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PHYS 342

HW1

Problem 1

$$\vec{A} = \hat{i} + 2\hat{j} - \hat{k}, \quad \vec{B} = -2\hat{i} + 3\hat{j} + \hat{k}$$

a.) $\vec{A} - \vec{B} \notin \{\vec{A}, \vec{B}\}$

$$\vec{A} - \vec{B} : (1+2)\hat{i} + (2-3)\hat{j} + (-1-1)\hat{k}$$

$$\vec{A} - \vec{B} = 3\hat{i} - \hat{j} - 2\hat{k}$$

$$|\vec{A} - \vec{B}| : \sqrt{3^2 + (-1)^2 + (-2)^2} = \sqrt{9+1+4} = \sqrt{14}$$

$$\vec{A} - \vec{B} = 3\hat{i} - \hat{j} - 2\hat{k}$$

$$|\vec{A} - \vec{B}| = \sqrt{14}$$

b.) $\text{Comp}_{\vec{A}} \vec{B} = \frac{\vec{B} \cdot \vec{A}}{|\vec{A}|}$

$$\vec{B} = -2\hat{i} + 3\hat{j} + \hat{k} \quad |\vec{A}| = \sqrt{6}$$

$$\vec{A} = \hat{i} + 2\hat{j} - \hat{k}$$

$$\vec{B} \cdot \vec{A} = -2(1) + 3(2) + 1(-1) = -2 + 6 - 1 = 3$$

$$\text{Comp}_{\vec{A}} \vec{B} = \frac{3}{\sqrt{6}}$$

c.) $\vec{A} \cdot \vec{B} = AB \cos \theta$

$$\vec{A} \cdot \vec{B} = 1(-2) + 2(3) - 1(1) = -2 + 6 - 1 = 3$$

$$|\vec{A}| = \sqrt{6}$$

$$|\vec{B}| = \sqrt{14}$$

$$3 = \sqrt{6} \cdot \sqrt{14} \cdot \cos \theta$$

$$3 = \sqrt{84} \cos \theta$$

$$3 = 2\sqrt{21} \cos \theta$$

$$\cos \theta = \frac{3}{2\sqrt{21}}$$

$$\theta = \cos^{-1}\left(\frac{3}{2\sqrt{21}}\right) = 70.9^\circ$$

$$\theta = 70.9^\circ$$

d.) $\vec{A} \times \vec{B}$

$$\vec{A} = \langle 1, 2, -1 \rangle$$

$$\vec{B} = \langle -2, 3, 1 \rangle$$

$$\vec{A} \times \vec{B} : \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 1 & 2 & -1 \\ -2 & 3 & 1 \end{vmatrix} = \langle 2(1) + (-3), -1(-2) - 1(1), 1(3) - 2(-2) \rangle \\ = \langle 5, 1, 7 \rangle$$

$$\vec{A} \times \vec{B} = \langle 5, 1, 7 \rangle$$

$$\vec{A} \times \vec{B} = 5\hat{i} + \hat{j} + 7\hat{k}$$

e.) $(\vec{A} - \vec{B}) \times (\vec{A} + \vec{B})$

$$(\vec{A} - \vec{B}) = 3\hat{i} - \hat{j} - 2\hat{k}$$

$$(\vec{A} + \vec{B}) = -\hat{i} + 5\hat{j} + 0\hat{k}$$

$$(\vec{A} - \vec{B}) \times (\vec{A} + \vec{B}) : \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 3 & -1 & -2 \\ -1 & 5 & 0 \end{vmatrix} = \langle -1(0) + 2(5), -2(-1) - 3(0), 3(5) + 1(-1) \rangle \\ = \langle 10, 2, 14 \rangle$$

$$(\vec{A} - \vec{B}) \times (\vec{A} + \vec{B}) = \langle 10, 2, 14 \rangle$$

$$(\vec{A} - \vec{B}) \times (\vec{A} + \vec{B}) = 10\hat{i} + 2\hat{j} + 14\hat{k}$$

Problem 2 $\vec{r} = 2b\sin(\omega t)\hat{i} + b\cos(\omega t)\hat{j}$

a.)

$$\frac{dr}{dt} = 2wb\cos(\omega t)\hat{i} - wb\sin(\omega t)\hat{j}$$

$$\frac{d^2r}{dt^2} = -2w^2b\sin(\omega t)\hat{i} - w^2b\cos(\omega t)\hat{j}$$

Speed is magnitude of velocity

$$|\vec{v}| = \sqrt{4w^2b^2\cos^2(\omega t) + w^2b^2\sin^2(\omega t)} \\ = \sqrt{w^2b^2(4\cos^2(\omega t) + \sin^2(\omega t))} \\ = \sqrt{w^2b^2(4\cos^2(\omega t) + 1 - \cos^2(\omega t))} \\ = \sqrt{w^2b^2(3\cos^2(\omega t) + 1)}$$

$$|\vec{v}| = wb\sqrt{3\cos^2(\omega t) + 1}$$

$$\cos^2(x) + \sin^2(x) = 1 \quad \therefore \quad \sin^2(x) = 1 - \cos^2(x)$$

$$\vec{v} = 2wb\cos(\omega t)\hat{i} - wb\sin(\omega t)\hat{j}$$

$$\vec{\alpha} = -2w^2b\sin(\omega t)\hat{i} - w^2b\cos(\omega t)\hat{j} \text{ or } -w^2\hat{j}$$

$$|\vec{v}| = wb\sqrt{3\cos^2(\omega t) + 1}$$

b.) $\vec{v} = 2wb\cos(\omega t)\hat{i} - wb\sin(\omega t)\hat{j}$
 $\vec{\alpha} = -2w^2b\sin(\omega t)\hat{i} - w^2b\cos(\omega t)\hat{j}$

$$t = \frac{\pi}{2}\omega$$

$$\vec{v}\left(\frac{\pi}{2}\omega\right) = 2wb\cos\left(\frac{\pi}{2}\right)\hat{i} - wb\sin\left(\frac{\pi}{2}\right)\hat{j} = 0\hat{i} - wb\hat{j}$$

$$\vec{\alpha}\left(\frac{\pi}{2}\omega\right) = -2w^2b\sin\left(\frac{\pi}{2}\right)\hat{i} - w^2b\cos\left(\frac{\pi}{2}\right)\hat{j} = -2w^2b\hat{i} + 0\hat{j}$$

$$\vec{v} \cdot \vec{\alpha} = 0\hat{i} \cdot (-2w^2b)\hat{i} - wb\hat{j} \cdot 0\hat{j} = 0 - 0 = 0$$

$$\vec{v} \cdot \vec{\alpha} = 0$$

$$\vec{v} \cdot \vec{\alpha} = |\vec{v}| \cdot |\vec{\alpha}| \cdot \cos(\theta)$$

$$|\vec{v}| = wb$$

$$|\vec{\alpha}| = 2w^2b$$

$$0 = (wb)(2w^2b)\cos(\theta)$$

$$0 = \cos(\theta)$$

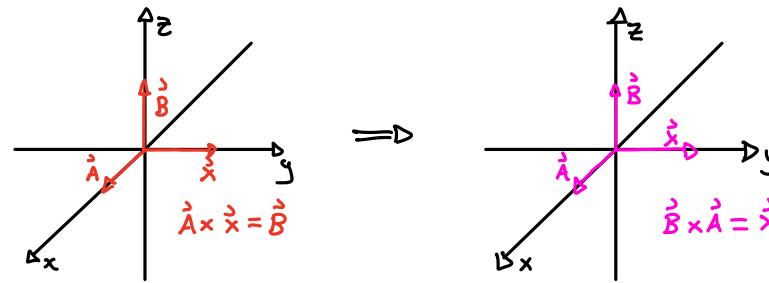
$$\theta = \cos^{-1}(0) = 90^\circ \notin 270^\circ$$

$$\theta = 90^\circ \text{ @ } t = \frac{\pi}{2}\omega$$

Problem 3

$$A \times \vec{x} = \vec{B} \quad A \cdot \vec{x} = \emptyset$$

$$\begin{aligned}\vec{A} &= A_x \hat{x} + A_y \hat{y} + A_z \hat{z} \\ \vec{B} &= B_x \hat{x} + B_y \hat{y} + B_z \hat{z}\end{aligned}$$



$$\vec{A} \times \vec{x} = \vec{B} \rightarrow \vec{x} = \vec{B} \times \vec{A}$$

$$A \times B = A \times A \times x$$

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 A B C

$$(A \cdot x)A - (A \cdot A)x = A \times B$$

$$\emptyset A - (A \cdot A)x = A \times B$$

$$\emptyset A - A \times B = (A \cdot A)x$$

$$x = \frac{\emptyset A - A \times B}{|A|^2}$$

$$X = \frac{\emptyset A - A \times B}{|A|^2}$$

Problem 4]

$$(a) \nabla r^n = nr^{(n-2)} \vec{r} \quad r = \sqrt{x^2 + y^2 + z^2} \\ r = (x^2 + y^2 + z^2)^{\frac{1}{2}} \Rightarrow r_n = (x^2 + y^2 + z^2)^{\frac{n-1}{2}}$$

$$\frac{\partial r}{\partial x} = \frac{n(x^2 + y^2 + z^2)^{\frac{n-1}{2}}}{2} \cdot 2x = x_n \cdot (x^2 + y^2 + z^2)^{\frac{n-1}{2}} \cdot (x^2 + y^2 + z^2)^{-1} = x_n \cdot r^{\frac{n-1}{2}} \cdot r^{-1}$$

$$\frac{\partial r}{\partial y} = \frac{n(x^2 + y^2 + z^2)^{\frac{n-1}{2}}}{2} \cdot 2y = y_n \cdot (x^2 + y^2 + z^2)^{\frac{n-1}{2}} \cdot (x^2 + y^2 + z^2)^{-1} = y_n \cdot r^{\frac{n-1}{2}} \cdot r^{-1}$$

$$\frac{\partial r}{\partial z} = \frac{n(x^2 + y^2 + z^2)^{\frac{n-1}{2}}}{2} \cdot 2z = z_n \cdot (x^2 + y^2 + z^2)^{\frac{n-1}{2}} \cdot (x^2 + y^2 + z^2)^{-1} = z_n \cdot r^{\frac{n-1}{2}} \cdot r^{-1}$$

$$\frac{\partial r}{\partial x} = n \cdot x r^{\frac{n-1}{2}} = n x r^{n-2}$$

$$\frac{\partial r}{\partial y} = n \cdot y r^{\frac{n-1}{2}} = n y r^{n-2}$$

$$\frac{\partial r}{\partial z} = n \cdot z r^{\frac{n-1}{2}} = n z r^{n-2}$$

$$\left. \begin{array}{l} \\ \\ \end{array} \right\} n r^{n-2} \cdot \vec{r} \quad \therefore$$

$$\nabla r^n = n r^{n-2} \vec{r}$$

$$(b) \nabla f(r) = \frac{\vec{r}}{r} \frac{df}{dr} \quad r = \sqrt{x^2 + y^2 + z^2}$$

$$\nabla f(r) = \frac{\partial f}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial f}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial f}{\partial r} \frac{\partial r}{\partial z} \quad \vec{r} = [\hat{x}, \hat{y}, \hat{z}]$$

$$\frac{\partial r}{\partial x} = \partial x \cdot \frac{1}{2} \cdot (x^2 + y^2 + z^2)^{-\frac{1}{2}} = \frac{x}{\sqrt{x^2 + y^2 + z^2}} = \frac{\hat{x}}{r}$$

$$\frac{\partial r}{\partial y} = \partial y \cdot \frac{1}{2} \cdot (x^2 + y^2 + z^2)^{-\frac{1}{2}} = \frac{y}{\sqrt{x^2 + y^2 + z^2}} = \frac{\hat{y}}{r}$$

$$\frac{\partial r}{\partial z} = \partial z \cdot \frac{1}{2} \cdot (x^2 + y^2 + z^2)^{-\frac{1}{2}} = \frac{z}{\sqrt{x^2 + y^2 + z^2}} = \frac{\hat{z}}{r}$$

$$\nabla f(r) = \frac{\partial f}{\partial r} \cdot \frac{\hat{x}}{r} + \frac{\partial f}{\partial r} \cdot \frac{\hat{y}}{r} + \frac{\partial f}{\partial r} \cdot \frac{\hat{z}}{r} = \frac{\vec{r}}{r} \frac{\partial f}{\partial r} \Rightarrow \frac{\vec{r}}{r} \frac{df}{dr}$$

$$\therefore \boxed{\nabla f(r) = \frac{\vec{r}}{r} \frac{df}{dr}}$$

$$(c) \nabla^2(\ln(r)) = \frac{1}{r^2} : r = \sqrt{x^2 + y^2 + z^2}, \nabla^2 = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

$$\frac{\partial^2 f}{\partial x^2} : \frac{\partial}{\partial x} (x^2 + y^2 + z^2)^{\frac{1}{2}} = \frac{x}{(x^2 + y^2 + z^2)^{\frac{1}{2}}} = \frac{x}{r}$$

$$\frac{\partial}{\partial x} \left[\frac{\partial}{\partial x} \ln(r) \right] = \frac{\partial}{\partial x} \left[\frac{\partial r}{\partial x} \frac{\partial \ln(r)}{\partial r} \right] = \frac{\partial}{\partial x} \left[\frac{\partial r}{\partial x} \frac{1}{r} \right]$$

$$r = (x^2 + y^2 + z^2)^{\frac{1}{2}}, r^{-2} = (x^2 + y^2 + z^2)^{-\frac{1}{2}} = ()^{-1}$$

$$\frac{\partial}{\partial x} \left[\frac{\partial r}{\partial x} \frac{1}{r} \right] = \frac{\partial}{\partial x} \left[\frac{x}{r} \cdot \frac{1}{r} \right] = \frac{\partial}{\partial x} \left[\frac{x}{r^2} \right] = \frac{1}{r^2}$$

$$\frac{\partial}{\partial x} \left[x (x^2 + y^2 + z^2)^{-1} \right] = \left[\frac{1}{r^2} - x \cdot 2x \cdot (x^2 + y^2 + z^2)^{-2} \right] = \frac{1}{r^2} - \frac{2x^2}{r^4}$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{1}{r^2} - \frac{2x^2}{r^4} : \frac{\partial^2 f}{\partial y^2} = \frac{1}{r^2} - \frac{2y^2}{r^4} : \frac{\partial^2 f}{\partial z^2} = \frac{1}{r^2} - \frac{2z^2}{r^4}$$

Same procedure for
y & z as x.

$$\begin{aligned} \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} &= \left(\frac{1}{r^2} - \frac{2x^2}{r^4} \right) + \left(\frac{1}{r^2} - \frac{2y^2}{r^4} \right) + \left(\frac{1}{r^2} - \frac{2z^2}{r^4} \right) \\ &= \frac{3}{r^2} - \frac{2(x^2 + y^2 + z^2)}{r^4} \quad (x^2 + y^2 + z^2) = r^2 \\ &= \frac{3}{r^2} - \frac{2r^2}{r^4} = \frac{3}{r^2} - \frac{2}{r^2} = \frac{1}{r^2} \end{aligned}$$

$\nabla^2(\ln(r)) = \frac{1}{r^2}$

Problem 5

a.) $\ddot{x} = m\ddot{x} = -Kx \quad K=4, m=1$
 $\ddot{x} = -4x$
 $\ddot{x} + 4x = 0 \quad ; \quad r^2 + 4$
 $\Delta = b^2 - 4ac = 0^2 - 4(1)(4) = -16$

$x(t) = C_1 \cos(2t) + C_2 \sin(2t)$

$x(t=0) = C_1 \cos(0) + C_2 \sin(0)$

$C_1 = 1$

$\dot{x}(t) = -2 \cdot C_1 \cdot \sin(2t) + 2 \cdot C_2 \cdot \cos(2t)$

$\dot{x}(t=0) = -2 \cdot C_1 \cdot \sin(0) + 2 \cdot C_2 \cdot \cos(0)$

$O = 2C_2$

$C_2 = 0$

The motion of mass is undamped so the oscillation doesn't change as time goes on. If friction were involved, the oscillation would slowly die down and eventually come to rest.

b.) $m\ddot{x} = -Kx - b\dot{x}$

$m\ddot{x} + b\dot{x} + Kx = 0$

$\uparrow \quad \uparrow \quad \uparrow$
a b c

$b^2 > 4mk$: Real Roots

$\Delta = b^2 - 4ac$
 $= b^2 - 4mk > 0 \quad \therefore x(t) = C_1 e^{r_1 t} + C_2 e^{r_2 t}$
 $r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = -\frac{b \pm \sqrt{b^2 - 4mk}}{2m}$
 $r_1 = \frac{-b + \sqrt{b^2 - 4mk}}{2m}, \quad r_2 = \frac{-b - \sqrt{b^2 - 4mk}}{2m}$

(i) $x(t) = C_1 e^{\frac{-b + \sqrt{b^2 - 4mk}}{2m} t} + C_2 e^{\frac{-b - \sqrt{b^2 - 4mk}}{2m} t}$

$b^2 < 4mk$: Imaginary roots

$\Delta = b^2 - 4ac$
 $\Delta = b^2 - 4mk < 0 \quad \therefore x(t) = e^{\alpha t} (C_1 \cos(\beta t) + C_2 \sin(\beta t))$
 $\alpha = \frac{-b}{2a} = \frac{-b}{2m}$
 $\beta = \frac{\sqrt{4ac - b^2}}{2a} = \frac{\sqrt{4mk - b^2}}{2m}$

(iii) $x(t) = e^{\frac{-b}{2m} t} (C_1 \cos(\frac{\sqrt{4mk - b^2}}{2m} t) + C_2 \sin(\frac{\sqrt{4mk - b^2}}{2m} t))$

$y_n = e^{\alpha t} (C_1 \cos(\beta t) + C_2 \sin(\beta t))$

$\alpha = \frac{-b}{2a} \quad \beta = \sqrt{\frac{4ac - b^2}{2a}}$

$a=1 \quad b=0 \quad c=4$

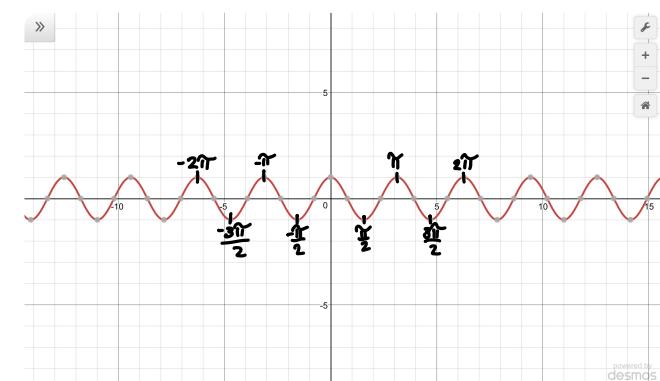
$\alpha=0 \quad \beta = \sqrt{\frac{4(4)-0}{2}} = \frac{4}{2} = 2$

$\beta=2$

$x(t) = C_1 \cos(2t) + C_2 \sin(2t)$

$C_1=1 \quad C_2=0$

$x(t) = \cos(2t)$



$b^2 = 4mk$: Repeated Roots

$\Delta = b^2 - 4ac$
 $\Delta = b^2 - 4mk = 0 \quad \therefore x(t) = C_1 e^{rt} + C_2 t e^{rt}$
 $r = \frac{-b}{2a} = \frac{-b}{2m}$

(ii) $x(t) = e^{\frac{-b}{2m} t} (C_1 + C_2 t)$

See next page for $C_1 = C_2$

if $C_1 = C_2$:

$$(i) \rightarrow x(t) = C \left(e^{\frac{-b + \sqrt{b^2 - 4mk}}{2m} t} + e^{\frac{-b - \sqrt{b^2 - 4mk}}{2m} t} \right)$$

$$(ii) \rightarrow x(t) = C e^{\frac{-b}{2m} t} (1 + t)$$

$$(iii) \rightarrow x(t) = C e^{\frac{-b}{2m} t} \left(\cos\left(\frac{\sqrt{4mk - b^2}}{2m} t\right) + \sin\left(\frac{\sqrt{4mk - b^2}}{2m} t\right) \right)$$

Problem 6

(a)

$$\int_0^1 \frac{1-e^x}{\sqrt{x}} dx$$

$$\sum_i^n \frac{f^{(n)}(x-a)^{(n)}}{n!} : f(x) = e^x @ a=0$$

$$f^{(0)} = 1$$

$$f'(x) = e^x : f'(0) = e^0 = 1$$

$$\sum_j = 1 + x + \frac{x^2}{2} + \frac{x^3}{6} + \frac{x^4}{24}$$

$$f''(x) = e^x : f''(0) = e^0 = 1$$

$$f'''(x) = e^x : f'''(0) = e^0 = 1$$

$$f''''(x) = e^x : f''''(0) = e^0 = 1$$

$$\int_0^1 \frac{1 - (1 + x + x^2/2 + x^3/6 + x^4/24)}{\sqrt{x}} dx$$

$$\int_0^1 \frac{-x - x^2/2 - x^3/6 - x^4/24}{\sqrt{x}} dx$$

$$\int_0^1 \frac{-x}{\sqrt{x}} - \frac{x^2}{2\sqrt{x}} - \frac{x^3}{6\sqrt{x}} - \frac{x^4}{24\sqrt{x}} dx = \int_0^1 -(x)^{1/2} - \frac{1}{2} \cdot (x)^{3/2} - \frac{1}{6} (x)^{5/2} - \frac{1}{24} (x)^{7/2} dx$$

$$[-\frac{2}{3}x^{3/2} - \frac{1}{5}x^{5/2} - \frac{1}{21}x^{7/2} - \frac{1}{108}x^{9/2}] \Big|_0^1$$

$$[-\frac{2}{3}(1) - \frac{1}{5}(1) - \frac{1}{21}(1) - \frac{1}{108}(1)] = -0.9235$$

Analytical result = -0.9235

The numerical results from MATLAB are on the next page. When the expansion of e^x is @ 0, the results yield a very accurate integral. It agrees very well with the numerical results in MATLAB.

Problem 7

$$f(x) = \ln(x+1) \quad f(x) = \ln(x)$$

$$\underline{f(x) = \ln(x+1)}$$

$$\sum_{n=0}^{\infty} \frac{f^{(n)}(x-a)^{(n)}}{n!} @ a=0 \quad f^{(0)} = \ln(1)$$

$$\frac{d}{dx} (x+1)^2 = 2(x+1)^1$$

$$f'(x) = \frac{1}{x+1} \quad f'(0) = 1$$

$$f''(x) = \frac{-1}{(x+1)^2} \quad f''(0) = -1$$

$$f'''(x) = \frac{2(x+1)}{(x+1)^4} = \frac{2}{(x+1)^3} \quad f'''(0) = 2$$

$$f(x) = \ln(x+1) = \sum_{n=1}^{\infty} \frac{f^{(n)}(x-a)^{(n)}}{n!} = \ln(1) + x - \frac{x^2}{2} + \frac{x^3}{3}$$

$$\underline{f(x) = \ln(x)}$$

$$\sum_{n=0}^{\infty} \frac{f^{(n)}(x-a)^{(n)}}{n!} @ a=0$$

$$f^{(0)} = \ln(0) \equiv \text{undefined}$$

$$f_x^{(0)} = \frac{1}{x} : f_x^{(0)} = \frac{1}{0} \equiv \text{undefined}$$

The function $\ln(x)$ cannot be represented by a series evaluated @ $x=0$ because all of the terms of the expansion are undefined.