

NANYANG TECHNOLOGICAL UNIVERSITY

SEMESTER II EXAMINATION 2023-2024

MH4601 – DIFFERENTIAL GEOMETRY

May 2024

TIME ALLOWED: 2 HOURS

INSTRUCTIONS TO CANDIDATES

1. This examination paper contains **FOUR (4)** questions and comprises **FOUR (4)** printed pages.
2. Answer **ALL** questions. The marks for each question are indicated at the start of each question.
3. Answer each question beginning on a **FRESH** page of the answer book.
4. This is a **CLOSED BOOK** exam.
5. Candidates may use calculators. However, they should write down systematically the steps in the workings.

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QUESTION 1.**(30 marks)**

- (a) Consider the following regular curve
- $\gamma: \mathbb{R} \rightarrow \mathbb{R}^3$

$$\gamma(t) = (4 \cos t, 1 - 5 \sin t, -3 \cos t).$$

Is this curve parameterized by arc length?

- (b) Calculate the Frenet frame, curvature and torsion of γ .
- (c) Prove that a Frenet curve in \mathbb{R}^3 lies in a plane if and only if its torsion is constantly zero.
- (d) Give an explicit geometric interpretation of the curve γ from Part (a).

QUESTION 2.**(20 marks)**

Let U be an open subset of \mathbb{R}^2 and let $f: U \rightarrow \mathbb{R}^3$ be a parameterized surface element. Let U' also be an open subset of \mathbb{R}^2 and let $\phi: U' \rightarrow U$ be a diffeomorphism. Define a second parameterized surface element $g: U' \rightarrow \mathbb{R}^3$ by reparameterizing f as follows: $g = f \circ \phi$.

- (a) Let
- $x \in U'$
- and set
- $y = \phi(x) \in U$
- . Prove that

$$\text{Im}(D_y f) = \text{Im}(D_x g)$$

as subspaces inside $T_{f(y)}\mathbb{R}^3$.

- (b) Derive a formula expressing a matrix representation of the pull-back of the first fundamental form by
- g
- in terms of a matrix representation of the pull-back of the first fundamental form by
- f
- .

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QUESTION 3.**(30 marks)**

Consider the function $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by the formula

$$f(u_1, u_2) = (u_2 \cos(u_1), u_2 \sin(u_1), u_1)$$

- (a) Show that this function is a parameterized surface element.
- (b) Determine the matrix representing the first fundamental form with respect to these parameters.
- (c) Compute a matrix representation of the shape operator of this surface.
- (d) What is the Gaussian curvature of this surface?
- (e) Is this a surface of rotation?
- (f) Is this a minimal surface?
- (g) Is this parameterization conformal? If it isn't, find a reparameterization which results in a conformal parameterization.

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QUESTION 4.**(20 marks)**

Consider a curve in \mathbb{R}^2 , $c(s) = (A(s), B(s))$, and assume that $c(s)$ is parameterized by arc-length and that $A(s) > 0$. From this curve we build the following surface of revolution $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$:

$$f(u_1, u_2) = (A(u_1) \cos(u_2), A(u_1) \sin(u_2), B(u_1)).$$

Let $\omega : I \rightarrow \mathbb{R}^2$ be a smooth curve $\omega(t) = (\omega^1(t), \omega^2(t))$ into the space of parameters with the property that $\Omega = f \circ \omega$ is a geodesic on this surface.

- (a) Write down an equation relating $A(s)$ and $B(s)$.
- (b) Write down a differential equation satisfied by the components of ω in terms of the Christoffel symbols of the surface.
- (c) By computing those Christoffel symbols, deduce that the components of ω satisfy the differential equations

$$\frac{d^2}{dt^2}(\omega^1) = A(\omega^1) \frac{dA}{ds}(\omega^1) \left(\frac{d}{dt}(\omega^2) \right)^2$$

and

$$\frac{d}{dt} \left((A(\omega^1))^2 \frac{d}{dt}(\omega^2) \right) = 0.$$

- (d) Prove Clairaut's theorem: If $\psi(t)$ denotes the angle between $\dot{\Omega}(t)$ and the meridian through $\Omega(t)$ (recall that a meridian is a curve on the surface obtained by varying the parameter u_1 while the parameter u_2 is held constant), then the quantity

$$A(\omega^1(t)) \sin \psi(t)$$

is constant. Draw an example of a geodesic to roughly illustrate what Clairaut's theorem says about geodesics on surfaces of revolution.

END OF PAPER