

PHYS 396 HOMEWORK SET 7 SOLUTIONS

for $ds^2 = a^2(d\theta^2 + \sin^2\theta d\varphi^2)$

$$g_{\theta\theta} = a^2$$

$$g_{\varphi\varphi} = a^2 \sin^2\theta$$

3) All possible combinations are...

$$\left[g_{\theta\theta}^{\delta}, g_{\theta\varphi}^{\delta}, g_{\varphi\theta}^{\delta}, g_{\varphi\varphi}^{\delta}, g_{\varphi\theta}^{\delta}, g_{\theta\varphi}^{\delta} \right]$$

1) Since $g_{\mu\nu} \Gamma_{\rho}^{\delta} = \frac{1}{2} \left(\frac{\partial g_{\mu\rho}}{\partial x^{\delta}} + \frac{\partial g_{\nu\rho}}{\partial x^{\mu}} - \frac{\partial g_{\rho\rho}}{\partial x^{\delta}} \right) \dots$

$$1) g_{\theta\theta} \Gamma_{\theta\theta}^{\delta} = \frac{1}{2} \left(\frac{\partial g_{\theta\theta}}{\partial \theta} + \frac{\partial g_{\theta\theta}}{\partial \theta} - \frac{\partial g_{\theta\theta}}{\partial \theta} \right) = \frac{1}{2} \frac{\partial}{\partial \theta} a^2 = 0$$

$$= g_{\theta\theta} \Gamma_{\theta\theta}^{\theta} \quad \therefore \left[\Gamma_{\theta\theta}^{\theta} = 0 \right]$$

$$2) g_{\theta\theta} \Gamma_{\theta\varphi}^{\delta} = \frac{1}{2} \left(\frac{\partial g_{\theta\theta}}{\partial \varphi} + \frac{\partial g_{\theta\varphi}}{\partial \theta} - \frac{\partial g_{\theta\varphi}}{\partial \theta} \right) = \frac{1}{2} \frac{\partial}{\partial \varphi} a^2 = 0$$

$$= g_{\theta\theta} \Gamma_{\theta\varphi}^{\theta} \quad \therefore \left[\Gamma_{\theta\varphi}^{\theta} = \Gamma_{\varphi\theta}^{\theta} = 0 \right]$$

$$3) g_{\varphi\theta} \Gamma_{\theta\theta}^{\delta} = \frac{1}{2} \left(\frac{\partial g_{\varphi\theta}}{\partial \theta} + \frac{\partial g_{\varphi\theta}}{\partial \theta} - \frac{\partial g_{\theta\theta}}{\partial \varphi} \right) = -\frac{1}{2} \frac{\partial}{\partial \varphi} a^2 = 0$$

$$= g_{\varphi\theta} \Gamma_{\theta\theta}^{\varphi} \quad \therefore \left[\Gamma_{\theta\theta}^{\varphi} = 0 \right]$$

$$4) g_{\theta\theta} \Gamma_{\varphi\varphi}^{\delta} = \frac{1}{2} \left(\frac{\partial g_{\theta\varphi}}{\partial \varphi} + \frac{\partial g_{\theta\varphi}}{\partial \varphi} - \frac{\partial g_{\varphi\varphi}}{\partial \theta} \right) = -\frac{1}{2} \frac{\partial}{\partial \theta} a^2 \sin^2\theta = -\frac{1}{2} \cdot 2a^2 \sin\theta \cos\theta = -a^2 \sin\theta \cos\theta$$

$$= g_{\theta\theta} \Gamma_{\varphi\varphi}^{\theta} = a^2 \Gamma_{\varphi\varphi}^{\theta} \quad \therefore \left[\Gamma_{\varphi\varphi}^{\theta} = -\sin\theta \cos\theta \right]$$

$$5) g_{\varphi\theta} \Gamma_{\varphi\theta}^{\delta} = \frac{1}{2} \left(\frac{\partial g_{\varphi\theta}}{\partial \theta} + \frac{\partial g_{\varphi\theta}}{\partial \varphi} - \frac{\partial g_{\varphi\theta}}{\partial \varphi} \right) = \frac{1}{2} \frac{\partial}{\partial \theta} a^2 \sin^2\theta = a^2 \sin\theta \cos\theta$$

$$= g_{\varphi\theta} \Gamma_{\varphi\theta}^{\varphi} = a^2 \sin^2\theta \Gamma_{\varphi\theta}^{\varphi} \quad \therefore \left[\Gamma_{\varphi\theta}^{\varphi} = \Gamma_{\theta\varphi}^{\varphi} = \frac{\cos\theta}{\sin\theta} \right]$$

$$6) g_{\varphi\varphi} \Gamma_{\varphi\varphi}^{\delta} = \frac{1}{2} \left(\frac{\partial g_{\varphi\varphi}}{\partial \varphi} + \frac{\partial g_{\varphi\varphi}}{\partial \varphi} - \frac{\partial g_{\varphi\varphi}}{\partial \varphi} \right) = \frac{1}{2} \frac{\partial}{\partial \varphi} a^2 \sin^2\theta = 0$$

$$= g_{\varphi\varphi} \Gamma_{\varphi\varphi}^{\varphi} \quad \therefore \left[\Gamma_{\varphi\varphi}^{\varphi} = 0 \right]$$

SO, IN SUMMARY, THE NON-ZERO CHRISTOFFEL SYMBOLS ARE...

$$\Gamma_{\phi\phi}^{\theta} = -\sin\theta \cos\theta$$

$$\Gamma_{\theta\phi}^{\phi} = \Gamma_{\phi\theta}^{\phi} = \frac{\cos\theta}{\sin\theta}$$

2. THE GEODESIC EQUATION IS OF THE FORM...

a)
$$\frac{d^2 x^\mu}{ds^2} = -\Gamma_{\rho\sigma}^\mu \frac{dx^\rho}{ds} \frac{dx^\sigma}{ds}$$

for A LINE ELEMENT OF THE FORM

$$ds^2 = \theta^2 (d\theta^2 + \sin^2 \theta d\varphi^2),$$

THE GEODESIC EQUATION HAS COMPONENTS OF THE FORM...

$$\frac{d^2 \theta}{ds^2} = -\Gamma_{\rho\sigma}^\theta \frac{dx^\rho}{ds} \frac{dx^\sigma}{ds} = -\Gamma_{\varphi\varphi}^\theta \frac{d\varphi}{ds} \frac{d\varphi}{ds} = \sin \theta \cos \theta \left(\frac{d\varphi}{ds} \right)^2$$

AND

$$\frac{d^2 \varphi}{ds^2} = -\Gamma_{\rho\sigma}^\varphi \frac{dx^\rho}{ds} \frac{dx^\sigma}{ds} = -\Gamma_{\theta\theta}^\varphi \frac{d\theta}{ds} \frac{d\theta}{ds} - \Gamma_{\varphi\varphi}^\varphi \frac{d\varphi}{ds} \frac{d\varphi}{ds} = -2 \frac{\cos \theta}{\sin \theta} \frac{d\theta}{ds} \frac{d\varphi}{ds}$$

SO IN SUMMARY...

$$\left[\begin{array}{l} \frac{d^2 \theta}{ds^2} = \sin \theta \cos \theta \left(\frac{d\varphi}{ds} \right)^2 \\ \frac{d^2 \varphi}{ds^2} = -2 \frac{\cos \theta}{\sin \theta} \frac{d\theta}{ds} \frac{d\varphi}{ds} \end{array} \right]$$

b) NOTICE THAT $\left[\varphi \rightarrow \varphi + \text{CONSTANT} \right]$ LEAVES THE LINE ELEMENT UNCHANGED AS $d\varphi \rightarrow d\varphi$; $ds^2 \rightarrow ds^2$

c) THE ASSOCIATED KILLING VECTOR IS

$$\left[\vec{S} = (\partial, 1) \right] \text{ SINCE } S^\theta = 0, S^\varphi = 1$$

d) $\ell \equiv \vec{S} \cdot \vec{u} = g_{AB} S^A u^B = g_{\varphi\varphi} S^\varphi u^\varphi = \theta^2 \sin^2 \theta \cdot 1 \cdot \frac{d\varphi}{ds}$

so

$$\left[\ell = \theta^2 \sin^2 \theta \frac{d\varphi}{ds} \right]$$

e) Equation (5) can be written as

$$\textcircled{1} = \frac{d^2\phi}{ds^2} + \frac{2\cos\theta}{\sin\theta} \frac{d\theta}{ds} \frac{d\phi}{ds} = \frac{1}{\sin^2\theta} \left[\sin^2\theta \frac{d^2\phi}{ds^2} + 2\sin\theta \cos\theta \frac{d\theta}{ds} \frac{d\phi}{ds} \right]$$

$$\text{But } \frac{d}{ds} \left(\sin^2\theta \frac{d\phi}{ds} \right) = \sin^2\theta \frac{d^2\phi}{ds^2} + 2\sin\theta \cos\theta \frac{d\theta}{ds} \frac{d\phi}{ds}$$

so

$$\textcircled{1} = \frac{1}{\sin^2\theta} \frac{d}{ds} \left(\sin^2\theta \frac{d\phi}{ds} \right) \quad \therefore \sin^2\theta \frac{d\phi}{ds} = \text{constant} = \frac{l}{a^2}$$

$$\therefore \left[l = a^2 \sin^2\theta \frac{d\phi}{ds} \right] \checkmark$$

3. $\vec{u} \cdot \vec{u} = 1$

a) so $\vec{u} \cdot \vec{u} = g_{AB} u^A u^B = g_{\theta\theta} (u^\theta)^2 + g_{\phi\phi} (u^\phi)^2$
 $= a^2 \left(\frac{d\theta}{ds} \right)^2 + a^2 \sin^2 \theta \left(\frac{d\phi}{ds} \right)^2 = 1$

(*) $\int_0^1 1 = a^2 \left[\left(\frac{d\theta}{ds} \right)^2 + \sin^2 \theta \left(\frac{d\phi}{ds} \right)^2 \right] ds$

b) Now $\frac{d\phi}{ds} = \frac{l}{a^2 \sin^2 \theta}$. Putting this into (*) yields..

$$1 = a^2 \left(\frac{d\theta}{ds} \right)^2 + a^2 \sin^2 \theta \cdot \frac{l^2}{a^4 \sin^4 \theta} = a^2 \left(\frac{d\theta}{ds} \right)^2 + \frac{l^2}{a^2 \sin^2 \theta}$$

Now solving for $\frac{d\theta}{ds} \dots$

$$a^2 \left(\frac{d\theta}{ds} \right)^2 = 1 - \frac{l^2}{a^2 \sin^2 \theta} = 1 - \frac{l^2}{a^2} \csc^2 \theta$$

Now taking a square root and solving for $\frac{d\theta}{ds} \dots$

$$\frac{d\theta}{ds} = \pm \left[1 - \frac{l^2}{a^2} \csc^2 \theta \right]^{1/2}$$

c) Now

(**) $\frac{d\theta}{d\phi} = \frac{d\theta/ds}{d\phi/ds}$ and $\frac{d\phi}{ds} = \frac{l}{a^2 \csc^2 \theta}$
 $\frac{d\theta}{d\phi} = \frac{\pm \left[1 - \frac{l^2}{a^2} \csc^2 \theta \right]^{1/2}}{\frac{l}{a^2 \csc^2 \theta}}$

Putting these into (**) yields...

$$\frac{d\theta}{d\phi} = \frac{\pm \left[1 - \frac{l^2}{a^2} \csc^2 \theta \right]^{1/2}}{\frac{l}{a^2 \csc^2 \theta}} = \frac{a^2}{l} \cdot \frac{\pm \left[1 - \frac{l^2}{a^2} \csc^2 \theta \right]^{1/2}}{\csc^2 \theta}$$

Now, separating variables...

$$\int \frac{l}{a^2} \frac{\csc^2 \theta d\theta}{\sqrt{1 - \frac{l^2}{a^2} \csc^2 \theta}} = \int d\phi \quad \text{so}$$

$$\varphi(\theta) = \frac{l}{a} \int \frac{\csc^2 \theta d\theta}{\sqrt{1 - \frac{l^2}{a^2} \csc^2 \theta}}$$

$$d) = \frac{l}{a} \int \frac{\csc^2 \theta d\theta}{\sqrt{1 - \frac{l^2}{a^2} - \frac{l^2}{a^2} (\csc^2 \theta - 1)}}$$

$$= \frac{l}{a} \int \frac{\csc^2 \theta d\theta}{\sqrt{(1 - l^2/a^2) - l^2/a^2 \cot^2 \theta}} = -\frac{l}{a} \int \frac{dx}{\sqrt{(1 - l^2/a^2) - \frac{l^2}{a^2} x^2}} = - \int \frac{dx}{\sqrt{(\frac{a^2}{l^2} - 1) - x^2}}$$

$$\text{let } x = \cot \theta \\ dx = -\csc^2 \theta d\theta$$

$$\text{let } k^2 = \frac{a^2}{l^2} - 1$$

$$= - \int \frac{dx}{\sqrt{k^2 - x^2}} = -k \int \frac{\cos \alpha d\alpha}{\sqrt{k^2(1 - \sin^2 \alpha)}} = - \int d\alpha = -\alpha + \phi_0 = -\sin^{-1}\left(\frac{x}{k}\right) + \phi_0$$

$$\text{let } x = k \sin \alpha \quad \therefore \alpha = \sin^{-1}\left(\frac{x}{k}\right)$$

$$\text{since } \cos^2 \alpha + \sin^2 \alpha = 1$$

$$dx = k \cos \alpha d\alpha$$

so

$$-(\varphi - \phi_0) = \sin^{-1}\left(\frac{x}{k}\right) \quad \text{or } x = k \sin^{-(\varphi - \phi_0)}$$

$$\frac{\cos \theta}{\sin \theta} = \cot \theta = k \sin(\phi_0 - \varphi) = \sqrt{\frac{a^2}{l^2} - 1} \sin(\phi_0 - \varphi)$$

NOW MULTIPLYING BOTH SIDES BY $\sin \theta$..

$$(*) \quad a \cos \theta = a \sqrt{\frac{a^2}{l^2} - 1} \sin(\phi_0 - \varphi) \sin \theta$$

$$= a \sqrt{\frac{a^2}{l^2} - 1} [\sin \phi_0 \cos \varphi - \sin \varphi \cos \phi_0] \sin \theta$$

$$= a \sqrt{\frac{a^2}{l^2} - 1} \sin \phi_0 (\sin \theta \cos \varphi) - a \sqrt{\frac{a^2}{l^2} - 1} \cos \phi_0 (\sin \varphi \sin \theta)$$

NOW

$$\text{let } \sqrt{\frac{a^2}{l^2} - 1} \sin \phi_0 = A$$

$$z = a \cos \theta$$

$$y = a \sin \theta \sin \varphi$$

$$x = a \sin \theta \cos \varphi$$

$$\sqrt{\frac{a^2}{l^2} - 1} \cos \phi_0 = B$$

$\therefore (*)$ becomes...

$$[z = Ax - By]$$

THIS IS THE EQUATION REPRESENTING A 2D PLANE SURFACE LOCATED AT THE CENTER OF A 3D AXZ A CYLINDER SURFACE.

4. THE LINE ELEMENT OF 3D FLAT SPACETIME IN POLAR COORDINATES IS..

$$ds^2 = -c^2 dt^2 + dr^2 + r^2 d\phi^2$$

$$\therefore g_{tt} = -c^2, g_{rr} = 1, g_{\phi\phi} = r^2$$

a) ALL POSSIBLE COMBINATIONS OF t, r, ϕ ARE..

$$g_{t\delta} \Gamma_{t\delta}^\delta, g_{t\delta} \Gamma_{t\delta}^\delta, g_{r\delta} \Gamma_{t\delta}^\delta, g_{t\delta} \Gamma_{r\delta}^\delta, g_{r\delta} \Gamma_{t\delta}^\delta, g_{r\delta} \Gamma_{r\delta}^\delta$$

NOW ALL POSSIBLE COMBINATIONS OF r, ϕ ARE...

$$g_{t\delta} \Gamma_{t\delta}^\delta : g_{t\delta} \Gamma_{t\delta}^\delta$$

$$g_{t\delta} \Gamma_{t\delta}^\delta : g_{t\delta} \Gamma_{t\delta}^\delta, g_{t\delta} \Gamma_{t\delta}^\delta$$

$$g_{r\delta} \Gamma_{t\delta}^\delta : g_{r\delta} \Gamma_{t\delta}^\delta, g_{r\delta} \Gamma_{t\delta}^\delta$$

$$g_{t\delta} \Gamma_{r\delta}^\delta : g_{t\delta} \Gamma_{r\delta}^\delta, g_{t\delta} \Gamma_{r\delta}^\delta, g_{t\delta} \Gamma_{r\delta}^\delta$$

$$g_{r\delta} \Gamma_{t\delta}^\delta : g_{r\delta} \Gamma_{t\delta}^\delta, g_{r\delta} \Gamma_{t\delta}^\delta, g_{r\delta} \Gamma_{t\delta}^\delta, g_{r\delta} \Gamma_{t\delta}^\delta$$

$$g_{r\delta} \Gamma_{r\delta}^\delta : g_{r\delta} \Gamma_{r\delta}^\delta, g_{r\delta} \Gamma_{r\delta}^\delta, g_{r\delta} \Gamma_{r\delta}^\delta, [g_{r\delta} \Gamma_{r\delta}^\delta], [g_{r\delta} \Gamma_{r\delta}^\delta], g_{r\delta} \Gamma_{r\delta}^\delta$$

\therefore 18 POSSIBLE COMBINATIONS

b) THE ONLY NONVANISHING DERIVATIVES OF THE METRIC TENSOR ARE...

$$\frac{\partial g_{\phi\phi}}{\partial r} \quad \text{WHICH COME FROM TWO ϕ 'S AND ONE r SO...}$$

$$g_{r\delta} \Gamma_{\phi\phi}^\delta = \frac{1}{2} \left(\frac{\partial g_{\phi\phi}}{\partial r} + \frac{\partial g_{\phi\phi}}{\partial r} - \frac{\partial g_{\phi\phi}}{\partial r} \right) = -\frac{1}{2} \frac{\partial}{\partial r} r^2 = -r = g_{rr} \Gamma_{\phi\phi}^r \therefore [\Gamma_{\phi\phi}^r = -r]$$

$$g_{\phi\delta} \Gamma_{r\phi}^\delta = \frac{1}{2} \left(\frac{\partial g_{r\phi}}{\partial \phi} + \frac{\partial g_{r\phi}}{\partial \phi} - \frac{\partial g_{r\phi}}{\partial \phi} \right) = \frac{1}{2} \frac{\partial}{\partial \phi} r^2 = r = g_{\phi\phi} \Gamma_{r\phi}^\phi = r^2 \Gamma_{r\phi}^\phi$$

$$\therefore [\Gamma_{r\phi}^\phi = \frac{1}{r}]$$

c) THE GEODESIC EQN

$$\frac{d^2 x^\alpha}{d\lambda^2} = -\Gamma_{\beta\gamma}^\alpha \frac{dx^\beta}{d\lambda} \frac{dx^\gamma}{d\lambda}$$

W. COMPONENTS...

for $\alpha = t \dots$

$$\frac{d^2 t}{d\lambda^2} = -\Gamma_{\beta\gamma}^t \frac{dx^\beta}{d\lambda} \frac{dx^\gamma}{d\lambda} = 0$$

AS AN $\Gamma_{\beta\gamma}^t = 0$ FOR ALL β, γ

for $\alpha = r \dots$

$$\frac{d^2 r}{d\lambda^2} = -\Gamma_{\beta\gamma}^r \frac{dx^\beta}{d\lambda} \frac{dx^\gamma}{d\lambda} = -\Gamma_{\phi\phi}^r \frac{d\phi}{d\lambda} \frac{d\phi}{d\lambda} = +r \left(\frac{d\phi}{d\lambda} \right)^2$$

for $\alpha = \phi \dots$

$$\frac{d^2 \phi}{d\lambda^2} = -\Gamma_{\beta\gamma}^\phi \frac{dx^\beta}{d\lambda} \frac{dx^\gamma}{d\lambda} = -\Gamma_{r\phi}^\phi \frac{dr}{d\lambda} \frac{d\phi}{d\lambda} - \Gamma_{\phi r}^\phi \frac{d\phi}{d\lambda} \frac{dr}{d\lambda} = -2\Gamma_{r\phi}^\phi \frac{dr}{d\lambda} \frac{d\phi}{d\lambda} = -\frac{2}{r} \frac{dr}{d\lambda} \frac{d\phi}{d\lambda}$$

SO IN SUMMARY...

$$\frac{d^2 t}{d\lambda^2} = 0$$

$$\frac{d^2 r}{d\lambda^2} = r \left(\frac{d\phi}{d\lambda} \right)^2$$

$$\frac{d^2 \phi}{d\lambda^2} = -\frac{2}{r} \frac{dr}{d\lambda} \frac{d\phi}{d\lambda} \quad \checkmark$$

d) SINCE $\underline{u} \cdot \underline{u} = 0$ FOR A NULL GEODESIC

$$\begin{aligned} 0 = \underline{u} \cdot \underline{u} &= g_{\alpha\beta} u^\alpha u^\beta = g_{tt} (u^t)^2 + g_{rr} (u^r)^2 + g_{\phi\phi} (u^\phi)^2 \\ &= -c^2 \left(\frac{dt}{d\lambda} \right)^2 + \left(\frac{dr}{d\lambda} \right)^2 + r^2 \left(\frac{d\phi}{d\lambda} \right)^2 \end{aligned}$$

e) SINCE $t \rightarrow t + \text{CONST.}$ LEAVES ds^2 UNCHANGED, THERE IS AN ASSOCIATED KILLING VECTOR: $\xi \equiv (\underline{1}, 0, 0)$

SINCE $\phi \rightarrow \phi + \text{CONST.}$ LEAVES ds^2 UNCHANGED, THERE IS AN ASSOCIATED KILLING VECTOR: $\eta = (0, 0, \underline{1})$

NOW

$$-E \equiv \underline{\xi} \cdot \underline{u} = g_{\alpha\beta} \xi^\alpha u^\beta = g_{tt} \xi^t u^t = -c^2 \frac{dt}{d\lambda}$$

$$\therefore \left[\frac{dt}{d\lambda} = \frac{E}{c^2} \right] \quad \text{WHICH IS EQUIVALENT TO} \quad \frac{d^2 t}{d\lambda^2} = 0$$

$$L \equiv \underline{\eta} \cdot \underline{u} = g_{\alpha\beta} \eta^\alpha u^\beta = g_{\phi\phi} \eta^\phi u^\phi = r^2 \frac{d\phi}{d\lambda}$$

$$\therefore \left[r^2 \frac{d\phi}{d\lambda} = L \right]$$

THIS IS EQUIVALENT TO (16)! TAKE A DERIVATIVE TO GET (17.)

5b) FROM THE PREVIOUS PROBLEM, $-E = \frac{g}{2} \cdot \frac{1}{r}$ YIELDS

$$\frac{dt}{d\lambda} = \frac{E}{c^2}$$

NOW, TAKING A λ DERIVATIVE...

$$\frac{d^2 t}{d\lambda^2} = 0 \quad \checkmark$$

also, $l = \eta \cdot u$ YIELDS $r^2 \frac{d\varphi}{d\lambda} = l$

TAKING A λ DERIVATIVE...

$$\frac{d}{d\lambda} \left(r^2 \frac{d\varphi}{d\lambda} \right) = r^2 \frac{d^2 \varphi}{d\lambda^2} + 2r \frac{dr}{d\lambda} \frac{d\varphi}{d\lambda} = r^2 \left[\frac{d^2 \varphi}{d\lambda^2} + \frac{2}{r} \frac{dr}{d\lambda} \frac{d\varphi}{d\lambda} \right] = 0 \quad \checkmark$$

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EQN (17) YIELDS:  $0 = -c^2 \left( \frac{dt}{d\lambda} \right)^2 + \left( \frac{dr}{d\lambda} \right)^2 + r^2 \left( \frac{d\varphi}{d\lambda} \right)^2$

EQN (18) YIELDS:  $\frac{dt}{d\lambda} = \frac{E}{c^2}$

EQN (19) YIELDS:  $\frac{d\varphi}{d\lambda} = \frac{l}{r^2}$

SUBSTITUTING (18) & (19) INTO (17)...

$$\begin{aligned} 0 &= -c^2 \cdot \frac{E^2}{c^4} + \left( \frac{dr}{d\lambda} \right)^2 + r^2 \cdot \frac{l^2}{r^4} \\ &= \left( \frac{dr}{d\lambda} \right)^2 - \frac{E^2}{c^2} + \frac{l^2}{r^2} \end{aligned}$$

NOW SOLVING FOR  $\frac{dr}{d\lambda}$  YIELDS...

$$\frac{dr}{d\lambda} = \left[ \frac{E^2}{c^2} - \frac{l^2}{r^2} \right]^{1/2} \quad \checkmark$$

c) SEPARATING VARIABLES YIELDS...

$$\int \frac{dr}{\left[ \frac{E^2}{c^2} - \frac{l^2}{r^2} \right]^{1/2}} = \int d\lambda \quad \text{as } \lambda(r) = \lambda_0 + \int \frac{r dr}{\left[ \frac{E^2}{c^2} r^2 - l^2 \right]^{1/2}}$$

NOW LET  $x = \frac{E^2}{c^2} r^2 - l^2$

$$dx = \frac{2E^2}{c^2} r dr \quad \therefore r dr = \frac{c^2}{2E^2} dx$$

so

$$\lambda(r) = \lambda_0 + \frac{c^2}{2e^2} \int \frac{dx}{x^{1/2}} = \lambda_0 + \frac{c^2}{e^2} x^{1/2} = \lambda_0 + \frac{c^2}{e^2} \left[ \frac{e^2}{c^2} r^2 - l^2 \right]^{1/2}$$

NOW SOLVING FOR  $r = r(\lambda) \dots$

$$\left[ \frac{e^2}{c^2} r^2 - l^2 \right]^{1/2} = \frac{c^2}{e^2} (\lambda - \lambda_0)$$

SQUARING

$$\frac{e^2}{c^2} r^2 - l^2 = \frac{c^4}{e^4} (\lambda - \lambda_0)^2$$

or

$$r^2 = \frac{c^2}{e^2} (\lambda - \lambda_0)^2 + \frac{c^2 l^2}{e^2} = \frac{c^2}{e^2} \left[ (\lambda - \lambda_0)^2 + \frac{c^4 l^2}{e^4} \right]$$

so

$$r(\lambda) = \frac{c}{e} \left[ (\lambda - \lambda_0)^2 + \frac{c^4 l^2}{e^4} \right]^{1/2}$$

d) EQN (19) YIELDS:  $\frac{d\varphi}{d\lambda} = \frac{l}{r^2}$ . NOW USING (\*)...

$$r^2 = \frac{c^2}{e^2} \left[ (\lambda - \lambda_0)^2 + \frac{c^4 l^2}{e^4} \right]$$

so

$$\frac{d\varphi}{d\lambda} = \frac{l}{\frac{c^2}{e^2} \left[ (\lambda - \lambda_0)^2 + \frac{c^4 l^2}{e^4} \right]}$$

so SOMEWHAT VALUABLES YIELDS..

$$\int d\varphi = \frac{lc^2}{e^2} \int \frac{d\lambda}{\left[ (\lambda - \lambda_0)^2 + \frac{c^4 l^2}{e^4} \right]} = K \int \frac{dx}{[x^2 + K^2]} = K \int \frac{K \sec^2 \theta d\theta}{K^2 (1 + \tan^2 \theta)} = \int d\theta$$

let  $x = \lambda - \lambda_0$   
 $dx = d\lambda$   
 $K \equiv \frac{lc^2}{e^2}$

let  $x = K \tan \theta$   
 $dx = K \sec^2 \theta d\theta$   
 $\theta = \tan^{-1} \left( \frac{x}{K} \right) = \tan^{-1} \left( \frac{\lambda - \lambda_0}{K} \right)$

or  $\sin^2 \theta + \cos^2 \theta = 1$   
 $\tan^2 \theta + 1 = \sec^2 \theta$

so

$$\varphi(\lambda) = \varphi_0 + \tan^{-1} \left( \frac{\lambda - \lambda_0}{K} \right) = \varphi_0 + \tan^{-1} \left( \frac{e^2}{lc^2} (\lambda - \lambda_0) \right)$$