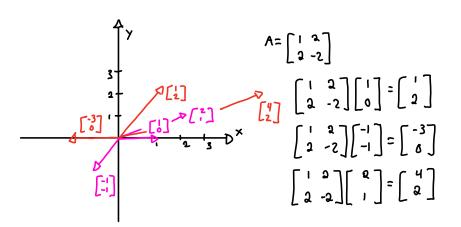
5.3 Eigenvalues and Eigenvectors 5.3 #6,8,20,72,74



Ex:
$$\int A\vec{v} = \lambda \vec{v}$$

 $A\vec{v} = \lambda \vec{l} \vec{v}$
 $A\vec{v} - \lambda \vec{l} \vec{v} = 0$
 $\vec{v}(A - \lambda \vec{l}) = 0$
 $A - \lambda \vec{l} = 0$ (Solve to find eigenvalues)
 $(A - \lambda \vec{l}) v_i = 0$ (To find eigenvector)

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 4 \end{bmatrix}$$

$$A - \lambda I = 0$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 4 \end{bmatrix} - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = 0$$

$$(1 - 2)(4 - 2)$$

$$4 - 52 + 2^{2}$$

$$\begin{bmatrix} 1 - 2 & 1 \\ 1 & 4 - 2 \end{bmatrix} = 0$$

$$(2^{2} - 52 + 4) - 1 = 0$$

$$2^{2} - 52 + 3 = 0$$

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 - \lambda & 1 & 1 \\ 0 & 1 - \lambda & 1 \\ 0 & 0 & 1 - \lambda \end{bmatrix} = (1 - \lambda)(1 - \lambda)^2 = 0$$

$$\lambda = \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \vec{v} = 0$$

$$\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$

Rotation (clockwise) by
$$O$$

$$\begin{vmatrix}
\cos -2 & -\sin O \\
\sin O & \cos -2
\end{vmatrix} = O$$

$$\begin{vmatrix}
\cos -2 & \cos -2 \\
\cos -2 & \cos -2
\end{vmatrix} = O$$

$$\begin{vmatrix}
\cos -2 & \cos -2 \\
\cos -2 & \cos -2
\end{vmatrix} = O$$

$$(\cos \theta - 2)^{2} = -\sin^{2}\theta$$

$$\cos \theta - 2 = \pm i \sin \theta + \cos \theta$$

$$R = \pm i \sin \theta + \cos \theta$$

Eigenvalue and Eigenvector

Let T: TV -D TV be a linear transformation from vector space TV into vector space TV. A scalar 2 is an eigenvalue of T if there is a nonzero vector vetv such that

Such a nonzero vector \vec{v} is called an eigenvector of T corresponding to λ .

If the linear transformation T is represented by an nxn matrix A, where $\nabla V = |R^N|$ and $\nabla U^{\dagger} = A(U^{\dagger})$ then \vec{V} and \vec{V} are represented by $A\vec{V} = 2\vec{V}$

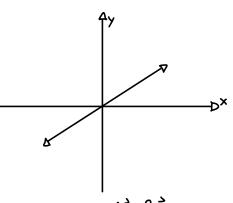
$$\begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \vec{v} = 0 \qquad \vec{V} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$

$$v_2 + v_3 = 0$$

$$v_3 = 0 \qquad \qquad \vec{e} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \text{Dim}(\vec{e}) = 1$$

$$v_1 = \text{Free variable}$$

$$4v$$



AX = 2×

$$(r^{2}-r-2)=0$$
 $y_{n}=c_{1}e^{r_{1}t}+c_{2}e^{r_{2}t}$ $x_{1}'=x_{2}$
 $(r-2)(r+1)=0$ $=c_{1}e^{-t}+c_{2}e^{at}$ $x_{2}'=\partial x_{1}+x_{2}$
 $r=-1,a$ $y_{n}=c_{1}e^{-t}+c_{2}e^{at}$

$$y'' - y' - 2y = 0$$
 $x_2 = x_1'$ $x_1' - x_2 - 2x_1 = 0$
 $x_2' - x_2 - x_1$

$$\dot{\vec{x}}' = A \dot{\vec{x}} \qquad \qquad \begin{aligned} x_1' &= x_2 \\ x_2' &= 2x_1 + x_2 \\ x_2' &= 2x_1 - x_2 \end{aligned}$$

Eigenvalues of A
$$\lambda = 0$$
 $\lambda = 0$ $\lambda =$