

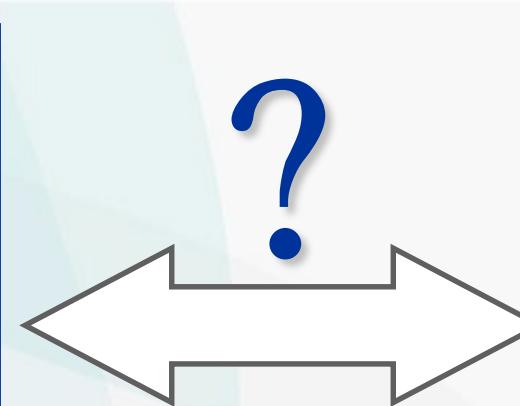
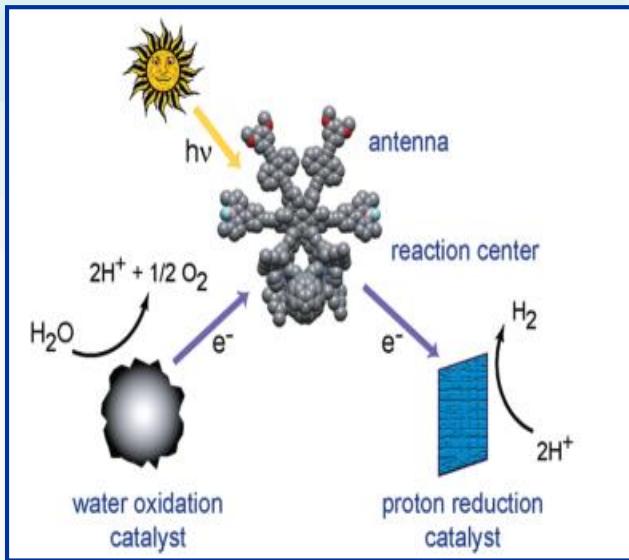
Nonadiabatic Dynamics and Machine Learning

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2024.02

South China Normal University

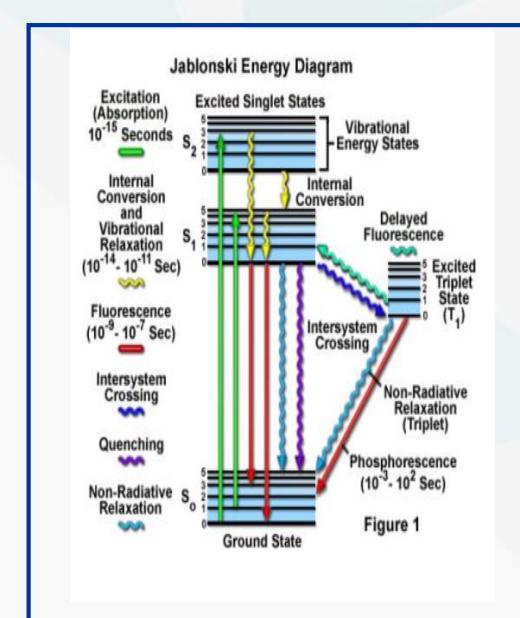
Introduction

2

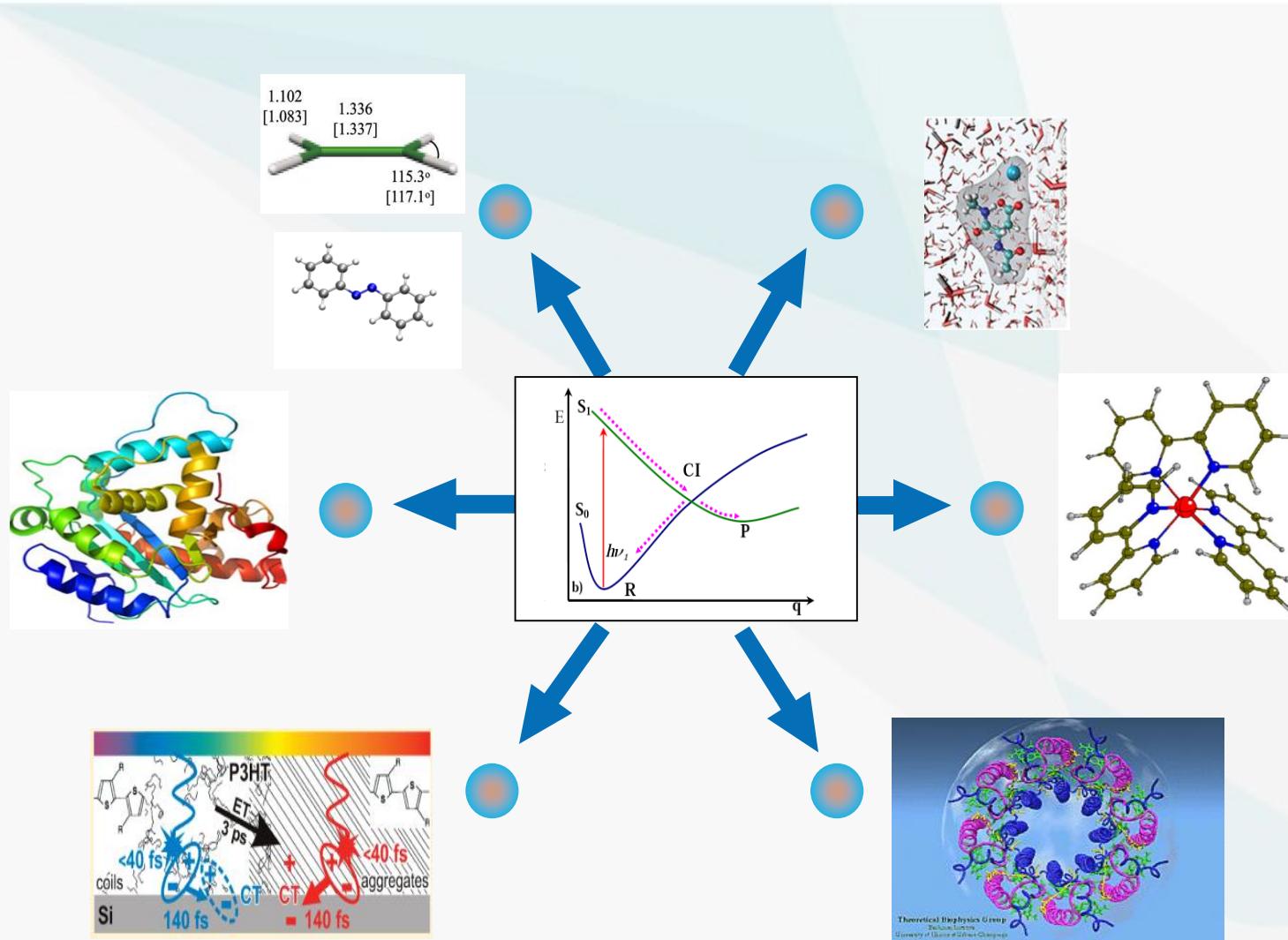


$$H\psi = E\psi, \quad i\hbar \frac{\partial \psi}{\partial t} = H\psi$$

$$\frac{dp_i}{dt} = -\frac{\partial H}{\partial q_i}, \quad \frac{dq_i}{dt} = +\frac{\partial H}{\partial p_i}$$



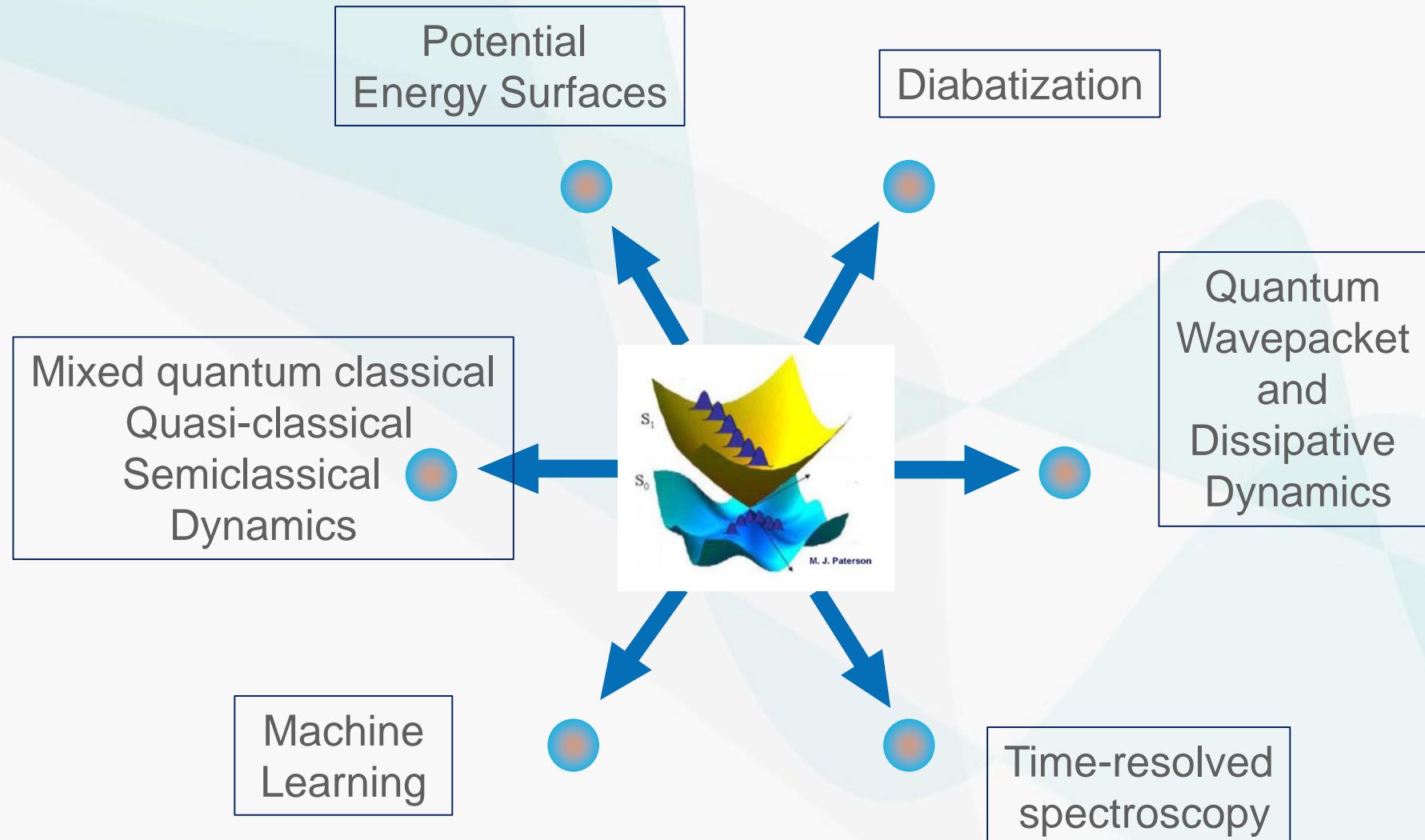
Nonadiabatic dynamics



- Failure of Born-Oppenheimer approximation
- Complex excited-state electronic wavefunctions
- Complexity in realistic polyatomic systems
- Interpretations of experimental observations

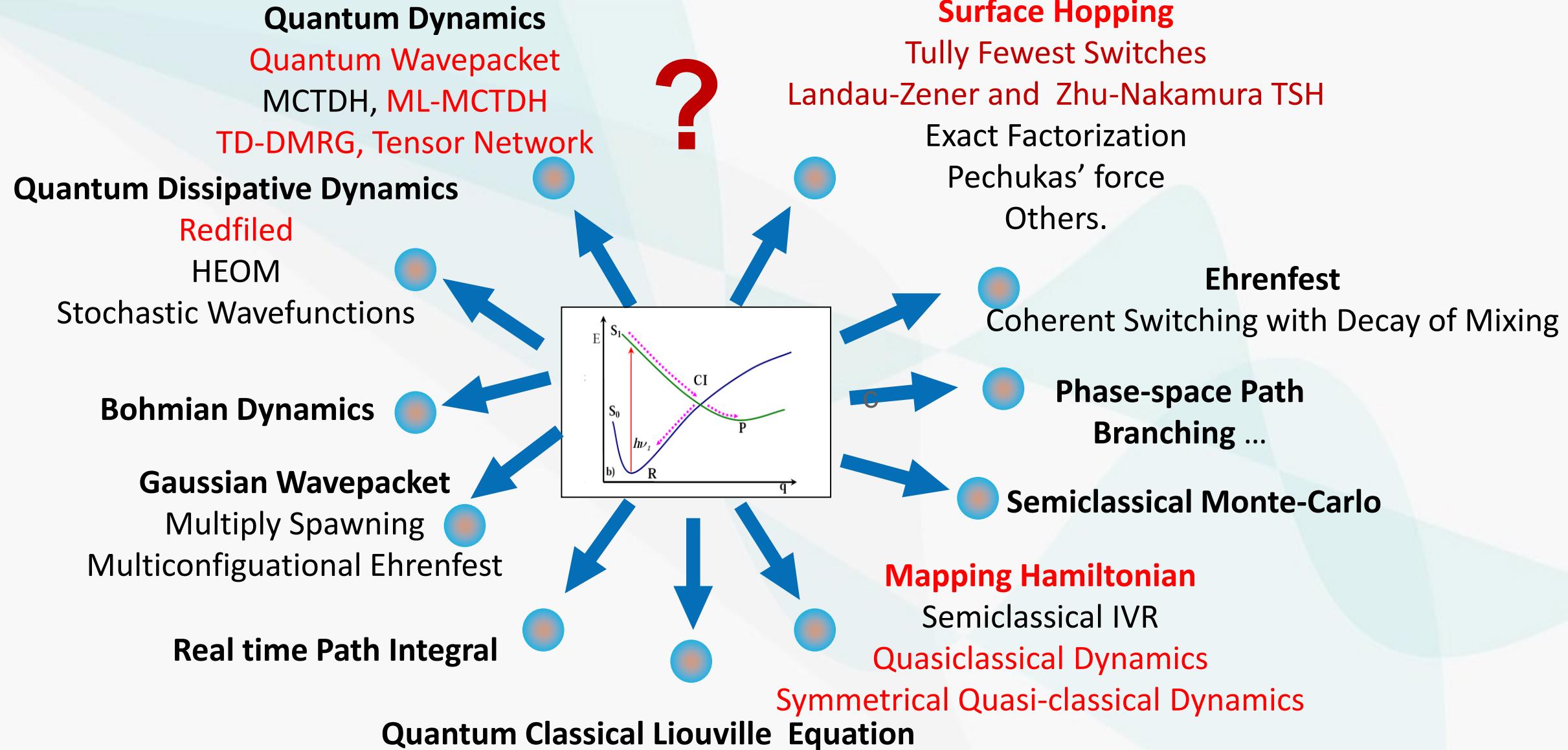
Research highlights

4



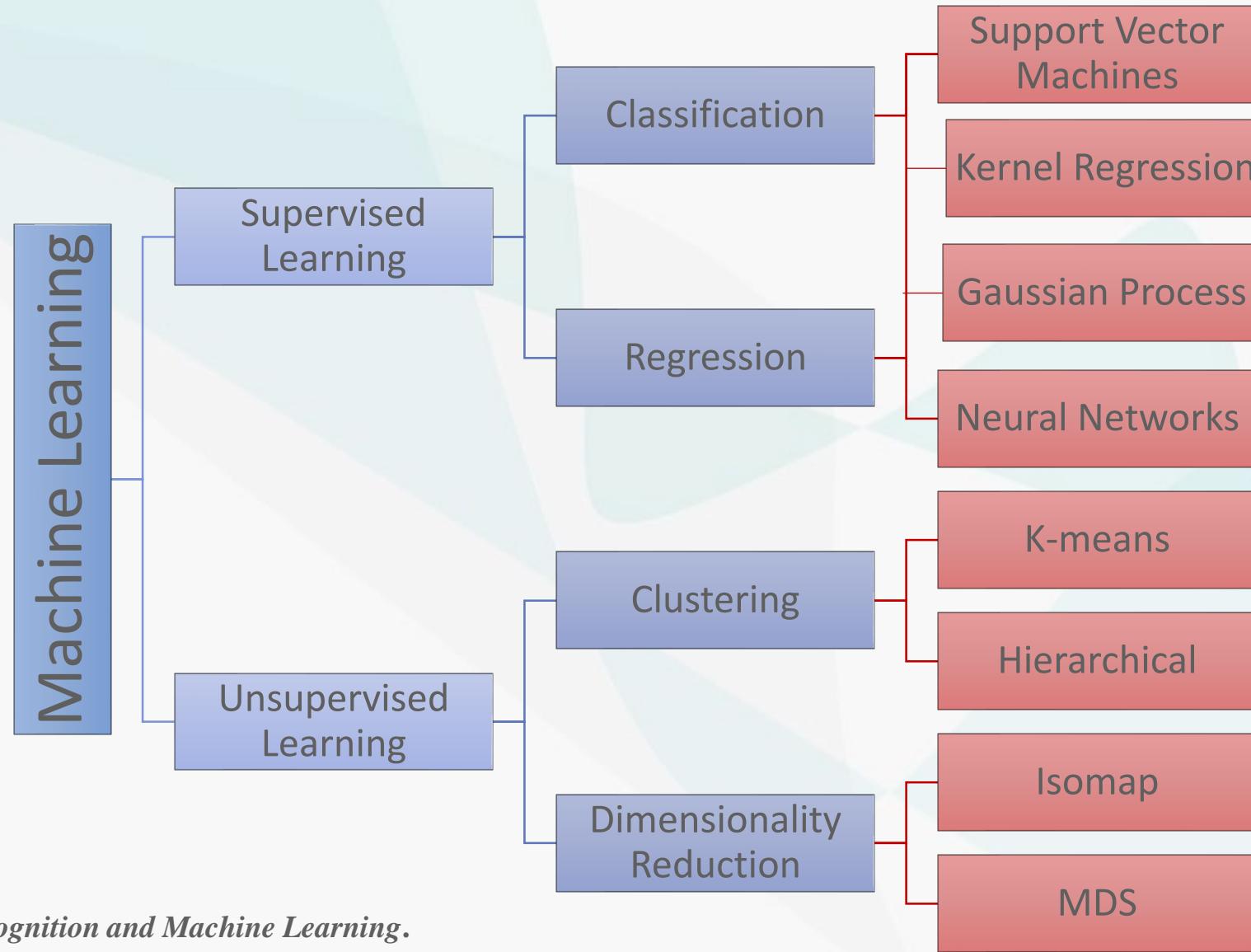
Nonadiabatic Dynamics Methods

5



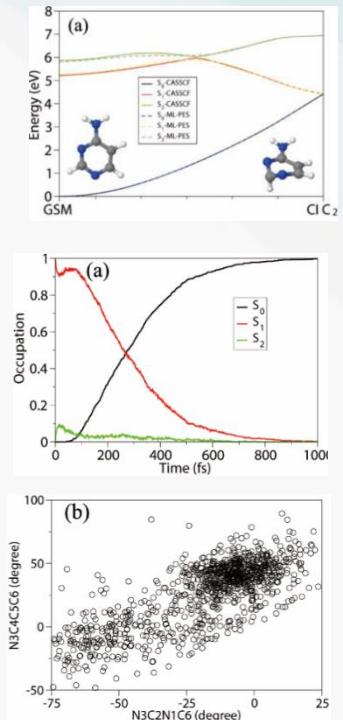
Machine Learning

6



Nonadiabatic Dynamics and Machine Learning

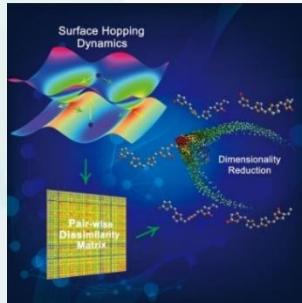
PES Fitting



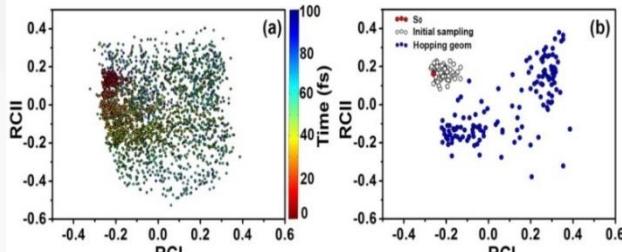
Fast Dynamics

[D. Hu, Z. Lan* et al., *J. Phys. Chem. Lett.*, 2018, 9, 2725]

Result Analyses



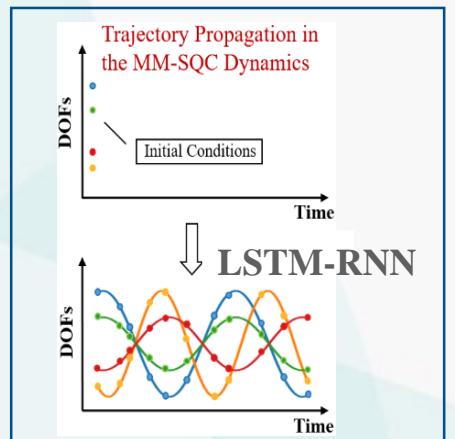
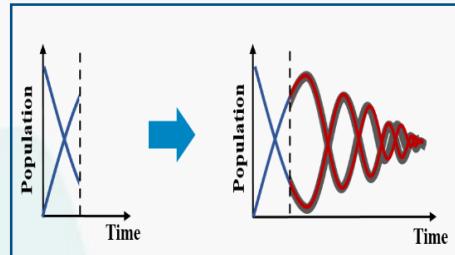
Dimensionality Reduction



Key Coordinates

[X. Li, Z. Lan* et al., *J. Chem. Theory Comput.*, 2017, 13, 4611;
X. Li, Z. Lan* et al., *J. Chem. Phys.*, 2018, 149, 244104;
J. Peng, Z. Lan* et al., *J. Chem. Phys.*, 2021, 159, 094122;
Y. Zhu, Z. Lan* et al., *Phys. Chem. Chem. Phys.*, 2022, 24, 24362]

Dynamics Evolution



Direct Solutions

[K. Lin, F.G. Gu*, Z. Lan* et al., *J. Phys. Chem. Lett.*, 2021, 12, 10225;
K. Lin, F.G. Gu*, Z. Lan* et al., *J. Phys. Chem. Lett.*, 2022, 13, 11678;
K. Lin, F.G. Gu*, Z. Lan* et al., *J. Chem. Theory Comput.*, 2022, 18, 5837]

Open Quantum Systems

8

Open Quantum System

$$H = H_S + H_B + H_{SB}$$

Environment

Hamiltonian H_B
System state ρ_B

Open System

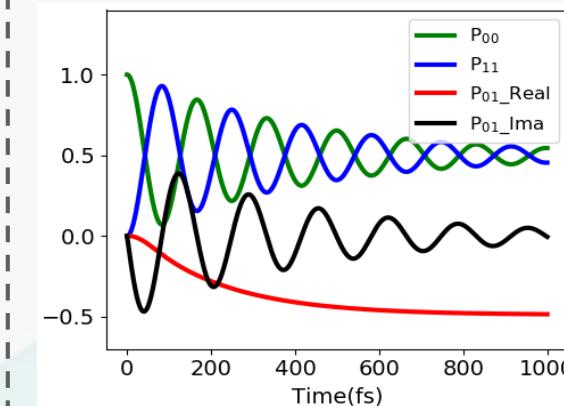
Hamiltonian H_S
System state ρ_S



[*Science*, 344, 1001-1005 (2014)]

[*Phys. Rep.*, 567, 1-78 (2015)]

System-plus-Bath Hamiltonian



$$H = H_S + H_B + H_{SB}$$

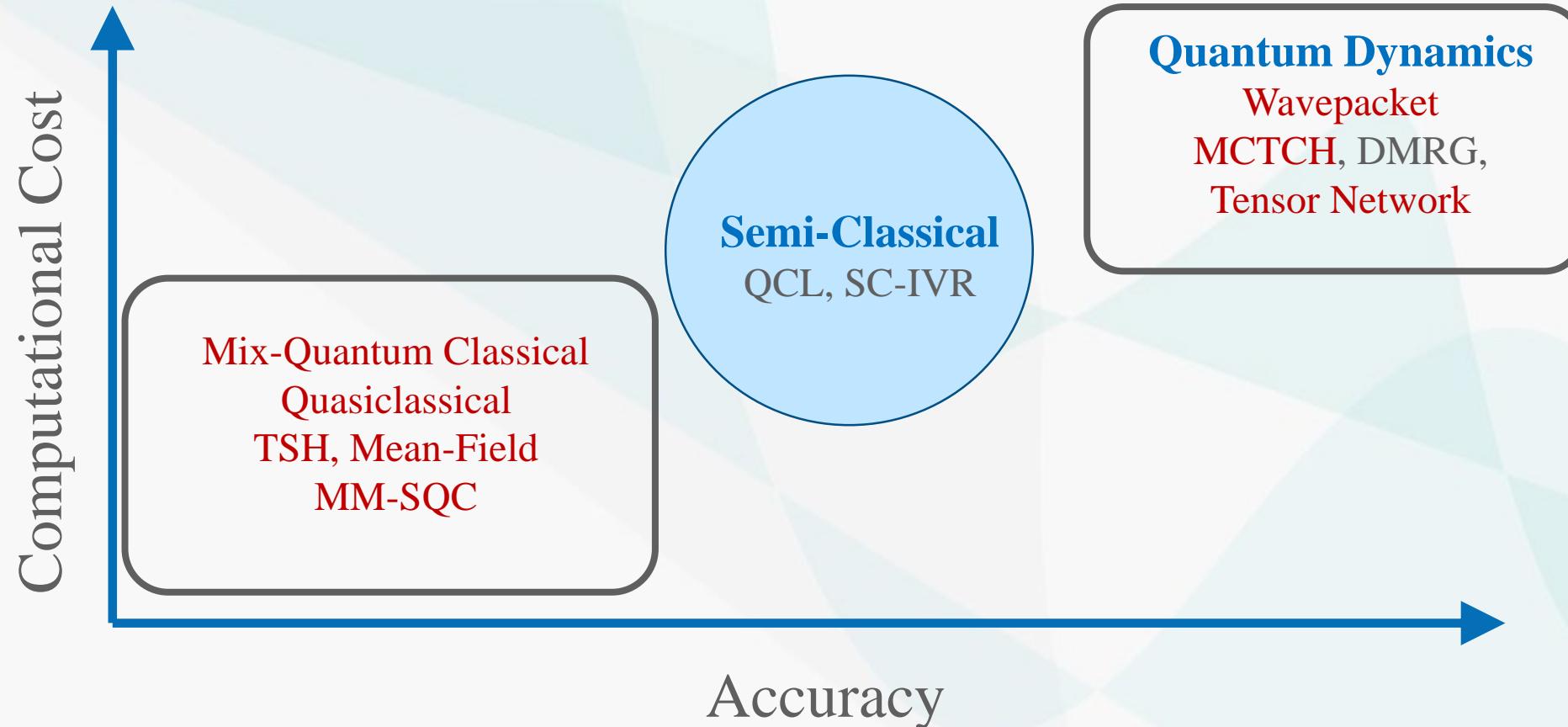
$$H_S = \sum_{k=1}^2 |\varphi_k\rangle V_{kk} \langle \varphi_k| + \sum_{k \neq l} |\varphi_k\rangle V_{kl} \langle \varphi_k|,$$

$$H_B = \sum_{k=1}^2 \sum_j^{N_b} \frac{1}{2} \omega_{kj} (Q_{kj}^2 + P_{kj}^2),$$

$$H_{SB} = \sum_{k=1}^2 |\varphi_k\rangle \left(\sum_j^{N_b} \kappa_{kj} Q_{kj} \right) \langle \varphi_k|.$$

Excited-State Dynamics

9



ML-MCTDH and Tensor Network

Standard propagation method ($f_{\max} \sim 10$)

$$\Psi(Q_1, \dots, Q_f, t) = \sum_{j_1=1}^{N_1} \dots \sum_{j_f=1}^{N_f} C_{j_1 \dots j_f}(t) \prod_{\kappa=1}^f \chi_{j_\kappa}^{(\kappa)}(Q_\kappa)$$

$$i \frac{\partial}{\partial t} C_J = \sum_L H_{JL} C_L$$

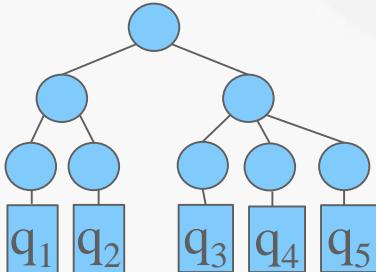


ML-MCTDH ($f_{\max} \sim 1500$)

$$\varphi_m^{z-1}(Q_{\kappa_{l-1}}, t) = \sum_{j_1=1}^{n_1} \dots \sum_{j_{p_{k_l}}=1}^{n_{k_l}} A_{j_1 \dots j_{p_{k_l}}}^z(t) \prod_{\kappa_l=1}^{p_{k_l}} \varphi_{j_{\kappa_l}}^{z, \kappa_l}(Q_{\kappa_l}, t)$$

$$i \dot{A}_J^l = \sum_L \langle \Phi_J^l | H | \Phi_L^l \rangle A_L^l$$

$$i \dot{\varphi}_n^{z, \kappa_l} = (1 - \hat{P}_{\kappa_l}^z) \sum_n (\rho^{z, \kappa_l})_{nj}^{-1} \langle H \rangle_{jm}^{z, \kappa_l} \varphi_m^{z, \kappa_l}$$



Tensor-Train

$$i\hbar \frac{d}{dt} |\Psi(t)\rangle = \hat{P}_T \hat{H} |\Psi(t)\rangle \longrightarrow i\hbar \frac{d}{dt} |\Psi(t)\rangle = - \sum_{i=1}^{m-1} \hat{P}_i^L \otimes \hat{P}_{i+1}^R \hat{H} |\Psi(t)\rangle$$

$$|\Psi\rangle = \sum_{\{s_i\}} \mathbf{L}^{s_1} \dots \mathbf{L}^{s_i} \dots \mathbf{L}^{s_m} |s_1 \dots s_i \dots s_m\rangle = \sum_{\{s_i\}} \mathbf{R}^{s_1} \dots \mathbf{R}^{s_i} \dots \mathbf{R}^{s_m} |s_1 \dots s_i \dots s_m\rangle$$

$$= \sum_{\{s_i\}} \mathbf{L}^{s_1} \dots \mathbf{L}^{s_{i-1}} \mathbf{M}^{s_i} \mathbf{R}^{s_{i+1}} \dots \mathbf{R}^{s_m} |s_1 \dots s_i \dots s_m\rangle$$

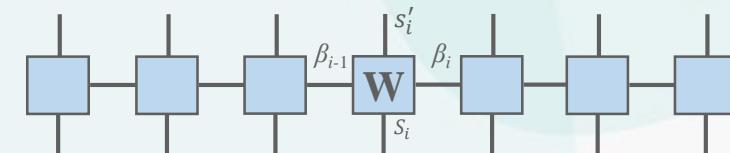
$$= \sum_{\{\alpha_{i-1}, s_i, \alpha_i\}} \left[\mathbf{M}^{s_i} \right]_{\alpha_{i-1}, \alpha_i} \left| \Psi_{L, \alpha_{i-1}}^{[1:i-1]} \right\rangle \left| s_i \right\rangle \left| \Psi_{R, \alpha_i}^{[i+1:m]} \right\rangle$$

$$\hat{O} = \sum_{\{s_i\}, \{\beta_i\}} \mathbf{W}_{\beta_0, \beta_1}^{s_1, s'_1} \dots \mathbf{W}_{\beta_{i-1}, \beta_i}^{s_i, s'_i} \dots \mathbf{W}_{\beta_{m-1}, \beta_m}^{s_m, s'_m} |s_1 \dots s_i \dots s_m\rangle \langle s'_1 \dots s'_i \dots s'_m|$$

$$\hat{P}_T = \sum_{i=1}^m \hat{P}_{i-1}^L \otimes \hat{I}_i \otimes \hat{P}_{i+1}^R - \sum_{i=1}^{m-1} \hat{P}_i^L \otimes \hat{P}_{i+1}^R$$

$$\hat{P}_i^L = \sum_{\alpha_i} \left| \Psi_{L, \alpha_i}^{[1:i]} \right\rangle \left\langle \Psi_{L, \alpha_i}^{[1:i]} \right|$$

$$\hat{P}_i^R = \sum_{\alpha_i} \left| \Psi_{R, \alpha_{i-1}}^{[i:m]} \right\rangle \left\langle \Psi_{R, \alpha_{i-1}}^{[i:m]} \right|$$



[*J. Chem. Phys.*, 128:164116 (2008)]

[*J. Chem. Phys.*, 119:1289 (2003)]

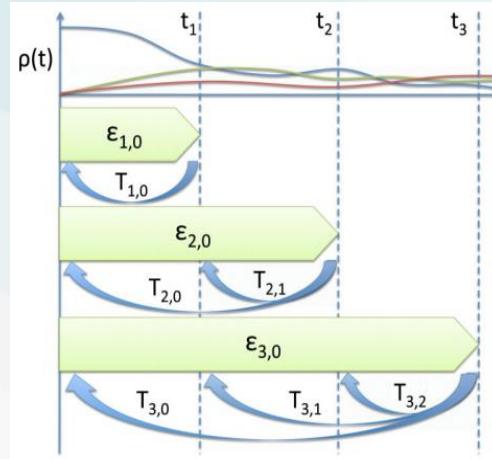
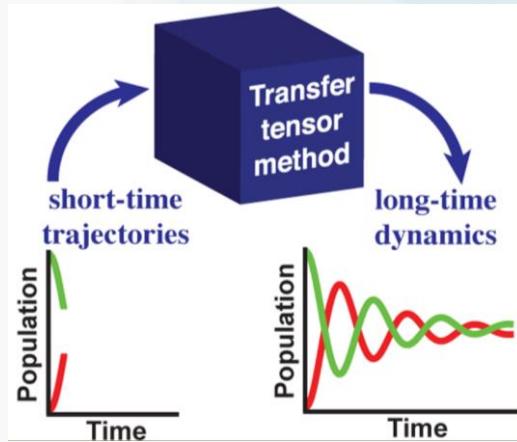
[*Phys. Rep.*, 324:100-105 (2000)]

[*J. Phys. Chem. A*, 119:7951-7965 (2015)]

[*Ann. Phys.* 326:96 (2011)]

[*Phys. Rev. B* 94:165116 (2016)]

Transfer-Tensor Method



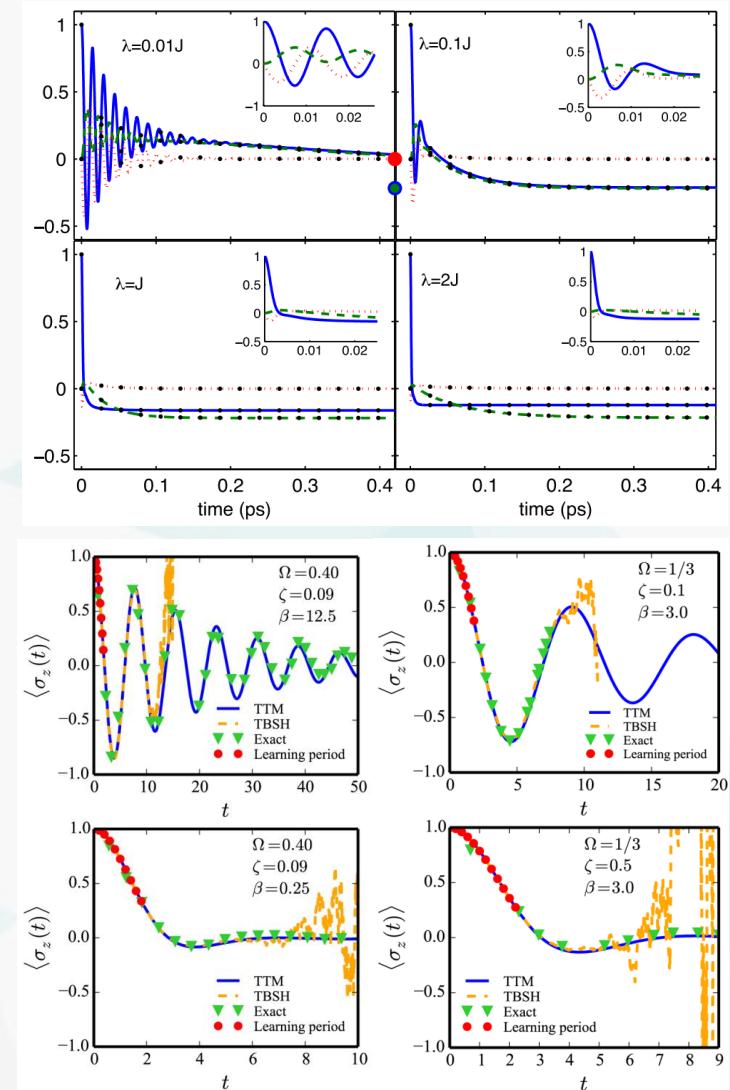
$$T_{n,0} = \mathcal{E}_n - \sum_{m=1}^{n-1} T_{n,m} \mathcal{E}_m,$$

$$\rho(t_n) = \sum_{k=0}^{n-1} T_{n,k} \rho(t_k)$$

$$\rho(t_m) = (T_1 T_2 \dots T_K) \begin{pmatrix} \rho(t_{m-1}) \\ \rho(t_{m-2}) \\ \vdots \\ \rho(t_{m-K}) \end{pmatrix}$$

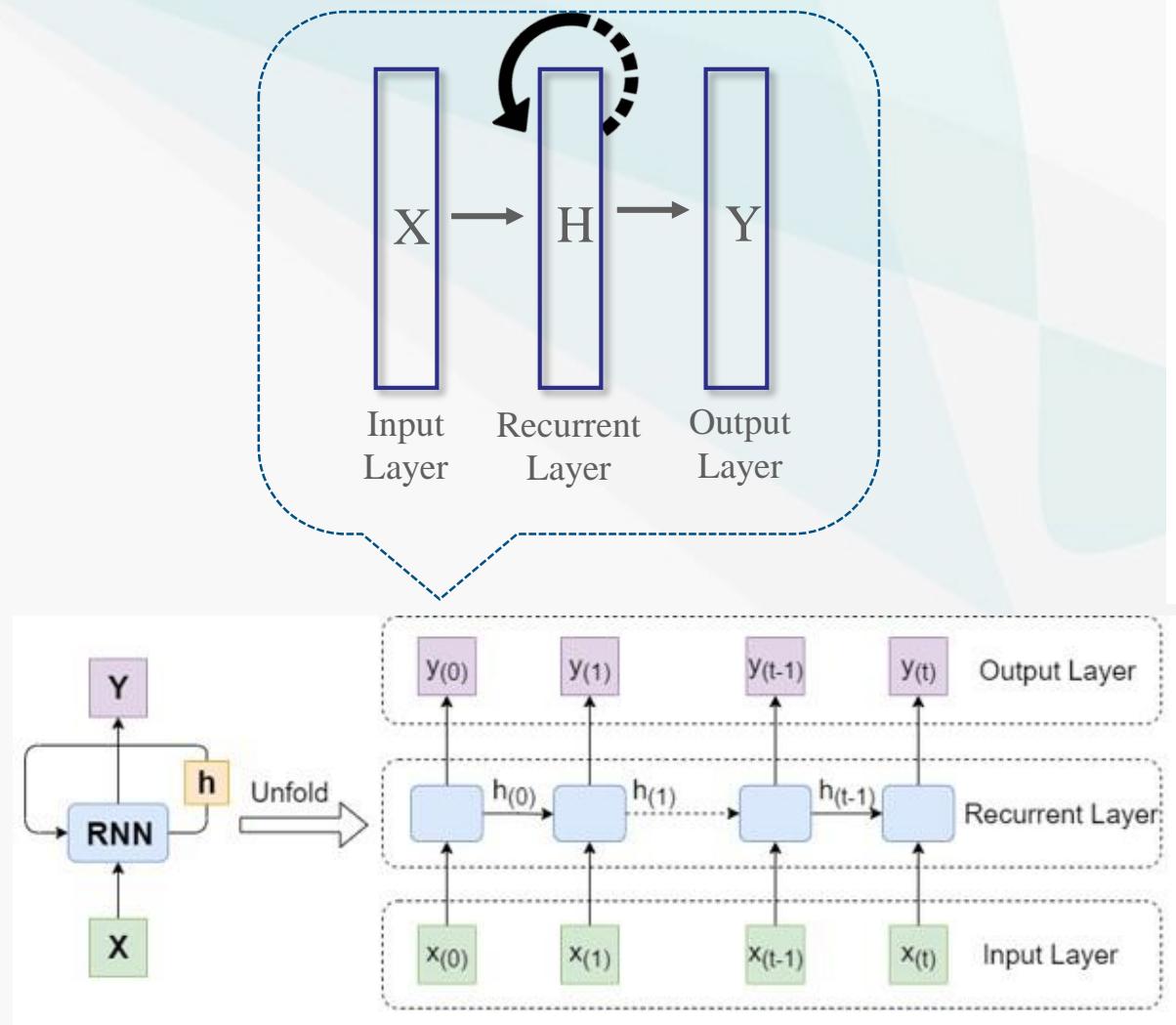
[Kananenka, A. A.; Hsieh, C.-Y.; Cao, J.; Geva, E. *J. Phys. Chem. Lett.*, 7, 4809-4814 (2016)]

[Cerrillo, J.; Cao, J. *Phy. Rev. Lett.*, 112, 110401 (2014)]

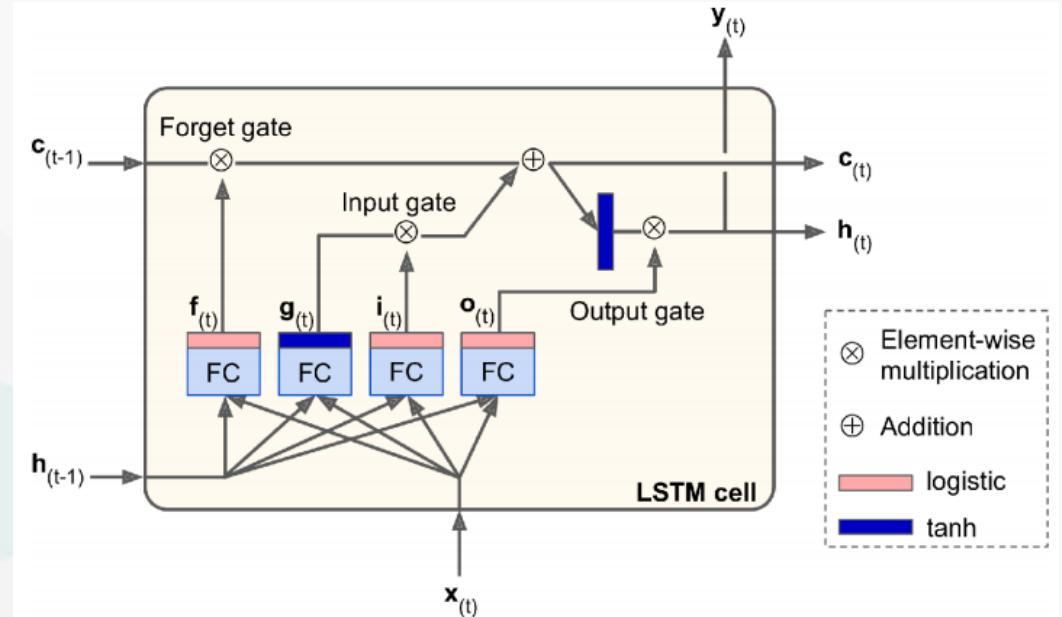


Long Short-Term Memory RNN

- The Simple RNN



- The LSTM Cell



$$i_t = \sigma(W_{xi}^T x_t + W_{hi}^T h_{(t-1)} + b_i),$$

$$f_t = \sigma(W_{xf}^T x_t + W_{hf}^T h_{(t-1)} + b_f),$$

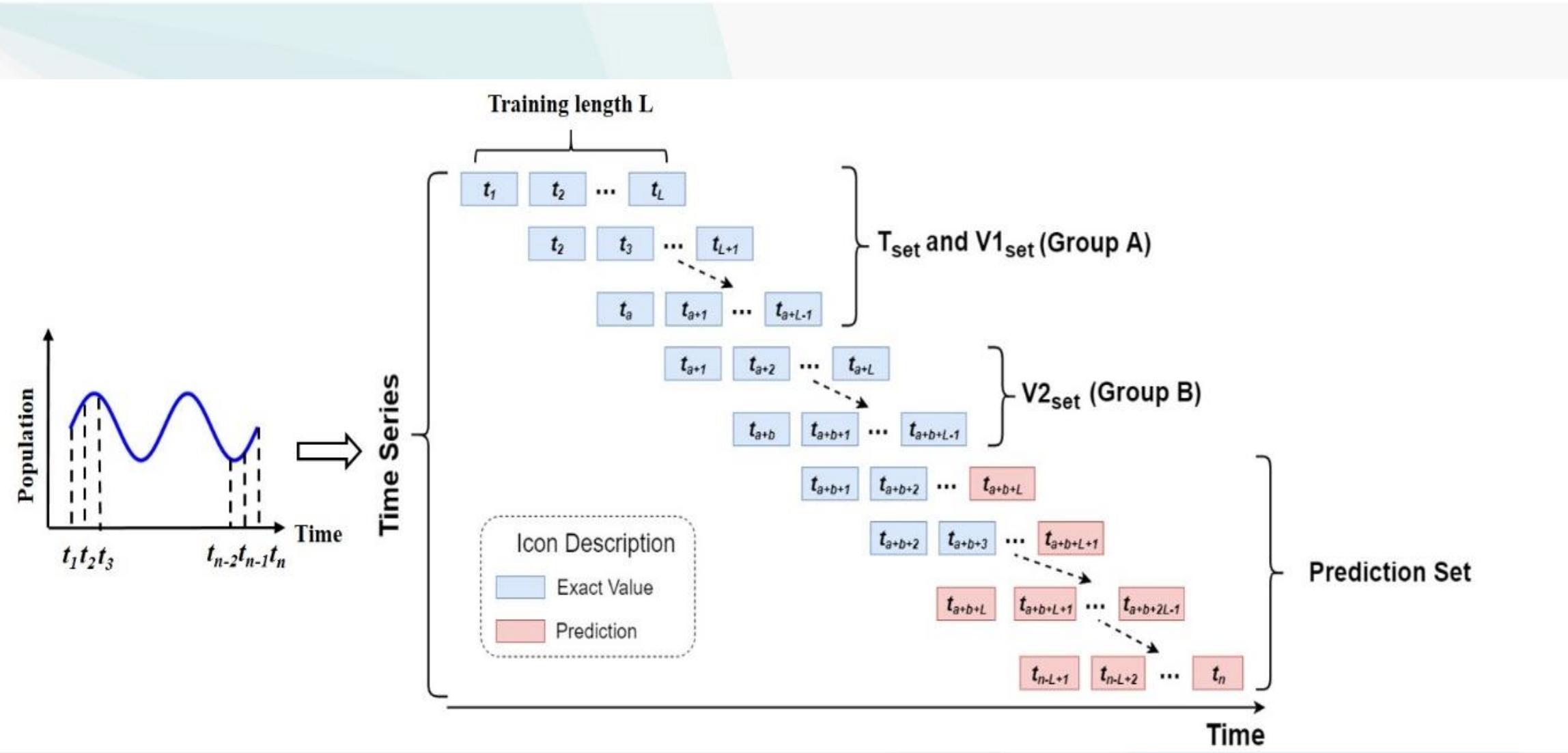
$$o_t = \sigma(W_{xo}^T x_t + W_{ho}^T h_{(t-1)} + b_o),$$

$$g_t = \tanh(W_{xg}^T x_t + W_{hg}^T h_{(t-1)} + b_g),$$

$$c_t = f_t \cdot c_{(t-1)} + i_t \cdot g_t,$$

$$y_t = h_t = o_t \cdot \tanh(c_t).$$

Data Processing



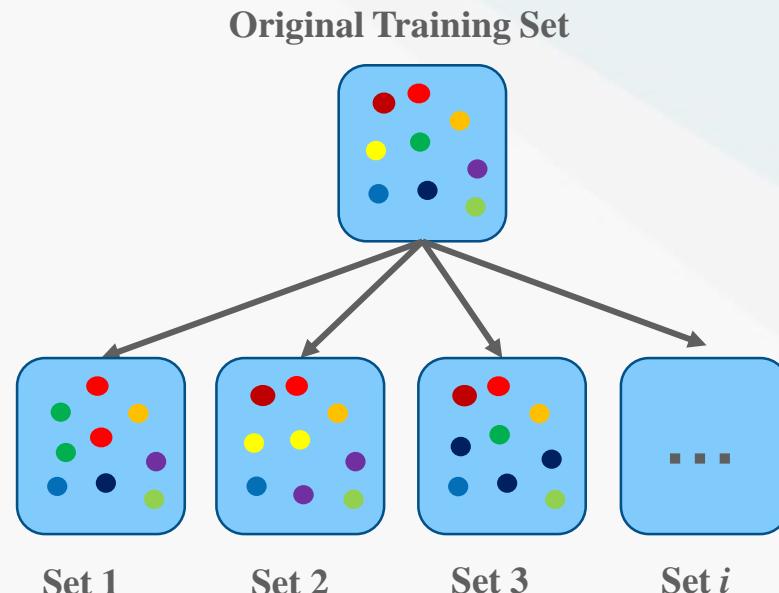
The estimation of the uncertainty is un-avoidable in all ML models

Two Uncertainties:

Model Misspecification

Model Uncertainty

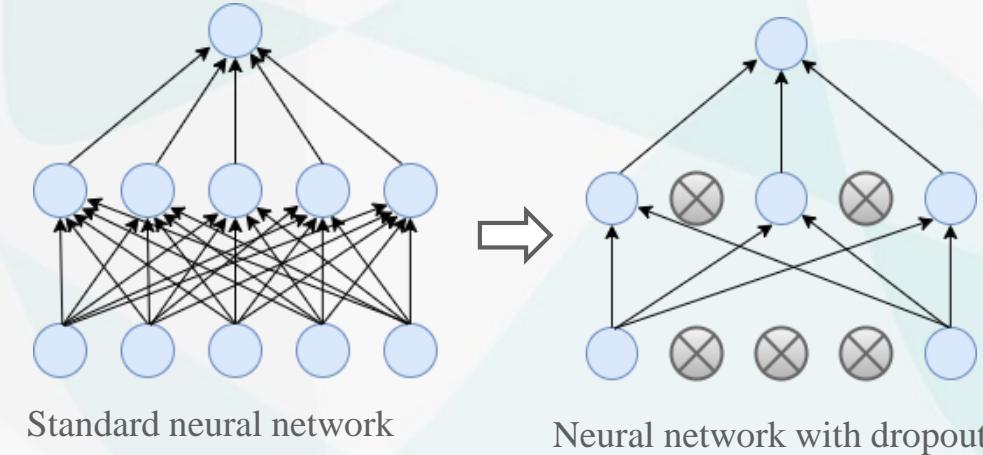
- Bootstrap Resampling Method



[Zhu, L.; Laptev, N. **IEEE**: 103-110(2017)]

[Bühlmann, P. **Stat. Sci.** 17, 52-72(2002)]

- Monte-Carlo Dropout Method

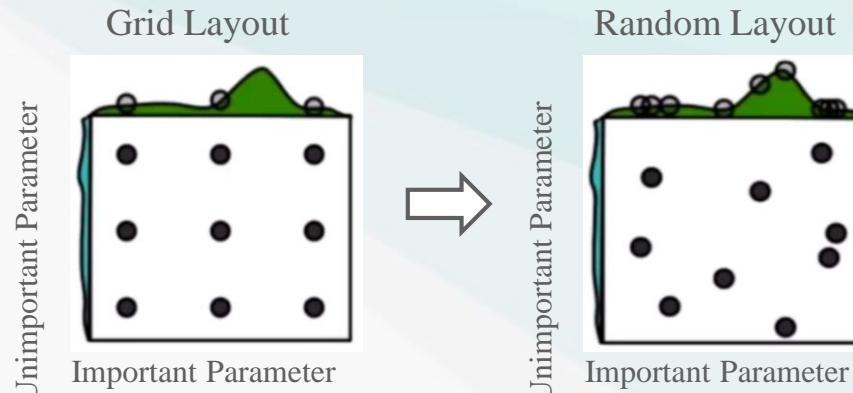


[Gal, Y.; Ghahramani, Z. **PMLR**: 48, 1050-1059(2016)]

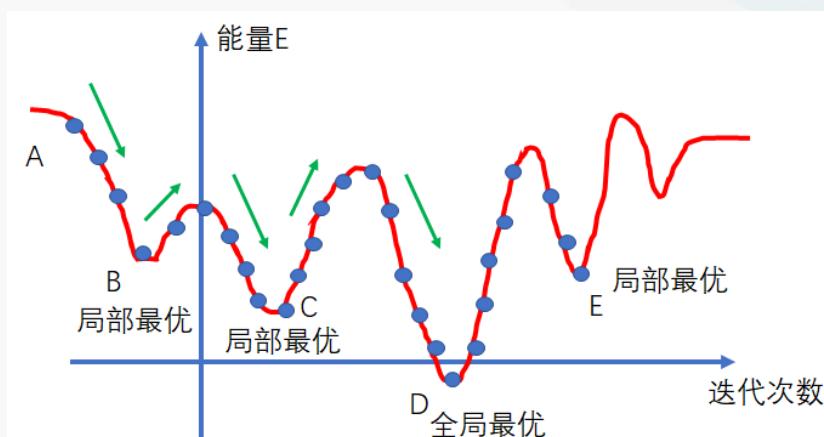
[Gal, Y.; Ghahramani, Z. *Advances in neural information processing systems*, 29(2016)]

Hyperparameter Optimization

- Random Search



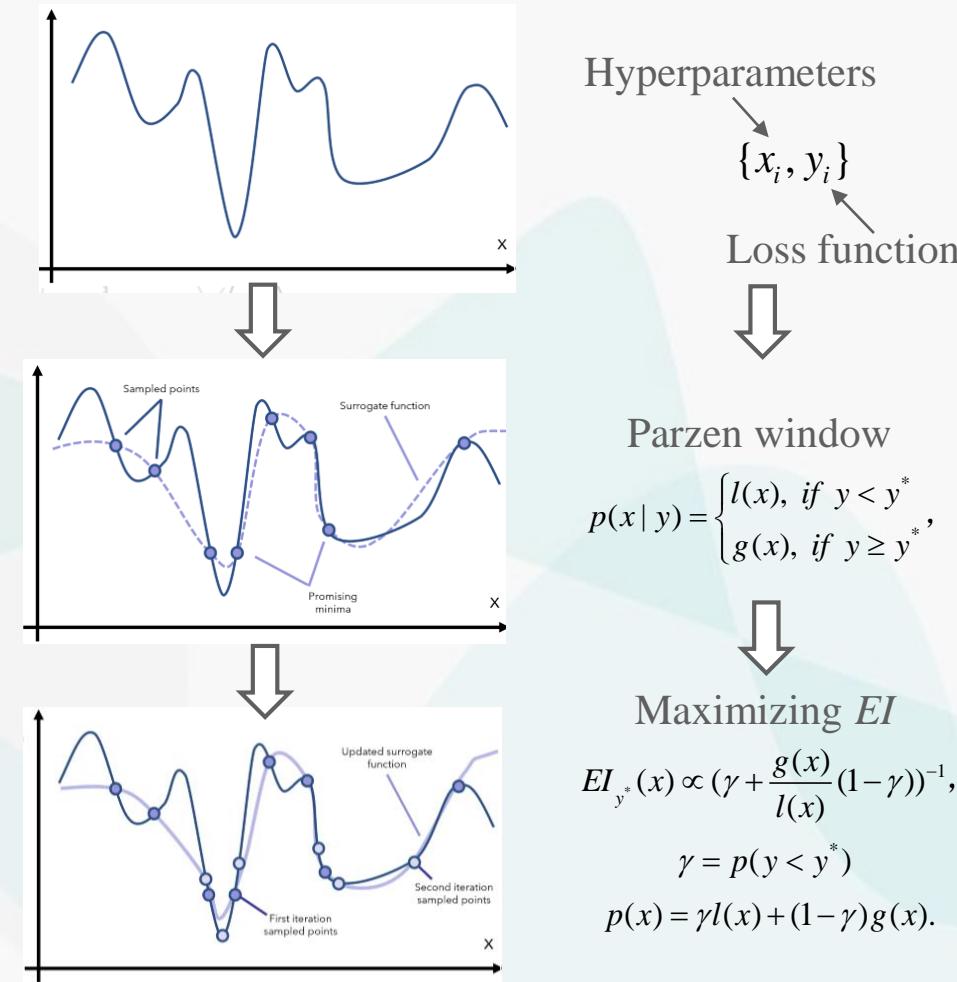
- Simulated Annealing



$$p = \begin{cases} \exp\left(-\frac{f(x_{t+1}) - f(x_t)}{T}\right) & \text{if } f(x_{t+1}) - f(x_t) \geq 0, \\ 1 & \text{if } f(x_{t+1}) - f(x_t) < 0 \end{cases}$$

[Yang, L.; Shami, A. *Neurocomputing*, 415, 295-316(2020)]

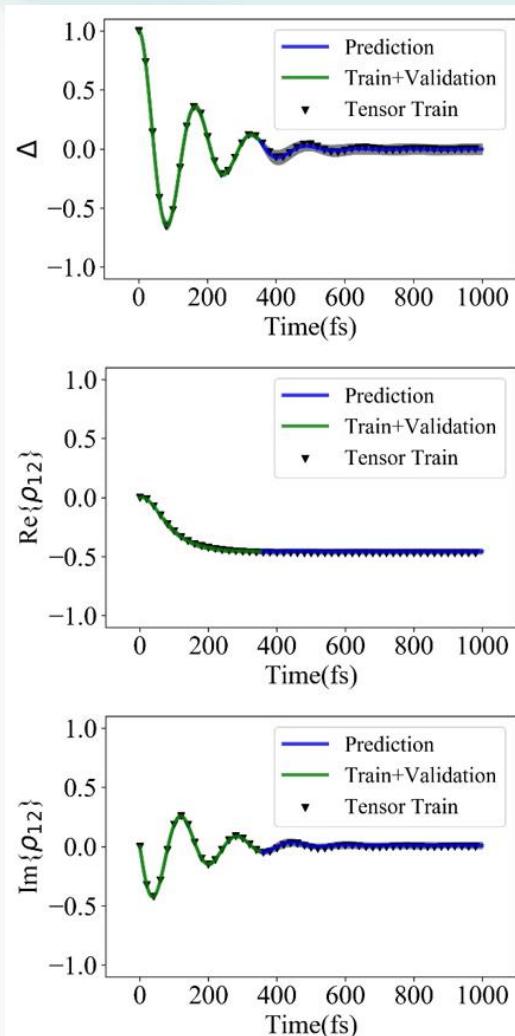
- Bayesian Optimization with TPE



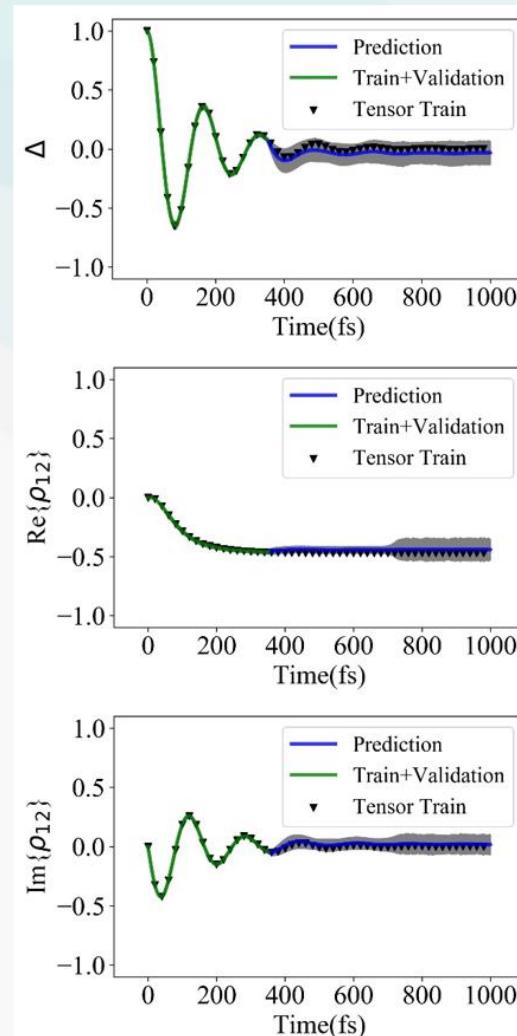
[Kirkpatrick, S.; Gelatt Jr, C. D.; Vecchi, M. P. *Science*, 220, 671-680(1983)]

Simulation of Open Quantum Dynamics with Uncertainty Analysis

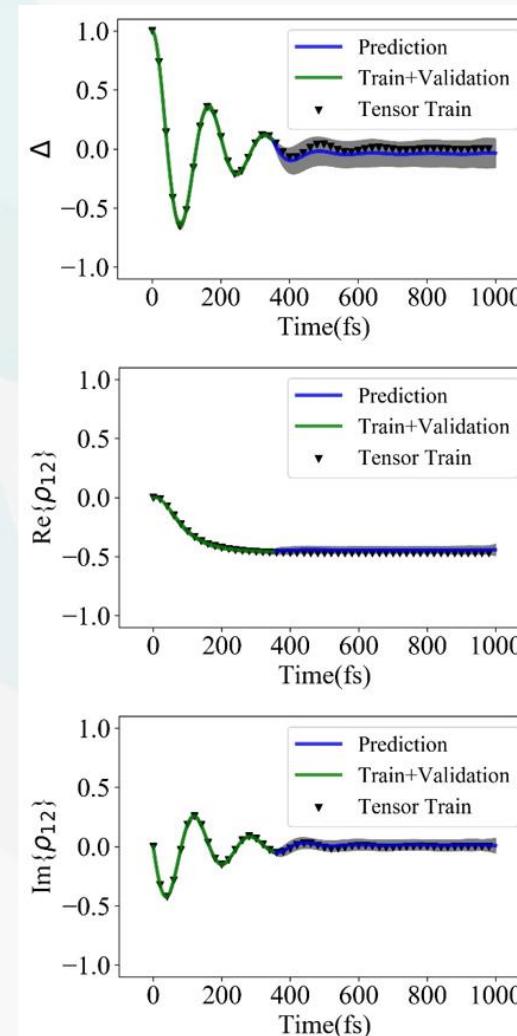
16



(a) Simulated Annealing
+ Bootstrap + MC dropout



(b) Bayesian Optimization
+ Bootstrap + MC dropout



(c) Random Search
+ Bootstrap + MC dropout

Model I (symmetric)

$$V_{12} = 0.0124 \text{ eV}$$

$$\omega_c = 200 \text{ cm}^{-1}$$

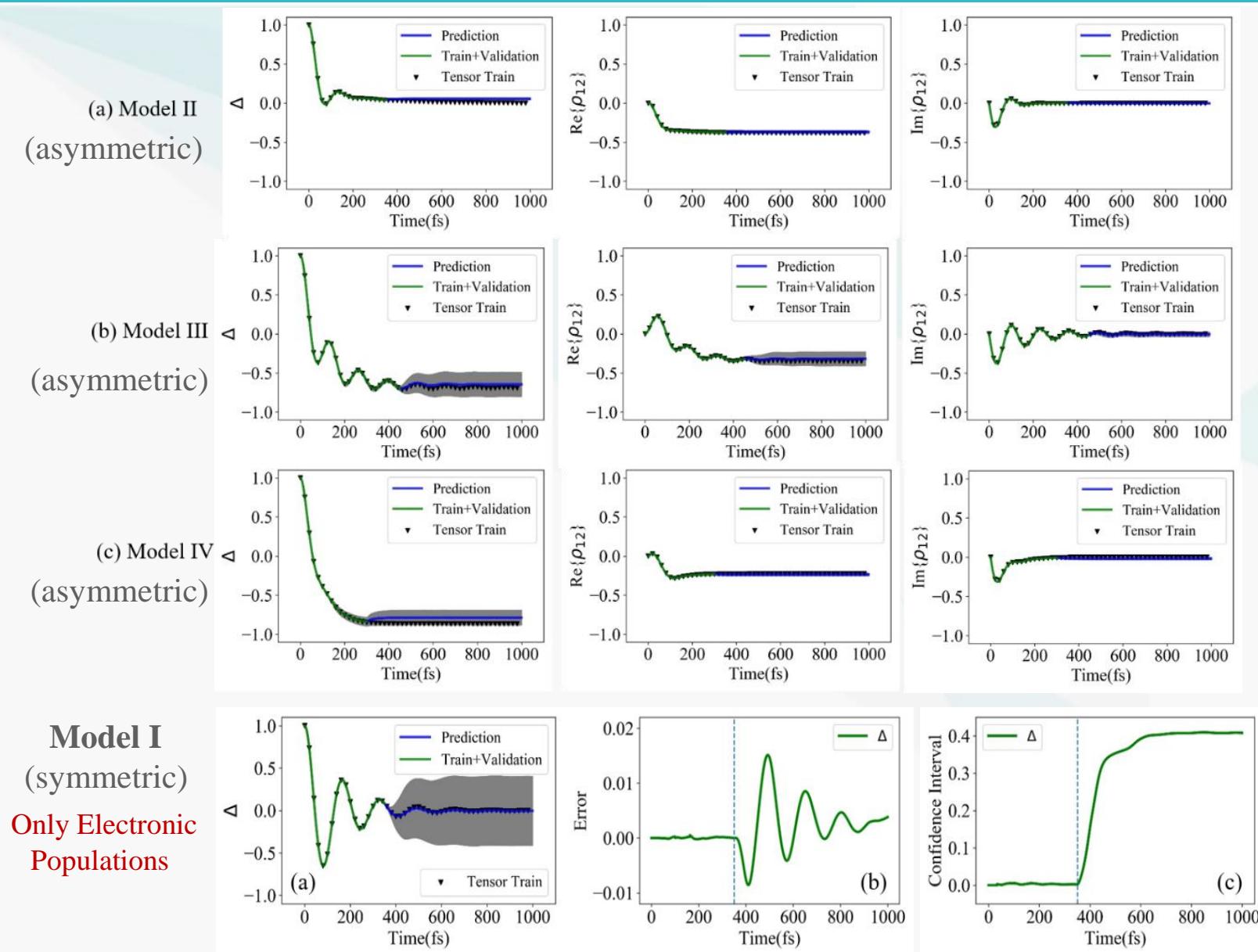
$$\lambda = 64 \text{ cm}^{-1}$$

Recommended
Choice
↓
Simulated Annealing
+
Bootstrap
+
MC dropout

[Lin, K.; Peng, J.; Gu, F. L.; Lan, Z.
J. Phys. Chem. Lett., 12(41), 10225–10234 (2021)]

[Lin, K.; Peng, J.; Xu, C.; Gu, F. L.; Lan, Z.
J. Chem. Theory Comput., 18(10), 5837–5855 (2022)]

Simulation of Open Quantum Dynamics with Uncertainty Analysis 17



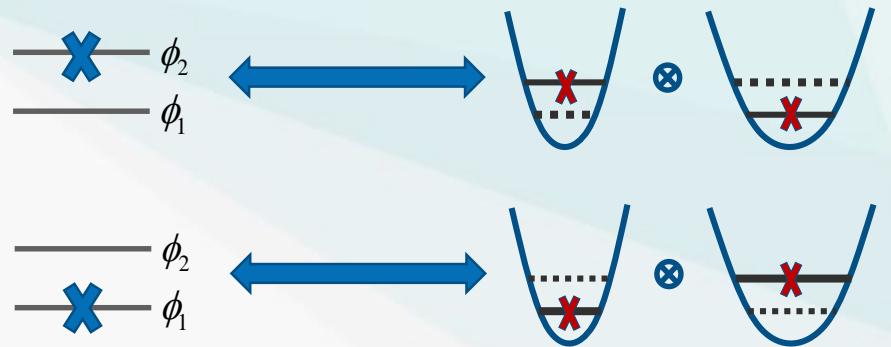
The excellent prediction results of symmetric and asymmetric site-exciton models.

[Lin, K.; Peng, J.; Gu, F. L.; Lan, Z.
J. Phys. Chem. Lett., 12(41), 10225–10234 (2021)]

[Lin, K.; Peng, J.; Xu, C.; Gu, F. L.; Lan, Z.
J. Chem. Theory Comput., 18(10), 5837–5855 (2022)]

The off-diagonal elements of the density matrix play a very important role.

Mapping Hamiltonian

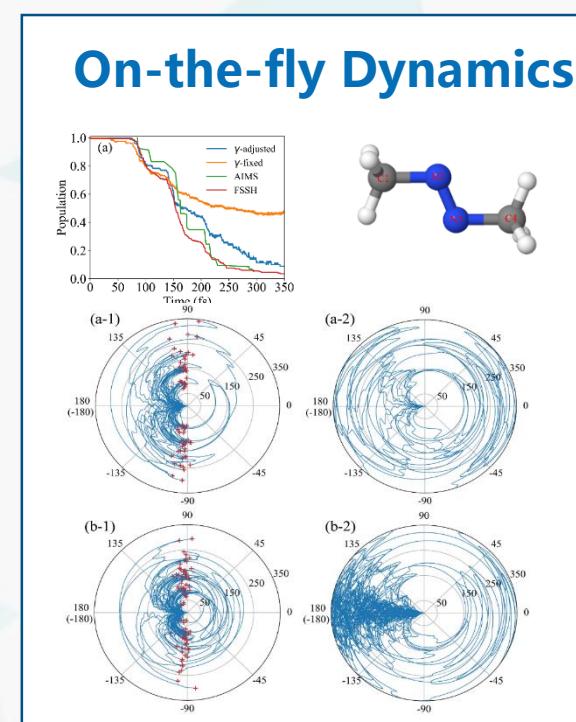
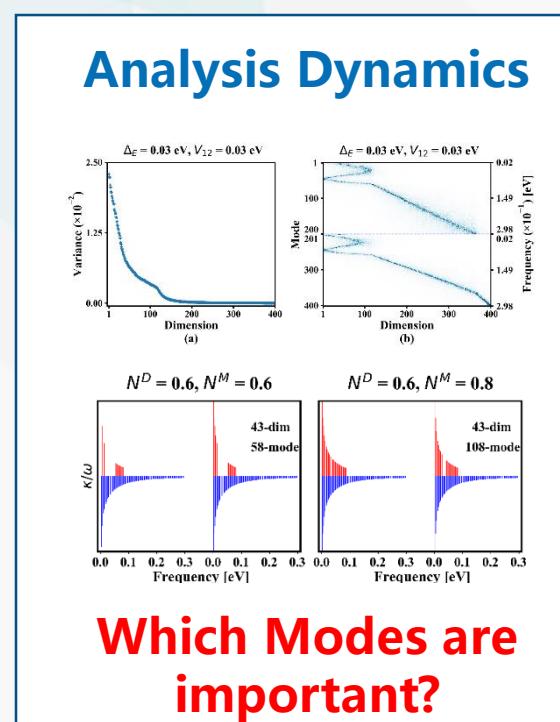
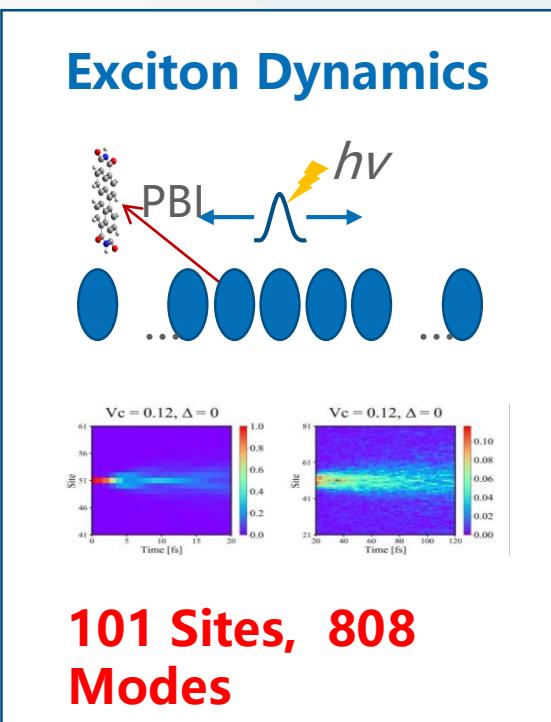


$$\hat{H} = \sum_{n,m} \hat{h}_{nm} |\phi_n\rangle\langle\phi_m|$$

$$\begin{aligned} |\phi_n\rangle\langle\phi_m| &\mapsto a_n^+ a_m^- \\ |\phi_n\rangle &\mapsto |0_1 \cdots 1_n \cdots 0_N\rangle \\ \hat{x}_n &= (\hat{a}_n^+ + \hat{a}_n^-)/\sqrt{2} \\ \hat{p}_n &= i(\hat{a}_n^+ - \hat{a}_n^-)/\sqrt{2} \end{aligned}$$

[J. Chem. Phys., 70: 3214-3223 (1979)]
 [Phys. Rev. Lett., 78: 578-581 (1997)]

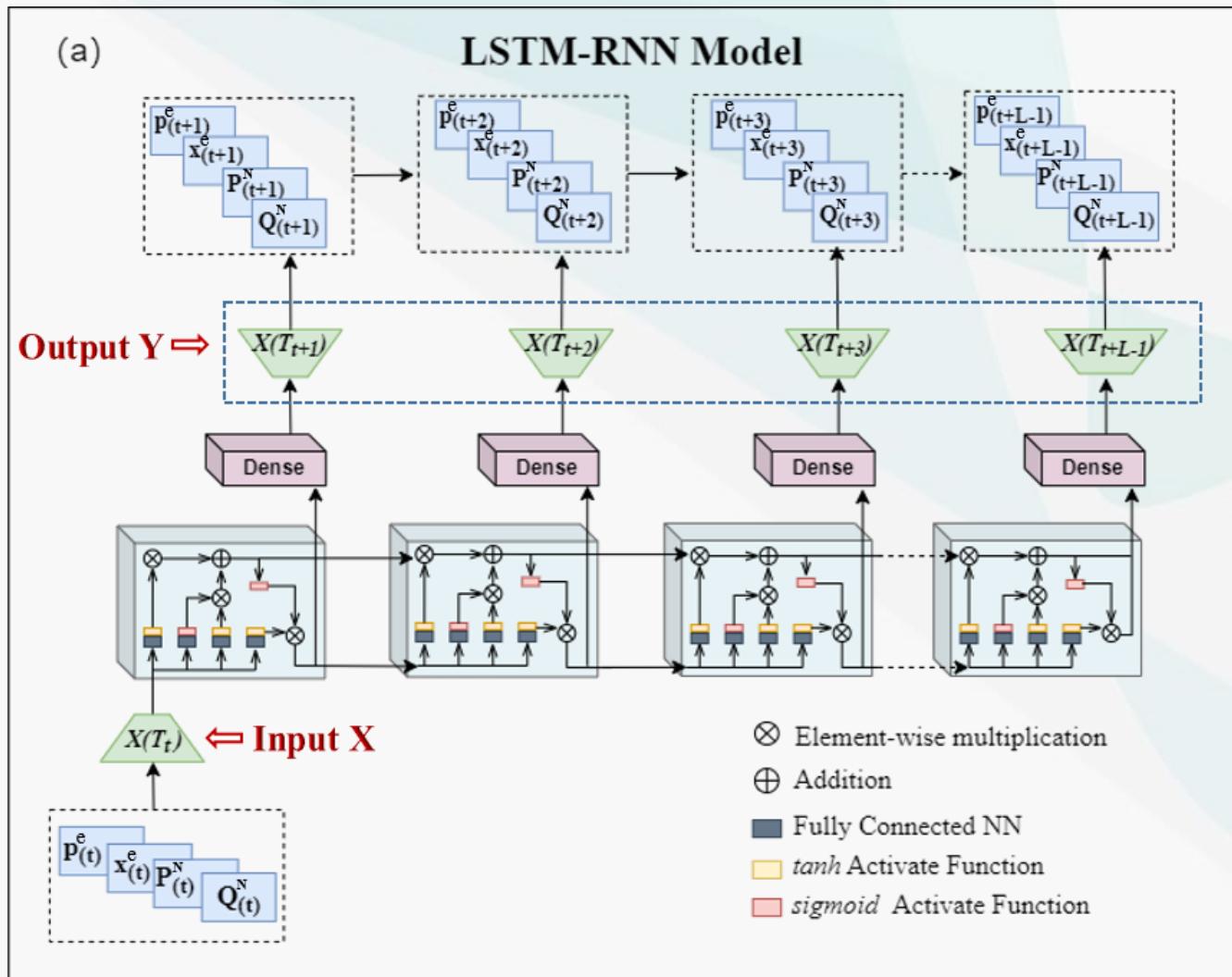
$$\begin{aligned} \hat{H} &= \sum_n \frac{1}{2} (\hat{x}_n^2 + \hat{p}_n^2 - 1) \hat{h}_{nn} \\ &+ \frac{1}{2} \sum_{n \neq m} (\hat{x}_n \hat{x}_m + \hat{p}_n \hat{p}_m) \hat{h}_{nm} \end{aligned}$$



The Prediction of Trajectory-Based MM-SQC Dynamics

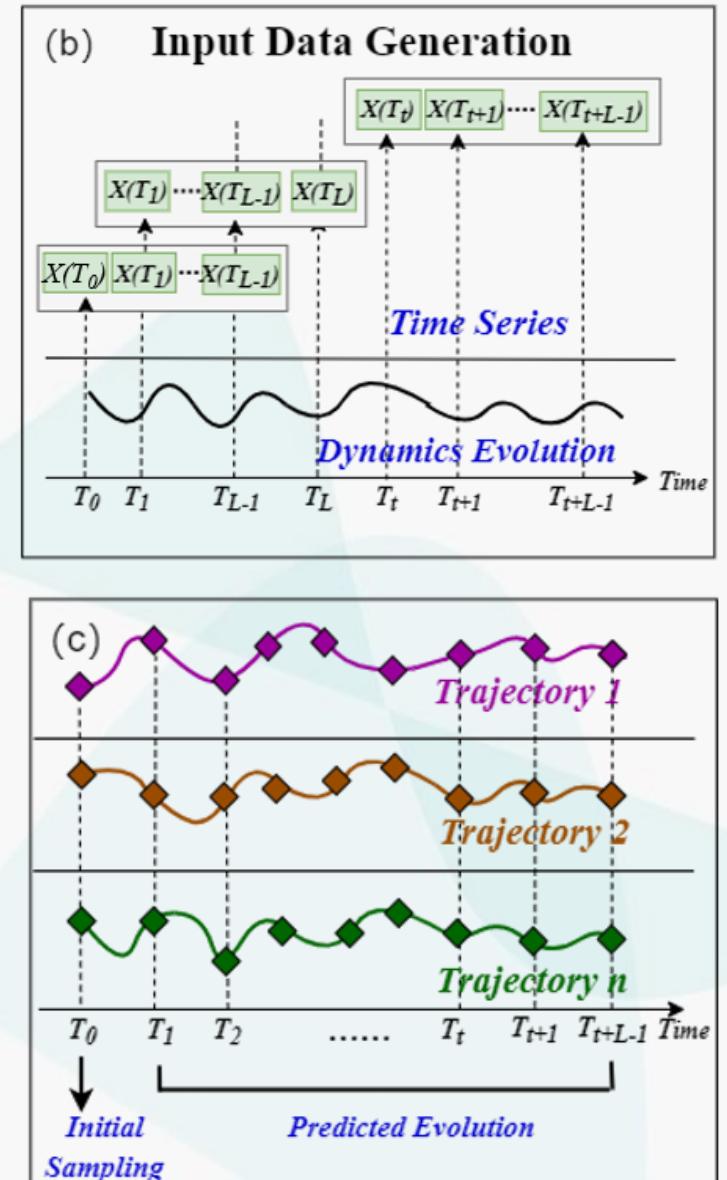
19

Working Process



Training

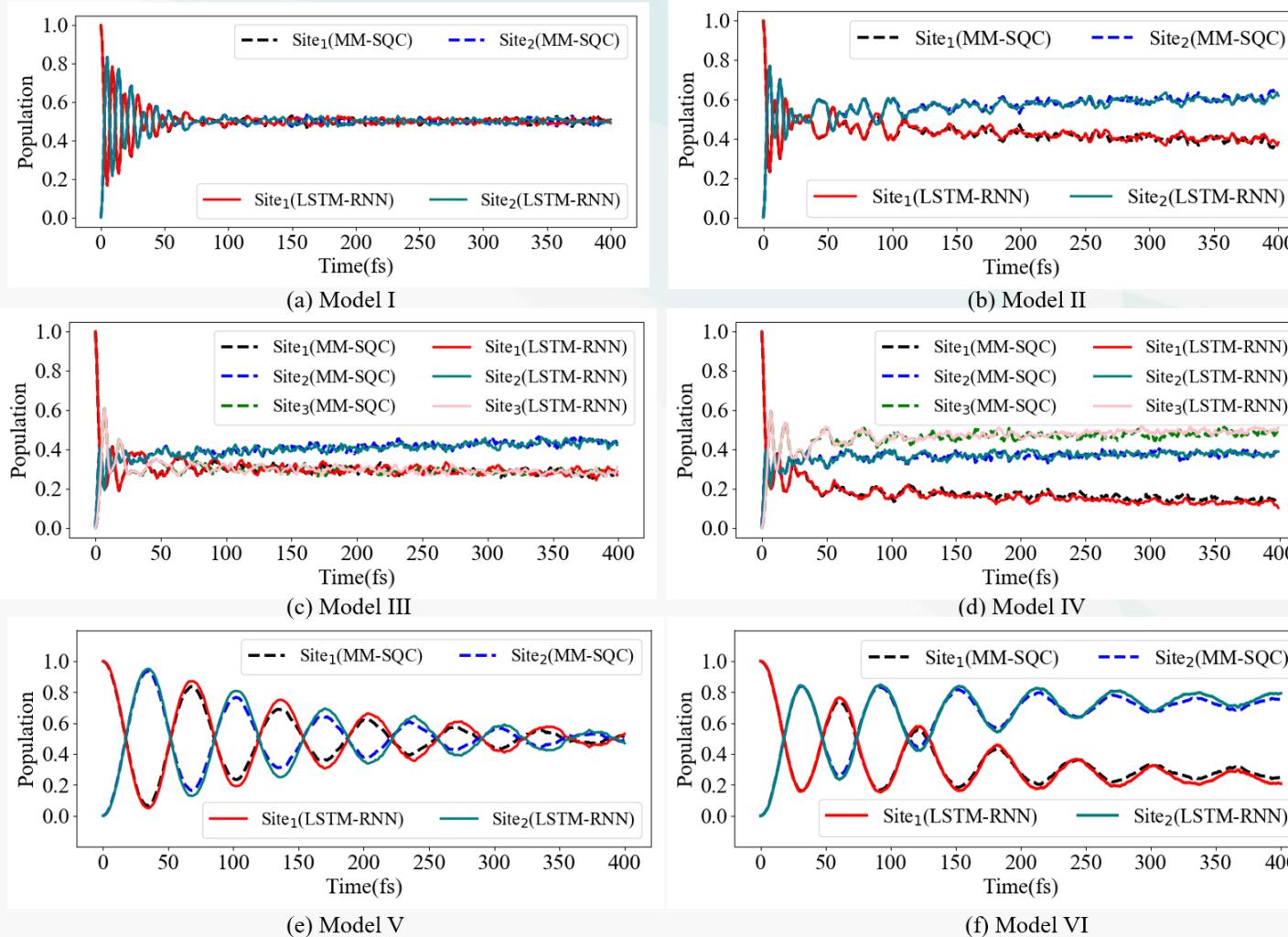
Prediction



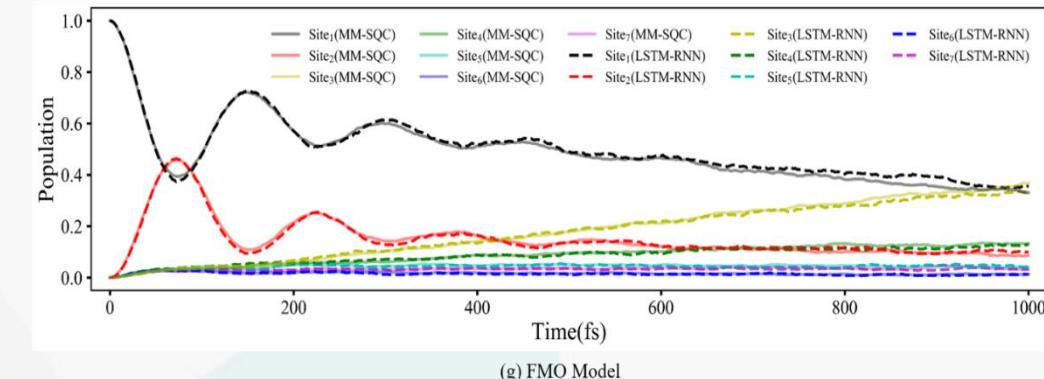
The Prediction of Trajectory-Based MM-SQC Dynamics

20

➤ Site-exciton models

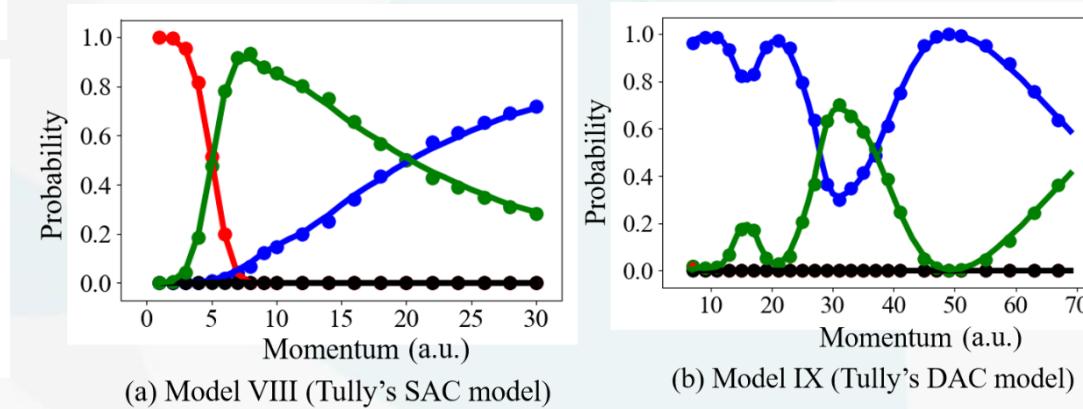


➤ FMO System



714 Dimensions

➤ Tully's scattering models



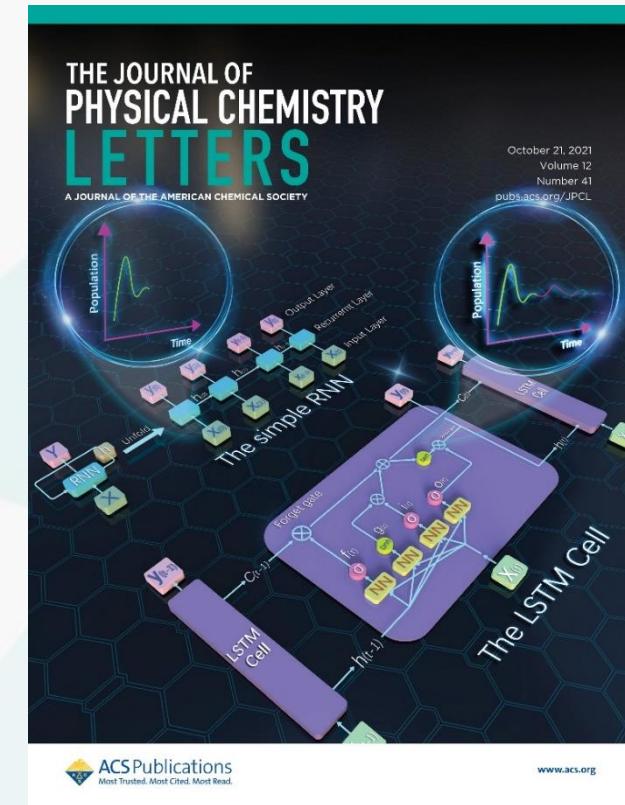
Time-Series ML Methods

Time-Series Machine Learning Methods
may be Used to Simulate the
Nonadiabatic Dynamics

Promising

?

Problems



[Lin, K.; Peng, J.; Gu, F. L.; Lan, Z. *J. Phys. Chem. Lett.*, 12, 10225–10234 (2021)]

[Lin, K.; Peng, J.; Xu, C.; Gu, F. L.; Lan, Z. *J. Chem. Theory Comput.*, 18(10), 5837–5855 (2022)]

[Lin, K.; Peng, J.; Xu, C.; Gu, F. L.; Lan, Z. *J. Phys. Chem. Lett.*, 13, 11678–11688 (2022)]

On-the-fly Nonadiabatic Dynamics

QM **MM**

$$\mathbf{H} = \mathbf{H}_{\text{QM}} + \mathbf{H}_{\text{MM}} + \mathbf{H}_{\text{QM/MM}}$$

Excited State Method
CASSCF, ADC(2), TDDFT, CIS, TDDFTB

$$\hat{H}_e \chi(\mathbf{r}, \mathbf{R}) = E_e(\mathbf{R}) \chi(\mathbf{r}, \mathbf{R})$$

$$\mathbf{H}\mathbf{C} = \mathbf{S}\mathbf{C}\mathbf{E}$$

$$\begin{pmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{A} \end{pmatrix} \begin{pmatrix} \mathbf{X} \\ \mathbf{Y} \end{pmatrix} = \omega \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \mathbf{X} \\ \mathbf{Y} \end{pmatrix}$$

Surface Hopping Dynamics

code development

Method and Code Developments:

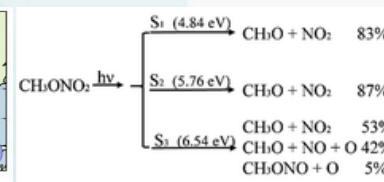
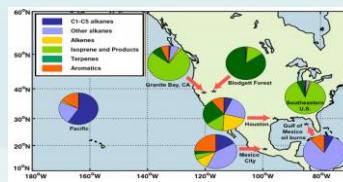
- Initial sampling
 - Wigner, Action-angle Sampling
- Dynamics Module:
 - Surface-hopping dynamics (Tully, Zhu-Nakamura)
 - Quasiclassical Dynamics with Mapping Hamiltonian
- Electronic Structure Module:
 - TDDFT, CIS, ADC(2), CASSCF, OM2/MRCI, XMS-CASPT2
 - Turbomole, Gaussian, GAMESS, Molpro, MNDO, BAGEL
- Analytical and Numerical NAC
- Hybrid QM/MM Methods

- L. Du, Z. Lan*, *J. Chem. Theory Comput.*, 2015, 11, 1360;
- D. Hu, Z. Lan* et al., *Phys. Chem. Chem. Phys.*, 2017, 19, 19168
- D. Hu, Z. Lan* et al., *J. Chem. Theory Comput.*, 2021, 17, 3279

Photochemistry and Photophysics

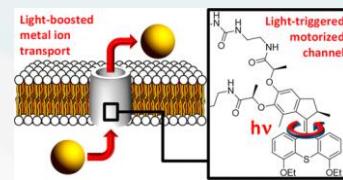
23

Environmental Photochemistry



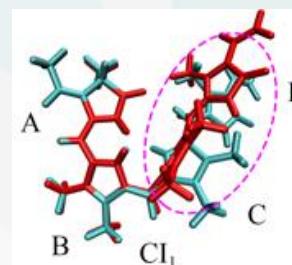
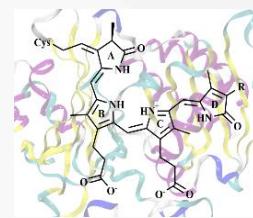
- J. Zhang, Z. Lan* et al., *Phys. Chem. Chem. Phys.*, 2021, 23, 25597
- S. Lin, F.G. Gu*, Z. Lan* et al., *J. Chem. Phys.*, 2021, 155, 214105
- K. Lin, F.G. Gu*, Z. Lan* et al., *Chemosphere.*, 2021, 281, 130831
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Photoisomerization



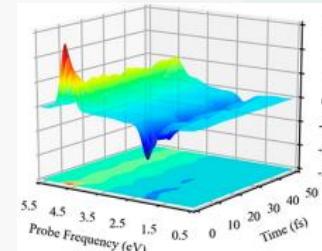
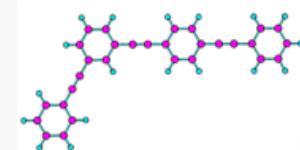
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Photobiology



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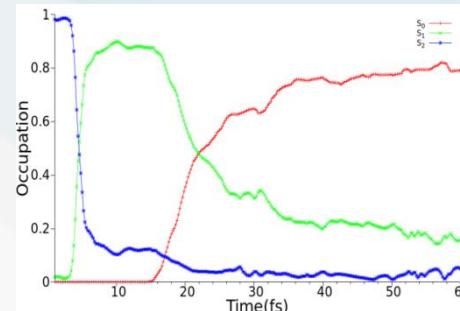
Photovoltaics



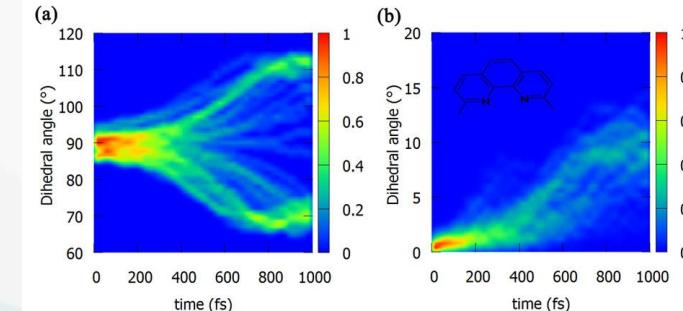
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What do we know from nonadiabatic molecular simulation ²⁴

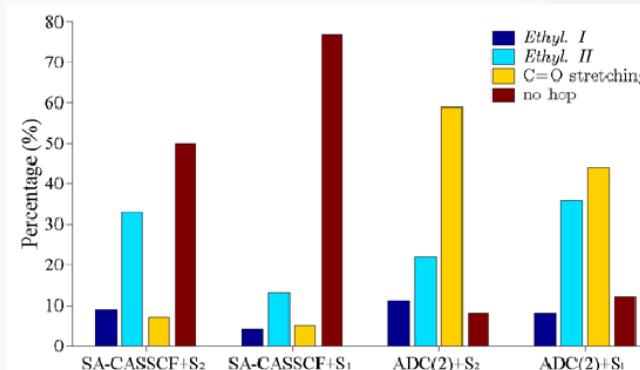
Population dynamics Lifetime



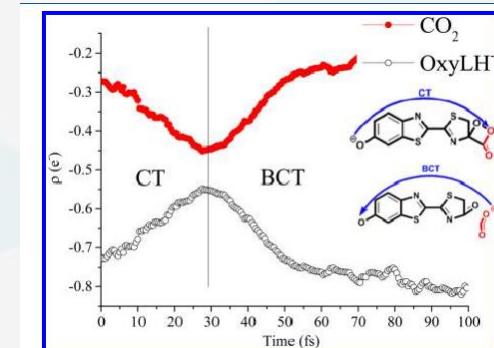
Geometry evolution



Reaction channels



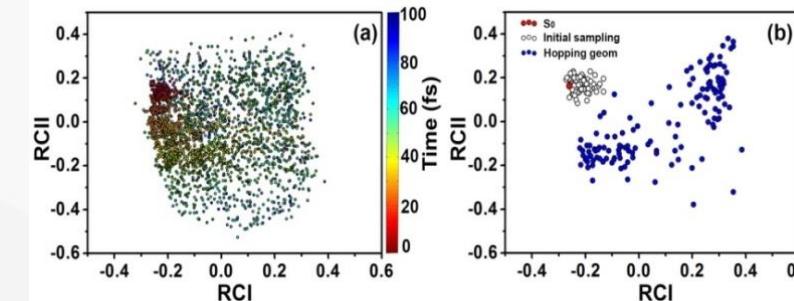
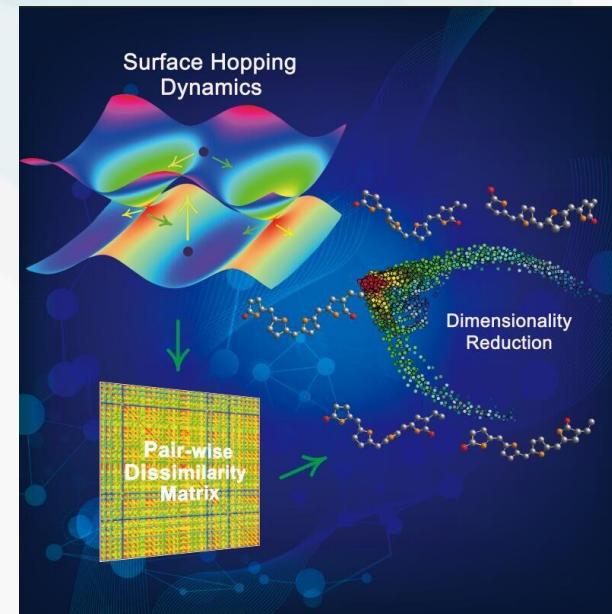
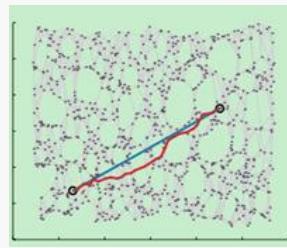
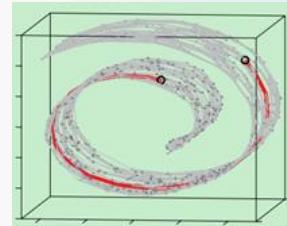
Physical quantities



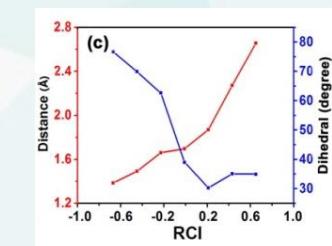
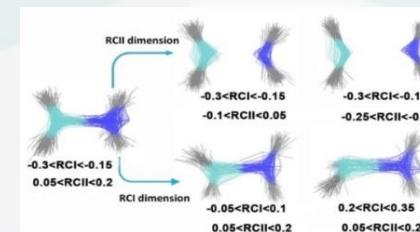
Analysis of trajectory evolution I: geometrical evolution

25

- Dimensionality reduction approaches to analyze the surface-hopping dynamics simulation results
- Extract the major molecular motion



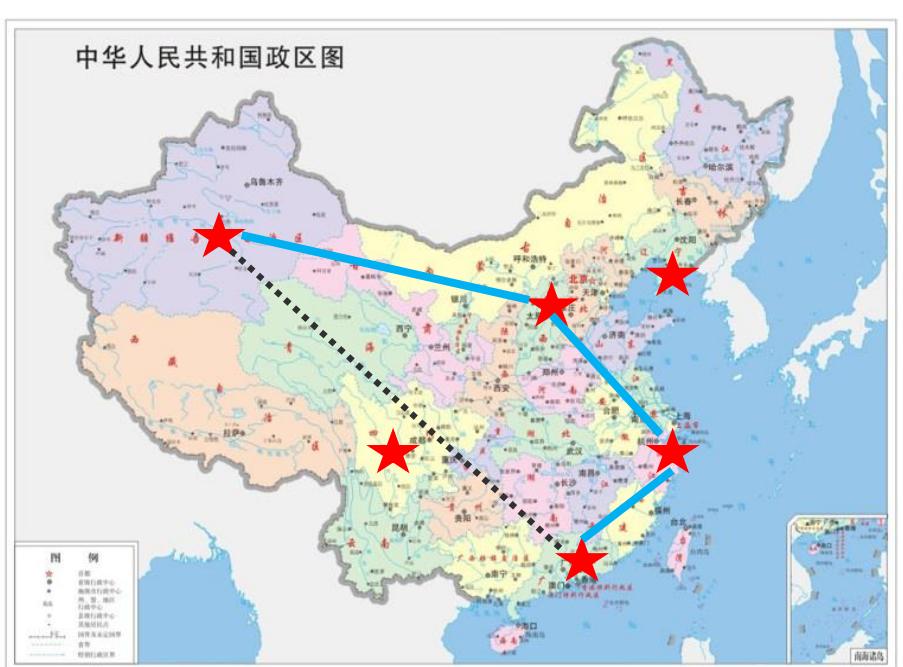
Dimensionality reduction
 $\{R_N\} \rightarrow \{r\}$



- A large number of trajectories
- Polyatomic molecules
- Many degrees of freedom

- Multidimensional scaling
- Isometric feature mapping

How to draw a map from the inter-city distances?

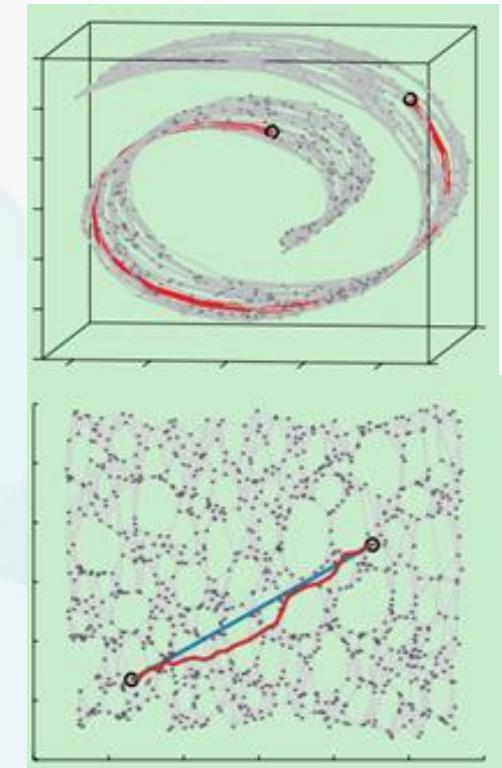


MDS (Multidimensional Scaling)

	A	B	C	D	E	F
A						
B						
C						
D						
E						
F						

Inter-city Distance Matrix (I, J)

ISOMAP (Isometric Mapping)

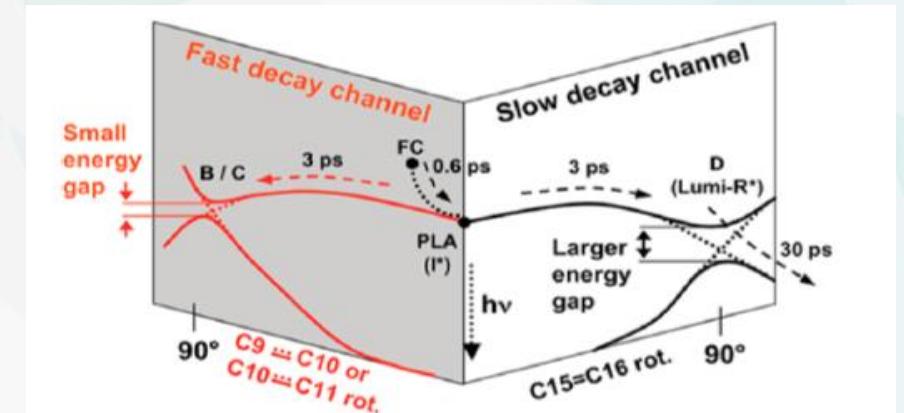
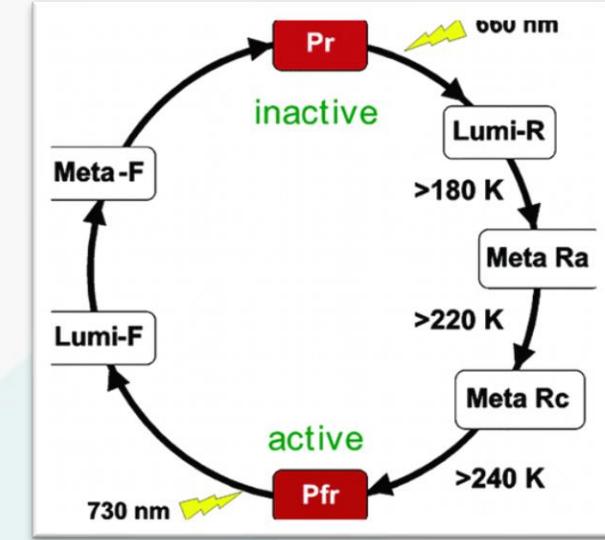
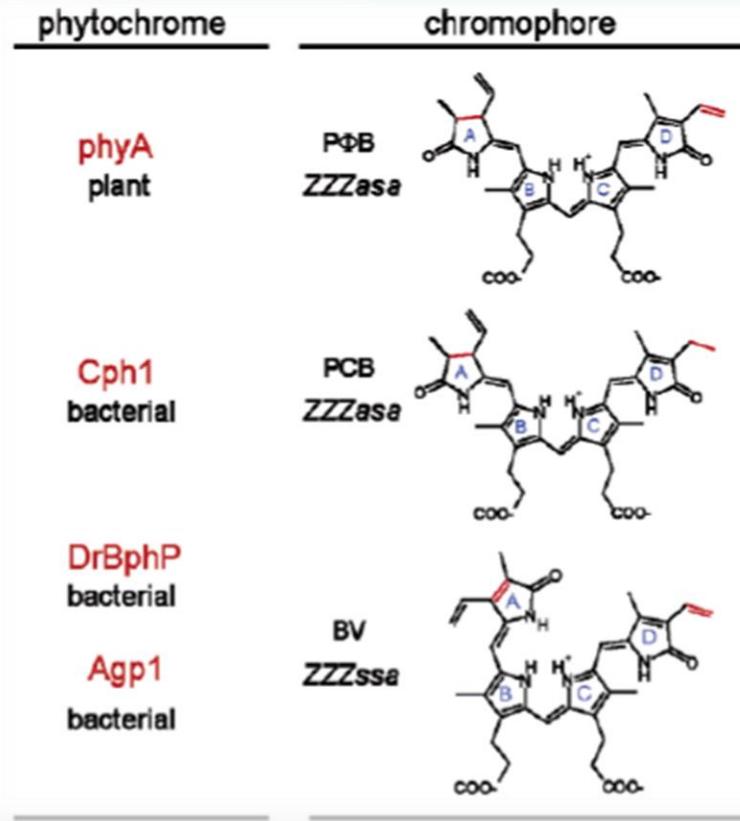


- Euclidean distance → Geodesic distance
- K-points or Epsilon-ball
- Dijkstra or Floyd–Warshall algorithm

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- [2] Borg, I.; Groenen, P. J. F. *Springer Science & Business Media*: America, 2005.
- [3] De Silva, V.; Tenenbaum, J. B.; *Technical report*: Stanford University, 2004.
- [4] Balasubramanian, M.; Schwartz, E. L. *Science* 2002, 295.
- [5] Tenenbaum, J. B.; de Silva, V.; Langford, J. C. *Science* 2000, 290, 2319-2323.

Example: ZaZsZa isomer of PΦB model

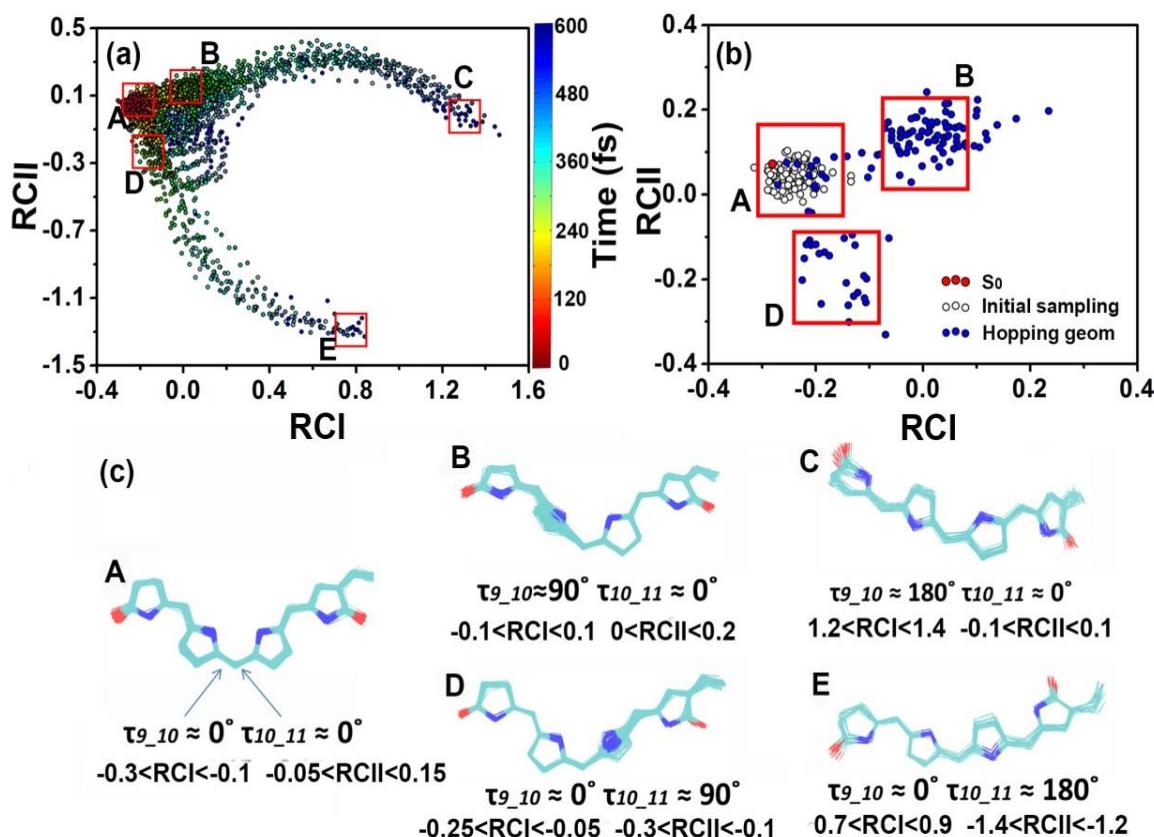
The PΦB model



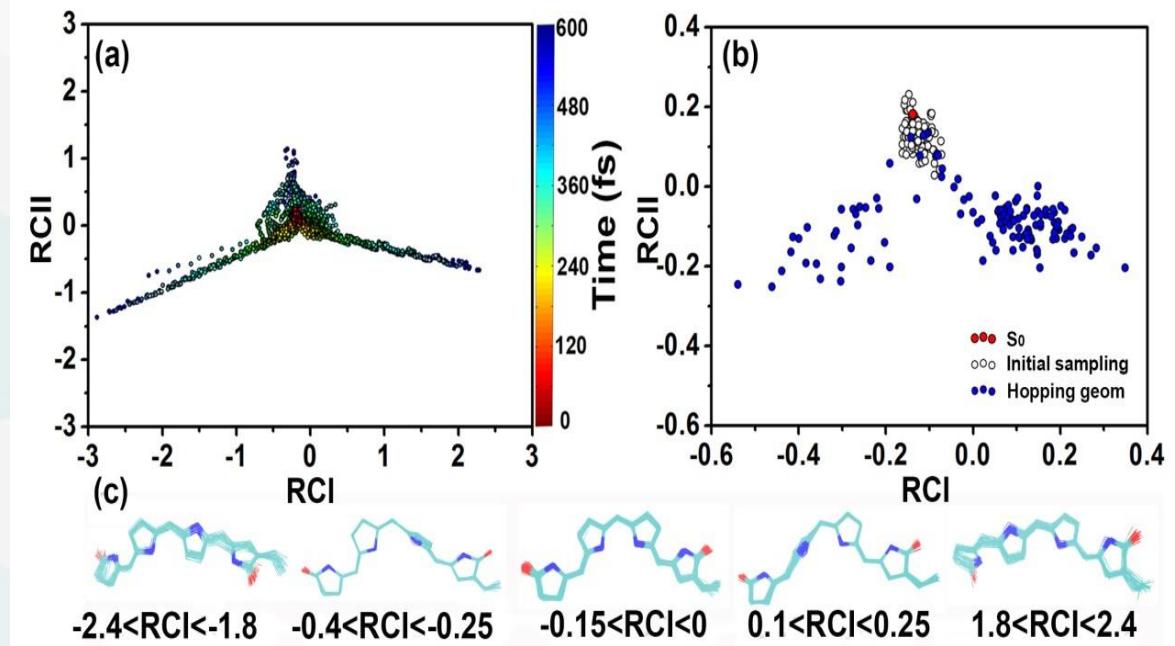
1. Maria A. M., Daniel H. M., Peter H. Acc. Chem. Res., 2007, 40 (4), pp 258–266
2. Samer G., Hoi L. L., Igor S., Olivucci M. Chem. Rev. 2017 DOI: 10.1021/acs.chemrev.7b00177

Example: ZaZsZa isomer of PΦB model

MDS



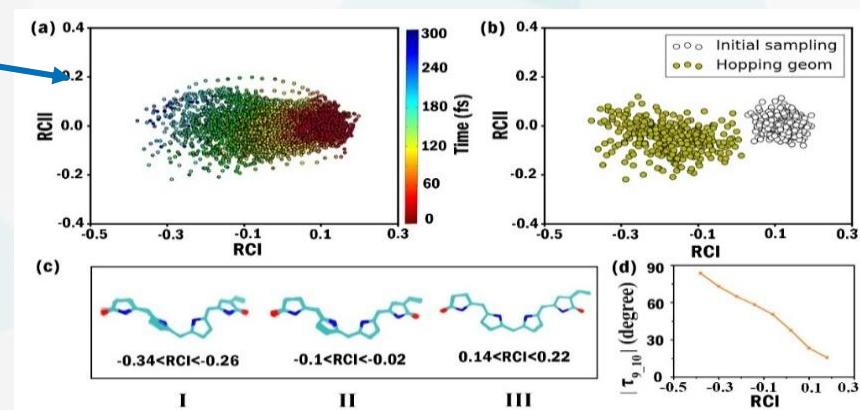
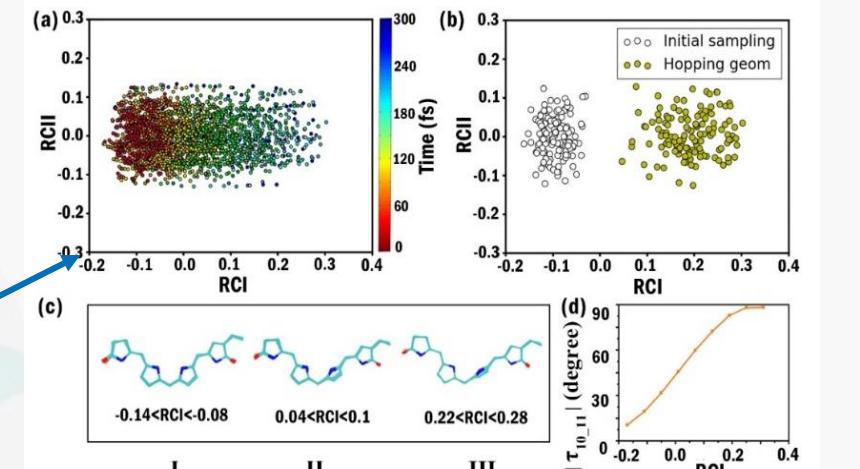
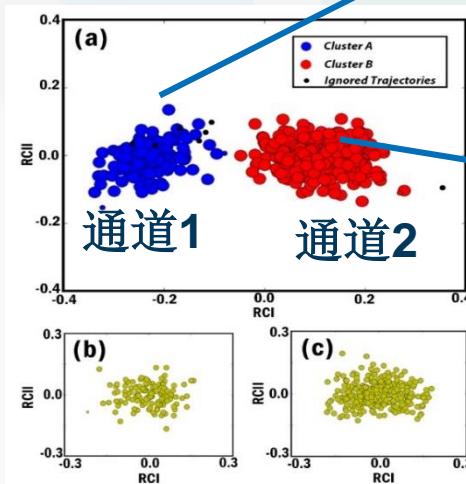
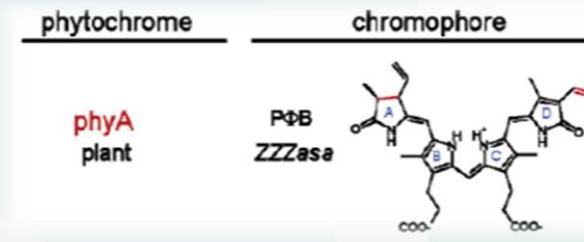
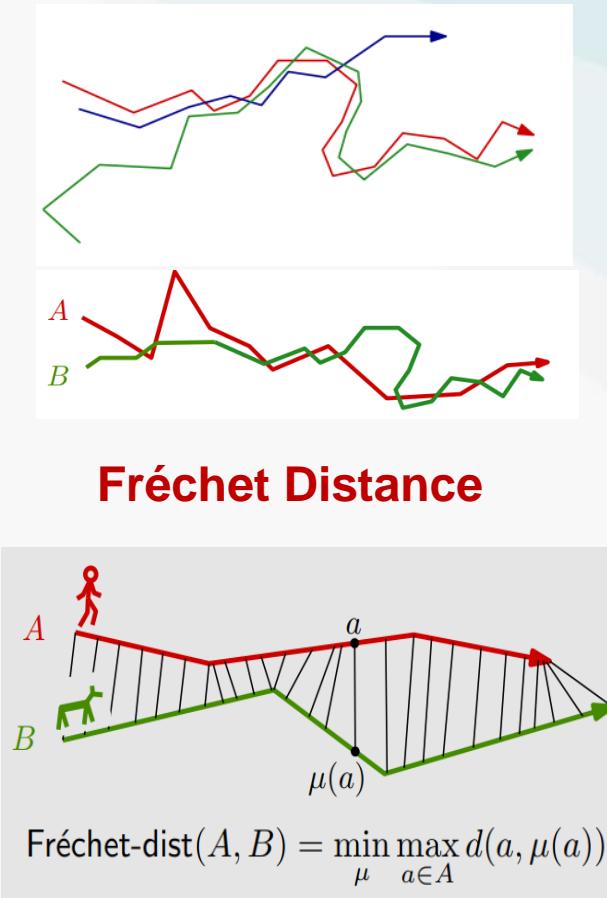
ISOMAP



Analysis of trajectory evolution II: trajectory similarity

29

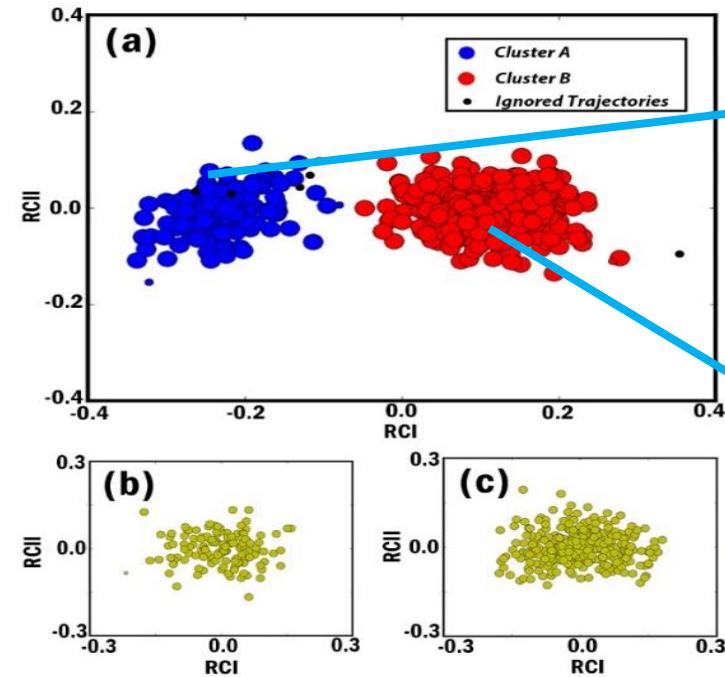
- An “automatic” approach to analyze the trajectory similarity and the configuration similarity in the on-the-fly trajectory surface hopping dynamics.



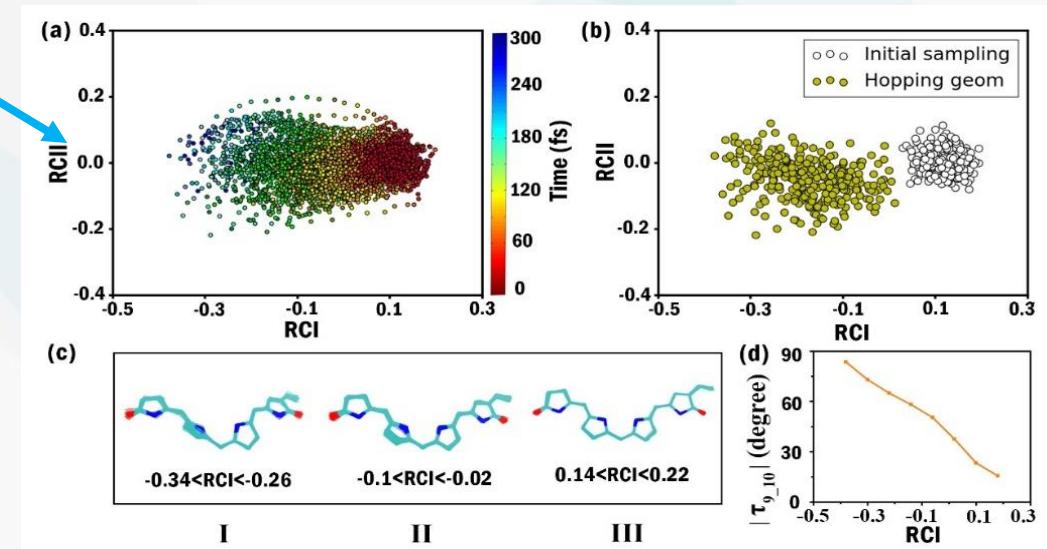
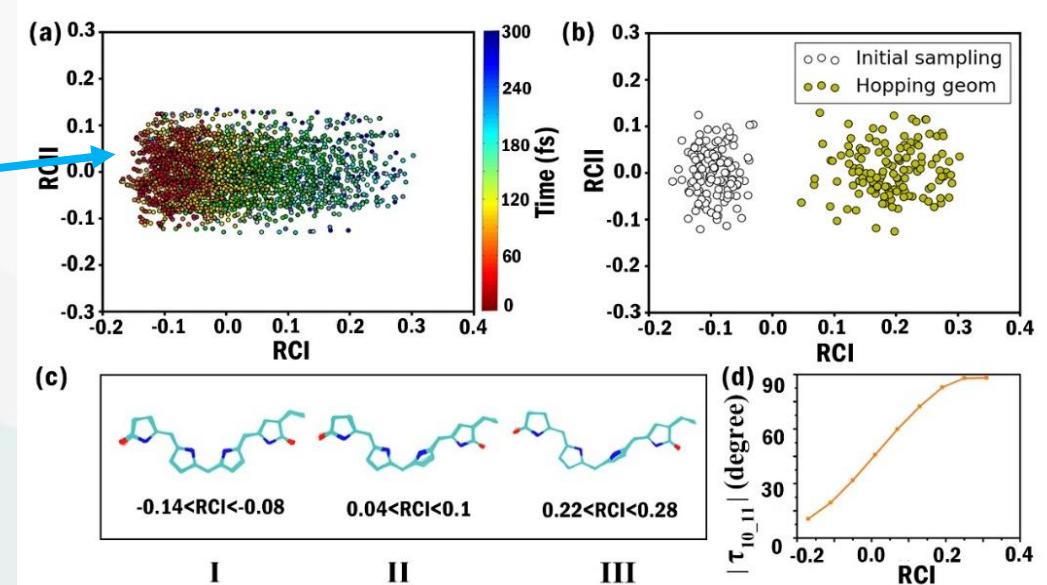
Application In Nonadiabatic Dynamics

31

Clustering Analysis of Trajectory Similarity before S₁-S₀ Hops



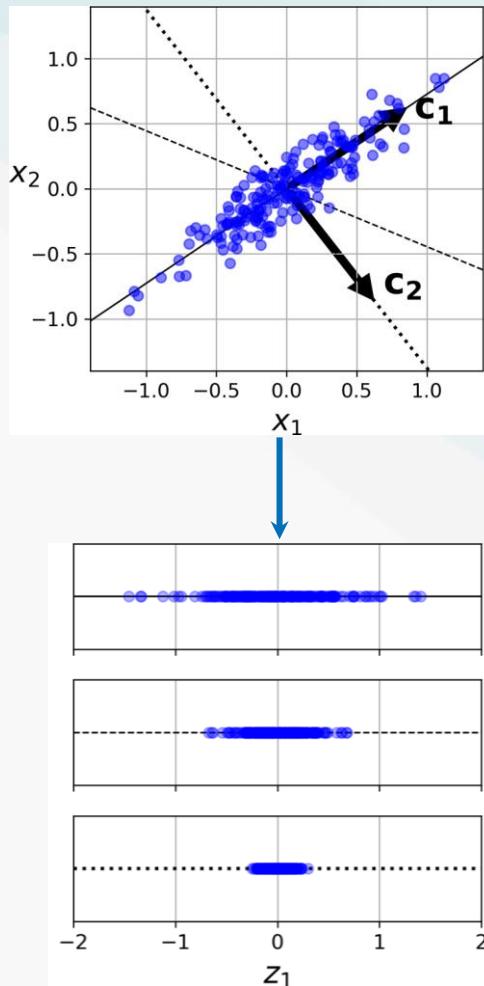
- I. Get dynamics results
- II. Select geometries
- III. Calculate trajectory distance
- IV. Clustering
- V. Dimensionality reduction analysis



Analysis of Trajectory Evolution III: Bath Motion

32

Principal Component Analysis



➤ Geometry Data Collections

The MM-SQC Dynamics

$$H_{MM}(x, p, Q, P) = \sum_k \left[\frac{1}{2} (x_k^2 + p_k^2) - \gamma \right] H_{kk}(Q, P) + \frac{1}{2} \sum_{k \neq l} (x_k x_l + p_k p_l) H_{kl}(Q, P)$$

➤ Descriptor Construction

- The Action Variable of the Bath Mode: $N_j = \frac{1}{2} Q_j^2 + \frac{1}{2} P_j^2$
- The Coordinate of the Bath Mode: Q_j

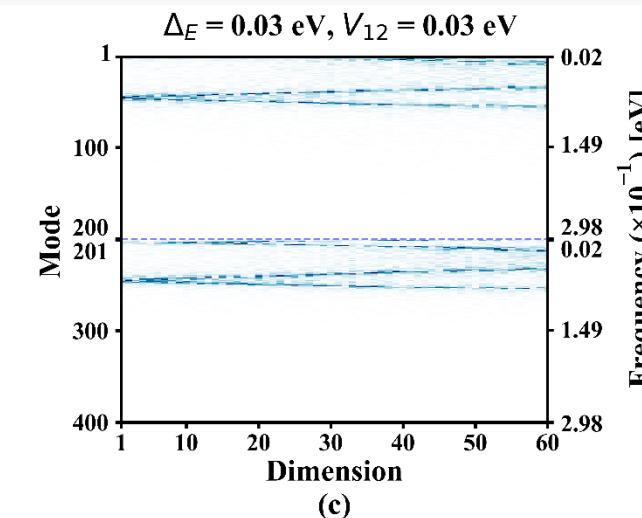
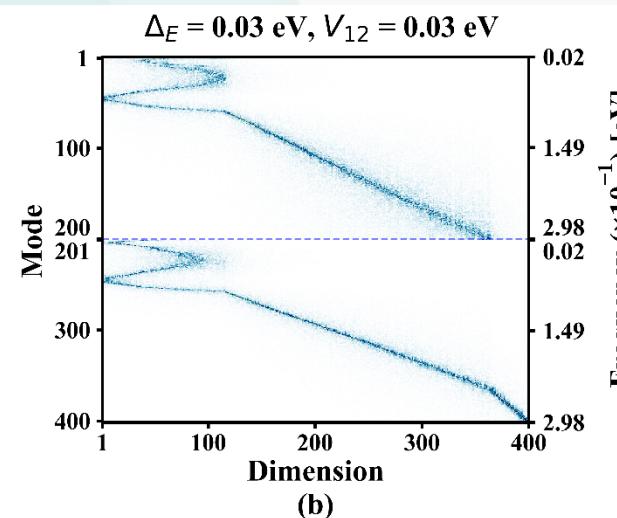
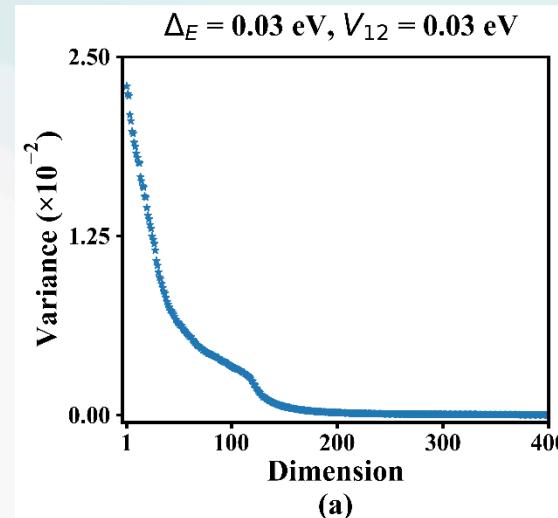
➤ Dimensionality Reduction

$$\mathbf{M}_{co} = (\mathbf{X} - \langle \mathbf{X} \rangle)^T (\mathbf{X} - \langle \mathbf{X} \rangle) = \mathbf{U}^T \mathbf{E} \mathbf{U}$$

Analysis of Trajectory Evolution III: Bath Motion

33

The Action Variable of the Bath Mode



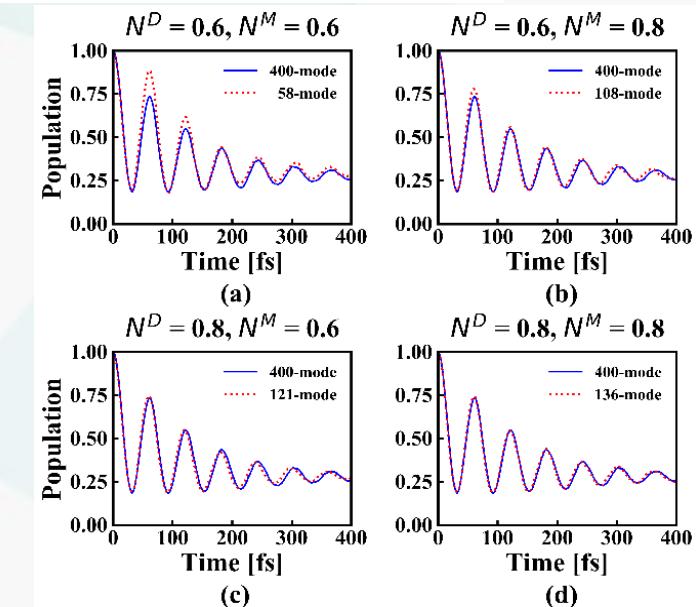
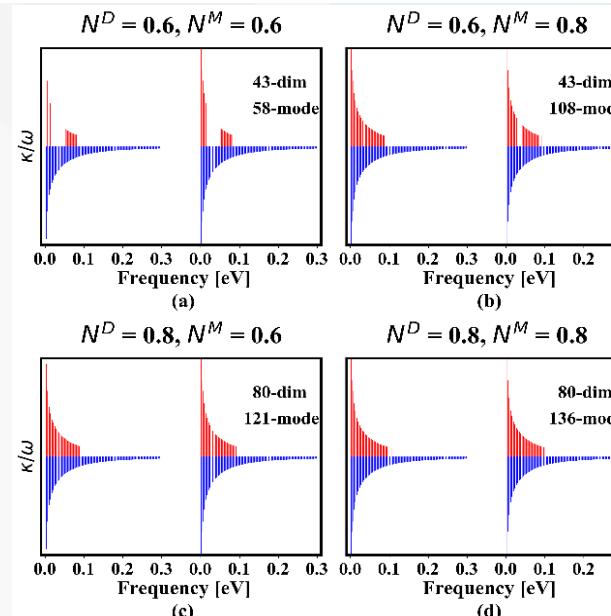
Reduced Model Construction

◆ Select Dimension

$$N^D \sim \sum_i E_i$$

◆ Select Modes

$$N_i^M \sim \sum_j |U_{ij}|^2$$

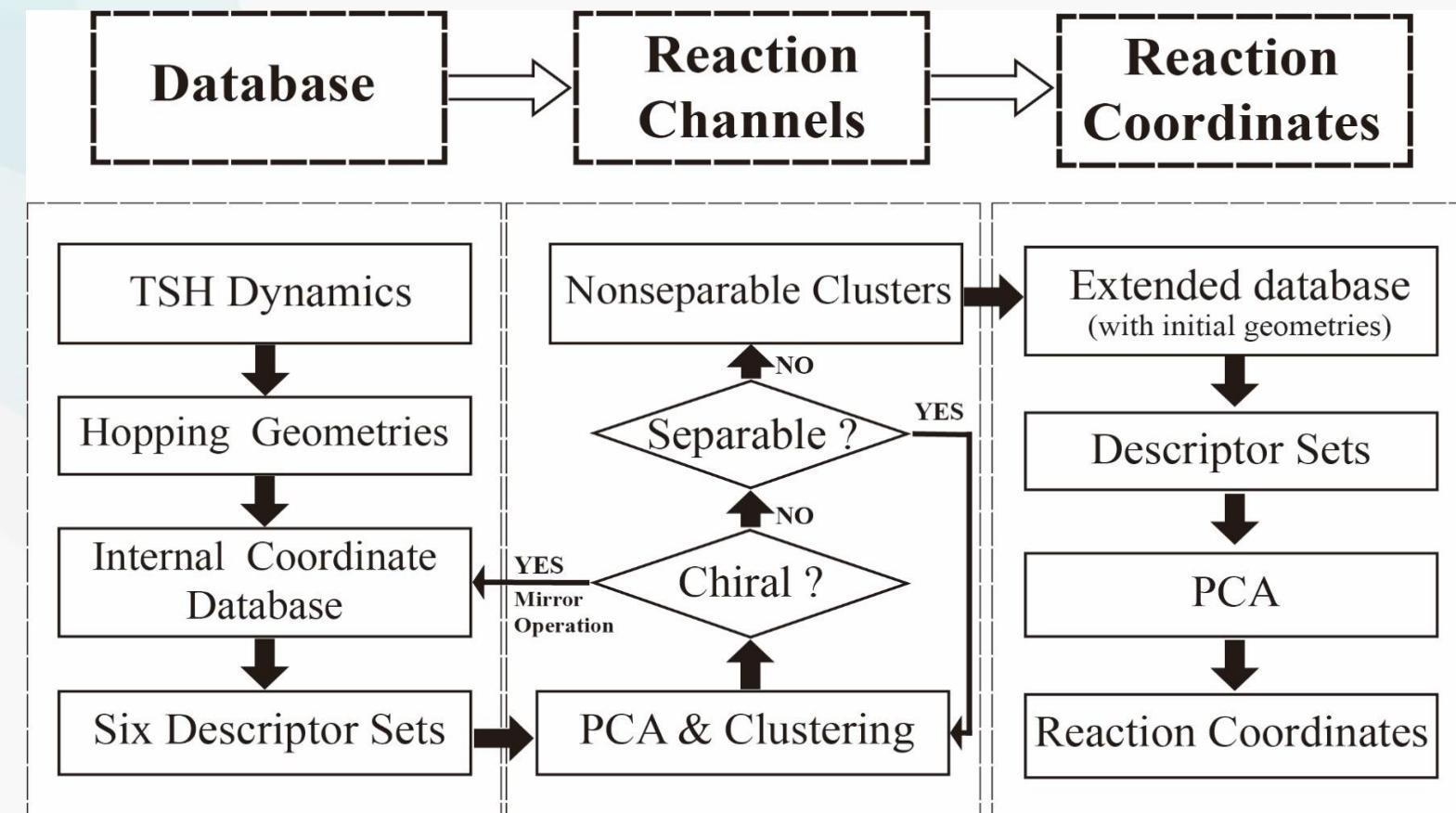
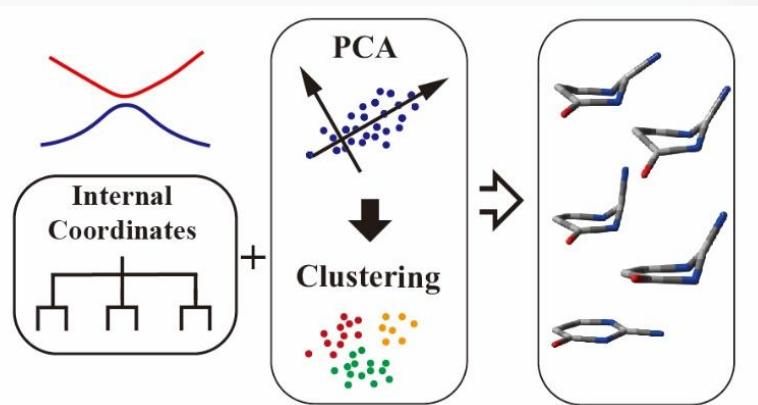


Analysis of Trajectory Evolution IV: Ring Motion

34

An **hierarchical** protocol based on the PCA and clustering methods for the **automatic** analysis of the **ring deformation** in the nonadiabatic dynamics

- Dimensionality reduction : PCA
- Clustering : DBSCAN & Agglomerative clustering

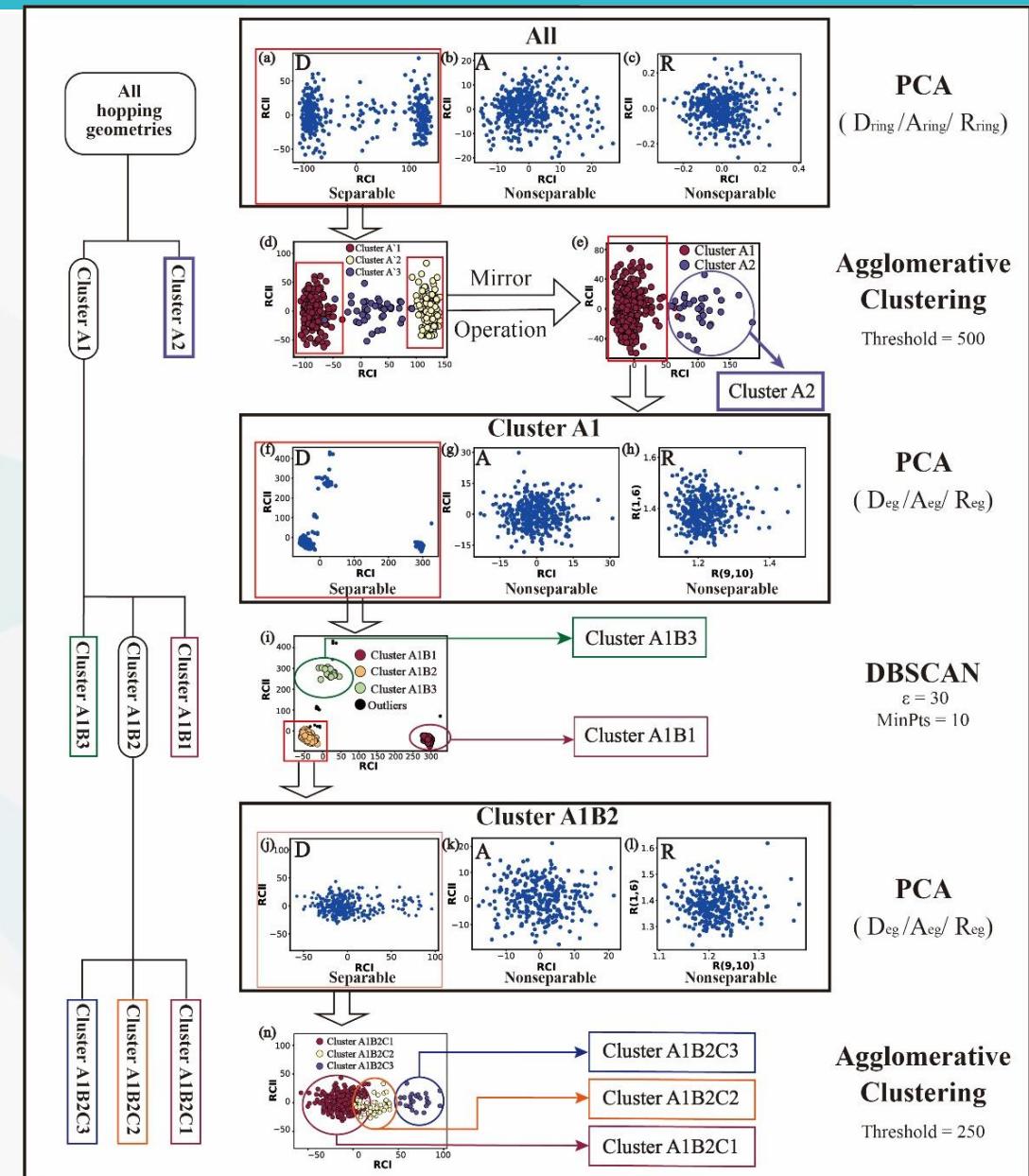


Analysis of Trajectory Evolution IV: Ring Motion

35

Division scheme and analysis process

Molecular Structure and Atomic Labels				
Keto-isocytosine				
Descriptor Sets				
D_{ring}	D(4,1,5,3)	D(5,1,4,10)	D(10,2,3,5)	D(3,2,10,4)
	D(4,1,5,3)	D(5,1,4,10)		
A_{ring}	A(4,1,5)	A(3,2,10)	A(2,3,5)	A(1,4,10)
	A(1,5,3)	A(2,10,4)		
R_{ring}	R(1,4)	R(1,5)	R(2,3)	R(4,10)
	R(3,5)	R(2,10)		
D_{eg}	D(6,1,5,3)	D(6,1,4,10)	D(1,4,10,9)	D(3,2,10,9)
A_{eg}	A(4,1,6)	A(2,10,9)	A(5,1,6)	A(4,10,9)
R_{eg}	R(1,6)	R(9,10)		

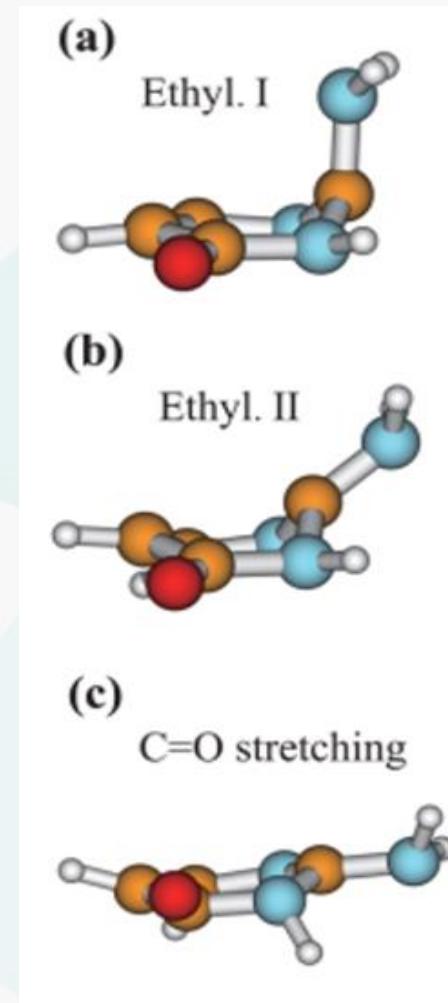
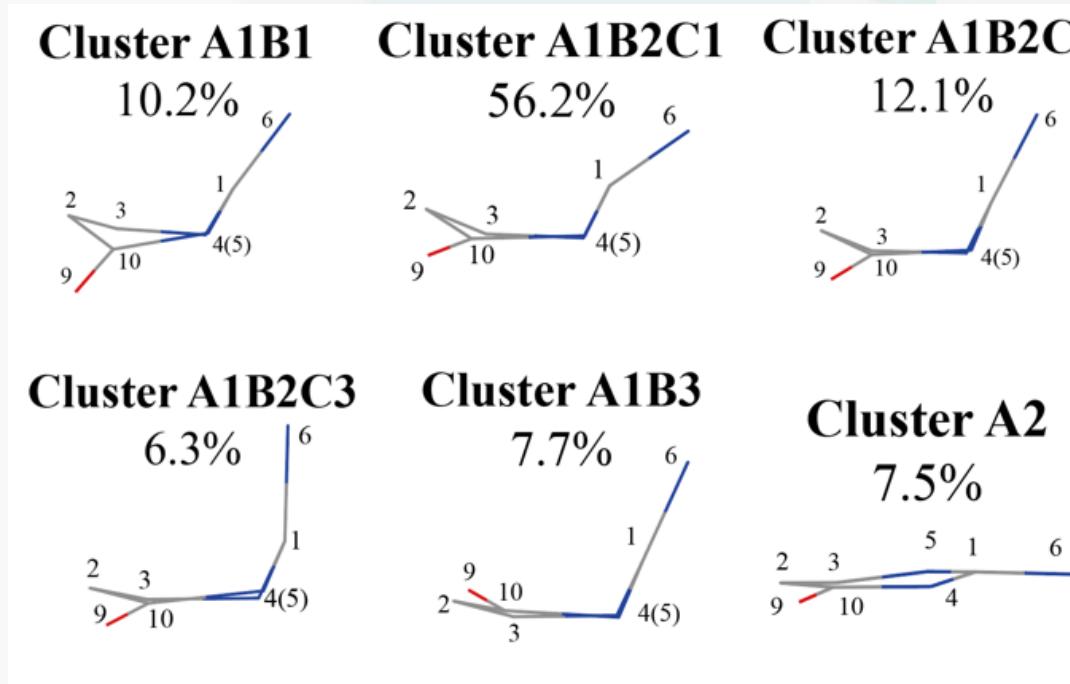


Analysis of Trajectory Evolution IV: Ring Motion

36

Identify reaction coordinates

- Key active coordinates (**major and minor**)
- Other related information (ratios etc.)
- Further physical insights



Un-supervised

Machine Learning Methods
may Bring Considerable Impact on
Nonadiabatic Dynamics Simulation

Promising

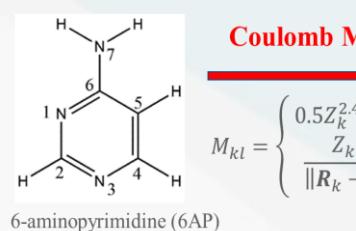
?

Problems

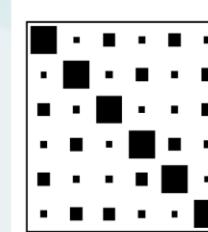
Machine-Learning PES in nonadiabatic dynamics

38

- The kernel ridge regression is used to build the excited-state PESs
- Nonadiabatic dynamics based on ML-PESs

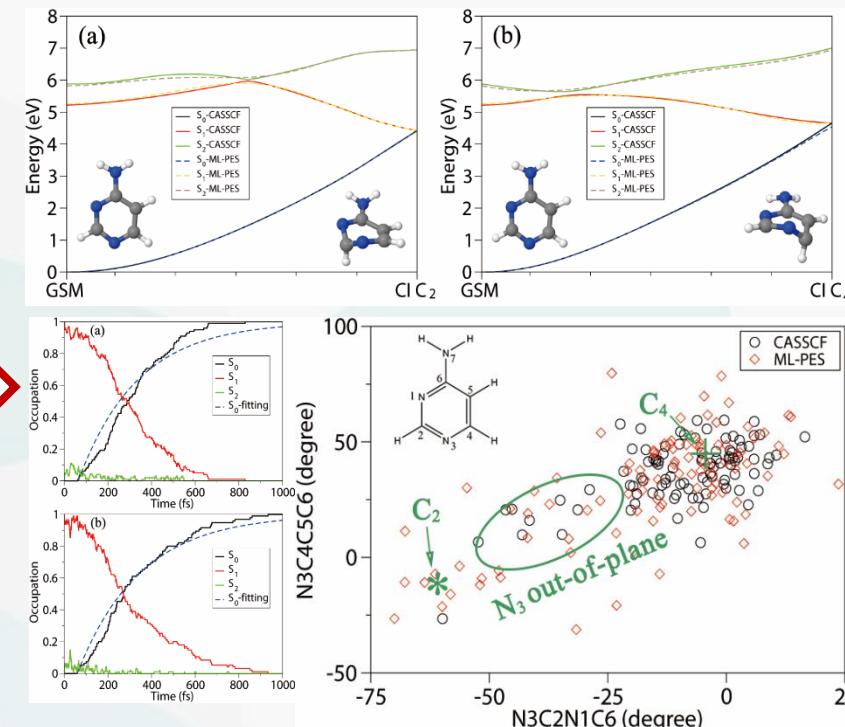


$$M_{kl} = \begin{cases} 0.5Z_k^{2.4} & k = l \\ \frac{Z_k Z_l}{\|R_k - R_l\|} & k \neq l \end{cases}$$



$$f(\mathbf{m}_i) = \sum_{j=1}^{N_t} c_j K(\mathbf{m}_i, \mathbf{m}_j)$$

$$K(\mathbf{m}_i, \mathbf{m}_j) = \exp\left(-\frac{\|\mathbf{m}_i - \mathbf{m}_j\|^2}{2\sigma^2}\right)$$



- Achieve the efficient massive dynamics simulations with a large number of trajectories.

Transient-Absorption Pump-Probe Signals

Hamiltonian

$$\hat{H}(t) = \hat{H}_M + \hat{H}_F(t)$$

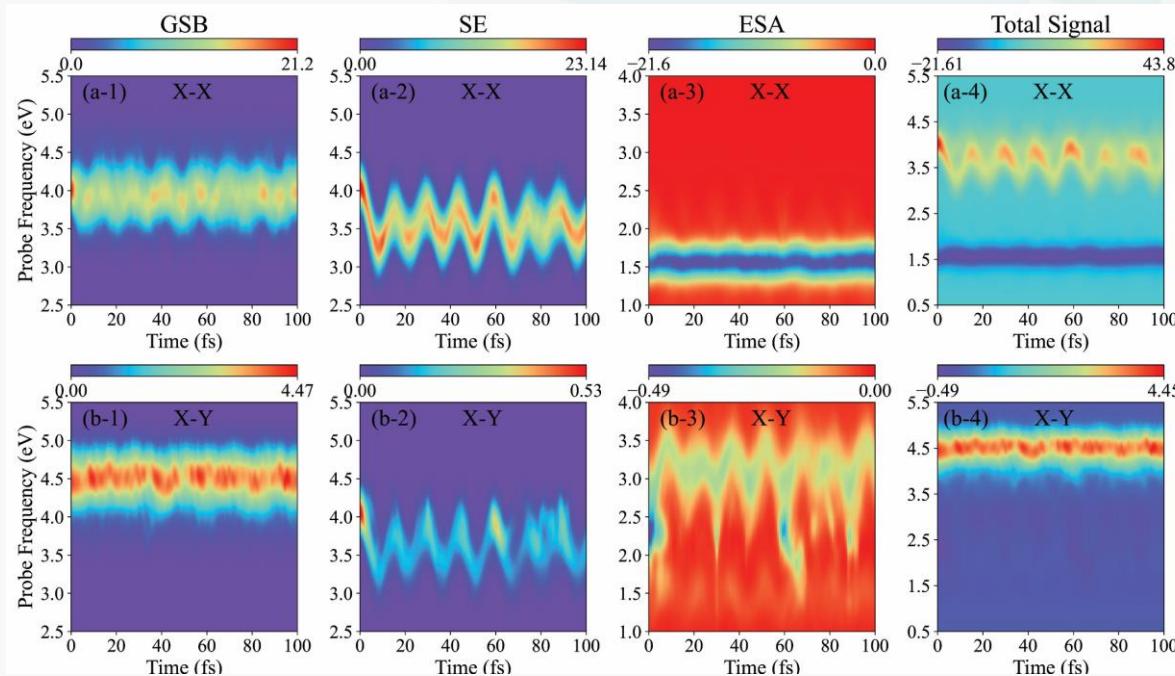
$$\hat{H}_F(t) = -\hat{\mu} \cdot \mathbf{E}(t)$$

Third-order polarization

$$\mathbf{P}^{(3)}(t) = (i)^3 \int_0^\infty dt_3 \int_0^\infty dt_2 \int_0^\infty dt_1 \mathbf{E}(t-t_3) \mathbf{E}(t-t_3-t_2) \mathbf{E}(t-t_3-t_2-t_1) S(t_3, t_2, t_1)$$

$$S(t_3, t_2, t_1) = \text{Tr}\{\hat{\mu}^I(t_1+t_2+t_3)[\hat{\mu}^I(t_1+t_2), [\hat{\mu}^I(t_1), [\hat{\mu}^I(0), \hat{\rho}(-\infty)]]]\}$$

$$\hat{\mu}^I(t) = e^{i\hat{H}_M(t-t_0)} \hat{\mu} e^{-i\hat{H}_M(t-t_0)}$$

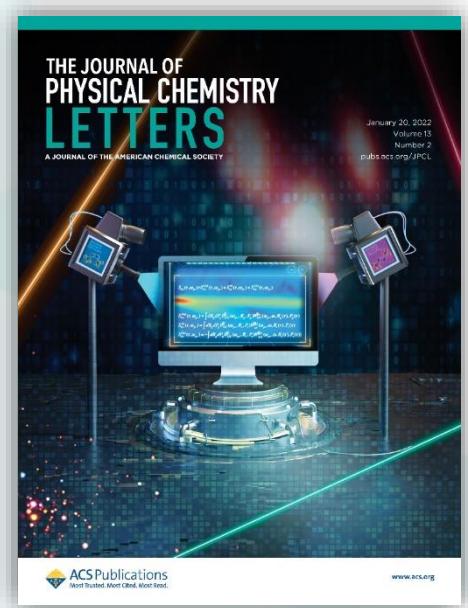
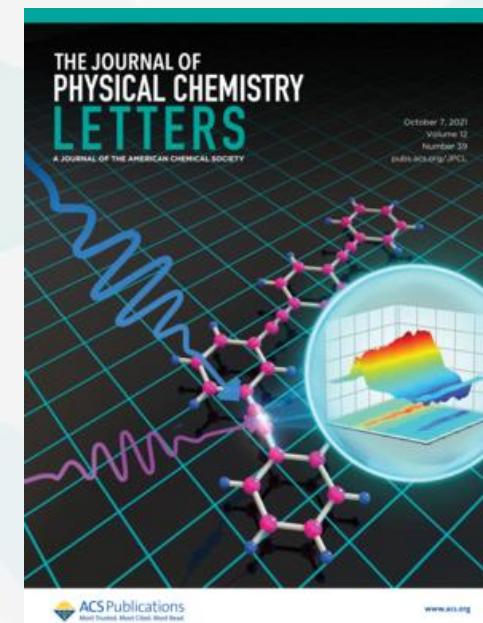


Hu, Peng, Chen, Gelin, Lan, *JPCL*, 2021, 12, 39, 9710–9719

Pump-probe signal

$$I_{\text{int}}(\tau, \omega_{pr}) = \omega_{pr} \text{Im} \left\{ \int_{-\infty}^{\infty} dt E_{pr}(t) e^{i\omega_{pr}t} P_{k_{pr}}^{(3)}(\tau, t) \right\}$$

$$I_{\text{dis}}(\tau, \omega) = \omega_{pr} \text{Im} \left\{ \varepsilon_{pr}(\omega) P_{k_{pr}}^{(3)}(\tau, \omega) \right\}$$

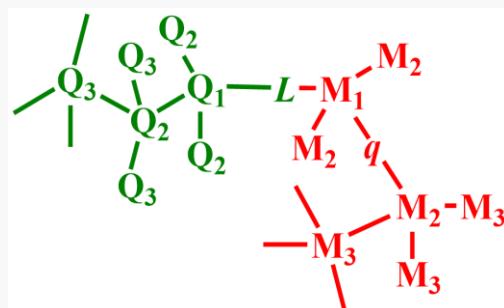
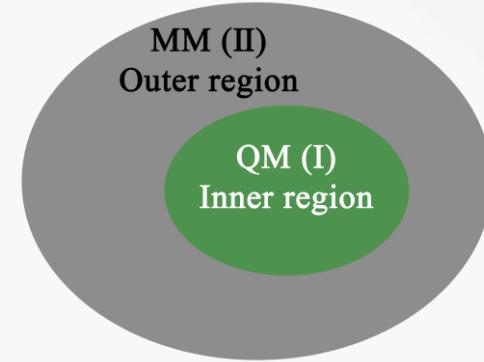
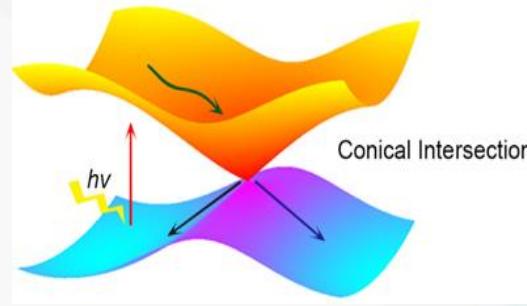


Xu, Lin, Hu, Gu, Gelin, Lan, *JPCL*, 2022, 13, 2, 661–668

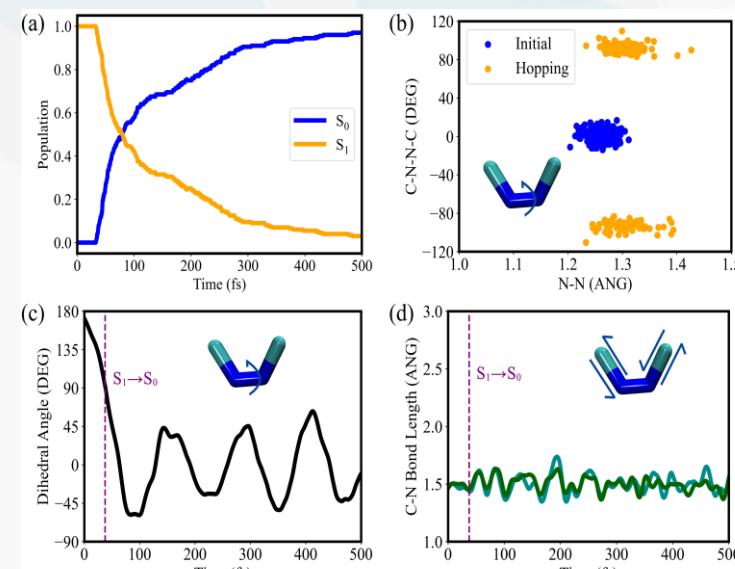
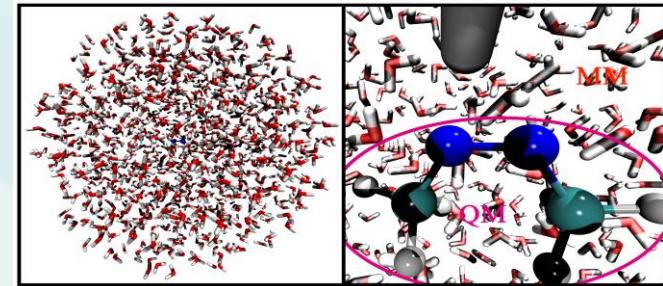
Nonadiabatic Dynamics in Solutions and Biological Environments

40

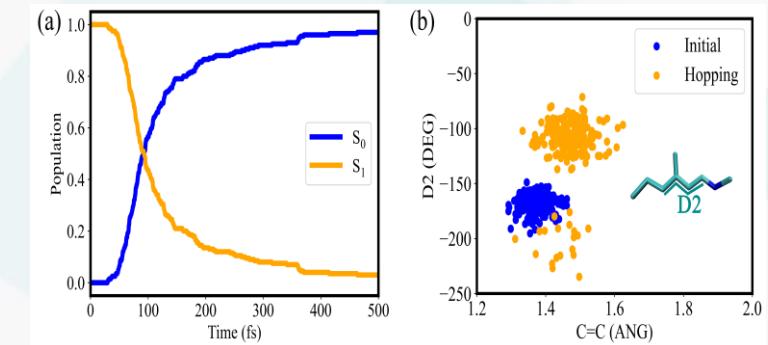
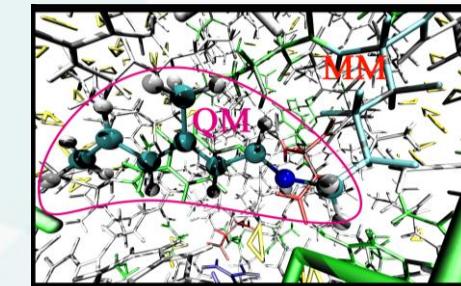
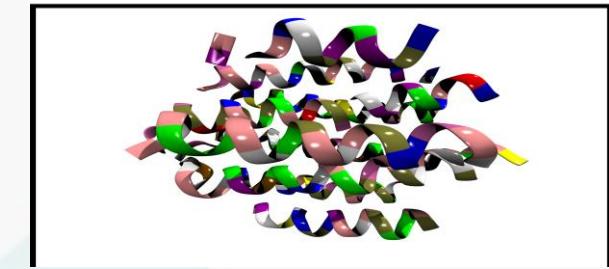
QM/MM Surface Hopping



Nonadiabatic Dynamics in Solutions



Nonadiabatic Dynamics in Proteins



Acknowledgement and Starting

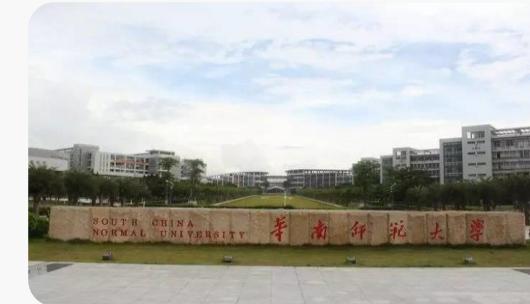
Guangzhou
in China



City view of
Guangzhou



South China
Normal University



Funding: NSCF

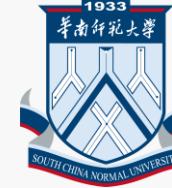
Thanks my current and previous group members:

- Mr. Jiawei Peng, Miss Juanjuan Zhang, Mr. Yifei Zhu,
- Mr. Xu Kang, Miss Sisi Liu, Mr Yutai Zhang
- Dr. Kunni Lin, Dr. Deping Hu, Dr. Yu Xie

Thanks my collaborators:

- Prof. Fenglong Gu, Prof. Chao Xu, Prof Maxim Gelin, Prof. Chenwei Jiang

New Postdoc and Research Assistant Positions are open !!!



华南師範大學
SOUTH CHINA NORMAL UNIVERSITY

Thank you !

Zhenggang Lan
2024.02



