decomposition by switching to a suitably chosen martingale measure for S. Indeed, as it is shown in [1] and [4], there exists a measure $\hat{P} \in \mathbb{P}$, which is the so called *minimal equivalent local martingale measure* (minimal ELMM), such that

$$V_t\left(\varphi^{lr}\right) = \hat{\mathbb{E}}[H \mid F_t], \quad t \in [0,T], \qquad (2.16)$$

where $\hat{\mathbb{E}}$ denotes the conditional expectation under $\hat{P}$.

Remark 2.5 *If there exists a locally risk minimizing strategy* φ^{lr}, *then we can use the expression of* $V_t\left(\varphi^{lr}\right)$ *appearing in* (2.16) *as a price of the contingent claim* H *at time* $t \in [0,T]$.

In the case where the process S is continuous (which is our case), Theorem 1 of [1] allows us to construct uniquely $\hat{P}$. Indeed, we have the following result:

Proposition 2.1 $\hat{P} \in \mathbb{P}$ *exists if and only if for all* $t \in [0,T]$

$$\hat{Z}_t = \exp\left(-\int_0^t \lambda_s \mathrm{d} M_s - \frac{1}{2}\int_0^t \lambda_s^2 \mathrm{d} \langle S \rangle_s\right) \qquad (2.17)$$

is a square integrable martingale under P.

Moreover, $\dfrac{\hat{P}}{P} := \hat{Z}_T \in L^2(P)$ defines a probability measure $\hat{P}$ equivalent to P which is in $\mathbb{P}$ since one easily verifies that $\hat{Z}S$ is a local P-martingale.

3.2. Markovian Regime Switching Case

Let S, Y and X given by the model (1.1), then the local risk minimizing hedging strategy can be obtained in two steps:

1) Determine $\hat{P} \in \mathbb{P}$ and deduce the dynamic of (S,Y) under $\hat{P}$.

2) Find the Galtchouk-Kunita-Watanabe decomposition of H with respect to S under $\hat{P}$.

Then, the optimal local risk minimizing hedging strategy is given by (2.12) and (2.13).

3.2.1. Finding $\hat{P}$

According to the previous subsection, the density process of the minimal ELMM $\hat{P} \in \mathbb{P}$ with respect to P is given by the Equation (2.17). We can firstly remark that

$$\hat{Z}_t := \exp\left(-\int_0^t \lambda_s \mathrm{d} M_s - \frac{1}{2}\int_0^t \lambda_s^2 \mathrm{d} \langle S \rangle_s\right)$$

$$= \exp\left(-\int_0^t \lambda_s \mathrm{d} M_s - \frac{1}{2} K_t\right).$$

Since S is continuous, we have first of all to deter-

mine the canonical decomposition

$$S_t = S_0 + M_t + \int_0^t \lambda_s \mathrm{d}\langle M \rangle_s$$

of the asset process S under P.

Proposition 2.2 *Assume that the regime stochastic volatility model follows* (1.1) *then we have, for all* $t \in [0,T]$, *that*

$$M_t = \int_0^t S_s Y_s \mathrm{d}W_s^1, A_t = \int_0^t \mu(s, Y_s, X_s) S_s \mathrm{d}s,$$

$$\langle M \rangle_t = \int_0^t S_s^2 Y_s^2 \mathrm{d}s,$$

$$\lambda_t = \frac{\mathrm{d}A_t}{\mathrm{d}\langle M \rangle_t} = \frac{\mu(t, Y_t, X_t)}{S_t Y_t^2}$$

and $K_t = \int_0^t \left(\frac{\mu(s, Y_s, X_s)}{Y_s} \right)^2 \mathrm{d}s,$

therefore we obtain

$$\hat{Z}$$

$$= \exp\left(-\int_0^t \frac{\mu(s, Y_s, X_s)}{Y_s} \mathrm{d}W_s^1 - \frac{1}{2} \int_0^t \left(\frac{\mu(s, Y_s, X_s)}{Y_s} \right)^2 \mathrm{d}s \right).$$

Proof. It comes immediately from the definition of the dynamic of our model (1.1).

We are now able to determine the dynamic of our model under $\hat{P} \in \mathbb{P}$.

Proposition 2.3 *Assume that* $\hat{Z}$ *is a true* P-martingale, then the dynamic of the model (1.1) *under* $\hat{P}$ *is given for all* $t \in [0,T]$ *by*

$$\mathrm{d}S_t = Y_t S_t \mathrm{d}\hat{W}_t^1, \tag{2.18}$$

$$\mathrm{d}Y_t = \hat{a}(t, Y_t, X_t)\mathrm{d}t$$
$$+ b(t, Y_t, X_t)\left(\rho\mathrm{d}\hat{W}_t^1 + \sqrt{1-\rho^2}\mathrm{d}\hat{W}_t^3 \right)$$

with

$$\hat{a}(t, Y_t, X_t) = a(t, Y_t, X_t)$$
$$- \frac{\rho}{Y_t} \mu(t, Y_t, X_t)b(t, Y_t, X_t). \tag{2.19}$$

Proof. Since $\hat{Z}$ is a P-martingale, Girsanov's theorem implies that $\hat{W}_t^1 := W_t^1 + \int_0^t \frac{\mu(s, Y_s, X_s)}{Y_s}\mathrm{d}s$ and $\hat{W}_t^3 := W_t^3$ are independent $\hat{P}$-Brownian motions. Hence

$$\mathrm{d}S_t = \mu(t, Y_t, X_t)S_t\mathrm{d}t + Y_t S_t\mathrm{d}W_t^1$$

$$= \mu(t, Y_t, X_t)S_t\mathrm{d}t + Y_t S_t\left(\mathrm{d}\hat{W}_t^1 - \frac{\mu(t, Y_t, X_t)}{Y_t}\mathrm{d}t \right)$$

$$= Y_t S_t\mathrm{d}\hat{W}_t^1.$$

and

$$\mathrm{d}Y_t$$

$$= a(t, Y_t, X_t)\mathrm{d}t + b(t, Y_t, X_t)\mathrm{d}W_t^2$$

$$= a(t, Y_t, X_t)\mathrm{d}t + b(t, Y_t, X_t)\left(\rho\mathrm{d}W_t^1 + \sqrt{1-\rho^2}\mathrm{d}W_t^3 \right)$$

$$= a(t, Y_t, X_t)\mathrm{d}t + b(t, Y_t, X_t)$$

$$\cdot \left(\rho\left(\mathrm{d}\hat{W}_t^1 - \frac{\mu(t, Y_t, X_t)}{Y_t}\mathrm{d}t \right) + \sqrt{1-\rho^2}\mathrm{d}\hat{W}_t^3 \right)$$

$$= \left(a(t, Y_t, X_t) - \frac{\rho}{Y_t}\mu(t, Y_t, X_t)b(t, Y_t, X_t) \right)\mathrm{d}t$$

$$+ b(t, Y_t, X_t)\left(\rho\mathrm{d}\hat{W}_t^1 + \sqrt{1-\rho^2}\mathrm{d}\hat{W}_t^3 \right). \square$$

3.2.2. Decomposition of the Contingent Claim H with Respect to S under $\hat{P}$

Let H be a contingent claim of the form $H = h(S_T, Y_T, X_T)$, then finding the Galtchouk-Kunita-Watanabe decomposition of H under $\hat{P}$ reduces to solve a system of partial differential equations if one exploits the Markovian structure. Indeed, using the Markov property, we can rewrite (2.16):

$$V_t(\varphi^{lr}) = \hat{\mathbb{E}}\left[h(S_T) \big| \mathcal{F}_t \right]$$

$$= \hat{v}(t, S_t, Y_t, X_t),$$

$$t \in [0,T],$$

for some function $\hat{v}$ defined on $[0,T] \times (0,\infty) \times \mathbb{R} \times \mathcal{S}$.

Proposition 2.4 *For all* $t \in [0,T]$, *if* $X_t = i \in \mathcal{S}$, *then* $\hat{v}$ *is the solution to the system of partial differential equations given by*

$$0 = \hat{v}_t(t, S_t, Y_t, i) + \hat{a}(t, Y_t, i)\hat{v}_y(t, S_t, Y_t, i)$$

$$+ \sum_{j \neq i, j \in \mathcal{S}} q_{ij}\left(\hat{v}(t, S_t, Y_t, j) - \hat{v}(t, S_t, Y_t, i) \right)$$

$$+ \frac{1}{2}\Big[S_t^2 Y_t^2 \hat{v}_{ss}(t, S_t, Y_t, i) + b(t, Y_t, i)^2 \hat{v}_{yy}(t, S_t, Y_t, i)$$

$$+ 2S_t Y_t b(t, Y_t, i)\rho\hat{v}_{sy}(t, S_t, Y_t, i) \Big] \tag{2.20}$$

with terminal condition for all $i \in \mathcal{S}$ given by

$\hat{v}(T, S_T, Y_T, i) = h(S_T, Y_T, i) := H$ and where $\hat{v}_t := \dfrac{\partial \hat{v}}{\partial t}$,

$\hat{v}_y := \dfrac{\partial \hat{v}}{\partial Y}$, $\hat{v}_{ss} := \dfrac{\partial^2 \hat{v}}{\partial S^2}$, $\hat{v}_{yy} := \dfrac{\partial^2 \hat{v}}{\partial Y^2}$ and $\hat{v}_{sy} := \dfrac{\partial^2 \hat{v}}{\partial S \partial Y}$.

Proof. Since

$$\hat{v}(t, S_t, Y_t, X_t)$$

$$= \hat{v}(0, S_0, Y_0, X_0) + \int_0^t \frac{\partial \hat{v}(u, S_u, Y_u, X_u)}{\partial u} du$$

$$+ \int_0^t \frac{\partial \hat{v}(u, S_u, Y_u, X_u)}{\partial S} dS_u$$

$$+ \frac{1}{2} \int_0^t \frac{\partial^2 \hat{v}(u, S_u, Y_u, X_u)}{\partial S^2} d\langle S \rangle_u + \int_0^t \frac{\partial \hat{v}(u, S_u, Y_u, X_u)}{\partial Y} dY_u$$

$$+ \frac{1}{2} \int_0^t \frac{\partial^2 \hat{v}(u, S_u, Y_u, X_u)}{\partial Y^2} d\langle Y \rangle_u$$

$$+ \int_0^t \frac{\partial^2 \hat{v}(u, S_u, Y_u, X_u)}{\partial S \partial Y} d\langle S, Y \rangle_u$$

$$+ \sum_{u \le T} \left[\hat{v}(u, S_u, Y_u, X_u) - \hat{v}(u, S_{u-}, Y_{u-}, X_{u-}) \right]$$

$$(2.21)$$

and notice that for any function g on $[0, T] \times (0, \infty) \times \mathbb{R} \times \mathcal{S}$, which is right continuous and with left limits in u, we have

$$\sum_{u \le T} \left[g(u, S_u, Y_u, X_u) - g(u, S_{u-}, Y_{u-}, X_{u-}) \right]$$

$$= \int_0^t \int_{\mathcal{S}} \left[g(u, S_u, Y_u, j) - g(u, S_{u-}, Y_{u-}, X_{u-}) \right] \nu(du, dj)$$

$$= \int_0^t \int_{\mathcal{S}} \left[g(u, S_u, Y_u, j) - g(u, S_{u-}, Y_{u-}, X_{u-}) \right] (\nu - \bar{\nu})(du, dj)$$

$$+ \int_0^t \sum_{j \in \mathcal{S}} \left[g(u, S_u, Y_u, j) - g(u, S_u, Y_u, X_u) \right] q_{X_u j} du,$$

$$= \int_0^t \int_{\mathcal{S}} \left[g(u, S_u, Y_u, j) - g(u, S_{u-}, Y_{u-}, X_{u-}) \right] (\nu - \bar{\nu})(du, dj)$$

$$+ \int_0^t Q g(u, S_u, Y_u, X_u) du.$$

Hence, replacing the last equality in (2.21) gives

$$\hat{v}(t, S_t, Y_t, X_t)$$

$$= \hat{v}(0, S_0, Y_0, X_0) + \int_0^t \frac{\partial \hat{v}(u, S_u, Y_u, X_u)}{\partial u} du$$

$$+ \int_0^t \frac{\partial \hat{v}(u, S_u, Y_u, X_u)}{\partial S} Y_u S_u d\hat{W}_u^1$$

$$+ \frac{1}{2} \int_0^t \frac{\partial^2 \hat{v}(u, S_u, Y_u, X_u)}{\partial S^2} S_u^2 Y_u^2 du$$

$$+ \int_0^t \frac{\partial \hat{v}(u, S_u, Y_u, X_u)}{\partial Y}$$

$$\cdot \left(\hat{a}(u, Y_u, X_u) du + b(u, Y_u, X_u) \left(\rho d\hat{W}_u^1 + \sqrt{1 - \rho^2} d\hat{W}_u^3 \right) \right)$$

$$+ \frac{1}{2} \int_0^t \frac{\partial^2 \hat{v}(u, S_u, Y_u, X_u)}{\partial Y^2} b^2 du$$

$$+ \int_0^t \frac{\partial^2 \hat{v}(u, S_u, Y_u, X_u)}{\partial S \partial Y} \rho S_u Y_u b(u, Y_u, X_u) du$$

$$+ \int_0^t \int_{\mathcal{S}} \left[\hat{v}(u, S_u, Y_u, j) - \hat{v}(u, S_{u-}, Y_{u-}, X_{u-}) \right] (\nu - \bar{\nu})(du, dj)$$

$$+ \int_0^t Q \hat{v}(u, S_u, Y_u, X_u) du.$$

The function $\hat{v}$ is a $\hat{P}$-martingale so all boundary terms are null. Hence we obtain that $\hat{v}$ need to satisfy

$$\frac{\partial \hat{v}(u, S_u, Y_u, X_u)}{\partial u} + \frac{1}{2} \frac{\partial^2 \hat{v}(u, S_u, Y_u, X_u)}{\partial S^2} S_u^2 Y_u^2$$

$$+ \frac{\partial \hat{v}(u, S_u, Y_u, X_u)}{\partial Y} \hat{a}(u, Y_u, X_u) + \frac{1}{2} \frac{\partial^2 \hat{v}(u, S_u, Y_u, X_u)}{\partial Y^2} b^2$$

$$+ \frac{\partial^2 \hat{v}(u, S_u, Y_u, X_u)}{\partial S \partial Y} \rho S_u Y_u b(u, Y_u, X_u)$$

$$+ Q \hat{v}(u, S_u, Y_u, X_u) = 0$$

with terminal condition $\hat{v}(T, S_T, Y_T, X_T) = h(S_T, Y_T, X_T)$. Moreover,

$$Q \hat{v}(u, S_u, Y_u, X_u)$$

$$= \sum_{j \ne i, j \in \mathcal{S}} q_{ij} \left(\hat{v}(u, S_u, Y_u, j) - \hat{v}(u, S_u, Y_u, i) \right),$$

where $\hat{v}(u, S_u, Y_u, i)$ means that at time $u \in [0, T]$ the Markov process is in state $i \in \mathcal{S}$ (i.e. $X_u = i$). Hence with $i \in \{0, 1, \cdots, N\}$, we obtain the expected result.□

Example 2.2 (Pricing European call options on the underlying process S) *The value of an European call option on the stock price S with maturity T and strike K is given by $h(S_T) = (S_T - K)^+$. Hence we can apply Proposition* 2.4 *with*

$$C_t = \hat{\mathbb{E}} \left[h(S_T) \mid \mathcal{F}_t \right] = \hat{\mathbb{E}} \left[(S_T - K)^+ \mid \mathcal{F}_t \right] = \hat{v}(t, S_t, Y_t, X_t)$$

where the terminal conditions for all $i \in \mathcal{S}$ are given by $C_T(i) = \hat{v}(T, s, y, i) = (S_T(i) - K)^+$.

According to (2.12) and (2.15), we are now able to find the decomposition of H with respect to S under $\hat{P}$ and so the locally risk minimizing H-admissible strategy φ^{lr}.

Theorem 2.1 *For all $t \in [0, T]$, we have that the locally risk-minimizing hedging strategy of H, $\varphi^{lr} := (v^{lr}, \eta^{lr})$ is given by*

$$v_t^{lr} = \hat{v}_s(u, S_u, Y_u, X_u)$$

$$+ \hat{v}_y(u, S_u, Y_u, X_u) \frac{\rho}{S_u Y_u} b(u, Y_u, X_u), \quad (2.22)$$

$$\eta_t^{lr} = V_t(\varphi^{lr}) - v_t^{lr} S_t, \quad (2.23)$$

where

$$V_t(\varphi^{lr}) = V_0(\varphi^{lr}) + \int_0^t v_s^{lr} dS_s + L_t^{lr},$$

and

$$L_t^{lr} = \int_0^t \sqrt{1 - \rho^2} \hat{v}_y(u, S_u, Y_u, X_u) b(u, Y_u, X_u) d\hat{W}_u^3$$

$$+ \int_0^t \int_{\mathcal{S}} \left[\hat{v}(u, S_u, Y_u, j) - \hat{v}(u, S_{u-}, Y_{u-}, X_{u-}) \right] (\nu - \bar{\nu})(du, dj)$$

Remark 2.6 *Moreover, taking the problem at time $t = T$, we get*

$$H := V_T\left(\varphi^{lr}\right) = V_0\left(\varphi^{lr}\right) + \int_0^T v_s^{lr}\, \mathrm{d}S_s + L_T^{lr},$$

which is the so-called Föllmer-Schweizer decomposition of the random variable H.

Proof. Let $t = T$, apply Ito's formula to $\hat{v}(T, S_T, Y_T, X_T) = h(S_T, Y_T, X_T) := H$, then by (2.21), we obtain:

$$h\left(S_T, Y_T, X_T\right)$$
$$= \hat{v}\left(0, s_0, y_0, x_0\right) + \int_0^T \hat{v}_s\left(u, S_u, Y_u, X_u\right)\mathrm{d}S_u$$
$$+ \int_0^T \hat{v}_u\left(u, S_u, Y_u, X_u\right)\mathrm{d}u + \frac{1}{2}\int_0^T \hat{v}_{ss}\left(u, S_u, Y_u, X_u\right)S_u^2 Y_u^2\,\mathrm{d}u$$
$$+ \int_0^T \hat{v}_y\left(u, S_u, Y_u, X_u\right)$$
$$\cdot \left(\hat{a}\left(u, Y_u, X_u\right)\mathrm{d}u + b\left(u, Y_u, X_u\right)\left(\rho\mathrm{d}\hat{W}_u^1 + \sqrt{1-\rho^2}\mathrm{d}\hat{W}_u^3\right)\right)$$
$$+ \frac{1}{2}\int_0^T \hat{v}_{yy}\left(u, S_u, Y_u, X_u\right)b^2\left(u, Y_u, X_u\right)\mathrm{d}u$$
$$+ \int_0^T \hat{v}_{sy}\left(u, S_u, Y_u, X_u\right)S_u Y_u \rho b\left(u, Y_u, X_u\right)\mathrm{d}u$$
$$+ \int_0^T \int_{\mathcal{S}}\left[\hat{v}\left(u, S_u, Y_u, j\right) - \hat{v}\left(u, S_{u-}, Y_{u-}, X_{u-}\right)\right]\left(\nu - \bar{\nu}\right)\left(\mathrm{d}u, \mathrm{d}j\right)$$
$$+ \int_0^T Q\hat{v}\left(u, S_u, Y_u, X_u\right)\mathrm{d}u.$$

We apply now the result of Proposition 2.4 to obtain

$$h\left(S_T, Y_T, X_T\right)$$
$$= \hat{v}\left(0, s_0, y_0, x_0\right) + \int_0^T \hat{v}_s\left(u, S_u, Y_u, X_u\right)\mathrm{d}S_u$$
$$+ \int_0^T \hat{v}_y\left(u, S_u, Y_u, X_u\right)\left(b\left(u, Y_u, X_u\right)\left(\rho\mathrm{d}\hat{W}_u^1 + \sqrt{1-\rho^2}\mathrm{d}\hat{W}_u^3\right)\right)$$
$$+ \int_0^t \int_{\mathcal{S}}\left[\hat{v}\left(u, S_u, Y_u, j\right) - \hat{v}\left(u, S_{u-}, Y_{u-}, X_{u-}\right)\right]\left(\nu - \bar{\nu}\right)\left(\mathrm{d}u, \mathrm{d}j\right)$$
$$= \hat{v}\left(0, s_0, y_0, x_0\right) + \int_0^T \hat{v}_s\left(u, S_u, Y_u, X_u\right)\mathrm{d}S_u$$
$$+ \int_0^T \hat{v}_y\left(u, S_u, Y_u, X_u\right)\frac{b\left(u, Y_u, X_u\right)\rho}{S_u Y_u}\mathrm{d}S_u$$
$$+ \int_0^T \hat{v}_y\left(u, S_u, Y_u, X_u\right)b\left(u, Y_u, X_u\right)\sqrt{1-\rho^2}\mathrm{d}\hat{W}_u^3$$
$$+ \int_0^T \int_{\mathcal{S}}\left[\hat{v}\left(u, S_u, Y_u, j\right) - \hat{v}\left(u, S_{u-}, Y_{u-}, X_{u-}\right)\right]\left(\nu - \bar{\nu}\right)\left(\mathrm{d}u, \mathrm{d}j\right)$$

Combining this result with

$V_t\left(\varphi^{lr}\right) = V_0\left(\varphi^{lr}\right) + \int_0^t v_s^{lr}\,\mathrm{d}S_s + L_t^{lr}$ gives the expected result.□

We can also obtain a formulation of the conditional expected squared cost on the time interval $[t, T]$ for the locally risk-minimizing strategy φ^{lr}.

Proposition 2.5 *We have, for all $t \in [0, T]$, that the conditional expected squared cost on the interval $[t, T]$ for the locally risk-minimizing strategy φ^{lr} is given by*

$$R_t^{lr} = \mathbb{E}\left[\left(\int_t^T \sqrt{1-\rho^2}\hat{v}_y\left(u\right)b\left(u\right)\mathrm{d}\hat{W}_u^3\right)^2 \middle| \mathcal{F}_t\right]$$
$$+ \mathbb{E}\left[\int_t^T \left[Q\hat{v}^2\left(u, X_{u-}\right) - 2\hat{v}\left(u, X_{u-}\right)Q\hat{v}\left(u, X_{u-}\right)\right]\mathrm{d}u\middle| \mathcal{F}_t\right]$$
$$+ 2\mathbb{E}\left[\left(\int_t^T \sqrt{1-\rho^2}\hat{v}_y\left(u\right)b\left(u\right)\mathrm{d}\hat{W}_u^3\right)\left(\int_t^T \int_{\mathcal{S}}\left[\hat{v}\left(u, j\right) - \hat{v}\left(u, X_{u-}\right)\right]\left(\nu - \bar{\nu}\right)\left(\mathrm{d}u, \mathrm{d}j\right)\right)\middle| \mathcal{F}_t\right]$$

Proof. Applying the result of Theorem 2.1 in (2.8) we obtain

$$R_t\left(\varphi^{lr}\right) = \mathbb{E}\left[\left(C_T\left(\varphi^{lr}\right) - C_t\left(\varphi^{lr}\right)\right)^2\middle|\mathcal{F}_t\right] = E\left[\left(L_T^{lr} - L_t^{lr}\right)^2\middle|\mathcal{F}_t\right]$$
$$= \mathbb{E}\left[\left(\int_t^T \sqrt{1-\rho^2}\hat{v}_y\left(u\right)b\left(u\right)\mathrm{d}\hat{W}_u^3 + \int_t^T \int_{\mathcal{S}}\left[\hat{v}\left(u, j\right) - \hat{v}\left(u, X_{u-}\right)\right]\left(\nu - \bar{\nu}\right)\left(\mathrm{d}u, \mathrm{d}j\right)\right)^2\middle|\mathcal{F}_t\right]$$
$$= \mathbb{E}\left[\left(\int_t^T \sqrt{1-\rho^2}\hat{v}_y\left(u\right)b\left(u\right)\mathrm{d}\hat{W}_u^3\right)^2\middle|\mathcal{F}_t\right] + \mathbb{E}\left[\left(\int_t^T \int_{\mathcal{S}}\left[\hat{v}\left(u, j\right) - \hat{v}\left(u, X_{u-}\right)\right]\left(\nu - \bar{\nu}\right)\left(\mathrm{d}u, \mathrm{d}j\right)\right)^2\middle|\mathcal{F}_t\right]$$
$$+ 2\mathbb{E}\left[\left(\int_t^T \sqrt{1-\rho^2}\hat{v}_y\left(u\right)b\left(u\right)\mathrm{d}\hat{W}_u^3\right)\left(\int_t^T \int_{\mathcal{S}}\left[\hat{v}\left(u, j\right) - \hat{v}\left(u, X_{u-}\right)\right]\left(\nu - \bar{\nu}\right)\left(\mathrm{d}u, \mathrm{d}j\right)\right)\middle|\mathcal{F}_t\right].$$

We can also simplify the second expectation

$$\mathbb{E}\left[\int_t^T \int_{\mathcal{S}}\left[\hat{v}\left(u, j\right) - \hat{v}\left(u, X_{u-}\right)\right]^2 \bar{\nu}\left(\mathrm{d}u, \mathrm{d}j\right)\middle|\mathcal{F}_t\right] = \mathbb{E}\left[\int_t^T \sum_{j\in\mathcal{S}}\left[\hat{v}^2\left(u, j\right) + \hat{v}^2\left(u, X_{u-}\right) - 2\hat{v}\left(u, j\right)\hat{v}\left(u, X_{u-}\right)\right]q_{X_{u-}j}\mathrm{d}u\middle|\mathcal{F}_t\right]$$
$$= \mathbb{E}\left[\int_t^T \left[Q\hat{v}^2\left(u, X_{u-}\right) - 2\hat{v}\left(u, X_{u-}\right)Q\hat{v}\left(u, X_{u-}\right)\right]\mathrm{d}u\middle|\mathcal{F}_t\right].□$$

To apply all the results about local risk minimizing hedging strategy , it remains to prove that $\hat{Z}$ is a true P-martingale and square integrable under P. A well-known sufficient condition for both is the boundedness of the mean variance tradeoff process K, stated in Proposition 0.2, uniformly in t and ω (see [12-14]).

Proposition 2.6 *If the mean variance tradeoff process K, defined in Proposition* 0.2, *is uniformly bounded in t and ω then we have that*:

1) $\hat{Z}$ is a true P-martingale and square integrable under P.

2) H admits a Föllmer-Schweizer decomposition given by (2.11).

3) $\varphi_t^{lr} := \left(v_t^{lr}, \eta_t^{lr} \right)_{t \in [0,T]}$, defined in (2.12) and (2.13), is the local risk minimizing hedging strategy.

Example 2.3 (Heston model) *We can take for the model* (1.1) *a Heston model case. Hence, by Example* 1.1, *we take*

$$\mu(t, Y_t, X_t) = \mu(X_t) Y_t$$
$$\text{with} \quad \mu = (\mu_1, \cdots, \mu_N) \in \mathbb{R}^N,$$

$$a(t, Y_t, X_t) = \frac{4\kappa(X_t)\theta(X_t) - \sigma(X_t)^2}{8Y_t}$$
$$-\frac{\kappa(X_t)}{2} Y_t,$$

$$\text{with} \quad \kappa = (\kappa_1, \cdots, \kappa_N), \theta = (\theta_1, \cdots, \theta_N),$$
$$\text{and} \quad \sigma = (\sigma_1, \cdots, \sigma_N),$$

$$b(t, Y_t, X_t) = \frac{\sigma(X_t)}{2} \quad \text{and} \quad \rho = \rho_0 \in \,]-1,1[.$$

The constants κ_i, θ_i and σ_i are all nonnegative for all $i \in \mathcal{S}$. And we assume for the existence and positivity of the solution Y that for all $i \in \mathcal{S}$,

$$\kappa_i \theta_i \geq \frac{1}{2}\sigma_i.$$

The model is then given by

$$dS_t = \mu(X_t) Y_t S_t dt + Y_t S_t dW_t^1,$$
$$dY_t^2 = \kappa(X_t)\left(\theta(X_t) - Y_t^2\right) dt + \sigma(X_t) Y_t dW_t^2,$$

and the corresponding mean variance tradeoff process is then given by

$$K_t = \int_0^t \frac{\mu(t, Y_s, X_s)^2}{Y_s^2} ds = \int_0^t \frac{\mu^2(X_s) Y_s^2}{Y_s^2} ds$$
$$= \int_0^t \mu^2(X_s) ds < \infty.$$

Hence the MVT process K is deterministic so bounded uniformly in $t \in [0,T]$ and ω. This implies that $\hat{Z}$ is a P-martingale and so that we can apply all the results

mentioned before.

4. Pricing Option on the Volatility: Y_t

We are now interested in establishing some formulae to price options based on the stochastic volatility process Y.

4.1. Variance Swap

A variance swap is a forward contract on the annualized variance, which is the square of the realized annual volatility. Thus, let Y_R^2 denote the realized annual stock variance over the life of the contract. Then it is given by:

$$Y_R^2 = \frac{1}{T} \int_0^T Y_t^2 dt. \tag{3.24}$$

Let K_v and M denote the delivery price for variance and the notional amount of the swap in dollars per annualized volatility point squared. Then, the payoff H of the variance swap at the maturity time T is given by $H = M\left(Y_R^2 - K_v\right)$. Intuitively, the buyer will receive M dollars for each point by which the realized annual variance Y_R^2 has exceeded the variance delivery price K_v. The results provided, in the sequel, are an extension of the results obtained in [10]. Indeed, firstly we study more general class of stochastic volatility models and secondly we apply our results, in the particular case of Heston model, but where not only the long-term volatility level depends on the regime but also the speed of mean reversion on the volatility of the volatility.

Hence, we start by considering the evaluation of the conditional price of a derivative H given the information about the sample path of the Markov process from time 0 to time T (*i.e.* $\mathcal{F}_T^X$). This means that we assume to know all the historical path of the Markov process X. Assume, also, that we are under the minimal ELMM $\hat{P} \in \mathbb{P}$. Thus, we recall that in this case our regime switching model is given by:

$$dS_t = Y_t S_t d\hat{W}_t^1,$$
$$dY_t = \hat{a}(t, Y_t, X_t) dt$$
$$+ b(t, Y_t, X_t)\left(\rho d\hat{W}_t^1 + \sqrt{1-\rho^2} d\hat{W}_t^3\right),$$

with

$$\hat{a}(t, Y_t, X_t) = a(t, Y_t, X_t) - \frac{\rho}{Y_t}\mu(t, Y_t, X_t) b(t, Y_t, X_t).$$ In particular, given $\mathcal{F}_T^X$, the conditional price of the variance swap $P(X)$ is given by

$$P(X) = \hat{\mathbb{E}}\left[H \mid F_T^X \right] = \hat{\mathbb{E}}\left[M\left(Y_R^2 - K_v\right) \mid F_T^X \right]$$
$$= M\hat{\mathbb{E}}\left[Y_R^2 \mid F_T^X \right] - MK_v. \tag{3.25}$$

Hence, if we denote as previous

$\hat{W}_t^2 = \rho d\hat{W}_t^1 + \sqrt{1 - \rho^2} d\hat{W}_t^3$, we obtain by Itô formula that for all $t \in [0, T]$,

$$Y_t^2 = Y_0^2 + \int_0^t \left(2Y_t \hat{a}(s, Y_s, X_s) + b^2(s, Y_s, X_s)\right) ds \\ + \int_0^t 2Y_t b(s, Y_s, X_s) d\hat{W}_s^2. \tag{3.26}$$

Thus, given $\mathcal{F}_T^X$, we get

$$\hat{\mathbb{E}}\left[Y_t^2 \mid F_T^X\right] := \hat{\mathbb{E}}^X\left[Y_t^2\right] \\ = Y_0^2 + \int_0^t \hat{\mathbb{E}}^X\left[2Y_s \hat{a}(s, Y_s, X_s) + b^2(s, Y_s, X_s)\right] ds. \tag{3.27}$$

So

$$\frac{d\hat{\mathbb{E}}^X\left[Y_t^2\right]}{dt} = \hat{\mathbb{E}}^X\left[2Y_t \hat{a}(t, Y_t, X_t) + b^2(t, Y_t, X_t)\right]. \tag{3.28}$$

Assumption 3.2 *Assume that we know the solution of Equation* (3.28) *which we will denote by* $y(t, Y_t, X_t)$, *for all* $t \in [0, T]$.

Proposition 3.7 *Under Assumption* 3.2, *we have, for all* $t \in [0, T]$, *that the conditional variance swap price* $P(X)$ *is given by*

$$P(X) = M\left(\frac{1}{T}\int_0^T y(t, Y_t, X_t) dt - K_v\right). \tag{3.29}$$

Example 3.4 (Heston Model) *Assume that we are in the Heston model case. Hence as mentioned in Example* 1.1 *we take*

$$\hat{a}(t, Y_t, X_t) = \frac{4\kappa(X_t)\theta(X_t) - \sigma(X_t)^2}{8Y_t} - \frac{\kappa(X_t)}{2}Y_t$$

and

$$b(t, Y_t, X_t) = \frac{\sigma(X_t)}{2}.$$

Then the dynamic of Y is given by

$$dY_t^2 = \kappa(X_t)\left(\theta(X_t) - Y_t^2\right) dt + \sigma(X_t)Y_t dW_t^2.$$

Moreover, (3.28) becomes

$$\frac{d\hat{\mathbb{E}}^X\left[Y_t^2\right]}{dt} = \kappa(X_t)\left(\theta(X_t) - \hat{\mathbb{E}}^X\left[Y_t^2\right]\right).$$

Let $y_t := \hat{\mathbb{E}}^X\left[Y_t^2\right]$, then we have to solve the differential equation $\frac{dy_t}{d_t} = \kappa(X_t)\left(\theta(X_t) - y_t\right)$. The solution of this differential equation is given for all $t \in [0, T]$ by

$$y_t = y_0 \exp\left(-\int_0^t \kappa(X_s) ds\right) \\ + \frac{\int_0^t \left(\exp\left(\int_0^s \kappa(X_u) du\right)\kappa_s\theta_s\right) ds}{\exp\left(\int_0^t \kappa(X_s) ds\right)}.$$

Thus, we get

$$\hat{\mathbb{E}}^X\left[Y_t^2\right] = Y_0^2 \exp\left(-\int_0^t \kappa(X_s) ds\right) \\ + \frac{\int_0^t \left(\exp\left(\int_0^s \kappa(X_u) du\right)\kappa_s\theta_s\right) ds}{\exp\left(\int_0^t \kappa(X_s) ds\right)}. \tag{3.30}$$

We can now obtain the conditional variance swap price by applying Proposition 3.7:

$$P(X) = M\left[\frac{1}{T}\int_0^T \left(Y_0^2 \exp\left(-\int_0^t \kappa(X_s) ds\right) + \frac{\int_0^t \left(\exp\left(\int_0^s \kappa(X_u) du\right)\kappa_s\theta_s\right) ds}{\exp\left(\int_0^t \kappa(X_s) ds\right)}\right) dt - K_v\right].$$

We can also obtain the value of the conditional variance given the full history of X.

Lemma 3.2 *For all* $t \in [0, T]$, *the conditional variance of* Y_t^2 *is given by*

$$\hat{Var}\left[Y_t^2 \mid \mathcal{F}_T^X\right] \\ = \int_0^t \hat{\mathbb{E}}^X\left[Y_s^2\left(4Y_s \hat{a}(s, Y_s, X_s) + 6b^2(s, Y_s, X_s)\right)\right] ds \\ - \left(\int_0^t \hat{\mathbb{E}}^X\left[2Y_s \hat{a}(s, Y_s, X_s) + b^2(s, Y_s, X_s)\right] ds\right)^2 \\ - 2Y_0^2 \int_0^t \hat{\mathbb{E}}^X\left[2Y_s \hat{a}(s, Y_t, X_t) + b^2(s, Y_s, X_s)\right] ds.$$

Proof. By Ito's lemma we get

$$dY_t^4 = Y_t^2\left(4Y_t \hat{a}(t, Y_t, X_t) + 6b^2(t, Y_t, X_t)\right) dt \\ + 4Y_t^2 b(t, Y_t, X_t) d\hat{W}_t^2$$

Hence, given $\mathcal{F}_T^X$, we find that

$$\hat{\mathbb{E}}^X\left[Y_t^4\right] = Y_0^4 \\ + \int_0^t \hat{\mathbb{E}}^X\left[Y_s^2\left(4Y_s \hat{a}(s, Y_s, X_s) + 6b^2(s, Y_s, X_s)\right)\right] ds. \tag{3.31}$$

Using (3.27) and the definition of the variance give the result.

Example 3.5 (Heston Model) *We continue the study of the Heston model case* (*see Example* 3.4). *Thus Equation* (3.31) *gives*

$$\frac{\hat{\mathbb{E}}^X\left[Y_t^4\right]}{dt} = \left(2\kappa(X_t)\theta(X_t) - \frac{\sigma(X_t)}{2}\right)\hat{E}^X\left[Y_t^2\right] \\ - 2\kappa(X_t)\hat{E}^X\left[Y_t^4\right] + \frac{3}{2}\sigma(X_t)^2.$$

Given (3.30), we know that

$$\hat{\mathbb{E}}^X\left[Y_t^2\right] = Y_0^2 \exp\left(-\int_0^t \kappa(X_s)\,\mathrm{d}s\right)$$

$$+ \frac{\int_0^t \left(\exp\left(\int_0^s \kappa(X_u)\,\mathrm{d}u\right)\kappa_s\theta_s\right)\mathrm{d}s}{\exp\left(\int_0^t \kappa(X_s)\,\mathrm{d}s\right)},$$

which is a function of time $t \in [0,T]$ and the Markov process X. Let $z_t := \hat{\mathbb{E}}^X\left[Y_t^4\right]$, then we have to solve the differential equation given by

$$\frac{\mathrm{d}z_t}{\mathrm{d}_t} = \left(2\kappa(X_t)\theta(X_t) - \frac{\sigma(X_t)}{2}\right)y_t$$

$$-2\kappa(X_t)z_t + \frac{3}{2}\sigma(X_t)^2.$$

The solution of this differential equation is given for all $t \in [0,T]$ by

$$z_t = \frac{1}{u_t}\int_0^t u_s q_s \,\mathrm{d}s + \frac{1}{u_t}z_0$$

where

$$u_t = \exp\left\{\int_0^t 2\kappa(X_s)\,\mathrm{d}s\right\},$$

$$q_t = \left(2\kappa(X_t)\theta(X_t) - \frac{\sigma(X_t)}{2}\right)y_t,$$

$$y_t = Y_0^2 \exp\left(-\int_0^t \kappa(X_s)\,\mathrm{d}s\right)$$

$$+ \frac{\int_0^t \left(\exp\left(\int_0^s \kappa(X_u)\,\mathrm{d}u\right)\kappa_s\theta_s\right)\mathrm{d}s}{\exp\left(\int_0^t \kappa(X_s)\,\mathrm{d}s\right)}.$$

We finally obtain in the Heston model case that

$$\hat{\mathbb{E}}^X\left[Y_t^4\right]$$

$$= e^{-\int_0^t 2\kappa(X_s)\,\mathrm{d}s}\int_0^t e^{\int_0^s 2\kappa(X_u)\,\mathrm{d}u}\left(2\kappa(X_s)\theta(X_s) - \frac{\sigma(X_s)}{2}\right)y_s$$

$$+ Y_0^4 e^{-\int_0^t 2\kappa(X_s)\,\mathrm{d}s}$$

and that the conditional variance is equal to

$$\hat{V}ar\left[Y_t^2 \mid \mathcal{F}_T^X\right]$$

$$= e^{-\int_0^t 2\kappa(X_s)\,\mathrm{d}s}\int_0^t e^{\int_0^s 2\kappa(X_u)\,\mathrm{d}u}\left(2\kappa(X_s)\theta(X_s) - \frac{\sigma(X_s)}{2}\right)y_s$$

$$-2\left(Y_0^2\exp\left(-\int_0^t\kappa(X_s)\,\mathrm{d}s\right)\frac{\int_0^t\left(\exp\left(\int_0^s\kappa(X_u)\,\mathrm{d}u\right)\kappa_s\theta_s\right)\mathrm{d}s}{\exp\left(\int_0^t\kappa(X_s)\,\mathrm{d}s\right)}\right)$$

$$-\left(\frac{\int_0^t\left(\exp\left(\int_0^s\kappa(X_u)\,\mathrm{d}u\right)\kappa_s\theta_s\right)\mathrm{d}s}{\exp\left(\int_0^t\kappa(X_s)\,\mathrm{d}s\right)}\right)^2.$$

4.2. Pricing Volatility Swaps

In this section, we follow the same methodology studied by Broadie and Jain in [8] where there is no regime switching component. We recall that the realized annual stock variance over the life of the contract is given by (3.24) and depends on the values of the Markov process X. Denote by $I_t = \int_0^t Y_s^2\,\mathrm{d}s$ the accumulated variance between time 0 to $t \in [0,T]$. We recall that the process Y^2 is the solution of the stochastic differential equation given by

$$\mathrm{d}Y_t^2 = \left(2Y_t\hat{a}(t,Y_t,X_t) + b^2(t,Y_t,X_t)\right)\mathrm{d}t$$

$$+2Y_t b(t,Y_t,X_t)\,\mathrm{d}\hat{W}_t^2.$$

Hence I_t is the solution of the stochastic differential equation given by $\mathrm{d}I_t = Y_t^2\,\mathrm{d}t$. Let define by E_t^T the expectation at time $t \in [0,T]$ with respect to $\mathcal{F}_T^X$

$$E_t^T = \hat{\mathbb{E}}_t\left[\frac{1}{T}\int_t^T Y_s^2\,\mathrm{d}s \mid \mathcal{F}_T^X\right] = \hat{\mathbb{E}}_t^X\left[\frac{1}{T}\int_t^T Y_s^2\,\mathrm{d}s\right]. \quad (3.32)$$

Hence $\left(E_t^T\right)_{t\in[0,T]}$ depends on the variance process Y^2 of the underlying asset and on the Markov process X. We call by fair conditional variance strike price the quantity K_v^* which is defined such that Equation 3.25 vanishes:

$$P(X) = \hat{\mathbb{E}}\left[H \mid F_T^X\right] = \hat{\mathbb{E}}\left[M\left(Y_R^2 - K_v^*\right) \mid F_T^X\right]$$

$$= \hat{\mathbb{E}}^X\left[M\left(Y_R^2 - K_v^*\right)\right] = 0.$$

Then, we have that $K_v^* = \hat{\mathbb{E}}\left[Y_R^2 \mid F_T^X\right]$ and for time $t = 0$, we obtain that $E_0^T = K_v^*$. We define now the forward price process Z_t^T as

$$Z_t^T = \hat{\mathbb{E}}_t\left[\sqrt{\frac{1}{T}\int_t^T Y_s^2\,\mathrm{d}s} \mid F_T^X\right] = \hat{\mathbb{E}}_t^X\left[\sqrt{\frac{1}{T}\int_t^T Y_s^2\,\mathrm{d}s}\right]. \quad (3.33)$$

Proposition 3.8 *The forward price process Z_t^T can be expressed as a function $F\left(t,Y_t^2,X_t,I_t\right)$ and it is the solution of the system of stochastic differential equations given by*

$$\frac{\partial F}{\partial t} + \frac{\partial F}{\partial I}Y_t^2 + \frac{\partial F}{\partial Y^2}\left(2Y_t\hat{a}(t,Y_t,X_t) + b_t^2\right)$$

$$+ \frac{1}{2}\frac{\partial^2 F}{\partial(Y^2)^2}4Y_t^2 b(t,Y_t,X_t)_t^2 + QF\left(t,Y_t^2,X_t,I_t\right) \quad (3.34)$$

$$= 0$$

with boundary condition given by

$$F\left(T,Y_T^2,X_T,I_T\right) = \sqrt{\frac{I_T}{T}}.$$

Proof. Rewrite Z_t^T as

$$Z_t^T = \hat{\mathbb{E}}_t^X \left[\sqrt{\frac{1}{T} \left(I_t + \int_t^T Y_s^2 \, ds \right)} \right] := F\left(t, Y_t^2, X_t, I_t \right).$$

Applying Itô Lemma to F, using (3.26) and the fact that the forward price measure F is a martingale give the expected result.

5. Conclusions

In this paper, we studied the problem of pricing and hedging options based on an asset which is modeled by a regime switching stochastic volatility model. We presented firstly this class of regime switching stochastic volatility models. We shown that this class of regime switching models encompasses a large panel of classical financial models. We also explained the interest in applications of this kind of models. Secondly, we used the local risk minimization approach to solve the problem of pricing and hedging contingent claims in this incomplete market. Thus, we obtained pricing and hedging formulae and also the formula of the optimal hedging strategy. Finally, we fund formulae to price volatility and variance swap options by solving a system of stochastic differential equations.

Some possible future directions in this field of research are the following:

- Develop a method to estimate all the parameters of this class of regime switching models, including the hidden Markov chain (its transition matrix);

- Apply these pricing and hedging formulae to economic and financial data. Indeed, regarding the existing literature, a good candidate could be the electricity spot price;

- Construct a method to evaluate quickly the solutions of the system of stochastic differential Equations (2.20) and (3.34). A system of spatial and time discretization grids could be considered and investigated.

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