DENVar: A global Dynamic Estimate of NDVI Variance

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Abstract

Since the 1980s, remote-sensing estimates of habitat productivity such as the Normalized Difference Vegetation Index (NDVI) have helped develop and support a variety of hypotheses and inform policy and industriy-related decisions. The free availability of such data has allowed widespread access and use of well-established metrics of habitat productivity. However, historically, users tended to focus solely on (predictable) trends in productivity. In recent years, people have been recognizing the importance of environmental unpredictability (stochasticity), particularly as climate change and human-induced rapid environmental change transform the ecosystems species have evolved in and adapted to. We address this gap by presenting a new global Dynamic Estimate of NDVI Variance, DENVar. We estimate 10 spatiotemporal trends in mean NDVI and the variance around the mean using Hierarchi-11 cal Generalized Additive Models, which provide a flexible yet transparent model structure, 12 unlike machine learning approaches such as neural netwoks. We show that DENVar can 13 be used as a reliable proxy of environmental stochasticity, strongly correlates with **XXX**, and can be used to test many hepotheses related to environmental stochasticity, such as 15 forage unpredictability, regime shifts, We conclude by offering some considerations 16 around quantifying and interpreting environmental stochasticity, and we provide a publicly 17 and freely available shiny app for estimating mean NDVI and the variance around it, DEN-18 Var, for given coordinates and optional dates. The app requires no knowledge of statistics or coding. Additionally, we provide a temporally static raster of mean NDVI and DENVar for the years 1981-2025 that can be used for GIS applications and does not require any knowledge of R.

23 Introduction

- ²⁴ Developments in remote sensing since the 1970s have greatly expanded our ability to quantify
- 25 and monitor lanscapes using satellite imagery
- NDVI is an estimate of greenness, NPP, forage availability
- NDVI has many uses and is often convenient because it's free, well-established, and
- many people focus on changes in the mean
- ability to predict and respond to changes in mean conditions (forage availability, phe-
- nology, etc.) depends on the scale of changes relative to the perception scale (Levin,
- 1992; Frankham & Brook, 2004; Riotte-Lambert & Matthiopoulos, 2020; Steixner-Kumar &
- Gläscher, 2020) and memory (Abrahms et al., 2019). Consequently, environmental stochas-
- ticity is also an important driver, besides changes in the mean (Mezzini et al., 2025)
- variance is hard to calculate, as it depends on a correct estimate of the mean
- paper on estimating the asymptote of environmental variance globally, but variance
- for a closed system must converge towards a finite value (Bachmaier & Backes, 2011;
- Fleming *et al.*, 2014)
- we present DENVar
- HGAMs are higly flexible models that allow us to estimate trends in the data without
- imposing preconceived expectations
- more transparent than black-box machine learning methods like neural networks, etc.
- https://www.sciencedirect.com/science/article/abs/pii/S0034425718305625
- https://silvis.forest.wisc.edu/data/dhis/

45 Methods

46 Choice of color schemes

We represent NDVI using a modified version of Fabio Crameri's divergent bukavu palette (Crameri, 2018), which has high-contrast for deuteranope and protanope vision. For NDVI values between 0 and 1 (the right half of the palette), the colors also have sufficient contrast for the colors to be distinguishable by both tritanope and achomatic vision. Appendix A contains an approximate representation of the color palette for each vision type. We obtained all color palettes from the khroma package (v. 1.14.0, Frerebeau, 2024) for R (v. 4.4.1, R Core Team, 2024).

54 Input data

The models we fit

56 NDVI data

- daily AVHRR-VIIRS
- 15-day average and aggregate(, 2) to make dataset small enough to fit in a single data frame

60 Predictor data

Maps are in Appendix A.

62 Modeling

We estimated spatiotemporal trends in mean NDVI using Hierarchical Generalized Additive Models (HGAMs) via the mgcv package for R (v. 1.9-3, Wood, 2017). To reduce modeling fitting times with negligible losses to model accuracy, we used the bam() function

with fast REstricted Marginal Likelihood (method = fREML) and covariate discretization (discrete = TRUE). The model structure is available below.

68 Results

output of draw()

hex plots of mean and var vs common metrics: * temperature * seasonal temperature

range * precip * seasonal temperature range * spp diversity * gross primary productivity * hfi

* max animal weight * https://silvis.forest.wisc.edu/globalwui/ * https://silvis.forest.wisc.

edu/data/dhis/: * NDVI16 (Normalized Difference Vegetation Index) * EVI16 (Enhanced

Vegetation Index) * FPAR8 (Fraction absorbed Photosynthetically Active Radiation) * LAI8

(Leaf Area Index) * GPP8 (Gross Primary Productivity) * https://silvis.forest.wisc.edu/

data/eurasia-trends/

77 Discussion

- green wave surfing
- migration routes are key habitat (Ortega et al., in prep), especially in stochastic envi-
- Sawyer et al. (2019)
- https://www.sciencedirect.com/science/article/pii/S0960982220308484
- https://onlinelibrary.wiley.com/doi/full/10.1111/gcb.15169
- industrial development affects animals' ability to respond to both predictable and unpredictable change (https://www.nature.com/articles/s41559-022-01887-9)
- effects of sudden deep snow in red desert on proghorn (https://www.sciencedirect.com/science/article/abs/pii/S0960982225002957)

- https://www.nature.com/articles/s41467-023-37750-z
- https://esajournals.onlinelibrary.wiley.com/doi/full/10.1002/ecy.4238
- see data for snow and pronghorn paper (Aikens et al. 2025)
- detecting regime shifts (in lakes: Bjorndahl et al., 2022)
- smoothness of mu impacts smoothness and size of s2: depends on animals' ability to respond to, learn, and predict E(R)

Why not use machine learning? / Advantages of not using ML

arguably, GAMs can be considered as a form of ML, but we are referring to NNs and other forms of black-box ML.

97 Useful references

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