

**NANYANG TECHNOLOGICAL UNIVERSITY**

SEMESTER II EXAMINATION 2023-2024

**MH4601 – DIFFERENTIAL GEOMETRY**

May 2024

TIME ALLOWED: 2 HOURS

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**INSTRUCTIONS TO CANDIDATES**

1. This examination paper contains **FOUR (4)** questions and comprises **FOUR (4)** printed pages.
2. Answer **ALL** questions. The marks for each question are indicated at the start of each question.
3. Answer each question beginning on a **FRESH** page of the answer book.
4. This is a **CLOSED BOOK** exam.
5. Candidates may use calculators. However, they should write down systematically the steps in the workings.

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**QUESTION 1.** (30 marks)

- (a) Consider the following regular curve  $\gamma: \mathbb{R} \rightarrow \mathbb{R}^3$

$$\gamma(t) = (4 \cos t, 1 - 5 \sin t, -3 \cos t).$$

Is this curve parameterized by arc length?

- (b) Calculate the Frenet frame, curvature and torsion of  $\gamma$ .
- (c) Prove that a Frenet curve in  $\mathbb{R}^3$  lies in a plane if and only if its torsion is constantly zero.
- (d) Give an explicit geometric interpretation of the curve  $\gamma$  from Part (a).

**QUESTION 2.** (20 marks)

Let  $U$  be an open subset of  $\mathbb{R}^2$  and let  $f: U \rightarrow \mathbb{R}^3$  be a parameterized surface element. Let  $U'$  also be an open subset of  $\mathbb{R}^2$  and let  $\phi: U' \rightarrow U$  be a diffeomorphism. Define a second parameterized surface element  $g: U' \rightarrow \mathbb{R}^3$  by reparameterizing  $f$  as follows:  $g = f \circ \phi$ .

- (a) Let  $x \in U'$  and set  $y = \phi(x) \in U$ . Prove that

$$\text{Im}(D_y f) = \text{Im}(D_x g)$$

as subspaces inside  $T_{f(y)}\mathbb{R}^3$ .

- (b) Derive a formula expressing a matrix representation of the pull-back of the first fundamental form by  $g$  in terms of a matrix representation of the pull-back of the first fundamental form by  $f$ .

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**QUESTION 3.** **(30 marks)**

Consider the function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  defined by the formula

$$f(u_1, u_2) = (u_2 \cos(u_1), u_2 \sin(u_1), u_1)$$

- (a) Show that this function is a parameterized surface element.
- (b) Determine the matrix representing the first fundamental form with respect to these parameters.
- (c) Compute a matrix representation of the shape operator of this surface.
- (d) What is the Gaussian curvature of this surface?
- (e) Is this a surface of rotation?
- (f) Is this a minimal surface?
- (g) Is this parameterization conformal? If it isn't, find a reparameterization which results in a conformal parameterization.

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**QUESTION 4. (20 marks)**

Consider a curve in  $\mathbb{R}^2$ ,  $c(s) = (A(s), B(s))$ , and assume that  $c(s)$  is parameterized by arc-length and that  $A(s) > 0$ . From this curve we build the following surface of revolution  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ :

$$f(u_1, u_2) = (A(u_1) \cos(u_2), A(u_1) \sin(u_2), B(u_1)).$$

Let  $\omega : I \rightarrow \mathbb{R}^2$  be a smooth curve  $\omega(t) = (\omega^1(t), \omega^2(t))$  into the space of parameters with the property that  $\Omega = f \circ \omega$  is a geodesic on this surface.

- (a) Write down an equation relating  $A(s)$  and  $B(s)$ .
- (b) Write down a differential equation satisfied by the components of  $\omega$  in terms of the Christoffel symbols of the surface.
- (c) By computing those Christoffel symbols, deduce that the components of  $\omega$  satisfy the differential equations

$$\frac{d^2}{dt^2}(\omega^1) = A(\omega^1) \frac{dA}{ds}(\omega^1) \left( \frac{d}{dt}(\omega^2) \right)^2$$

and

$$\frac{d}{dt} \left( (A(\omega^1))^2 \frac{d}{dt}(\omega^2) \right) = 0.$$

- (d) Prove Clairaut's theorem: If  $\psi(t)$  denotes the angle between  $\dot{\Omega}(t)$  and the meridian through  $\Omega(t)$  (recall that a meridian is a curve on the surface obtained by varying the parameter  $u_1$  while the parameter  $u_2$  is held constant), then the quantity

$$A(\omega^1(t)) \sin \psi(t)$$

is constant. Draw an example of a geodesic to roughly illustrate what Clairaut's theorem says about geodesics on surfaces of revolution.

**END OF PAPER**