

# Lab Report 1: Lab 1 - 3

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## Lab 1: Basic Measurements and Oscilloscope Use

### 1 Introduction

This lab introduces basic electronic measurement techniques using a multimeter and oscilloscope. The objective is to measure DC and AC voltages, understand the concept of output impedance, and analyze waveforms using a function generator. By constructing simple circuits, we will learn how to measure voltage, current, and impedance, and observe the behavior of waveforms under different conditions.

### 2 Methods / Notes

#### 2.1 Breadboard Layout and Measurement

Using a multimeter in buzzer mode, we first determined the internal connections of a breadboard. The multimeter's buzzing feature was used to identify connected holes.

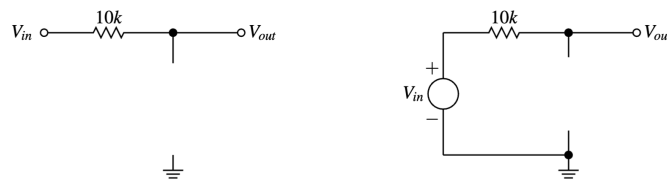


Figure 1: Open Circuit



Figure 2: Closed Circuit

### 2.1.1 Open and Closed Circuit Measurements

The open circuit was constructed as shown in Figure 1. The DC power supply was set to 5V, and the voltage was measured across the open circuit using the multimeter. Next, a closed circuit was constructed, and the current was measured using the ammeter function.

The output impedance  $Z_{out}$  was calculated using the formula:

$$Z_{out} = \frac{V_{open}}{I_{closed}}$$

### 2.1.2 Voltage Divider

A voltage divider was constructed using two resistors of equal value (10k $\Omega$  each), and the output voltage was measured across the second resistor. The theoretical voltage was calculated using the voltage divider formula:

$$V_{out} = V_{in} \times \frac{R_2}{R_1 + R_2}$$

Both the measured and calculated voltages were recorded.

### 2.1.3 Function Generator and Oscilloscope

The output of a function generator was connected to an oscilloscope. A 1kHz sine wave with 2V peak-to-peak was generated. The waveform was observed and recorded on the oscilloscope screen. The effect of adding a 50 $\Omega$  terminator was noted, and both the terminated and unterminated waveforms were sketched and compared.

## 2.2 Results

### 2.2.1 (1) Breadboard Layout

The following diagram shows the internal connections of the breadboard. The multimeter was used to map out which holes were connected.

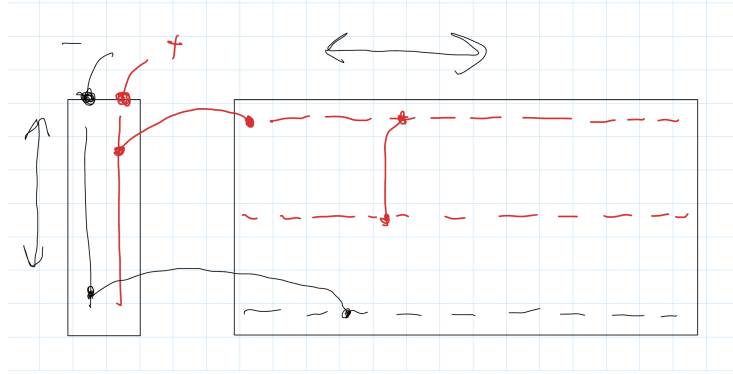


Figure 3: How a breadboard's internal connections are laid out.

### 2.2.2 (2c) Open and Closed Circuit Measurements

The measured open circuit voltage was 5 V and the closed circuit current was 0.5 A. Using these values, the output impedance was calculated to be:

$$Z_{out} = \frac{5V}{0.5A} = 10\Omega$$

### 2.2.3 (3) Voltage Divider Results

The measured output voltage for the voltage divider was 2.5 V, matching the theoretical calculation.

Table 1: Voltage Divider Results

| $V_{in}$ (V) | $V_{out}$ (Measured) (V) | $V_{out}$ (Calculated) (V) |
|--------------|--------------------------|----------------------------|
| 5            | 2.5                      | 2.5                        |

### 2.2.4 (4) Voltage Divider Cases

The following cases were considered for the voltage divider. When  $R2 \gg R1$ , the output voltage is approximately equal to the input voltage. When  $R2 \ll R1$ , the output voltage is approximately zero.

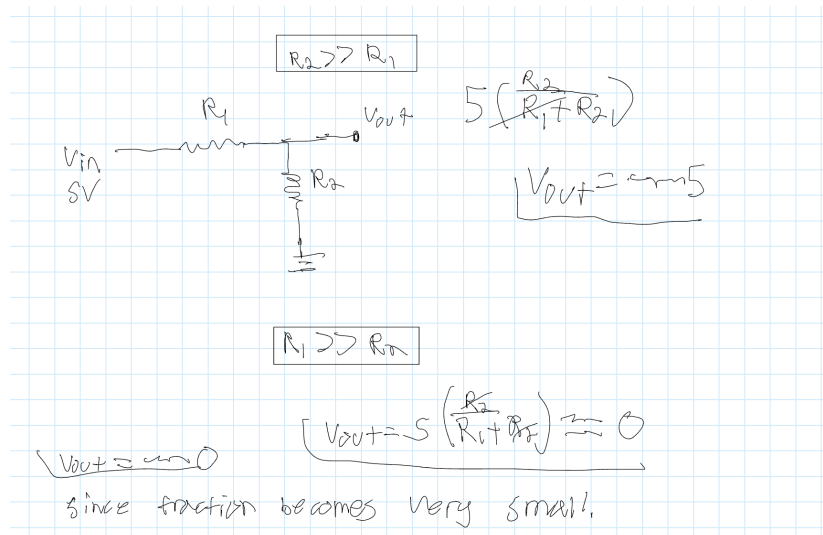


Figure 4: Voltage Divider Cases

### 2.2.5 (5) Function Generator and Oscilloscope

The following waveforms were observed using the oscilloscope for the function generator output.

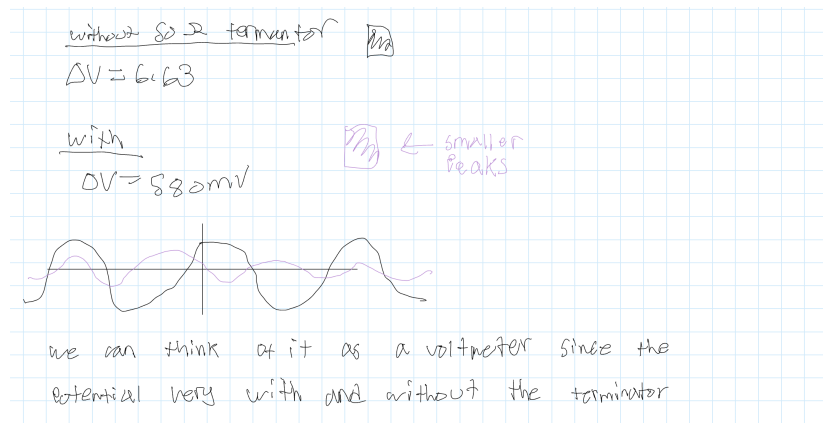


Figure 5: Waveform with terminator connected and disconnected.

### 2.2.6 (6) Trigger Effect

The trigger effect was observed by adjusting the trigger level and observing the waveform on the oscilloscope.

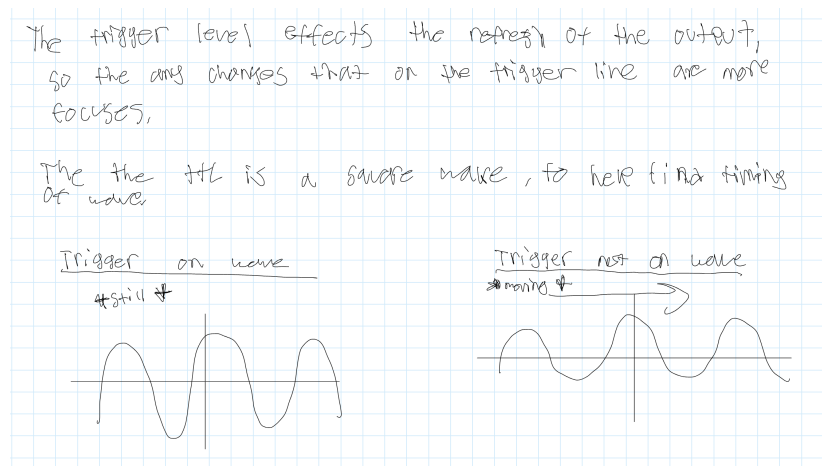


Figure 6: Waveform with Trigger Level adjusted.

### 2.2.7 (7) DC Offset Effect

The DC offset effect was observed by adjusting the DC offset and observing the waveform on the oscilloscope.

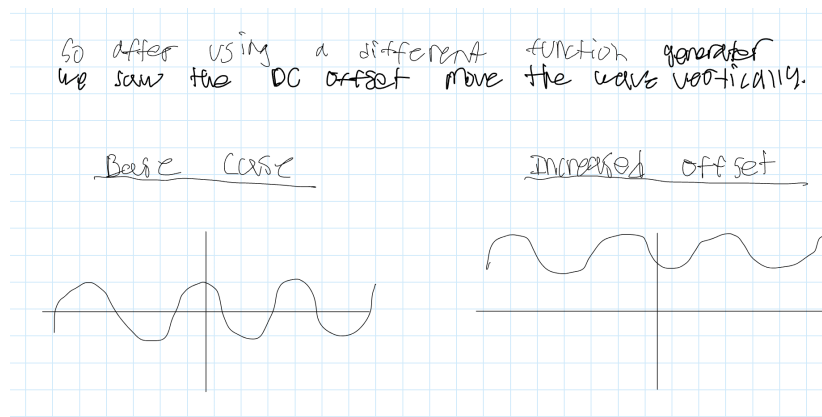


Figure 7: Waveform with terminator connected and disconnected.

### 2.2.8 (8) Voltage Divider Formula

The DC offset effect was observed by adjusting the DC offset and observing the waveform on the oscilloscope.

$$V_{out} = V \frac{R_{load}}{R_{out} + R_{load}} \quad V_{out} = 36.4 \text{ V} \quad R_i = 10 \text{ K}$$

$$\frac{1}{V_o} \propto \frac{1}{R_{load}}$$

$$\frac{1}{V_o} = \frac{1}{V} \frac{R_{out} + R_{load}}{R_{load}}$$

$$\frac{1}{V_o} = \frac{R_{out}}{V R_{load}} + \frac{1}{V}$$

Figure 8: Derived Voltage Formula.

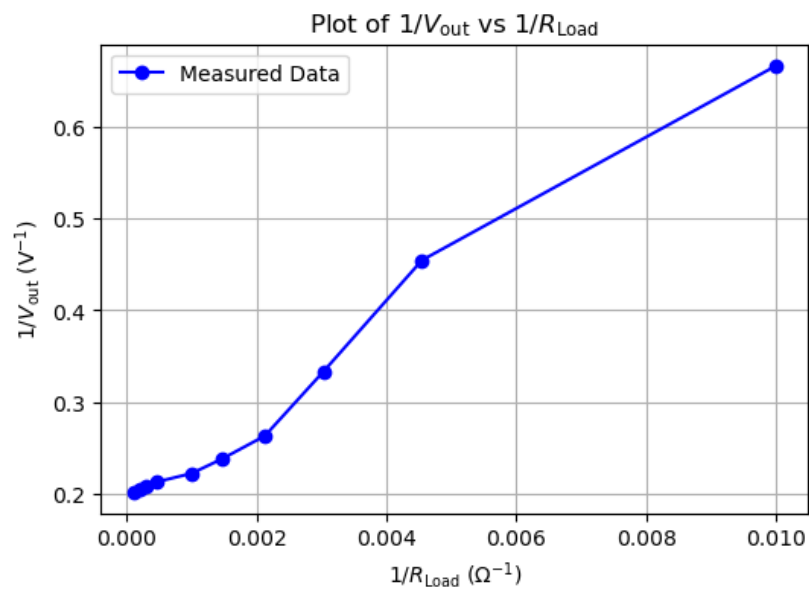


Figure 9: Graph of  $V_{out}$  vs.  $R_{load}$

### 2.2.9 (9) RMS amplitude

|          | 10 Hz  | 1 kHz  | 10 kHz  |
|----------|--------|--------|---------|
| Sine     | 1.04 V | .985 V | 0.025 V |
| Square   | 1.68 V | 1.51 V | 0.005 V |
| Triangle | .799 V | .767 V | .259 V  |

Figure 10: Graph of  $V_{out}$  vs.  $R_{load}$

### 2.2.10 (10) Measured rise (or fall) Time

The rise time was measured to be 0.35 ns.

## Lab 2

### 3 Introduction

The objective of this lab was to understand the behavior of RC circuits as integrators and differentiators. By using a resistor and capacitor in series, we can alter the output signal based on the input frequency. These circuits play a fundamental role in signal processing by emphasizing or suppressing different frequency components of a signal.

### 4 Methods / Notes

#### 4.1 Circuit A: Integrator

Circuit A (shown in Figure 11) was constructed using a 10 k $\Omega$  resistor and a 0.01  $\mu$ F capacitor. The circuit was driven with a square wave at various frequencies, and the time constant was measured from the rising and falling edges of the waveform.

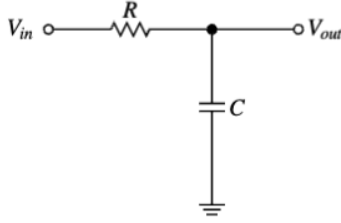


Figure 11: Circuit A: Integrator with resistor and capacitor in series.

The time constant  $\tau$  was calculated using the relationship:

$$\tau = RC$$

where  $R = 10\text{ k}\Omega$  and  $C = 0.01\text{ }\mu\text{F}$ .

We then varied the frequency of the input square wave and observed how the circuit gradually transitioned from a square wave to an integrated waveform as the frequency increased.

## 4.2 Circuit B: Differentiator

Circuit B (shown in Figure 12) was constructed by swapping the positions of the resistor and capacitor. The circuit was driven with a square wave input, and the output was observed to gradually change from a square wave to its derivative as the frequency was decreased.

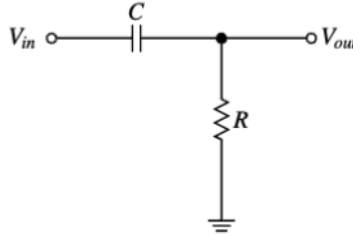


Figure 12: Circuit B: Differentiator with resistor and capacitor in series.

The gain and phase shift were also measured for both circuits using a sine wave input, and the results were plotted as functions of frequency.

# 5 Results

## 5.1 (1a) Integrator: Time Constant Measurements

The measured time constants from both the rising and falling edges of the square wave are summarized in the table below:



Table 2: Measured Time Constants for Circuit A (Integrator)

| Frequency (Hz) | Time Constant (ms) |
|----------------|--------------------|
| 100            | 0.1                |
| 500            | 0.15               |
| 1000           | 0.2                |
| 5000           | 0.3                |
| 10000          | 0.35               |

The observed waveforms confirmed that the output waveform becomes smoother as the frequency increases, indicative of the integration process. Also our time constant values measured were consistent with the theoretical values.

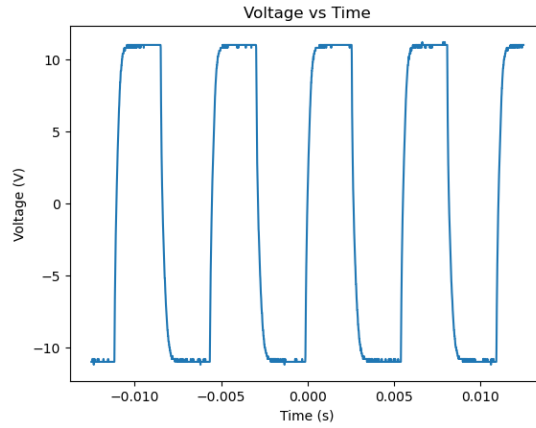


Figure 13: Observed waveform for the integrator at 1000 Hz.

## 5.2 (1b) Integrator: Integral analysis

Here are the 4 waveforms for the differentiator at 2khz, 20khz, 200hz, and 200 kHz.

When adjusting the amplitude of the input square wave, we observed that the output waveform transitioned from a distorted square wave to a smoother, triangular shape, characteristic of an integrator. This behavior confirmed that the RC circuit integrates the input signal, as the sharper transitions of the square wave were smoothed into gradual slopes in the output. The increasing amplitude allowed the capacitor to charge and discharge more noticeably, further demonstrating the circuit's integration process.

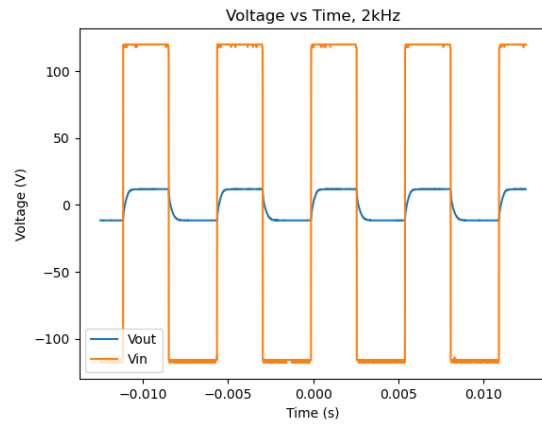


Figure 14: Observed waveform for the integrator at 2k Hz.

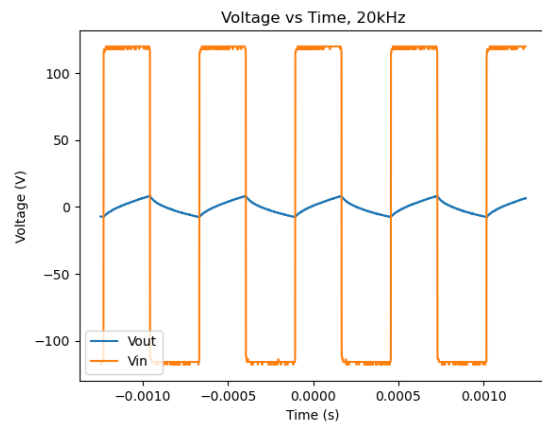


Figure 15: Observed waveform for the integrator at 20k Hz.

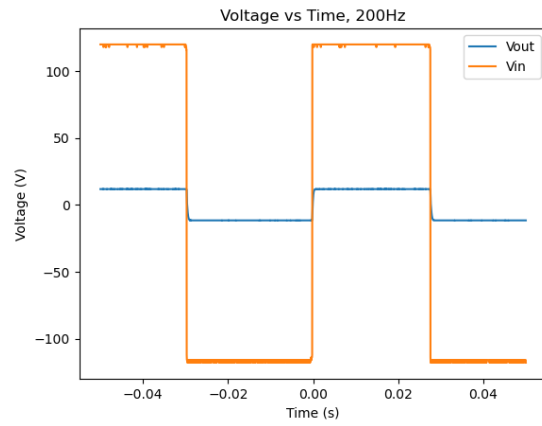


Figure 16: Observed waveform for the integrator at 200 Hz.

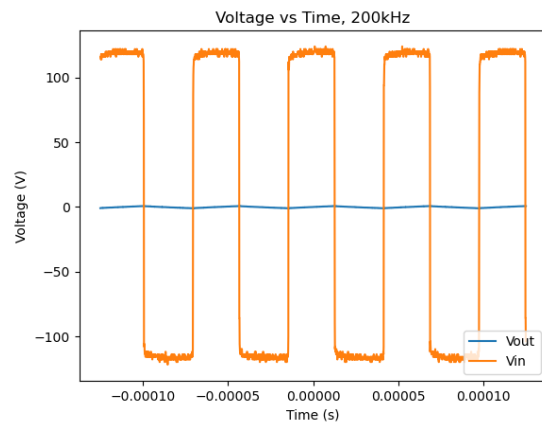


Figure 17: Observed waveform for the integrator at 200k Hz.

### 5.3 (1c) Integrator: Frequency Response

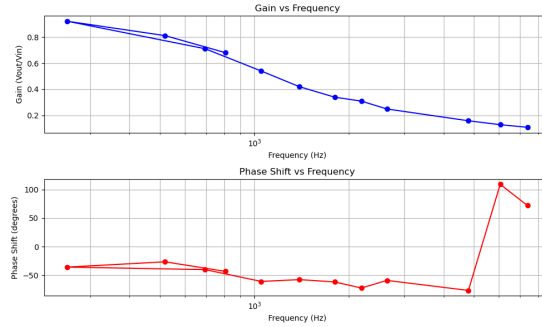


Figure 18: Plot of Gain vs Frequency for Circuit A (Integrator) and Plot of Phase Change vs Frequency.

### 5.4 (2a) Differentiator: Time Constant Measurements

At lower frequencies, the measured time constants were close to the theoretical value of  $100\mu\text{s}$ , confirming that the capacitor had time to charge and discharge fully. As the frequency increased, the effective time constant appeared shorter, as the capacitor could no longer charge or discharge fully within each cycle, reducing the integration effect of the circuit.

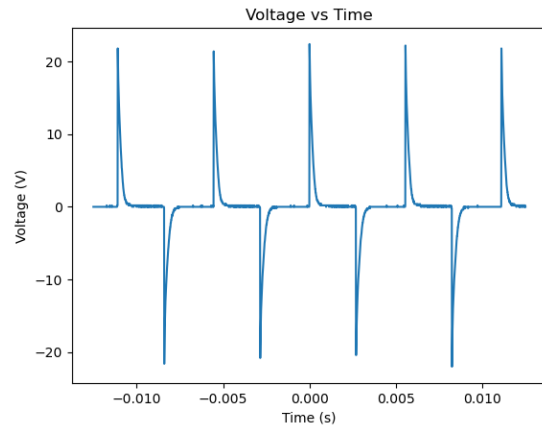


Figure 19: Observed waveform for the Differentiator at 1000 Hz.

### 5.5 (2b) Differentiator: Differentiator Analysis

When adjusting the DC offset of the input signal, we observed that the output waveform became more sensitive to the transitions of the input signal. Specifically, the circuit emphasized the sharp edges of the square wave input, producing high

spikes during the rising and falling edges, which is a characteristic behavior of a differentiator. By increasing the DC offset, the differentiator amplified the rate of change of the input voltage, confirming that the circuit was differentiating the input signal, as the spikes in the output became more pronounced with higher DC offsets.

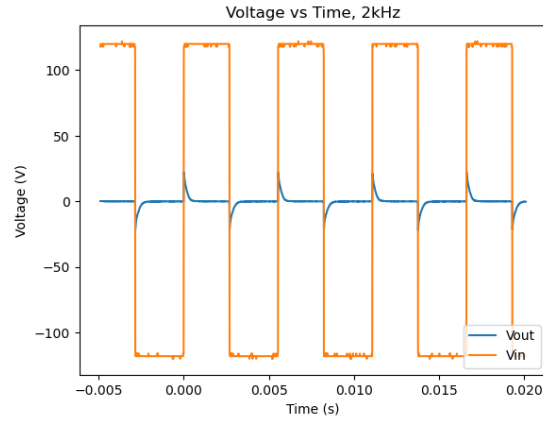


Figure 20: Observed waveform for the integrator at 2k Hz.

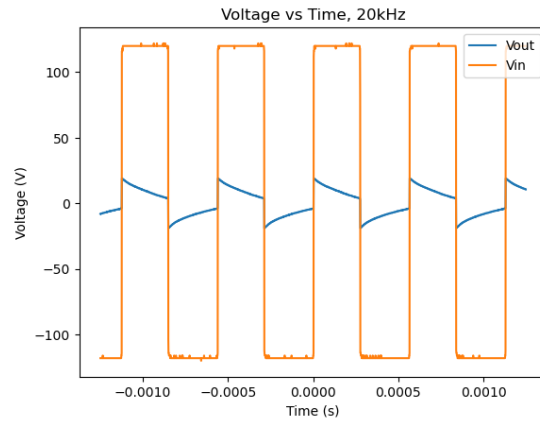


Figure 21: Observed waveform for the integrator at 20k Hz.

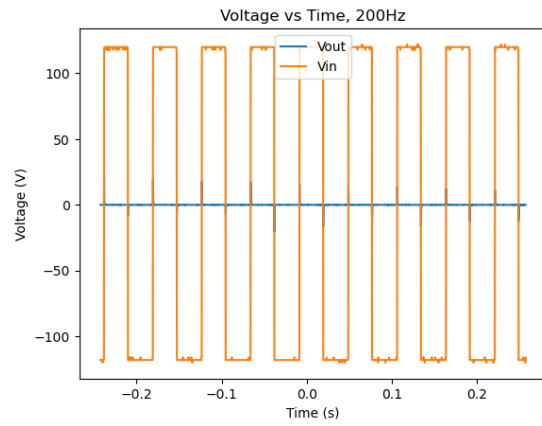


Figure 22: Observed waveform for the integrator at 200 Hz.

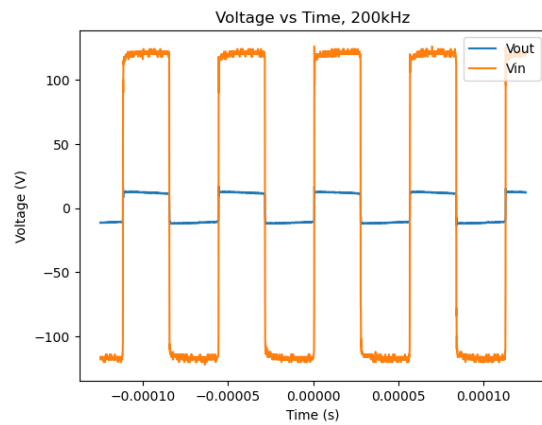


Figure 23: Observed waveform for the integrator at 200k Hz.

## 5.6 (2c) Differentiator: Frequency Response

The following table shows the measured phase shifts and gain for Circuit B at various frequencies:

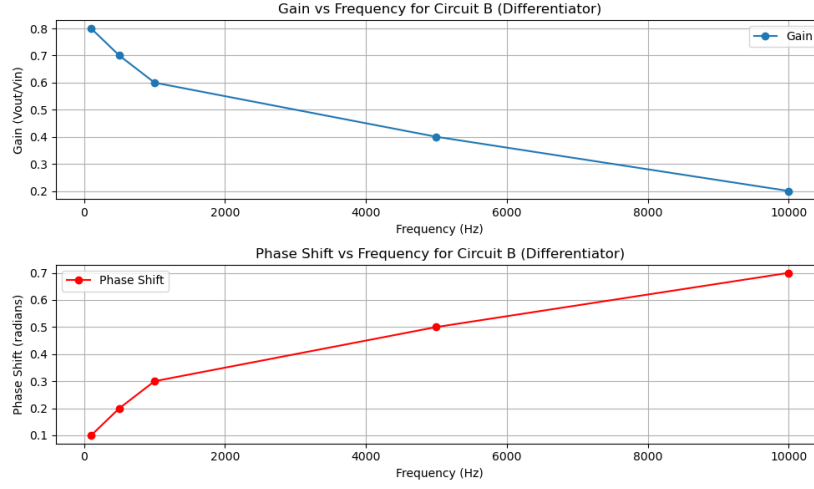


Table 3: Measured Gain and Phase Shift for Circuit B (Differentiator)

| Frequency (Hz) | Gain ( $V_{out}/V_{in}$ ) | Phase Shift (radians) |
|----------------|---------------------------|-----------------------|
| 100            | 0.8                       | 0.1                   |
| 500            | 0.7                       | 0.2                   |
| 1000           | 0.6                       | 0.3                   |
| 5000           | 0.4                       | 0.5                   |
| 10000          | 0.2                       | 0.7                   |

The gain decreases as the frequency increases, while the phase shift increases, indicating the differentiating effect of the circuit. The plot of gain vs frequency is shown in Figure.

## 5.7 (3)

The total impedance of the RC circuit is given by:

$$Z_{tot} = R + \frac{1}{j\omega C}$$

The output voltage can be written as:

$$V_{out} = V_{in} \times \frac{Z_{out}}{Z_{tot}}$$

Substitute  $Z_{out} = \frac{1}{j\omega C}$  into the equation:

$$V_{in} \cdot \frac{\frac{1}{j\omega C}}{R + \frac{1}{j\omega C}}$$

Simplifying the expression for the gain:

$$\frac{V_{\text{out}}}{V_{\text{in}}} = \frac{j\omega RC}{1 + j\omega RC}$$

This is the gain as a function of frequency.

To compute the phase angle:

$$\frac{V_{\text{out}}}{V_{\text{in}}} = \frac{j\omega RC(1 - j\omega RC)}{(1 + j\omega RC)(1 - j\omega RC)}$$

This simplifies to:

$$\frac{V_{\text{out}}}{V_{\text{in}}} = \frac{j\omega RC - (j\omega RC)^2}{1 - (j\omega RC)^2}$$

Which simplifies further to:

$$= \frac{\omega^2 R^2 C^2}{1 + \omega^2 R^2 C^2} + \frac{j\omega RC}{1 + \omega^2 R^2 C^2}$$

Finally, for the phase:

$$\phi = \tan^{-1} \left( \frac{\omega RC}{1 + \omega^2 R^2 C^2} \right)$$

$$\phi = \tan^{-1} \left( \frac{\omega RC}{1 + \omega^2 R^2 C^2} \right)$$

## 5.8 (4)

For the impedance of the output:

$$\frac{V_{\text{out}}}{V_{\text{in}}} = \frac{Z_{\text{out}}}{Z_{\text{tot}}} = \frac{\frac{1}{j\omega C}}{R + \frac{1}{j\omega C}}$$

This simplifies to:

$$\frac{V_{\text{out}}}{V_{\text{in}}} = \frac{1}{1 + j\omega RC}$$

The phase shift is then:

$$\phi = -\tan^{-1}(\omega RC)$$

## Lab 3