

# Linear Systems With Real Eigenvalues

# 5-8, 9-22, 25-34

# 52, 55, 56

(1)  $ax'' + bx' + c = 0$

(2)  $x' = Ax$

The roots of the characteristic are the eigenvalues of  $A$ .

$$\begin{aligned}\dot{x} &= e^{\lambda t} \dot{v} \\ \lambda e^{\lambda t} \dot{v} &= A e^{\lambda t} \dot{v} \\ e^{\lambda t} A \dot{v} - \lambda e^{\lambda t} I \dot{v} &= \vec{0} \\ e^{\lambda t} (A - \lambda I) \dot{v} &= \vec{0} \\ (A - \lambda I) \dot{v} &= \vec{0}\end{aligned}$$

## Solving Homogeneous Linear 2x2 DE Systems

For a two-dimensional system of homogeneous linear differential equations  $\vec{x}' = A\vec{x}$ , where  $A$  is a matrix of constants that has eigenvalues  $\lambda_1$  and  $\lambda_2$  with corresponding eigenvectors  $\vec{v}_1$  and  $\vec{v}_2$ , we obtain two solutions:

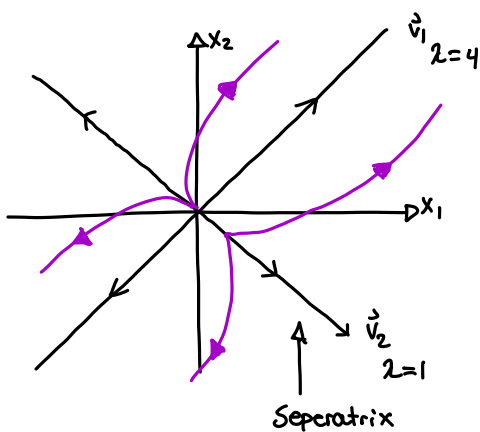
$$\vec{x}_1 = e^{\lambda_1 t} \vec{v}_1, \quad \vec{x}_2 = e^{\lambda_2 t} \vec{v}_2$$

If  $\lambda_1 \neq \lambda_2$ , these two solutions are linearly independent and form a basis for the solution space. Thus the general solution

$$\vec{x}(t) = c_1 e^{\lambda_1 t} \vec{v}_1 + c_2 e^{\lambda_2 t} \vec{v}_2$$

Ex 2  $\vec{x}' = \begin{bmatrix} 2 & 2 \\ 1 & 3 \end{bmatrix} \vec{x}$

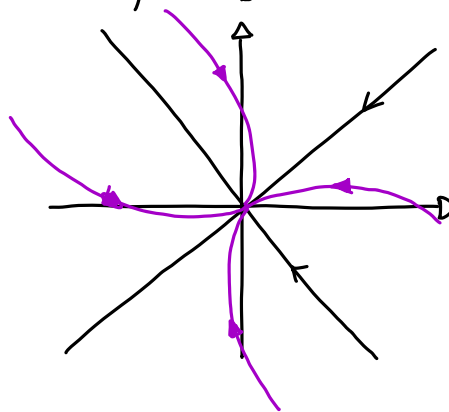
$\lambda = 4, \lambda = 1$   $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$   $\vec{v}_2 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$



Ex 3

$\vec{x}' = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix} \vec{x}$   $\lambda_1 = -1$   $\lambda_2 = -3$

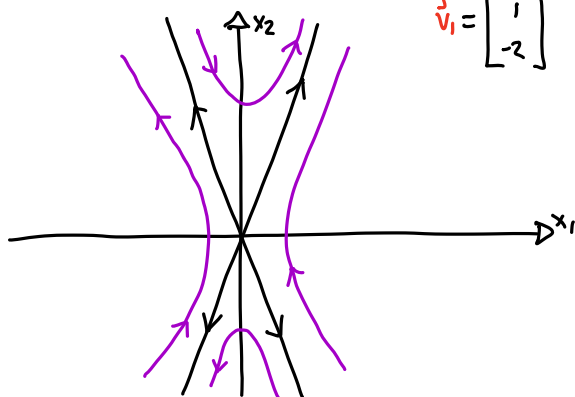
$\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$   $\vec{x} = c_1 e^{-t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^{-3t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$



Ex 1

$\vec{x}' = A\vec{x} = \begin{bmatrix} 1 & 1 \\ 4 & 1 \end{bmatrix} \vec{x}$

$\lambda_1 = -1$   $\lambda_2 = 3$   $\vec{v}_1 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$   $\vec{v}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$



Ex 5

$$\vec{x}' = A\vec{x} = \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} \vec{x}$$

$$\lambda_1 = \lambda_2 = 3$$

$$\vec{x} = c_1 e^{3t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 e^{3t} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} c_1 e^{3t} \\ c_2 e^{3t} \end{bmatrix}$$

Ex 6

$$\vec{x}' = \begin{bmatrix} 2 & -1 \\ 4 & 6 \end{bmatrix} \vec{x}$$

$$\bar{x}_1 \quad \lambda_1 = \lambda_2 = 4 \quad \vec{v} = \begin{bmatrix} 1 \\ -2 \end{bmatrix} \quad \vec{x}_1 = e^{4t} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$\bar{x}_2 = c_2 t e^{2t} \vec{v} + e^{2t} \vec{u} \quad \vec{x}' = A\vec{x}$$

$$e^{2t} \vec{v} + \underline{4t} e^{2t} \vec{v} + 4e^{4t} \vec{u} = A(t e^{4t} \vec{v} + e^{4t} \vec{u})$$

$$4\vec{v} = A\vec{v} \quad 0 = (A - 4I)\vec{v}$$

$$\vec{v} + 4\vec{u} = A\vec{u} \quad \vec{v} = (A - 4I)\vec{u}$$

$$\vec{v} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ -2 \end{bmatrix} = (A - 4I) \vec{u}$$

$$\begin{bmatrix} -2 & -1 & | & 1 \\ 4 & 2 & | & -2 \end{bmatrix}$$

$$u_1 + \frac{1}{2}u_2 = \frac{1}{2} \quad u_1 = k$$

$$u_2 = -2k + 1$$

$$u = k \begin{bmatrix} 1 \\ -2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

### Generalized Eigenvector

1.) Find an eigenvector corresponding to  $\lambda$

2.) Find a nonzero  $\vec{u}$

$$(A - \lambda I)\vec{u} = \vec{v}$$

$$3.) \quad \vec{x}(t) = c_1 e^{\lambda t} \vec{v} + c_2 e^{\lambda t} (t\vec{v} + \vec{u})$$