4.4 undetermined Coefficients 4.4 # 22,24,44,36,42 4.4.22 undetermined coefficients

0= 43 -3=cz

$$y'' + 4y = 1$$

$$y_h : \Delta = b^2 - 4ac \qquad y_h = e^{act} (c_1 cos \beta t + c_2 sin \beta t)$$

$$= 0^2 - 4c_1)(4)$$

$$= -16 \qquad \alpha = -\frac{b}{2a} \qquad \beta = \frac{\sqrt{4ac - b^2}}{2a}$$

$$\alpha = 0 \qquad \beta = \frac{\sqrt{4c_1}(4) - o}{2c_1} = \frac{\sqrt{16}}{2} = \frac{4}{2} = 2$$

$$\beta = \frac{\sqrt{4c}}{2c}$$

$$\beta = \frac{\sqrt{4c}}{2c}$$

$$\beta = \frac{\sqrt{16}}{2} = \frac{1}{2} = \frac{1}{2}$$

Yp: By inspection
$$y''+4y=1$$
 or $2+br+c=b$

Yp= $\frac{1}{4}$

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1/6 = C10052++C25in2++4

Yp: ay"+by1+cy=d

d= 3-6t

yp= At + B

yp= A y"p=0

$$4.4.24$$
 Undetermined Coefficients $y_6 = y_h + y_p$
 $y'' + y' - 2y = 3-6t$

$$C = 1, -2$$

$$y_6 = c_1 e^t + c_2 e^{-2t} + 3t$$

 $Y_b = Y_h + Y_P$

$$y_h: 0 = b^2 - 4ac$$

$$(2)^2 - 4(1)(1)$$

$$4 - 4$$

$$y_h = c_1e^{-t} + c_2te^{-t}$$

$$\frac{2}{2(1)} = \frac{1}{100} \frac{1}{100} + \frac{1}{100} \frac{1}{100} \frac{1}{100} + \frac{1}{100} \frac{1}{100} \frac{1}{100} + \frac{1}{100} \frac{1}{100} \frac{1}{100} + \frac{1}{100} \frac{1}{10$$

y"+2y'+y=6cosc+)

YP= 3t

0 + A - 2(At+B) = 3 - 6t

-2A=-6 , A=3 , B=0

A - 2At - 2B = 3-6t

A-2B=3

$$y = c_1e^{-t} + c_2te^{-t} + 3\sin(t)$$
 $c_1 = 1$
 $1 = c_1e^0 + c_2(\omega)e^0 + 3\sin(t)$
 $c_2 = 3$
 $c_2 = 3$
 $c_3 = c_4e^{-t} + c_2(\omega)e^0 + 3\sin(t)$
 $c_4 = c_1e^0 + c_2(\omega)e^0 + 3\sin(t)$
 $c_5 = c_1e^0 + c_2(\omega)e^0 + 3\cos(t)$
 $c_6 = c_1e^0 + c_2(\omega)e^0 + 3\cos(t)$

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4.4.36
           y''+3y'=Sinct)+2cosct)
                                        L= -P712
              r2+3r=0
             (C+3)=0 , r=0,-3
                                                                               γ= (1+4e<sup>-36</sup>+ ½(5;nct)-cos(t))
            △= 62-4ac
                                       =\frac{-3+3}{2(0)}=0
               = (3)2-4(1)(0)
                                        =-\frac{3-\sqrt{5}}{2(0)}=-\frac{6}{2}=-3
                =9
   Yh: Y= cierit + Gert
                                       yp: Sinct) +2cosct) yp = Acosct) + Bsinct) yp = ½(Sinct) - cosct)
           = c,+cze-3t
                                                             Yp = -Asinct) + Bcosct)
                                       y"+3y1
         Y_h = C_1 + C_2 e^{-3t}
                                                             Yp"=-Acos(+) - Boinc+)
                                       -A(cos(+)-Bsin(+)+3(-Asin(+)+Bcos(+))=Sin(+)+2(cos(+))
                                        - Acosct) - Bsinct) - 3Asinct) + 3Bcasct) = sinct) + 2cosct)
                                              cos(+)(-A+3B) = 2 cos(+) A = \begin{bmatrix} -1 & 3 & 2 \\ -3 & -1 & 1 \end{bmatrix} A = -\frac{1}{2}

S_{in}(+)(-3A-B) = S_{in}(+) S_{in}(+)
4.4.42 y"+ 4y"+4y=te-t y(0)=-1 y(0)=1
       y_h: (^2+4r+4) y_h = 4e^{rt} + c_2te^{rt}, r = -\frac{b}{2a} y_p: y_p = te^{-t} y_p = Ate^{-t} + Be^{-t} y_p = te^{-t} - 2e^{-t}
                                                                      Yp = Ae-t-Ate-t -Be-t
             (r+2)(r+2)
                                                      (= -4 = -2 Yp"= -Ae-+ -Ae-+ Ate-+ Be-t
        Yh = c1e-2++c2+e-2+
                                                                       Yp"= Ate-+ Be-+- anc-+
                                         Ate^{-t}+Be^{-t}-2Ae^{-t}+4(Ae^{-t}-Ate^{-t}-Be^{-t})+4(Ate^{-t}+Be^{-t})=te^{-t}
                                          Ate-t+Be-t-2Ae-t+4Ae-t-4Ate-496-t+486-t+486-t=te-t
                                                    Ate++Be++ZAe+ = te-+
   y=c1e-2++c2te-2++te-t-2e-t
                                                                   Ate-t=te-t e-t(B+2A)=0
                                      C1=1, C2=0
  ~1= C1-Q
                                                                      A=1
                                                                                        2A = -B
   1=4
                                                                      B=-a
  Y'=-24e-2++c2e-2+ 26te-2++ e-+-te-+ +Ze-+
                                                             y= e- Rt + te-t-ze-t
   1 = -2c1e0 + C2e0 - ZC260)e0 + e0 -0e0 + 2e0
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1=-2+02+1+2

1=ひ+1 0=ひ