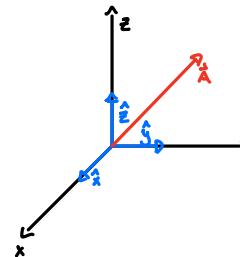


Ch.1 Vector AnalysisScalars

- Magnitude only
- Invariant under coordinate transformations

Vectors

- Direction and Magnitude
- Boldface in text, arrowed quantity in notes.
- Let $\hat{x}, \hat{y}, \hat{z}$ Be basis vector

Vector Space

Let \vec{A} be expanded in terms of these basis vectors....

$$\vec{A} = A_x \hat{x} + A_y \hat{y} + A_z \hat{z}$$

$\hookrightarrow A_x, A_y, A_z$ are components of \vec{A}

Four vector operations : Addition: Three kinds of Multiplication

i) Addition of two vectors

Geometrically : Tip to tail method

$$\begin{aligned} \text{Algebraically : } \vec{A} + \vec{B} &= (A_x \hat{x} + A_y \hat{y} + A_z \hat{z}) + (B_x \hat{x} + B_y \hat{y} + B_z \hat{z}) = (A_x + B_x) \hat{x} + (A_y + B_y) \hat{y} + (A_z + B_z) \hat{z} \\ &= (B_x + A_x) \hat{x} + (B_y + A_y) \hat{y} + (B_z + A_z) \hat{z} = \vec{B} + \vec{A} \end{aligned}$$

Notice:

$$\vec{A} - \vec{A} = \vec{0} = \vec{A} + (-\vec{A})$$

To Subtract a vector, Add opposite :

$$\vec{A} - \vec{B} = \vec{A} + (-\vec{B})$$

Note: vector addition is commutative

and associative

$$\vec{A} + (\vec{B} + \vec{C}) = (\vec{A} + \vec{B}) + \vec{C}$$

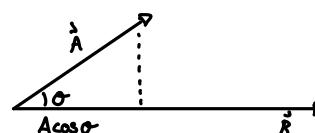
ii) Multiplication of a vector by a scalar :

$$\alpha \vec{A} = \alpha(A_x \hat{x} + A_y \hat{y} + A_z \hat{z}) = (\alpha A_x) \hat{x} + (\alpha A_y) \hat{y} + (\alpha A_z) \hat{z}$$

$$\alpha(\vec{A} + \vec{B}) = \alpha \vec{A} + \alpha \vec{B}$$

iii) Dot (Scalar) product of two vectors

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$



so....

$$\vec{A} \cdot \vec{B} = (A_x \hat{x} + A_y \hat{y} + A_z \hat{z}) \cdot (B_x \hat{x} + B_y \hat{y} + B_z \hat{z})$$

$$\hat{x} \cdot \hat{x} = 1 : \hat{y} \cdot \hat{y} = 1 : \hat{z} \cdot \hat{z} = 1$$

$$\hat{x} \cdot \hat{y} = 0 : \hat{x} \cdot \hat{z} = 0 \dots$$

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z \Rightarrow \text{To calculate the scalar product, multiply like components and add}$$

$$\vec{B} \cdot \vec{A} = B_x A_x + B_y A_y + B_z A_z \therefore \text{Dot product is commutative}$$

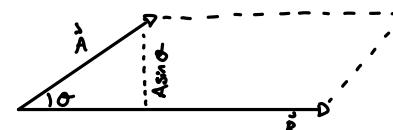
Notice:

$$\vec{A} \cdot \vec{A} = A_x^2 + A_y^2 + A_z^2 = A^2$$

iv) Cross Product (Vector Product) of Two vectors

$$\vec{A} \times \vec{B} = AB \sin \theta \hat{n} \quad \hat{n} - \text{unit vector Normal to } \vec{A} \& \vec{B} \text{ plane}$$

Direction given by RHR



Cross Product:

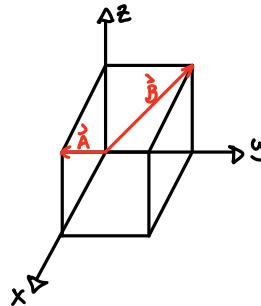
$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix} = \hat{x}(A_y B_z - A_z B_y) + \hat{y}(A_z B_x - A_x B_z) + \hat{z}(A_x B_y - A_y B_x)$$

$$\vec{A} \times \vec{B} = - \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ B_x & B_y & B_z \\ A_x & A_y & A_z \end{vmatrix} = - \vec{B} \times \vec{A} \quad \therefore \text{Cross Product is not commutative}$$

8-22-18

Geometrically: $|\vec{A} \times \vec{B}|$ is the area of the parallelogram generated by \vec{A}, \vec{B}
 $\vec{A} \times \vec{A} = 0$

i.e. Find the angle between the face diagonals of a unit cube.



$$\vec{A} = \hat{x} + \hat{z}$$

$$\vec{B} = \hat{y} + \hat{z}$$

$$\vec{A} \cdot \vec{B} = (\hat{x} + \hat{z}) \cdot (\hat{y} + \hat{z}) = 1$$

$$1 = AB \cos \theta$$

$$\vec{A} \cdot \vec{A} = A^2 = 2 \quad \therefore A = \sqrt{2}$$

$$\vec{B} \cdot \vec{B} = B^2 = 2 \quad \therefore B = \sqrt{2}$$

$$1 = \sqrt{2} \sqrt{2} \cos \theta$$

$$1 = 2 \cos \theta$$

$$\theta = \cos^{-1}(\frac{1}{2}) = 60^\circ$$

Scalar Triple Product

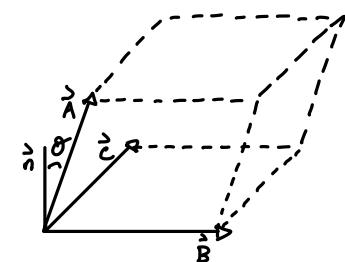
$$\vec{A} \cdot (\vec{B} \times \vec{C}) = (A_x \hat{x} + A_y \hat{y} + A_z \hat{z}) \cdot \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ B_x & B_y & B_z \\ C_x & C_y & C_z \end{vmatrix} = \begin{vmatrix} A_x & A_y & A_z \\ B_x & B_y & B_z \\ C_x & C_y & C_z \end{vmatrix} = A_x(B_y C_z - B_z C_y) + A_y(B_z C_x - B_x C_z) + A_z(B_x C_y - B_y C_x)$$

Geometrically: $|\vec{A} \cdot (\vec{B} \times \vec{C})|$ is the volume of the parallelepiped generated by $\vec{A}, \vec{B}, \vec{C}$
 $|\vec{B} \times \vec{C}|$ is the area of the base.

$$\text{Notice: } \vec{A} \cdot (\vec{B} \times \vec{C}) = \begin{vmatrix} A_x & A_y & A_z \\ B_x & B_y & B_z \\ C_x & C_y & C_z \end{vmatrix} = - \begin{vmatrix} A_x & A_y & A_z \\ C_x & C_y & C_z \\ B_x & B_y & B_z \end{vmatrix} = \begin{vmatrix} C_x & C_y & C_z \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

$$= \vec{C} \cdot (\vec{A} \times \vec{B}) = (\vec{A} \times \vec{B}) \cdot \vec{C}$$

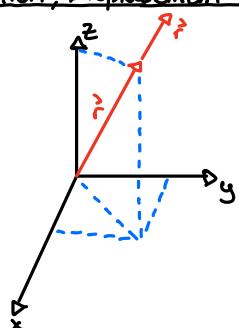
$$(\cdot, \cdot) \rightarrow D(x, \cdot)$$



Vector Triple Product

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B})$$

Position, Displacement: Separation Vectors



The position vector is
 $\vec{r} = x\hat{x} + y\hat{y} + z\hat{z}$ in 3D Cartesian coordinates

The magnitude is
 $r = (\vec{r} \cdot \vec{r})^{1/2} = [(x\hat{x} + y\hat{y} + z\hat{z}) \cdot (x\hat{x} + y\hat{y} + z\hat{z})]^{1/2}$
 $[r = \sqrt{x^2 + y^2 + z^2}]$

The radial unit vector.....

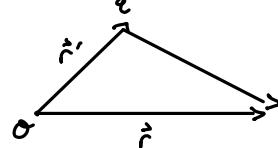
$$\hat{r} = \frac{\vec{r}}{|\vec{r}|} = \frac{x\hat{x} + y\hat{y} + z\hat{z}}{\sqrt{x^2 + y^2 + z^2}}$$

The infinitesimal displacement vector is ...

$$\delta \vec{l} = (\vec{r} + d\vec{r}) - \vec{r} = [(x + dx)\hat{x} + (y + dy)\hat{y} + (z + dz)\hat{z}] - [x\hat{x} + y\hat{y} + z\hat{z}]$$

$$\delta \vec{l} = dx\hat{x} + dy\hat{y} + dz\hat{z}$$

Imagine an Electric charge located at \vec{r}' : we wish to calculate the electric (or magnetic) field at \vec{r}



The Separation vector, \vec{r} , is...

$$[\vec{r} \equiv \vec{r} - \vec{r}']$$

$$\begin{aligned}\vec{r} &= (x\hat{x} + y\hat{y} + z\hat{z}) - (x'\hat{x} + y'\hat{y} + z'\hat{z}) \\ &= (x-x')\hat{x} + (y-y')\hat{y} + (z-z')\hat{z}\end{aligned}$$

Its magnitude is ...

$$r = (\vec{r} \cdot \vec{r})^{1/2} = [(x-x')^2 + (y-y')^2 + (z-z')^2]^{1/2}$$

The unit vector in the direction of \vec{r}

$$\hat{r} = \frac{\vec{r}}{r} = \frac{(x-x')\hat{x} + (y-y')\hat{y} + (z-z')\hat{z}}{\sqrt{(x-x')^2 + (y-y')^2 + (z-z')^2}}$$

8-24-18 Differential Calculus

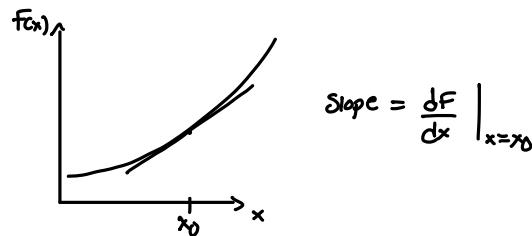
The derivative

Consider $f(x)$

Q: If we change x by a tiny amount, dx , how does $f(x)$ change.

A: $dF = \left(\frac{df}{dx}\right) dx$

Geometrically: $\frac{df}{dx}$ is the slope of the $f(x)$ vs. x curve



The gradient

Consider $T(x, y, z)$

Q: If we change x, y, z by a tiny amount, dx, dy, dz , how does $T(x, y, z)$ change?

A: $\begin{aligned}dT &= \left(\frac{\partial T}{\partial x}\right) dx + \left(\frac{\partial T}{\partial y}\right) dy + \left(\frac{\partial T}{\partial z}\right) dz \\ &= \left[\hat{x} \frac{\partial T}{\partial x} + \hat{y} \frac{\partial T}{\partial y} + \hat{z} \frac{\partial T}{\partial z}\right] \cdot [\hat{x} dx + \hat{y} dy + \hat{z} dz] \\ &= \vec{\nabla} T \cdot d\vec{l}\end{aligned}$

$\vec{\nabla} T$ is the gradient of T

Note: T is a scalar, $\vec{\nabla} T$ is a vector.

Now....

$$dT = |\vec{\nabla} T| |d\vec{l}| \cos \theta$$

Notice: For a fixed $|d\vec{l}|$, dT is a maximum when $\theta=0$

(since $\cos 0 = 1$)

$$(dT)_{\max} = |\vec{\nabla} T| |d\vec{l}| \text{ where } d\vec{l} = |d\vec{l}| \hat{d\vec{l}}$$

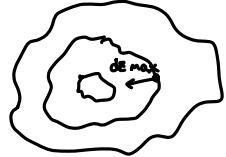
∴ The gradient points in the direction of maximum increase of the function T .

$|\vec{\nabla}T|$ gives the rate of increase along this maximum direction.
i.e. Contour Map

$Z(x,y)$

Now

$$dZ = \vec{\nabla}Z \cdot d\vec{l} = |\vec{\nabla}Z| dl \cos\theta$$



$$\vec{\nabla}Z = \hat{x}\hat{i} + \hat{y}\hat{j} + \hat{z}\hat{k}$$

- Stationary point

- Direction of steepest ascent is direction of $\vec{\nabla}Z$
- $|\vec{\nabla}Z|$ is the Slope of the steepest ascent
- When $\theta = 90^\circ$, $dZ = |\vec{\nabla}Z| dl \cos(90^\circ) = 0$
- \Rightarrow Contour lines \perp to $\vec{\nabla}Z$, Steepest Slope along contour lines.

The $\vec{\nabla}$ operator

The gradient of T is

$$\vec{\nabla}T = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right)$$

$\vec{\nabla}$ (Del) operator in cartesian coordinates

$\Rightarrow \nabla$ is w/out meaning until it operates on a function

\Rightarrow Vector Operator

Note:

$\vec{\nabla}$ Behaves like an ordinary vector, Simply replace "multiply" with "Act upon"

3 ways ∇ can act:

1. $\vec{\nabla}T$ - The gradient of a scalar function
2. $\vec{\nabla} \cdot \vec{V}$ - The divergence of a vector function
3. $\vec{\nabla} \times \vec{V}$ - The curl of a vector function

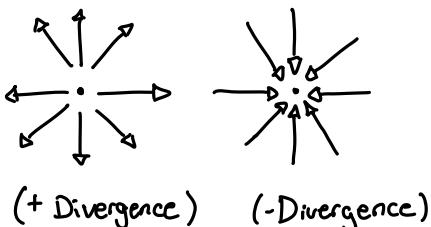
The Divergence

..... of a vector function \vec{V} is of the form

$$\vec{\nabla} \cdot \vec{V} = \left[\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right] \cdot \left[\hat{x}V_x + \hat{y}V_y + \hat{z}V_z \right]$$

$$\vec{\nabla} \cdot \vec{V} = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z} \quad \text{Note: } \vec{V} \text{ is a vector function}$$

Geometrical Interpretation: $\vec{\nabla} \cdot \vec{v}$ is a measure of how much the vector \vec{v} "spreads out" (Diverges) from the point in question



The curl

... of a vector function, \vec{v} , is of the form

$$\vec{\nabla} \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix} = \hat{x} \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) + \hat{y} \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) + \hat{z} \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right)$$

Geometrical Interpretation: $\vec{\nabla} \times \vec{v}$ is a measure of how much the vector \vec{v} "curls around" the point in question

Consider the scalar functions f, g

Consider a couple of vector functions \vec{A}, \vec{B}

$$\vec{\nabla}(f+g) = \vec{\nabla}f + \vec{\nabla}g$$

$$\vec{\nabla} \cdot (\vec{A} + \vec{B}) = (\vec{\nabla} \cdot \vec{A}) + (\vec{\nabla} \cdot \vec{B})$$

$$\vec{\nabla} \times (\vec{A} + \vec{B}) = (\vec{\nabla} \times \vec{A}) + (\vec{\nabla} \times \vec{B})$$

Also consider the constant K

$$\vec{\nabla}(Kf) = K\vec{\nabla}f$$

$$\vec{\nabla} \cdot (KA) = K(\vec{\nabla} \cdot \vec{A})$$

$$\vec{\nabla} \times (K\vec{A}) = K(\vec{\nabla} \times \vec{A})$$

8-27-18

Now, for the vector derivatives of a product. There are 6 product rules.

2 for Gradients

$$i) \vec{\nabla}(fg) = f\vec{\nabla}g + g\vec{\nabla}f$$

$$ii) \vec{\nabla} \cdot (\vec{A} \cdot \vec{B}) = \vec{A} \times (\vec{\nabla} \times \vec{B}) + \vec{B} \times (\vec{\nabla} \times \vec{A}) + (\vec{A} \cdot \vec{\nabla})\vec{B} + (\vec{B} \cdot \vec{\nabla})\vec{A}$$

2 for Divergences

$$iii) \vec{\nabla} \cdot (f\vec{A}) = f(\vec{\nabla} \cdot \vec{A}) + \vec{A} \cdot \vec{\nabla}f$$

$$iv) \vec{\nabla} \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\vec{\nabla} \times \vec{A}) - \vec{A} \cdot (\vec{\nabla} \times \vec{B})$$

2 for Curls

$$v) \vec{\nabla} \times (f\vec{A}) = f(\vec{\nabla} \times \vec{A}) - \vec{A} \times (\vec{\nabla} f)$$

$$vi) \vec{\nabla} \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \vec{\nabla})\vec{A} - (\vec{A} \cdot \vec{\nabla})\vec{B} + \vec{A}(\vec{\nabla} \cdot \vec{B}) - \vec{B}(\vec{\nabla} \cdot \vec{A})$$

Proof of ...

$$\begin{aligned} \vec{\nabla} \cdot (f\vec{A}) &= \left[\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right] \cdot \left[\hat{x} f A_x + \hat{y} f A_y + \hat{z} f A_z \right] = \frac{\partial}{\partial x}(f A_x) + \frac{\partial}{\partial y}(f A_y) + \frac{\partial}{\partial z}(f A_z) \\ &= A_x \frac{\partial f}{\partial x} + f \frac{\partial A_x}{\partial x} + A_y \frac{\partial f}{\partial y} + f \frac{\partial A_y}{\partial y} + A_z \frac{\partial f}{\partial z} + f \frac{\partial A_z}{\partial z} \\ &= (A_x \frac{\partial f}{\partial x} + A_y \frac{\partial f}{\partial y} + A_z \frac{\partial f}{\partial z}) + f \left(\frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} \right) = \vec{A} \cdot \vec{\nabla} f + f(\vec{\nabla} \cdot \vec{A}) \end{aligned}$$

Second Derivatives

1. $\vec{\nabla} T$ is a vector, so we have

(1) $\vec{\nabla} \cdot (\vec{\nabla} T)$ - The divergence of a gradient

(2) $\vec{\nabla} \times (\vec{\nabla} T)$ - The curl of a gradient

2. $\vec{\nabla} \cdot \vec{v}$ is a scalar, so we have

(3) $\vec{\nabla}(\vec{\nabla} \cdot \vec{v})$ - The gradient of the divergence.

3. $\vec{\nabla} \times \vec{v}$ is a vector, so we have

(4) $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{v})$ - The divergence of the curl

(5) $\vec{\nabla} \times (\vec{\nabla} \times \vec{v})$ - The curl of the curl

(1) The divergence of the gradient of T ...

$$\vec{\nabla} \cdot (\vec{\nabla} T) = \left[\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right] \cdot \left[\hat{x} \frac{\partial T}{\partial x} + \hat{y} \frac{\partial T}{\partial y} + \hat{z} \frac{\partial T}{\partial z} \right]$$

$$= \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \equiv \nabla^2 T - \text{The laplacian of } T$$

Note: $\nabla^2 T$ is a scalar

(2) The Laplacian of a Vector....

$$\nabla^2 \vec{v} \equiv \hat{x}(\nabla^2 v_x) + \hat{y}(\nabla^2 v_y) + \hat{z}(\nabla^2 v_z)$$

The curl of the gradient of T

One can show that..

$$\vec{\nabla} \times (\vec{\nabla} T) = 0 \text{ for any scalar function } T$$

(3) The Gradient of the Divergence

$$\vec{\nabla}(\vec{\nabla} \cdot \vec{v}) \neq \nabla^2 \vec{v}, \text{ is not equal to the laplacian of } \vec{v}$$

(4) The Divergence of the curl of \vec{v}

One can show that

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{v}) = 0 \text{ for any vector function } \vec{v}$$

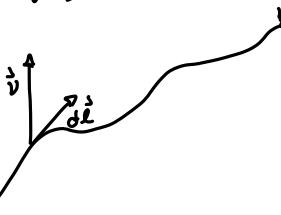
(5) The curl of the curl of \vec{v}

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{v}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{v}) - \nabla^2 \vec{v}$$

Integral Calculus

Line integrals of \vec{v}

$$\int_a^b \vec{v} \cdot d\vec{l} \Rightarrow$$



where

$$d\vec{l} = \hat{x} dx + \hat{y} dy + \hat{z} dz$$

$$\vec{v} = \hat{x} v_x + \hat{y} v_y + \hat{z} v_z$$

$$\int_a^b \vec{v} \cdot d\vec{l} = \int_a^b (v_x dx + v_y dy + v_z dz)$$

Normally the value of the line integral depends on the particular path taken. There is a special class of vector functions for which the line integral is independent of the path.

8-29-31

i.e #6

$$\vec{v} = y^2 \hat{x} + 2x(y+1) \hat{y}$$

$$\vec{a} = (1, 1, 0) : \vec{b} = (2, 2, 0)$$

$$d\vec{l} = \hat{x} dx + \hat{y} dy$$

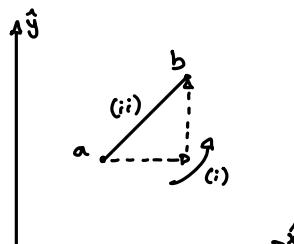
$$(ii) \int \vec{v} \cdot d\vec{l}$$

$$\vec{v} \cdot d\vec{l} = y^2 dx + 2x(y+1) dy$$

1st along path (i)

$$(i) \quad dy=0, y=1$$

$$\int_1^2 y^2 dx \Big|_{y=1} \int_1^2 dx = 1$$



$$(i) \quad dx=0, x=2$$

$$\int_1^2 2x(y+1) dy \Big|_{x=2} \int_1^2 4(y+1) dy = 4 \left(\frac{y^2}{2} + y \right) \Big|_1^2 = 10$$

$$\int_a^b \vec{v} \cdot d\vec{l} = 11$$

$$(i) + (ii) = 1 + 10 = 11$$

\int_a^b along path 2

(2) $x=y$, $dx=dy$

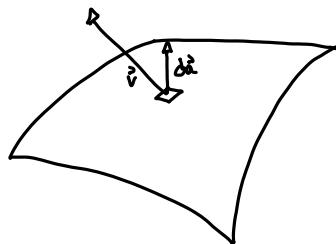
$$\int_a^b \vec{v} \cdot d\vec{l} = \int (y^2 dx + 2x(y+1) dy) \Big|_{\substack{x=y \\ dx=dy}} = \int_1^2 x^2 dx + 2x^2 + 2x dx = \int_1^2 3x^2 + 2x dx = \left. x^3 + x^2 \right|_1^2 = 12 - 2 = 10$$

Surface Integral

$$\int_S \vec{v} \cdot d\vec{a}$$

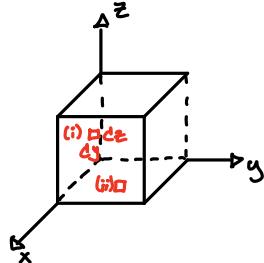
where $\vec{v} = v_x \hat{x} + v_y \hat{y} + v_z \hat{z}$

$d\vec{a}$ = infinitesimal patch of area, direction \perp to Surface



Note: The sign of $d\vec{a}$ is ambiguous. The convention is, if the surface is closed the outward normal is positive.

example $\vec{v} = 2xz \hat{x} + (x+2) \hat{y} + y(z^2-3) \hat{z}$



(i) $d\vec{a} = dy dz \hat{x}$

$$\vec{v} \cdot d\vec{a} = 2xz dy dz \Big|_{x=2} = 4z dy dz$$

$$(i) \int \vec{v} \cdot d\vec{a} = \int_0^2 \int_0^2 4z dy dz = 4y \Big|_0^2 \frac{z^2}{2} \Big|_0^2 = 4 \cdot 2 \cdot 2 = 16$$

(ii) $d\vec{a} = dx dy \hat{-z}$

$$\vec{v} \cdot d\vec{a} = \int_0^2 \int_0^2 -y(z^2-3) dx dy \Big|_{z=0} = \int_0^2 \int_0^2 -y(-3) dx dy = 3 \int_0^2 \int_0^2 y dx dy = 3 \cdot 2 \cdot 2 = 12$$

Volume Integral of T

$$\int_V T d\gamma \text{ where } T = T(x, y, z) \text{ is a scalar function}$$

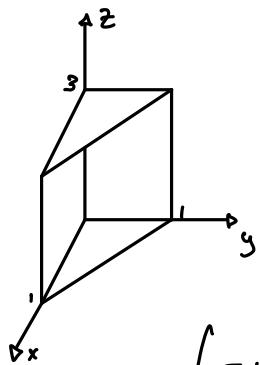
$d\gamma = dx dy dz$ is an infinitesimal volume element

Volume Integral of \vec{v}

$$\int_V \vec{v} d\gamma \text{ where } \vec{v} = v_x \hat{x} + v_y \hat{y} + v_z \hat{z} \text{ is a vector function}$$

$$= \int_V (V_x \hat{x} + V_y \hat{y} + V_z \hat{z}) dV = \hat{x} \int V_x dV + \hat{y} \int V_y dV + \hat{z} \int V_z dV$$

Ex 8 $T = xy z^2$, Volume integral of T over prism



$$\begin{aligned} \int_V T dV &= \iiint xyz^2 dx dy dz = \int_0^3 z^2 dz \int_0^1 y dy \int_0^{1-y} x dx \\ &= \int_0^3 z^2 dz \int_0^1 y dy \cdot \frac{x^2}{2} \Big|_0^{1-y} = \frac{9}{2} \int_0^1 y dy (1-y^2) \\ &= \frac{9}{2} \int_0^1 y (1-2y+y^2) dy = \frac{9}{2} \int_0^1 y^3 - 2y^2 + y dy \\ &= \frac{9}{2} \left(\frac{y^4}{4} - \frac{2}{3}y^3 + \frac{1}{2}y^2 \right) \Big|_0^1 = \frac{9}{2} \left(\frac{1}{4} - \frac{2}{3} + \frac{1}{2} \right) \\ &= \frac{9}{2} \left(\frac{3}{12} - \frac{8}{12} + \frac{6}{12} \right) = \frac{9}{2} \left(\frac{1}{12} \right) = \frac{9}{24} = \frac{3}{8} \end{aligned}$$

Fundamental Theorem of Calculus

$$\int_a^b F(x) dx = F(b) - F(a)$$

$$F(x) = \frac{dF}{dx}$$

so

$$\int_a^b \frac{dF}{dx} \cdot dx = \int_a^b dF = F \Big|_a^b = F(b) - F(a)$$

The integral of a derivative over an interval is given by the value of the function at the end points.

8-31-18

The Fundamental Theorem For Gradients

$$\int_a^b \vec{\nabla} T \cdot d\vec{l} = T(b) - T(a)$$

Proof: Recall from 1.2.2 gradients are
 $\vec{\nabla} T \cdot d\vec{l} = dT$

$$\text{so } \int_a^b \vec{\nabla} T \cdot d\vec{l} = \int_a^b dT = T \Big|_a^b = T(b) - T(a)$$

Notice: RHS has no reference to the path, only to the end points

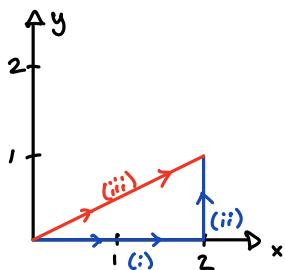
Corollary 1: $\int_a^b \vec{\nabla} T \cdot d\vec{l}$ is independent of the path From a to b

Corollary 2: $\oint \vec{\nabla} T \cdot d\vec{l} = 0$

i.e. $T(x,y) = xy^2$ check Fundamental theorem for gradients.

$$\vec{a} = [0, 0, 0]$$

$$\vec{b} = [2, 1, 0]$$



$$\vec{\nabla}T = \hat{x}\frac{\partial T}{\partial x} + \hat{y}\frac{\partial T}{\partial y}$$

$$\vec{\nabla}T = y^2\hat{x} + 2xy\hat{y} \quad \therefore \vec{\nabla}T \cdot d\vec{l} = y^2dx + 2xydy$$

$$d\vec{l} = dx\hat{x} + dy\hat{y}$$

Along path (i) ...

$$dy=0 : y=0$$

$$\int_0^2 y^2 dx = 0$$

Along path (ii) ...

$$dx=0 : x=2$$

$$(i) + (ii) = 2$$

$$\int_0^1 4y dy = 2y^2 \Big|_0^1 = 2(1)^2 - 2(0)^2 = 2$$

Along path (iii) ...

$$y = \frac{1}{2}x, \quad dy = \frac{1}{2}dx$$

$$\vec{\nabla}T \cdot d\vec{l} = y^2dx + 2xydy \quad y = \frac{1}{2}x$$

$$\vec{\nabla}T \cdot d\vec{l} = (\frac{1}{2}x)^2 dx + 2x(\frac{1}{2}x)(\frac{1}{2})dx = \frac{3}{4}x^2 dx$$

$$\frac{3}{4} \int_0^2 x^2 dx = \frac{3}{4} \cdot \frac{x^3}{3} \Big|_0^2 = 2$$

Now...

$$T(b) - T(a) : T(2,1,0) - T(0,0,0)$$

$$2 \cdot 1^2 - 0 = 2$$

The Divergence Theorem

$\left[\int_V (\vec{\nabla} \cdot \vec{v}) dV = \oint_S \vec{v} \cdot d\vec{a} \right] - \text{The integral of the divergence over a volume is equal to the value of the function at the surface.}$

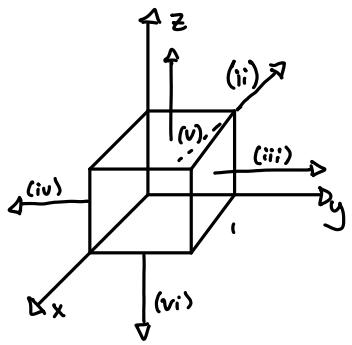
Geometrical interpretation:

Let \vec{v} be the flow of an incompressible fluid...

Then $\oint_S \vec{v} \cdot d\vec{a}$ is the flux (Total amount of fluid passing through a surface, per unit time)

$\int_V (\vec{v} \cdot \vec{v}) dV$ measures the spreading out of the fluid through the volume

$\therefore \int_V (\text{Faucets within the volume}) = \oint_S (\text{Flow out of the surface})$



$$\vec{v} = y^2 \hat{x} + (2xy + z^2) \hat{y} + (2yz) \hat{z}$$

$$\begin{aligned}\vec{\nabla} \cdot \vec{v} &= \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \\ &= \frac{\partial}{\partial x}(y^2) + \frac{\partial}{\partial y}(2xy + z^2) + \frac{\partial}{\partial z}(2yz) \\ &= 2x + 2y = 2(x+y)\end{aligned}$$

$$\int (\vec{\nabla} \cdot \vec{v}) d\vec{l} = \int_0^1 \int_0^1 \int_0^1 2(x+y) dx dy dz$$

$$\begin{aligned}2 \int_0^1 dz \int_0^1 dy \int_0^1 (x+y) dx &= 2 \int_0^1 dy \left(\frac{x^2}{2} + yx \right) \Big|_0^1 \\ &= 2 \int_0^1 dy \left(\frac{1}{2} + y \right) + 2 \left[\frac{1}{2}y \Big|_0^1 + \frac{y^2}{2} \Big|_0^1 \right] = 2 \left[\frac{1}{2} + \frac{1}{2} \right] = 2\end{aligned}$$

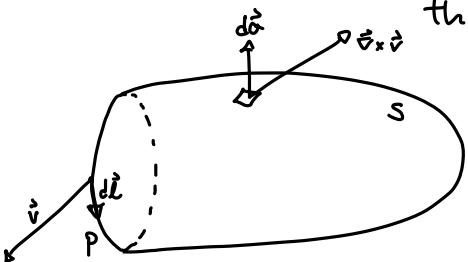
$$(i) : d\vec{a} = dy dz \hat{x}$$

$$\vec{v} \cdot d\vec{a} = y^2 dy dz \Big|_{x=1}$$

$$\int_{(i)} \vec{v} \cdot d\vec{a} = \int_0^1 \int_0^1 y^2 dy dz = \frac{y^3}{3} \Big|_0^1 \cdot 2 \Big|_0^1 = \frac{1}{3}$$

Stokes Theorem

$\left[\int_S (\vec{\nabla} \times \vec{v}) \cdot d\vec{a} = \oint_P \vec{v} \cdot d\vec{l} \right]$ - The integral of the curl over a surface (flux of curl) is equal to the value of the function at the perimeter. How much flow is following the boundary.



Geometrical interpretation:

$\int_S (\vec{\nabla} \times \vec{v}) \cdot d\vec{a}$ - The total amount of swirl

9-3-18

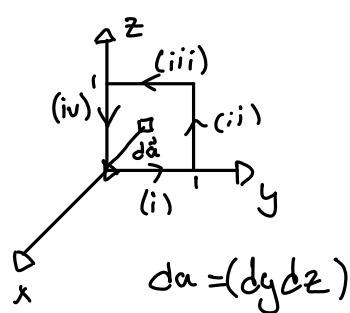
Corollary 1 :

$\int (\vec{\nabla} \times \vec{v}) \cdot d\vec{a}$ - Does not depend on the particular surface used.

Corollary 2:

$\oint (\vec{\nabla} \times \vec{v}) \cdot d\vec{a} = 0$ - For any closed surface

$$\text{i.e. } \vec{v} = (2xz + 3y^2)\hat{y} + (4yz^2)\hat{z}$$



$$\vec{\nabla} \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 2xz+3y^2 & 4yz^2 \end{vmatrix} = \hat{x} \left(\frac{\partial}{\partial y}(4yz^2) - \frac{\partial}{\partial z}(2xz+3y^2) \right) + \hat{y} \left(-\frac{\partial}{\partial x}(4yz^2) \right) + \hat{z} \left(\frac{\partial}{\partial x}(2xz+3y^2) \right) = (4z^2 - 2x)\hat{x} + (2z)\hat{z}$$

$$\int (\vec{\nabla} \times \vec{v}) \cdot d\vec{\alpha} = \int_0^1 \int_0^1 (4z^2 - 2x) \Big|_{x=0} dy dz = 4 \int_0^1 \int_0^1 z^2 dy dz$$

$$4 \cdot \frac{z^3}{3} \Big|_0^1 \cdot y \Big|_0^1 = \frac{4}{3}$$

$$\boxed{\frac{4}{3}}$$

$$\int_V \vec{v} \cdot d\vec{l} \quad d\vec{l} = dy \hat{y} : dx = dz = 0$$

$$\int V \cdot d\vec{l} = \int_0^1 2xz + 3y^2 dy \Big|_{x=0, z=0} = \int_0^1 3y^2 dy = y^3 \Big|_0^1 = 1$$

Integration By Parts

The product rule is

$$\frac{d}{dx}(fg) = f \frac{dg}{dx} + g \frac{df}{dx} \therefore \frac{f \frac{dg}{dx}}{dx} = \frac{d}{dx}(fg) - (g) \frac{df}{dx}$$

Multiplying both sides by dx : integrating from a to b yields

$$\int_a^b f \frac{dg}{dx} dx = \int_a^b \frac{d}{dx}(fg) dx - \int_a^b g \frac{df}{dx} dx = fg \Big|_a^b - \int_a^b g \frac{df}{dx} dx$$

Now, taking the divergence of a scalar function times a vector function

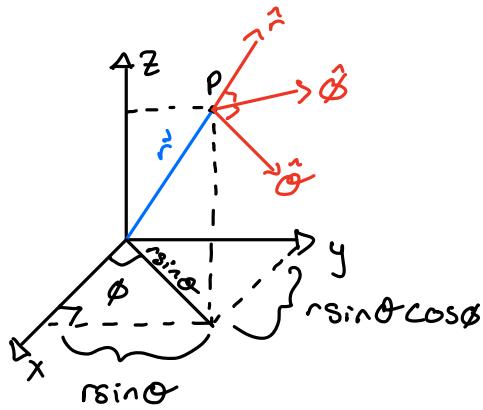
$$\vec{\nabla} \cdot (f \vec{A}) = f(\vec{\nabla} \cdot \vec{A}) + \vec{A} \cdot (\vec{\nabla} f) - P.R (5)$$

$$\therefore f(\vec{\nabla} \cdot \vec{A}) = \vec{\nabla} \cdot (f \vec{A}) - \vec{A} \cdot (\vec{\nabla} f)$$

Multiplying both sides by $d\gamma$ and integrating

$$\int_V f(\vec{\nabla} \cdot \vec{A}) \cdot d\gamma = \int_V \vec{\nabla} \cdot (f \vec{A}) d\gamma - \int_V \vec{A} \cdot (\vec{\nabla} f) d\gamma = \int_S f \vec{A} \cdot d\vec{\alpha} - \int_V \vec{A} \cdot (\vec{\nabla} f) d\gamma$$

Spherical Polar Coordinates



$$x = r \sin\theta \cos\phi$$

$$y = r \sin\theta \sin\phi$$

$$z = r \cos\theta$$

The 3 spherical polar unit vectors can be written in terms of $\hat{x}, \hat{y}, \hat{z}$, we have...

$$\hat{r} = \sin\theta \cos\phi \hat{x} + \sin\theta \sin\phi \hat{y} + \cos\theta \hat{z}$$

$$\hat{\theta} = \cos\theta \cos\phi \hat{x} + \cos\theta \sin\phi \hat{y} - \sin\theta \hat{z}$$

$$\hat{\phi} = -\sin\phi \hat{x} + \cos\phi \hat{y}$$

now, any vector can be written in terms of these unit vectors . . .

$$\vec{A} = A_r \hat{r} + A_\theta \hat{\theta} + A_\phi \hat{\phi}$$

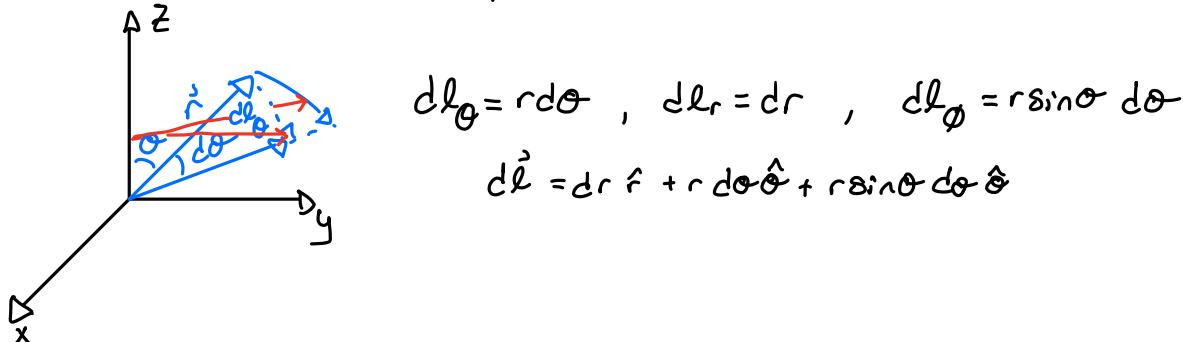
\Rightarrow Notice that $\hat{r}, \hat{\theta}, \hat{\phi}$ change directions as P moves so,

$$\hat{r} = \hat{r}(\theta, \phi)$$

$$\hat{\theta} = \hat{\theta}(\theta, \phi)$$

$$\hat{\phi} = \hat{\phi}(\theta, \phi)$$

now $d\vec{r} = dr \hat{r} + d\theta \hat{\theta} + d\phi \hat{\phi}$



The infinitesimal volume element becomes

$$dV = dr d\theta d\phi = dr \cdot r d\theta \cdot r \sin\theta d\phi$$

$$= r^2 \sin\theta \cdot dr d\theta d\phi$$

$$0 \leq r \leq \infty$$

$$0 \leq \theta \leq \pi$$

$$0 \leq \phi \leq 2\pi$$

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Spherical Polar Coordinates

$$\begin{aligned}\vec{dl} &= dr \hat{r} + r d\theta \hat{\theta} + r \sin\theta d\phi \hat{\phi} \\ \vec{v} &= v_r \hat{r} + v_\theta \hat{\theta} + v_\phi \hat{\phi} \\ dv &= r^2 \sin\theta dr d\theta d\phi\end{aligned}$$

i.e 1.13

$$\begin{aligned}V &= \int dv = \int_0^{2\pi} \int_0^R \int_0^\pi r^2 \sin\theta dr d\theta d\phi \\ &= \int_0^R r^2 dr \int_0^\pi \sin\theta d\theta \int_0^{2\pi} d\phi \\ &= \frac{r^3}{3} \left| \cos\theta \right|_0^\pi \left| \phi \right|_0^{2\pi} = \frac{R^3}{3} (2)(2\pi) = \frac{4}{3} \pi R^3\end{aligned}$$

The Gradient of some Scalar Function in cartesian coordinates

$$\vec{\nabla} T = \hat{x} \frac{\partial}{\partial x} T + \hat{y} \frac{\partial}{\partial y} T + \hat{z} \frac{\partial}{\partial z} T$$

The Gradient of some Scalar Function in Spherical polar coordinates

$$\vec{\nabla} T = \hat{r} \frac{\partial}{\partial r} T + \hat{\theta} \frac{1}{r} \frac{\partial}{\partial \theta} T + \hat{\phi} \frac{1}{r \sin\theta} \frac{\partial}{\partial \phi} T$$

The Divergence of \vec{v} is

$$\vec{\nabla} \cdot \vec{v} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} (\sin\theta v_\theta) + \frac{1}{r \sin\theta} \frac{\partial v_\phi}{\partial \phi}$$

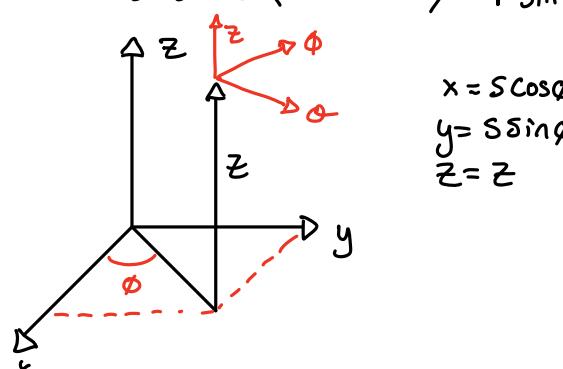
The Curl of \vec{v} is

$$\vec{\nabla} \times \vec{v} = \frac{1}{r \sin\theta} \left[\frac{\partial}{\partial \theta} (\sin\theta v_\phi) - \frac{\partial v_\theta}{\partial \phi} \right] \hat{r} + \frac{1}{r} \left[\frac{1}{\sin\theta} \frac{\partial v_r}{\partial \phi} - \frac{\partial}{\partial r} (r v_\phi) \right] \hat{\theta} + \frac{1}{r} \left[\frac{\partial}{\partial r} (r v_\theta) - \frac{\partial v_r}{\partial \theta} \right] \hat{\phi}$$

The Laplacian of T is . . .

$$\nabla^2 T = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial T}{\partial r} \right) + \frac{1}{r^2 \sin\theta} \frac{\partial}{\partial \theta} \left(\sin\theta \frac{\partial T}{\partial \theta} \right) + \frac{1}{r^2 \sin^2\theta} \frac{\partial^2 T}{\partial \phi^2}$$

Cylindrical Coordinates



$$\begin{aligned}x &= s \cos\phi \\ y &= s \sin\phi \\ z &= z\end{aligned}$$

The three cylindrical unit vectors in terms of the cartesian coordinates are,

$$\begin{aligned}\hat{s} &= \cos\phi \hat{x} + \sin\phi \hat{y} \\ \hat{\phi} &= -\sin\phi \hat{x} + \cos\phi \hat{y} \\ \hat{z} &= \hat{z}\end{aligned}$$

Now any vector can be written in terms of these unit vectors and these are of the form

$$\vec{A} = A_s \hat{s} + A_\phi \hat{\phi} + A_z \hat{z}$$

Notice that

$$\begin{aligned}\hat{s} &= \hat{s}(\phi) \\ \hat{\phi} &= \hat{\phi}(\phi)\end{aligned}$$

Now

$$d\vec{l} = dl_s \hat{s} + dl_\phi \hat{\phi} + dl_z \hat{z}$$

$$\begin{aligned}\text{where: } dl_s &= ds \\ dl_\phi &= s d\phi \\ dl_z &= dz\end{aligned}$$

so

$$d\vec{l} = ds \hat{s} + s d\phi \hat{\phi} + dz \hat{z}$$

The infinitesimal volume element is

$$dV = dl_s dl_\phi dl_z = ds \cdot s d\phi \cdot dz = s ds d\phi dz \quad \text{notice}$$

$$\begin{aligned}0 < s < \infty \\ 0 < \phi < 2\pi \\ -\infty < z < \infty\end{aligned}$$

The Gradient of some scalar function is

$$\vec{\nabla}T = \hat{s} \frac{\partial T}{\partial s} + \hat{\phi} \frac{1}{s} \frac{\partial T}{\partial \phi} + \hat{z} \frac{\partial T}{\partial z}$$

The Divergence is

$$\vec{\nabla} \cdot \vec{v} = \frac{1}{s} \frac{\partial}{\partial s} (s v_s) + \frac{1}{s} \frac{\partial v_\phi}{\partial \phi} + \frac{\partial v_z}{\partial z}$$

The Curl is

$$\vec{\nabla} \times \vec{v} = \left(\frac{1}{s} \frac{\partial}{\partial \phi} v_z - \frac{\partial}{\partial z} v_\phi \right) \hat{s} + \left(\frac{\partial v_s}{\partial z} - \frac{\partial v_z}{\partial s} \right) \hat{\phi} + \frac{1}{s} \left(\frac{\partial}{\partial s} (s v_\phi) - \frac{\partial v_s}{\partial \phi} \right) \hat{z}$$

The Laplacian is

$$\nabla^2 T = \frac{1}{s} \frac{\partial}{\partial s} \left(s \frac{\partial T}{\partial s} \right) + \frac{1}{s^2} \left(\frac{\partial^2}{\partial \phi^2} T \right) + \frac{\partial^2 T}{\partial z^2}$$

Potentials

Consider a vector field \vec{F} (representing \vec{E} & \vec{B})

say $\vec{\nabla} \times \vec{F} = 0$ then $\vec{F} = -\vec{\nabla} V$

\vec{F} can be written as minus the gradient of some scalar function.

Proof : let $\vec{F} = -\vec{\nabla} V$

then $\vec{\nabla} \times \vec{F} = -\vec{\nabla} \times \vec{\nabla} V = 0$

for any V - The curl of a gradient is always zero

Theorem 1 : Curl-less fields

\vec{F} satisfies iff it satisfies all the others

- a) $\vec{\nabla} \times \vec{F} = 0$
- b) $\int_a^b \vec{F} \cdot d\vec{l}$ is independent of path
- c) $\oint \vec{F} \cdot d\vec{l} = 0$
- d) $\vec{F} = -\vec{\nabla} V$

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If $\vec{\nabla} \times \vec{F} = 0$ then $\vec{F} = -\vec{\nabla} V$

notice

$$V \rightarrow V + C$$

then $\vec{F} = -\vec{\nabla} V \rightarrow -\vec{\nabla}(V+C) = -\vec{\nabla} V - \vec{\nabla} C = \vec{F}$ - Any constant can be added to the potential V without changing \vec{F}

IF $\vec{\nabla} \cdot \vec{F} = 0$, then $\vec{F} = \vec{\nabla} \times \vec{A}$ (\vec{F} can be written as the curl of a vector potential)

Proof : Let $\vec{F} = \vec{\nabla} \times \vec{A}$, then $\vec{\nabla} \cdot \vec{F} = \vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0$

Theorem 2 : Divergence-less fields

\vec{F} satisfies one iff it satisfies all the others

- a) $\vec{\nabla} \cdot \vec{F} = 0$
- b) $\int_S \vec{F} \cdot d\vec{a}$ is independent of the surface
- c) $\oint_S \vec{F} \cdot d\vec{a} = 0$
- d) $\vec{F} \times \vec{A}$

Notice : Let $\vec{A} \rightarrow \vec{A} + \vec{\nabla} \phi$

$$\text{then } \vec{F} = \vec{\nabla} \times \vec{A} \rightarrow \vec{\nabla} \times (\vec{A} + \vec{\nabla} \phi) \\ = \vec{\nabla} \times \vec{A} + \vec{\nabla} \times \vec{\nabla} \phi = \vec{\nabla} \times \vec{A} = \vec{F}$$

Any gradient of a scalar function can be added to \vec{A} without changing \vec{F}