

## 4.2 Orthogonal Vector Expansions

### Discrete and Inverse Discrete Transform Matrices

Let  $V$  be a vector of length  $n$  expanded in terms of  $n$  orthogonal vectors  $g_1, g_2, \dots, g_n$ , each of length  $n$

$$V = C_1 g_1 + C_2 g_2 + \dots + C_n g_n$$

$$C_k = \frac{\langle V, g_k \rangle}{\langle g_k, g_k \rangle}, \quad k=1, 2, \dots, n$$

The discrete transform matrix relative to  $g_1, g_2, \dots, g_n$  is the  $n \times n$  matrix  $H$

The  $k^{\text{th}}$  row consists of the orthonormalized vector  $h_k^T$

$$h_k = \frac{g_k}{\langle g_k, g_k \rangle}$$

$$\langle g_k, g_k \rangle = C, \quad k=1, 2, \dots, n,$$

For some constant  $C$ , then  $H$  has the form

$$H = \frac{1}{C} \begin{bmatrix} g_{11} & g_{12} & \dots & g_{1n} \\ g_{21} & g_{22} & \dots & g_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ g_{n1} & g_{n2} & \dots & g_{nn} \end{bmatrix}$$