

4.6 Forced Oscillations

4.6 # 11, 14, 24

4.6.11) $100\ddot{x} + 500\dot{x} + 4900x = 100\cos\omega_f t$

LRC Circuit equivalent

$$L\ddot{Q} + R\dot{Q} + \frac{1}{C}Q = f(t) \Rightarrow 100\ddot{Q} + 500\dot{Q} + 4900Q = 100\cos(\omega_f t)$$

$$L = 100$$

$$R = 500$$

$$\frac{1}{C} = 4900$$

$$100\ddot{Q} + 500\dot{Q} + 4900Q = 100\cos(\omega_f t)$$

4.6.14) $L = 4$ Henries $Q(0) = 0, \dot{Q}(0) = 0$

$$C = 0.01 \text{ Farads} \quad 1 = 0 \quad L\ddot{Q} + R\dot{Q} + \frac{1}{C}Q = f(t)$$

$$v(t) = 10\cos(4t) \quad 4\ddot{Q} + 100Q = 10\cos(4t)$$

$$t = 0, I = 0$$

$$y = y_h + y_p$$

$$y_h: 4r^2 + 100 = 0$$

$$4(r^2 + 25) = 0$$

$$r = \pm 5i$$

$$4(4)(100)$$

$$1600$$

$$y_h: e^{\alpha t}(c_1 \cos \beta t + c_2 \sin \beta t) \quad \alpha = 0, \beta = 5$$

$$y_h = c_1 \cos 5t + c_2 \sin 5t$$

$$\alpha = \frac{-b}{2a} \quad \alpha = 0$$

$$\beta = \frac{\sqrt{4ac - b^2}}{2a} \quad \beta = \frac{40}{2(4)} = 5$$

$$y = y_h + y_p$$

$$y = c_1 \cos 5t + c_2 \sin 5t + \frac{5}{18} \cos(4t) \quad c_1 = -\frac{5}{18}$$

$$0 = c_1 \cos(0) + c_2 \sin(0) + \frac{5}{18} \cos(0) \quad c_2 = 0$$

$$0 = c_1 + \frac{5}{18}$$

$$-\frac{5}{18} = c_1$$

$$y' = -5c_1 \sin(5t) + 5c_2 \cos(5t) - \frac{20}{18} \sin(4t)$$

$$0 = -5c_1 \sin(0) + 5c_2 \cos(0) - \frac{20}{18} \sin(0)$$

$$0 = 5c_2$$

$$0 = c_2$$

4.6.24) $m = 1 \text{ slug}$

$$K = 12 \text{ lb/ft}$$

$$f(t) = 16 \cos \omega t$$

$$m\ddot{x} + b\dot{x} + Kx = f(t)$$

$$\ddot{x} + 12x = 16 \cos(2\sqrt{3}t)$$

$$y(0) = 0$$

$$\dot{y}(0) = 0$$

$$y = y_h + y_p$$

$$y_h: \Delta = b^2 - 4ac$$

$$= 0^2 - 4(1)(12)$$

$$= -48$$

$$y_h = e^{\alpha t}(c_1 \cos \beta t + c_2 \sin \beta t)$$

$$\alpha = \frac{-b}{2a}$$

$$\alpha = 0$$

$$\beta = \frac{\sqrt{4ac - b^2}}{2ca}$$

$$\beta = 2\sqrt{3}$$

$$\beta = \frac{\sqrt{4(1)(12)}}{2(1)}$$

$$W = \sqrt{\frac{K}{m} - \frac{b^2}{2m^2}}$$

$$W = 2\sqrt{3}$$

$$y_h = c_1 \cos(2\sqrt{3}t) + c_2 \sin(2\sqrt{3}t)$$

$$y = c_1 \cos(2\sqrt{3}t) + c_2 \sin(2\sqrt{3}t) + \frac{4}{\sqrt{3}} t \sin(2\sqrt{3}t)$$

$$4\ddot{Q} + 100Q = 10\cos(4t)$$

$$y_p: y_p = A \cos(4t) + B \sin(4t) = 10 \cos(4t)$$

$$y_p' = -4A \sin(4t) + 4B \cos(4t)$$

$$y_p'' = -16A \cos(4t) - 16B \sin(4t)$$

$$y_p = \frac{5}{18} \cos(4t)$$

$$4(-16A \cos(4t) - 16B \sin(4t)) + 100(A \cos(4t) + B \sin(4t)) = 10 \cos(4t)$$

$$-64A \cos(4t) - 64B \sin(4t) + 100A \cos(4t) + 100B \sin(4t) = 10 \cos(4t)$$

$$36A \cos(4t) + 36B \sin(4t) = 10 \cos(4t)$$

$$36A = 10 \quad A = \frac{5}{18}$$

$$36B = 0 \quad B = 0$$

$$Q = -\frac{5}{18} \cos(5t) + \frac{5}{18} \cos(4t)$$

$$y_p: At \cos(2\sqrt{3}t) + Bt \sin(2\sqrt{3}t) = 16 \cos(2\sqrt{3}t)$$

$$y_p' = A(\cos(2\sqrt{3}t) - 2\sqrt{3}t \sin(2\sqrt{3}t)) + B(2\sqrt{3}t \cos(2\sqrt{3}t) + \sin(2\sqrt{3}t)) = 16 \cos(2\sqrt{3}t)$$

$$y_p'' = A(-2\sqrt{3} \sin(2\sqrt{3}t) - 12t \cos(2\sqrt{3}t) - 2\sqrt{3} \sin(2\sqrt{3}t)) + B(2\sqrt{3} \cos(2\sqrt{3}t) - 12t \sin(2\sqrt{3}t) + 2\sqrt{3} \cos(2\sqrt{3}t)) = 16 \cos(2\sqrt{3}t)$$

$$B(4\sqrt{3}) \cos(2\sqrt{3}t) = 16 \cos(2\sqrt{3}t)$$

$$y_p = \frac{4}{\sqrt{3}} t \sin(2\sqrt{3}t)$$

$$B = \frac{4}{\sqrt{3}}$$

$$y = c_1 \cos(2\sqrt{3}t) + c_2 \sin(2\sqrt{3}t) + \frac{4}{\sqrt{3}} t \sin(2\sqrt{3}t) \quad c_1 = 0$$

$$c_2 = 0$$

$$y = \frac{4}{\sqrt{3}} t \sin(2\sqrt{3}t)$$

$$0 = c_1 \cos(0) + c_2 \sin(0) + \frac{4}{\sqrt{3}}(0) \sin(0)$$

$$0 = c_1$$

$$y' = 2\sqrt{3} c_2 \cos(2\sqrt{3}t) + \frac{4}{\sqrt{3}} \sin(2\sqrt{3}t) + 8t \cos(2\sqrt{3}t)$$

$$0 = 2\sqrt{3} c_2 \cos(0) + \frac{4}{\sqrt{3}} \sin(0) + 8(0) \cos(0)$$

$$0 = c_2$$