



Program Optimization

These slides adapted from materials provided by the textbook authors.

Program Optimization

- Overview
- Generally Useful Optimizations
 - Code motion/precomputation
 - Strength reduction
 - Sharing of common subexpressions
 - Removing unnecessary procedure calls
- Optimization Blockers
 - Procedure calls
 - Memory aliasing
- Exploiting Instruction-Level Parallelism

Exploiting Instruction-Level Parallelism

- Need general understanding of modern processor design
 - Hardware can execute multiple instructions in parallel
- Performance limited by data dependencies
- Simple transformations can yield dramatic performance improvement
 - Compilers often cannot make these transformations
 - Lack of associativity and distributivity in floating-point arithmetic

Benchmark Computation

```
void combine1(vec_ptr v, data_t *dest)
{
    long int i;
    *dest = IDENT;
    for (i = 0; i < vec_length(v); i++) {
        data_t val;
        get_vec_element(v, i, &val);
        *dest = *dest OP val;
    }
}</pre>
```

Compute sum or product of vector elements

Data Types

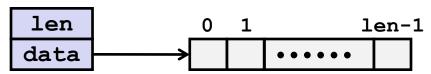
- Use different declarations for data t
- int
- long
- float.
- double

Operations

- Use different definitions of OP and IDENT
- + / 0
- * / 1

Benchmark Example: Data Type for Vectors

```
/* data structure for vectors */
typedef struct{
    size_t len;
    data_t *data;
} vec;
```



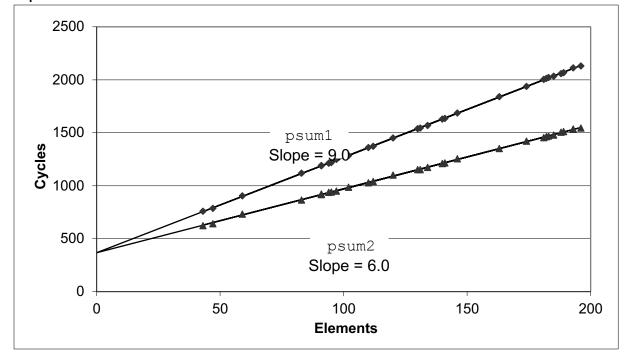
Data Types

- Use different declarations for data t
- int
- long
- float
- double

```
/* retrieve vector element
   and store at val */
int get_vec_element
   (*vec v, size_t idx, data_t *val)
{
   if (idx >= v->len)
      return 0;
   *val = v->data[idx];
   return 1;
}
```

Cycles Per Element (CPE)

- Convenient way to express performance of program that operates on vectors or lists
- Length = n
- In our case: CPE = cycles per OP
- T = CPE*n + Overhead
 - CPE is slope of line



Benchmark Performance

```
void combine1(vec_ptr v, data_t *dest)
{
    long int i;
    *dest = IDENT;
    for (i = 0; i < vec_length(v); i++) {
        data_t val;
        get_vec_element(v, i, &val);
        *dest = *dest OP val;
    }
}</pre>
```

Compute sum or product of vector elements

Method	Integer		Double FP	
Operation	Add	Mult	Add	Mult
Combine1 unoptimized	22.68	20.02	19.98	20.18
Combine1 -O1	10.12	10.12	10.17	11.14

Basic Optimizations

```
void combine4(vec_ptr v, data_t *dest)
{
  long i;
  long length = vec_length(v);
  data_t *d = get_vec_start(v);
  data_t t = IDENT;
  for (i = 0; i < length; i++)
     t = t OP d[i];
  *dest = t;
}</pre>
```

- Move vec_length out of loop
- Avoid bounds check on each cycle
- Accumulate in temporary

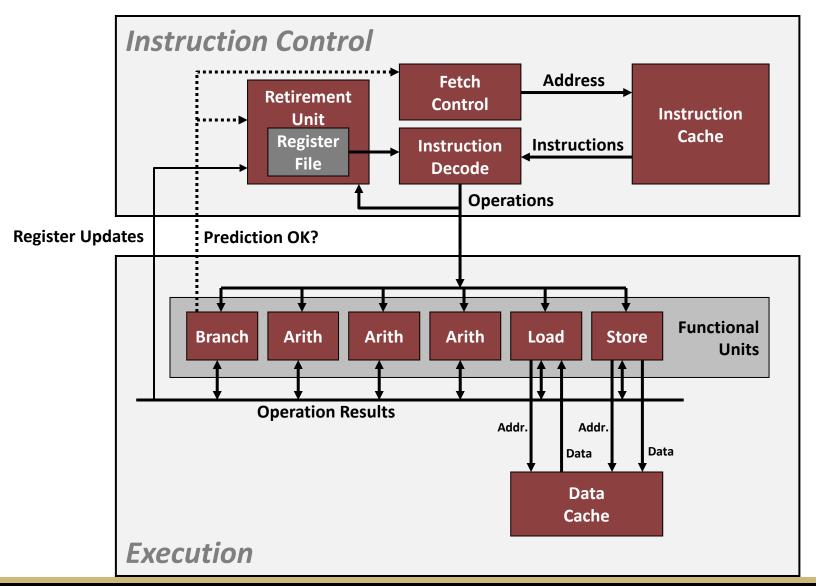
Effect of Basic Optimizations

```
void combine4(vec_ptr v, data_t *dest)
{
  long i;
  long length = vec_length(v);
  data_t *d = get_vec_start(v);
  data_t t = IDENT;
  for (i = 0; i < length; i++)
    t = t OP d[i];
  *dest = t;
}</pre>
```

Method	Inte	ger	Doub	le FP
Operation	Add Mult		Add	Mult
Combine1 -O1	10.12	10.12	10.17	11.14
Combine4	1.27	3.01	3.01	5.01

Eliminates sources of overhead in loop

Modern CPU Design

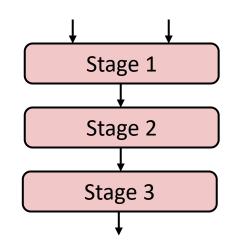


Superscalar Processor

- Definition: A superscalar processor can issue and execute multiple instructions in one cycle. The instructions are retrieved from a sequential instruction stream and are usually scheduled dynamically.
- Benefit: without programming effort, superscalar processor can take advantage of the instruction level parallelism that most programs have
- Most modern CPUs are superscalar.
- Intel: since Pentium (1993)

Pipelined Functional Units

```
long mult_eg(long a, long b, long c) {
    long p1 = a*b;
    long p2 = a*c;
    long p3 = p1 * p2;
    return p3;
}
```



	Time							
	1	2	3	4	5	6	7	
Stage 1	a*b	a*c			p1*p2			
Stage 2		a*b	a*c			p1*p2		
Stage 3			a*b	a*c			p1*p2	

- Divide computation into stages
- Pass partial computations from stage to stage
- Stage i can start on new computation once values passed to i+1
- E.g., complete 3 multiplications in 7 cycles, even though each requires 3 cycles

Haswell CPU

- 8 Total Functional Units
- Multiple instructions can execute in parallel
 - 2 load, with address computation
 - 1 store, with address computation
 - 4 integer
 - 2 FP multiply
 - 1 FP add
 - 1 FP divide

Some instructions take > 1 cycle, but can be pipelined

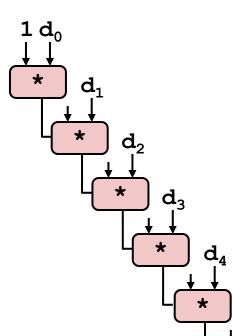
Instruction	Latency	Cycles/Issue
Load / Store	4	1
Integer Multiply	3	1
Integer/Long Divide	3-30	3-30
Single/Double FP Multiply	5	1
Single/Double FP Add	3	1
Single/Double FP Divide	3-15	3-15

x86-64 Compilation of Combine4

Inner Loop (Case: Integer Multiply)

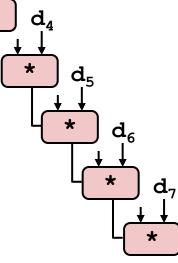
Method	Inte	ger	Double FP		
Operation	Add	Mult	Add	Mult	
Combine4	1.27	3.01	3.01	5.01	
Latency Bound	1.00	3.00	3.00	5.00	

Combine4 = Serial Computation (OP = *)



Computation (length=8)

- Sequential dependence
 - Performance: determined by latency of OP



Loop Unrolling (2x1)

```
void unroll2a combine(vec ptr v, data_t *dest)
{
    long length = vec length(v);
    long limit = length-1;
    data t *d = get vec start(v);
    data t x = IDENT;
    long i;
    /* Combine 2 elements at a time */
    for (i = 0; i < limit; i+=2) {
       x = (x OP d[i]) OP d[i+1];
    /* Finish any remaining elements */
    for (; i < length; i++) {
       x = x OP d[i];
    *dest = x;
```

Perform 2x more useful work per iteration

Effect of Loop Unrolling

Method	Integer		Double FP	
Operation	Add	Mult	Add	Mult
Combine4	1.27	3.01	3.01	5.01
Unroll 2x1	1.01	3.01	3.01	5.01
Latency Bound	1.00	3.00	3.00	5.00

Helps integer add

Achieves latency bound

$$x = (x OP d[i]) OP d[i+1];$$

- Others don't improve. Why?
 - Still sequential dependency

Loop Unrolling with Reassociation (2x1a)

```
void unroll2aa combine(vec ptr v, data t *dest)
{
    long length = vec length(v);
    long limit = length-1;
    data t *d = get vec start(v);
    data t x = IDENT;
    long i;
    /* Combine 2 elements at a time */
    for (i = 0; i < limit; i+=2) {
       x = x OP (d[i] OP d[i+1]);
    /* Finish any remaining elements */
    for (; i < length; i++) {
       x = x OP d[i];
                                  Compare to before
                                  x = (x OP d[i]) OP d[i+1];
    *dest = x;
```

- Can this change the result of the computation?
- Yes, for FP. Why?

Effect of Reassociation

Method	Integer		Double FP	
Operation	Add	Mult	Add	Mult
Combine4	1.27	3.01	3.01	5.01
Unroll 2x1	1.01	3.01	3.01	5.01
Unroll 2x1a	1.01	1.51	1.51	2.51
Latency Bound	1.00	3.00	3.00	5.00
Throughput Bound	0.50	1.00	1.00	0.50

Nearly 2x speedup for Int *, FP +, FP *

Reason: Breaks sequential dependency

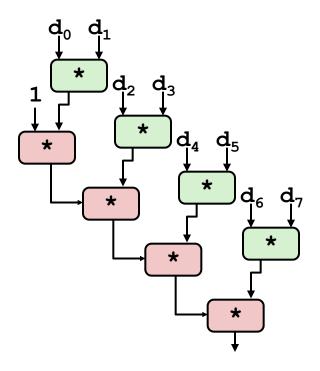
$$x = x OP (d[i] OP d[i+1]);$$

Why is that? (next slide)

4 func. units for int + 2 func. units for load

Reassociated Computation

$$x = x OP (d[i] OP d[i+1]);$$



What changed:

 Ops in the next iteration can be started early (no dependency)

Overall Performance

- N elements, D cycles latency/op
- (N/2+1)*D cycles:CPE = D/2

Loop Unrolling with Separate Accumulators

(2x2)

```
void unroll2a combine(vec ptr v, data_t *dest)
    long length = vec length(v);
    long limit = length-1;
    data t *d = get vec start(v);
    data t x0 = IDENT;
    data t x1 = IDENT;
    long i;
    /* Combine 2 elements at a time */
    for (i = 0; i < limit; i+=2) {
       x0 = x0 \text{ OP d[i]};
       x1 = x1 OP d[i+1];
    /* Finish any remaining elements */
    for (; i < length; i++) {
       x0 = x0 \text{ OP d[i]};
    *dest = x0 OP x1;
```

Different form of reassociation

Effect of Separate Accumulators

Method	Integer		Double FP	
Operation	Add	Mult	Add	Mult
Combine4	1.27	3.01	3.01	5.01
Unroll 2x1	1.01	3.01	3.01	5.01
Unroll 2x1a	1.01	1.51	1.51	2.51
Unroll 2x2	0.81	1.51	1.51	2.51
Latency Bound	1.00	3.00	3.00	5.00
Throughput Bound	0.50	1.00	1.00	0.50

Int + makes use of two load units

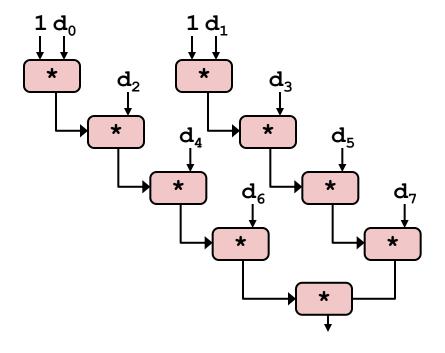
```
x0 = x0 OP d[i];
x1 = x1 OP d[i+1];
```

2x speedup (over unroll2) for Int *, FP +, FP *

Separate Accumulators

```
x0 = x0 \text{ OP d[i]};

x1 = x1 \text{ OP d[i+1]};
```



What changed:

Two independent "streams" of operations

Overall Performance

- N elements, D cycles latency/op
- Should be (N/2+1)*D cycles:
 CPE = D/2
- CPE matches prediction!

What Now?

Unrolling & Accumulating

Idea

- Can unroll to any degree L
- Can accumulate K results in parallel
- L must be multiple of K

Limitations

- Diminishing returns
 - Cannot go beyond throughput limitations of execution units
- Large overhead for short lengths
 - Finish off iterations sequentially

Accumulators

Unrolling & Accumulating: Double *

Case

- Intel Haswell
- Double FP Multiplication
- Latency bound: 5.00. Throughput bound: 0.50

FP *	Unrolling Factor L							
K	1	2	3	4	6	8	10	12
1	5.01	5.01	5.01	5.01	5.01	5.01	5.01	
2		2.51		2.51		2.51		
3			1.67					
4				1.25		1.26		
6					0.84			0.88
8						0.63		
10							0.51	
12								0.52

Accumulators

Unrolling & Accumulating: Int +

Case

- Intel Haswell
- Integer addition
- Latency bound: 1.00. Throughput bound: 0.50

FP *	Unrolling Factor L							
K	1	2	3	4	6	8	10	12
1	1.27	1.01	1.01	1.01	1.01	1.01	1.01	
2		0.81		0.69		0.54		
3			0.74					
4				0.69		1.24		
6					0.56			0.56
8						0.54		
10							0.54	
12								0.56

Achievable Performance

Method	Integer		Double FP	
Operation	Add	Mult	Add	Mult
Best	0.54	1.01	1.01	0.52
Latency Bound	1.00	3.00	3.00	5.00
Throughput Bound	0.50	1.00	1.00	0.50

- Limited only by throughput of functional units
- Up to 42X improvement over original, unoptimized code

Getting High Performance

- Good compiler and flags
- Watch out for hidden algorithmic inefficiencies
- Write compiler-friendly code
 - Watch out for optimization blockers: procedure calls & memory references
- Look carefully at innermost loops (where most work is done)