Math 360 Ch 9.1-9.3: Vectors, Inner Products, Cross Products

Scalars are quantities that are determined by magnitude only. (Temperature, speed, etc.)

<u>Vectors</u> are quantities that are determined by magnitude and direction (Force, velocity, etc)

When graphing a vector, it can be convenient and useful to locate its initial point at the origin and its terminal point at a certain ordered pair (in R2) and ordered triple in R3, etc.

Example Consider the vector $\vec{v} = \vec{AB}$, where A=(1,1), B=(2,3).





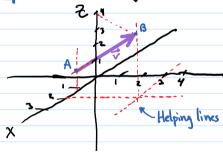
- In graph on left, we graph v by
first plotting A & B.

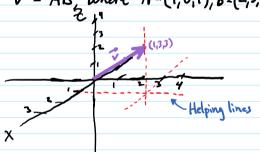
- In graph on right, we graph
the position vector for v, given by v = [2-1,3-1] = [1,2]

Note that the magnitude of i is given by 1 v 2 12+22 = 15

The unit vector is in the direction of i is given by $\vec{u} = \frac{\vec{v}}{|\vec{v}|} = \frac{1}{|\vec{v}|} [1,2] = [\frac{1}{|\vec{v}|}, \frac{2}{|\vec{v}|}] = \frac{1}{|\vec{v}|} [\frac{1}{|\vec{v}|} + \frac{2}{|\vec{v}|}]$

Example Let's try this in 123: " = AB, where A=(1,0,1), B=(2,3,4)





Graph of v found by connecting points A and B

Graph of v using position vector: v = [2-1,3-0,4-1] = [1,3,3]

Read: - Vector addition definition on page 357 for position vectors, and review triangle law for vector addition in Figure 170, for general vectors

- Also read Ex 2 in Ch 9.1, and review i, j, 7k vectors (unit coord vector)

DEFINITION

Fig. 170. Vector

The sum $\mathbf{a} + \mathbf{b}$ of two vectors $\mathbf{a} = [a_1, a_2, a_3]$ and $\mathbf{b} = [b_1, b_2, b_3]$ is obtained by adding the corresponding components,

(3)
$$\mathbf{a} + \mathbf{b} = [a_1 + b_1, a_2 + b_2, a_3 + b_3].$$

Geometrically, place the vectors as in Fig. 170 (the initial point of b at the terminal point of \mathbf{a}); then $\mathbf{a} + \mathbf{b}$ is the vector drawn from the initial point of \mathbf{a} to the terminal point of b.

Two ways of Multiplying Vectors

1) Inner Product a. b = |allilcost = a,b, + azbz + azbz

Properties:

1) a. T is scalar rathed

2) a.J., roughly speaking, measures how much of a is in direction of T

3) à d' measures amount of work done by force à in direction b (see p. 364)

adj side = |a| coso } projection of a onto I

- If $0 = \frac{\pi}{2}$ rads = 90°, then $\cos\theta = 0$ and $\vec{a} \cdot \vec{b} = 0$. In this case \vec{a} & \vec{b} are said to be orthogonal.

2) Cross Product $\vec{a} \times \vec{b} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a & a_1 & a_3 \\ b & b_2 & b_3 \end{vmatrix} = (a_1b_3 - b_2a_3)\vec{i} - (a_1b_3 - b_1a_3)\vec{j} + (a_1b_2 - b_1a_2)\vec{k} = \text{vector valued}$

Properties

- 1) | ax 6 | 2 | a | 16 | sin 6
- 2) ax 6 is orthogonal to a & 6
- 3) ax 6 is a normal vector to plane determined by a and 6.

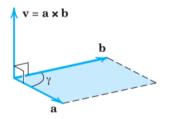


Fig. 185. Vector product

- 4) [a x 6] = aren of parallelogroum deturmined by a & 6
- S) Taxi yields moment vector whose direction is given by axis of rotation.

Read 1) Ex 1 on p. 370 gives example of cross product calculation.

- 2) Ex 3 m p371 gives example of moment of force
- 3) Ex 5 on p.372 discusses velocity of rotating body
- 4) Sealer Triple Broduct p.373 L. rohme of paralleligiped - see Ex 6 L. this gets used in Ch 10 derivations