

Reasoning with Uncertainty



Bayes Net: Inference

Review: Active / Inactive Paths

- Question: Are X and Y conditionally independent given evidence variables {Z}?

- Yes, if X and Y “d-separated” by Z
- Consider all (undirected) paths from X to Y
- No active paths = independence!

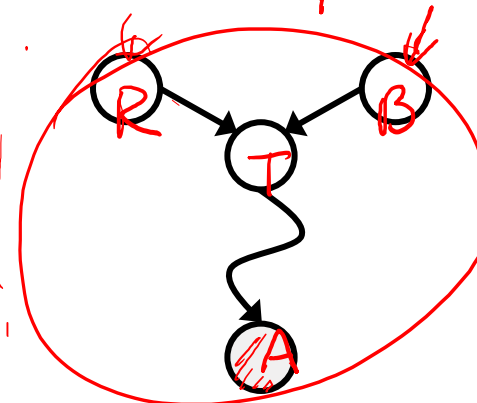
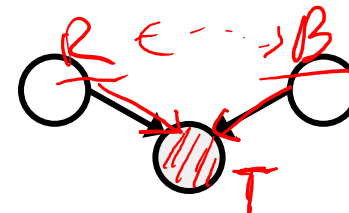
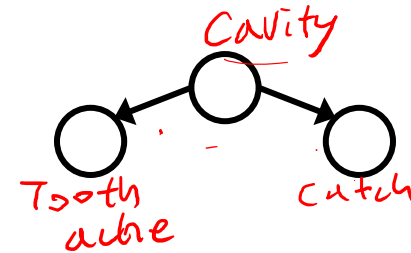
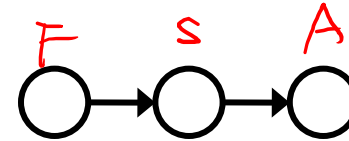
- A path is active if each triple is active:

- Causal chain $A \rightarrow B \rightarrow C$ where B is unobserved (either direction)
- Common cause $A \leftarrow B \rightarrow C$ where B is unobserved
- Common effect (aka v-structure)
 $A \rightarrow B \leftarrow C$ where B or one of its descendants is observed

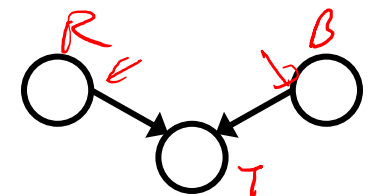
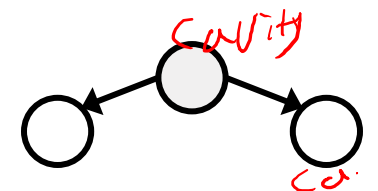
- All it takes to block a path is a single inactive segment

cond. indep

Active Triples



Inactive Triples



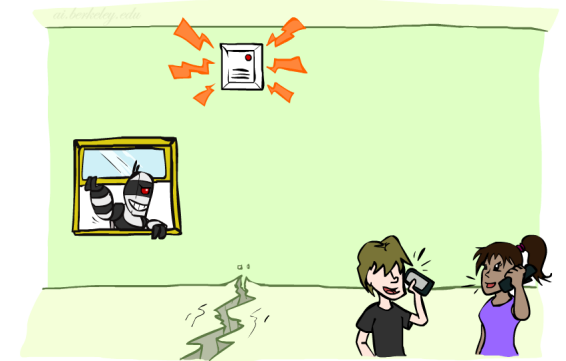
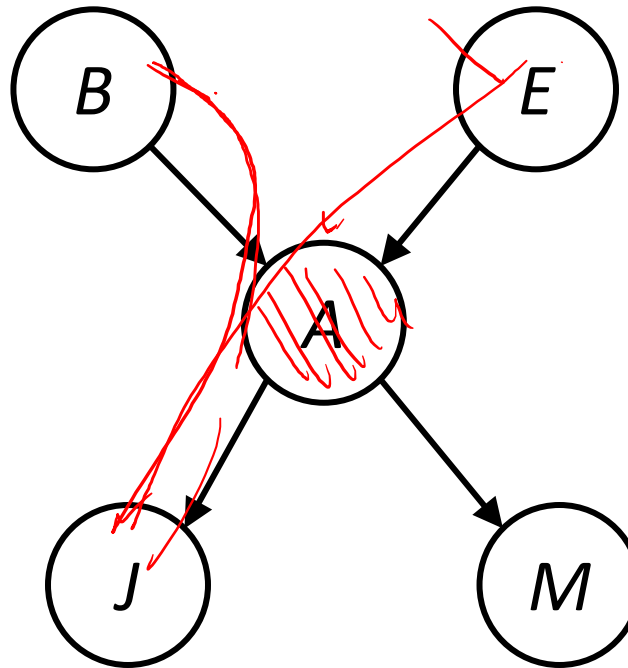
Review: Alarm Network

B	P(B)
+b	0.001
-b	0.999

E	P(E)
+e	0.002
-e	0.998

A	J	P(J A)
+a	+j	0.9
+a	-j	0.1
-a	+j	0.05
-a	-j	0.95

A	M	P(M A)
+a	+m	0.7
+a	-m	0.3
-a	+m	0.01
-a	-m	0.99



B	E	A	P(A B,E)
+b	+e	+a	0.95
+b	+e	-a	0.05
+b	-e	+a	0.94
+b	-e	-a	0.06
-b	+e	+a	0.29
-b	+e	-a	0.71
-b	-e	+a	0.001
-b	-e	-a	0.999

$$\begin{aligned}
 P(+b, -e, +a, -j, +m) &= P(+b) P(-e) P(+a|+b, -e) P(-j|+a) P(+m|+a) \\
 &= 0.001 \times 0.998 \times 0.94 \times 0.1 \times 0.7
 \end{aligned}$$

Handwritten red annotations above the equation:
 $P(+b)$
 $P(-e|+b)$
 $P(+a|b, e)$
 $a|+b$
 $b|e$

Inference

- Inference: calculating some useful quantity from a joint probability distribution

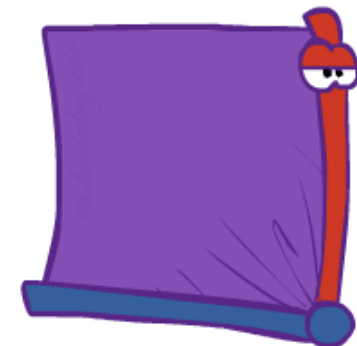
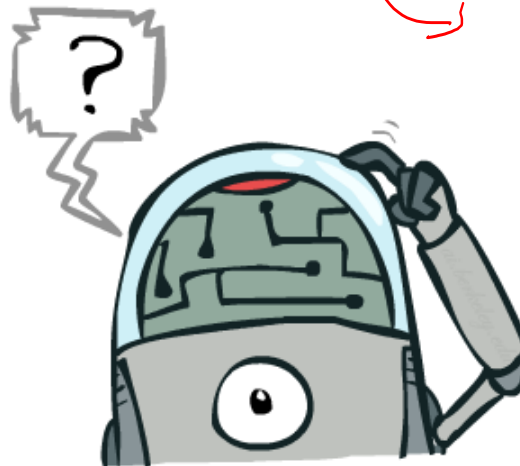
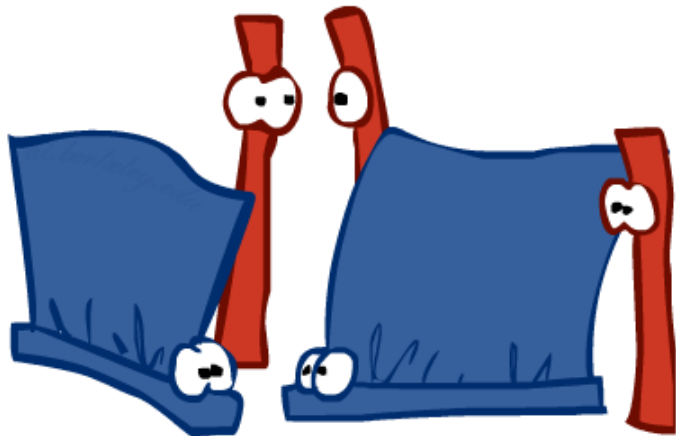
- Examples:

- Posterior probability

$$P(Q|E_1 = e_1, \dots, E_k = e_k)$$

- Most likely explanation:

$$\operatorname{argmax}_q P(Q = q | E_1 = e_1 \dots)$$



Inference by Enumeration \Rightarrow JPT : tabular method

- General case:

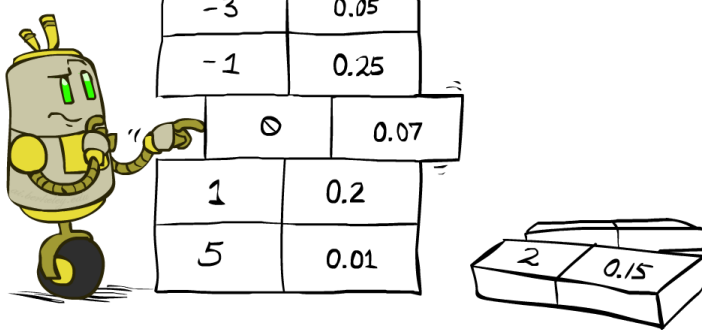
- Evidence variables: $E_1 \dots E_k = e_1 \dots e_k$
 - Query* variable: Q
 - Hidden variables: $H_1 \dots H_r$
- $\left. \begin{array}{l} E_1 \dots E_k = e_1 \dots e_k \\ Q \\ H_1 \dots H_r \end{array} \right\} \begin{array}{l} \{X_1, X_2, \dots, X_n\} \\ \text{All variables} \end{array}$

- We want:

* Works fine with multiple query variables, too

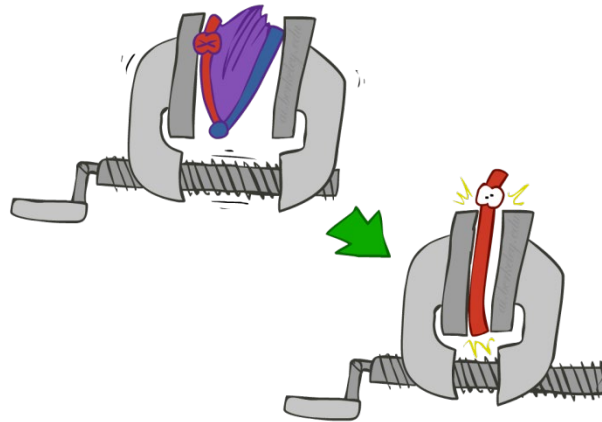
$$\underline{P(Q|e_1 \dots e_k)}$$

- Step 1: Select the entries consistent with the evidence

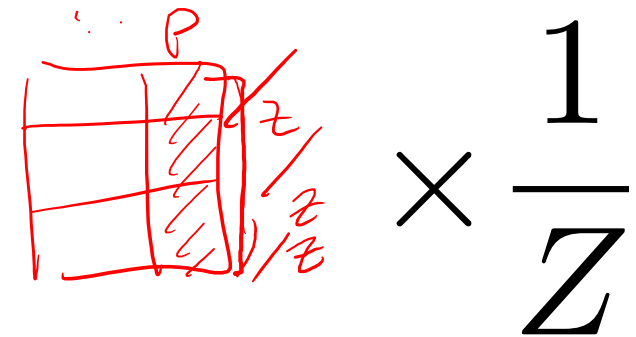


x	P(x)
-3	0.05
-1	0.25
0	0.07
1	0.2
5	0.01

- Step 2: Sum out H to get joint of Query and evidence



- Step 3: Normalize



$$\times \frac{1}{Z}$$

$$P(Q, e_1 \dots e_k) = \sum_{\underline{h_1 \dots h_r}} \underbrace{P(Q, h_1 \dots h_r, e_1 \dots e_k)}_{X_1, X_2, \dots, X_n}$$

$$Z = \sum_q P(Q, e_1 \dots e_k)$$

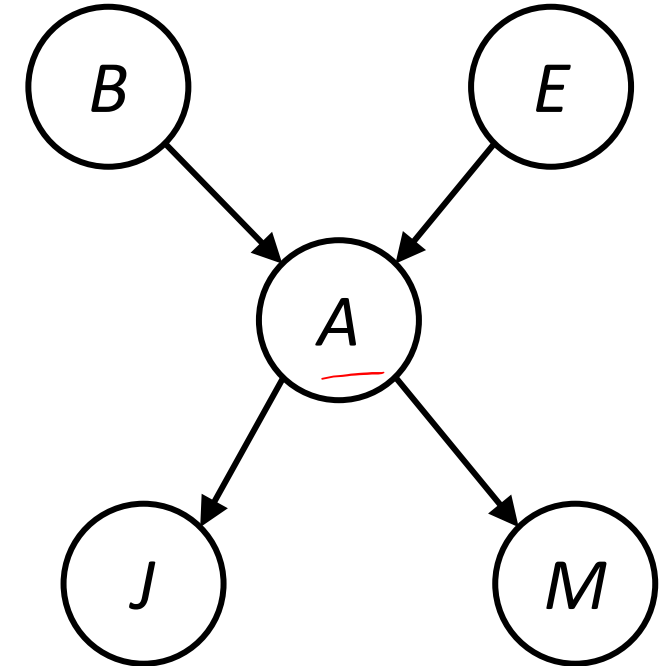
$$\underline{P(Q|e_1 \dots e_k)} = \frac{1}{Z} P(Q, e_1 \dots e_k)$$

Inference by Enumeration in Bayes' Net

- Given unlimited time, inference in BNs is easy
- Reminder of inference by enumeration by example:

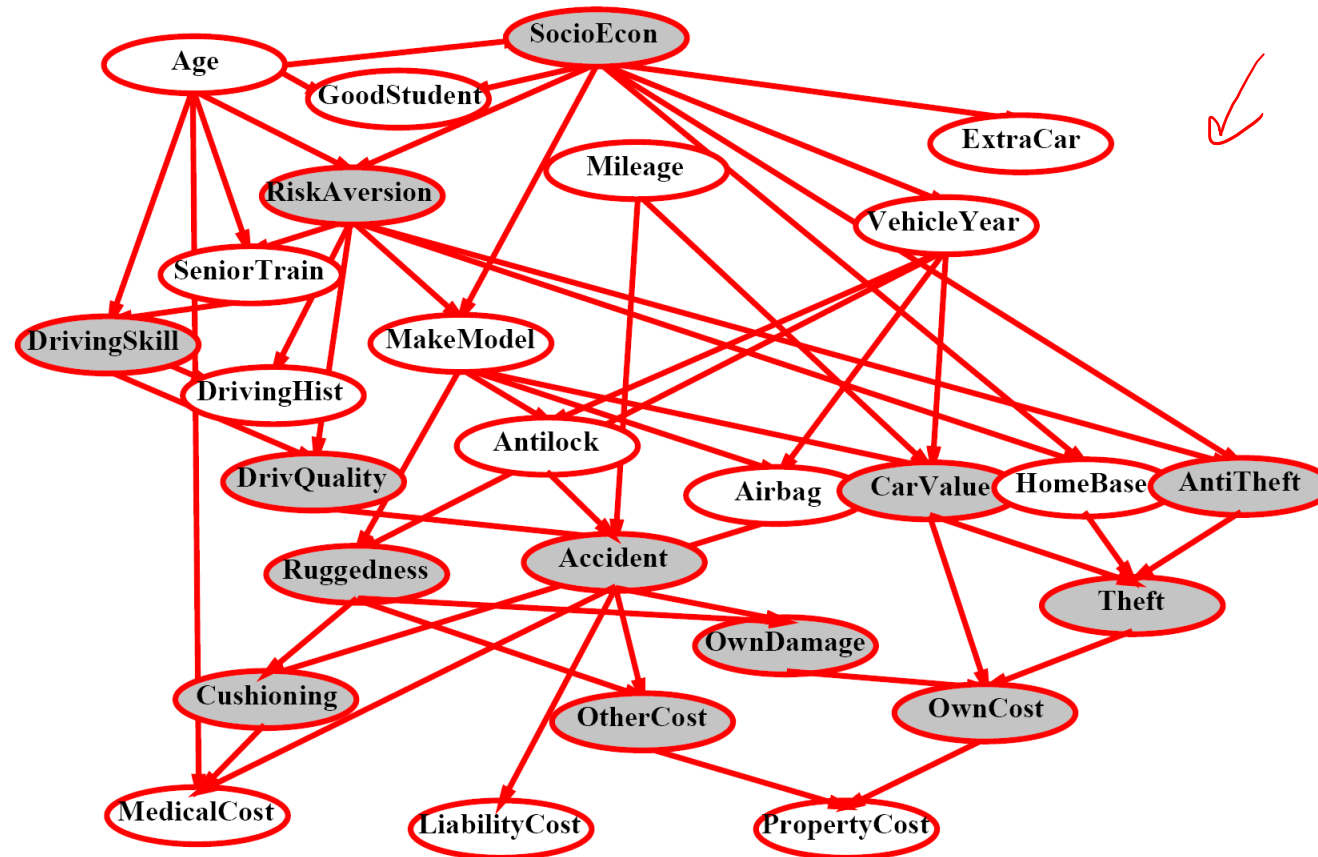
$$\begin{aligned}
 P(B \mid \text{+}j, \text{+}m) &\propto_B P(B, \text{+}j, \text{+}m) \\
 &= \sum_{e,a} P(B, e, a, \text{+}j, \text{+}m) \\
 &= \sum_{e,a} P(B)P(e)P(a|B, e)P(\text{+}j|a)P(\text{+}m|a)
 \end{aligned}$$

Handwritten notes: Red arrows point from the '+' signs in the first term to the 'Assigned' label. Red boxes highlight the summation variables and the joint probability term.



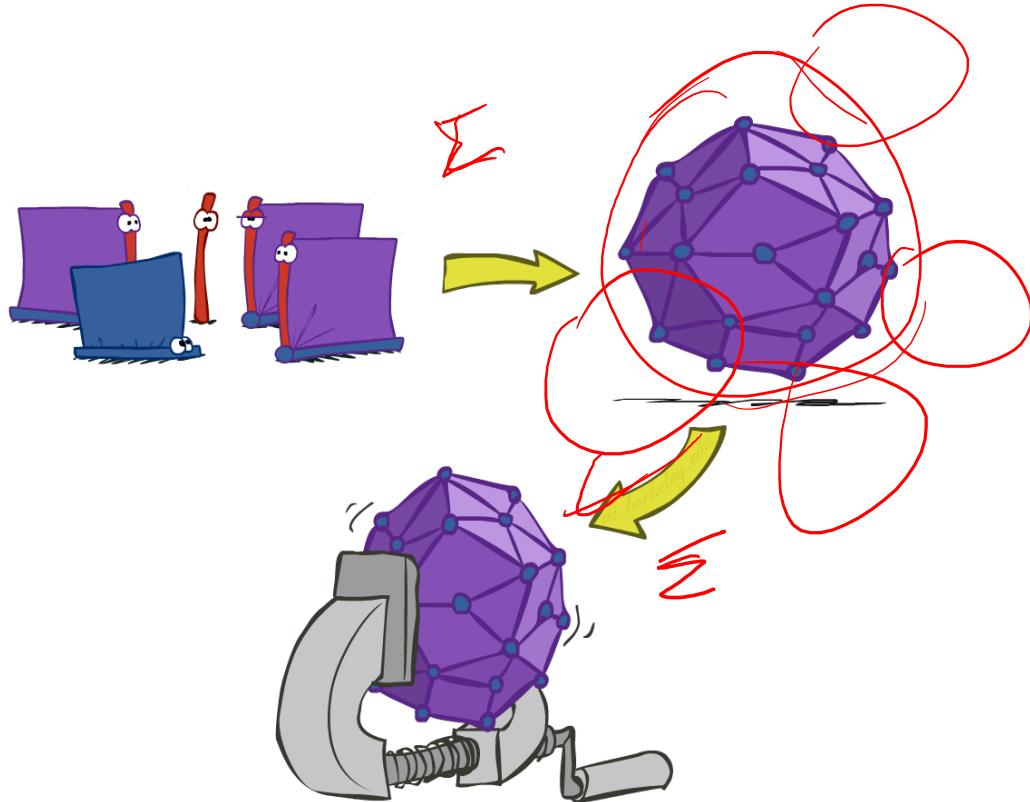
$$\begin{aligned}
 &= P(B)P(\text{+}e)P(\text{+}a|B, \text{+}e)P(\text{+}j|\text{+}a)P(\text{+}m|\text{+}a) + P(B)P(\text{+}e)P(-a|B, \text{+}e)P(\text{+}j|-a)P(\text{+}m|-a) \\
 &\quad P(B)P(-e)P(\text{+}a|B, -e)P(\text{+}j|\text{+}a)P(\text{+}m|\text{+}a) + P(B)P(-e)P(-a|B, -e)P(\text{+}j|-a)P(\text{+}m|-a)
 \end{aligned}$$

Inference by Enumeration?

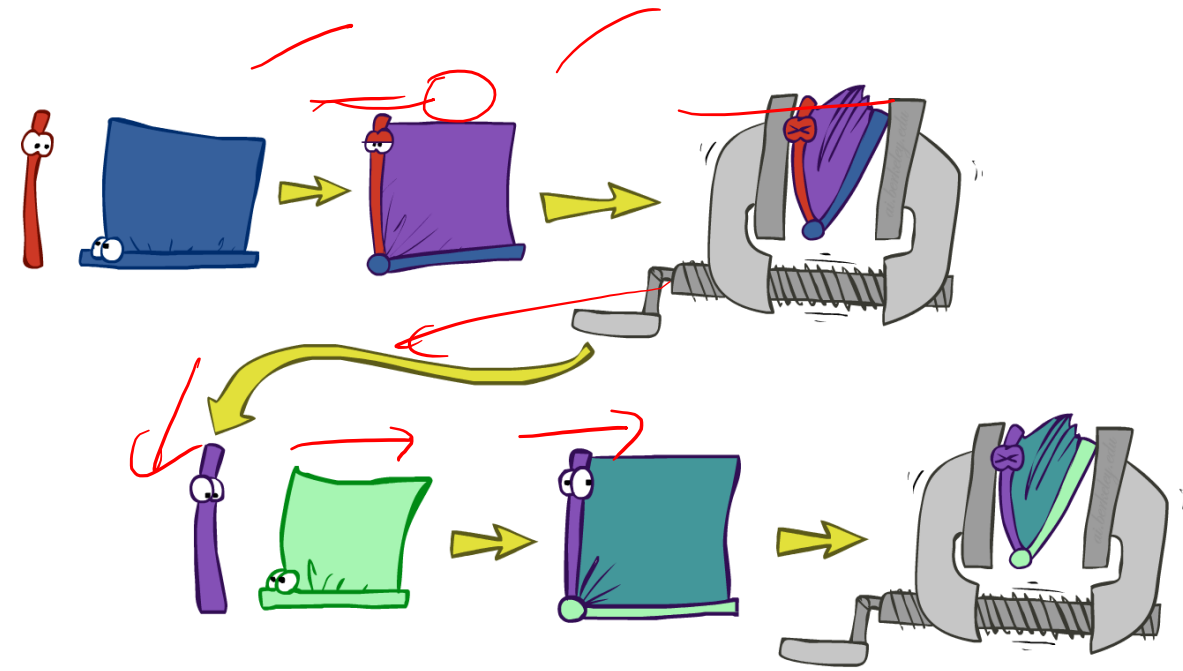


Inference by Enumeration vs. Variable Elimination

- Why is inference by enumeration so slow?
 - You join up the whole joint distribution before you sum out the hidden variables

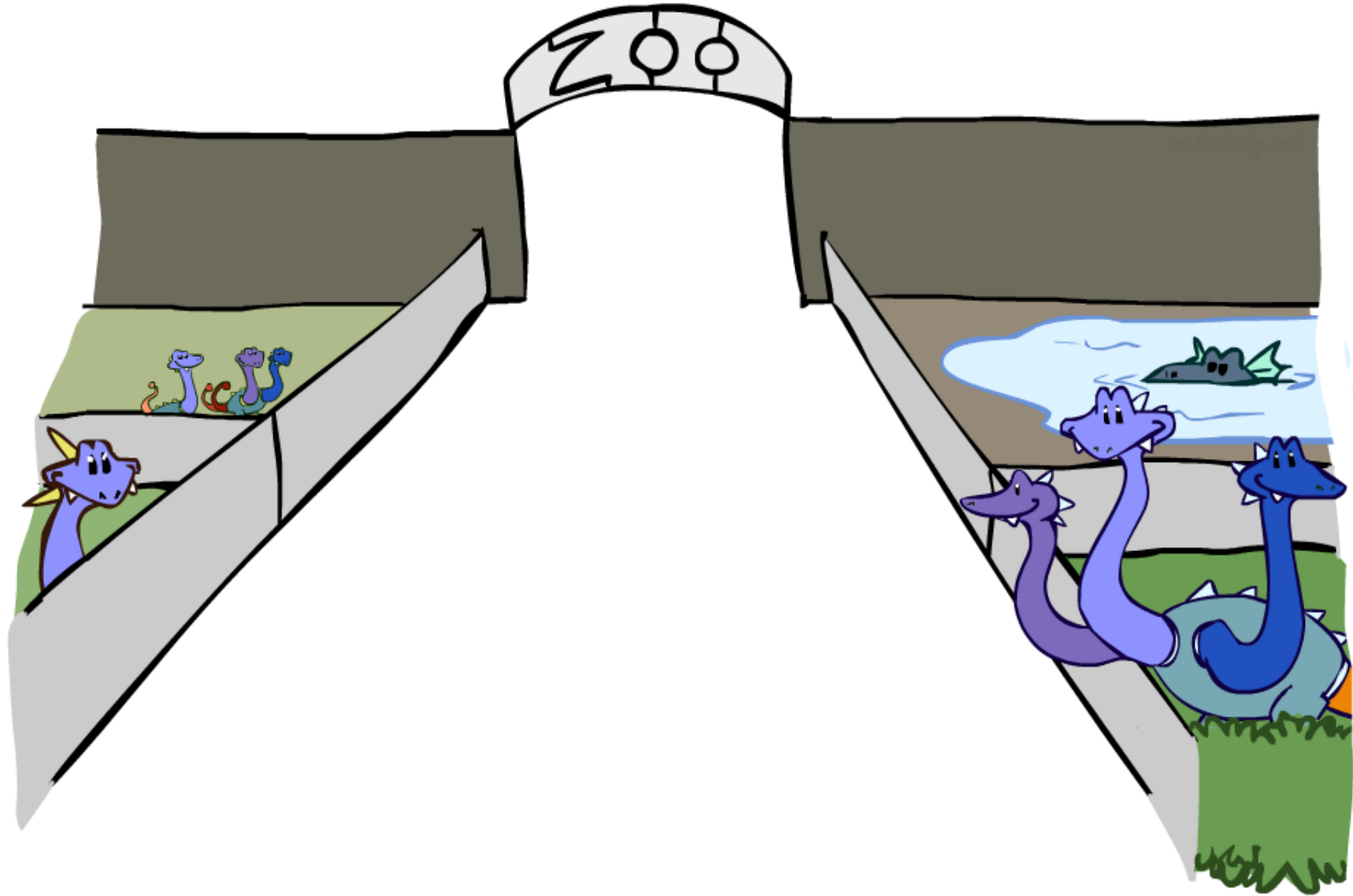


- Idea: **interleave joining and marginalizing!**
 - Called “Variable Elimination”
 - Still NP-hard, but usually much faster than inference by enumeration



- First we'll need some new notation: factors

Factor Zoo



Factor Zoo I

- Joint distribution: $P(X,Y)$

- Entries $P(x,y)$ for all x, y
- Sums to 1

$P(T, W)$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

- Selected joint: $P(x,Y)$

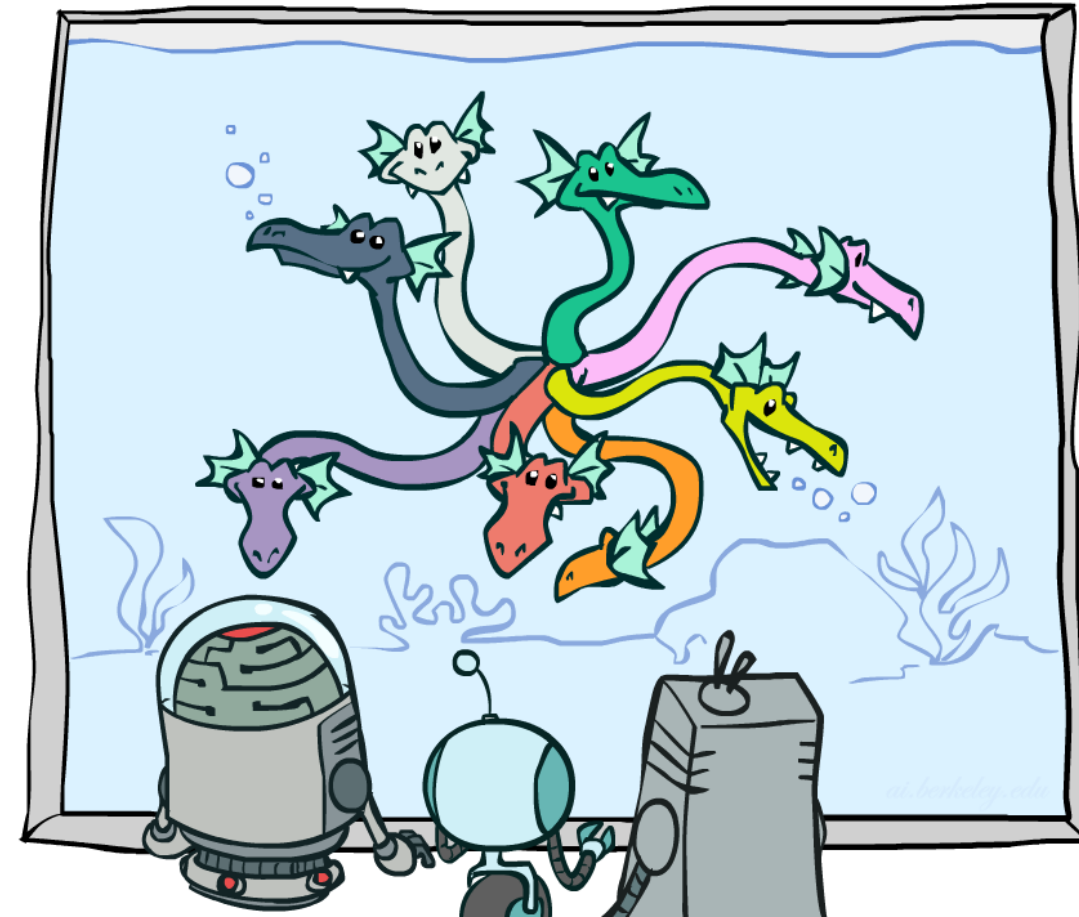
- A slice of the joint distribution
- Entries $P(x,y)$ for fixed x , all y
- Sums to $P(x)$

$P(\text{cold}, W)$

T	W	P
cold	sun	0.2
cold	rain	0.3

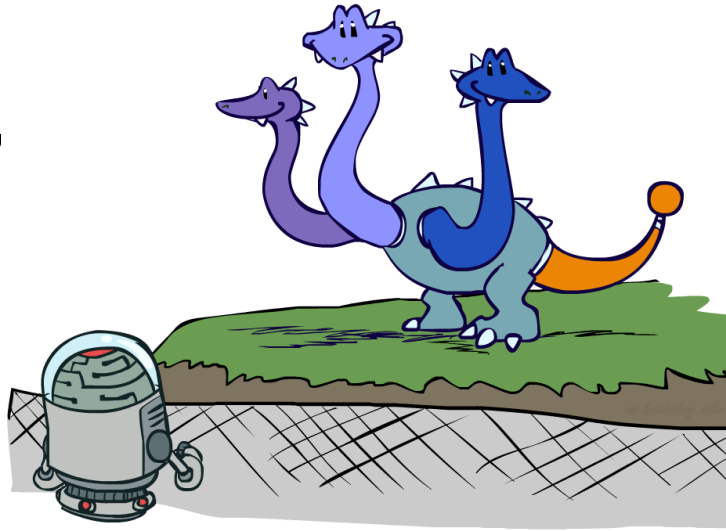
- Number of capitals = dimensionality of the table

$P(x, y, z)$ 3D



Factor Zoo II

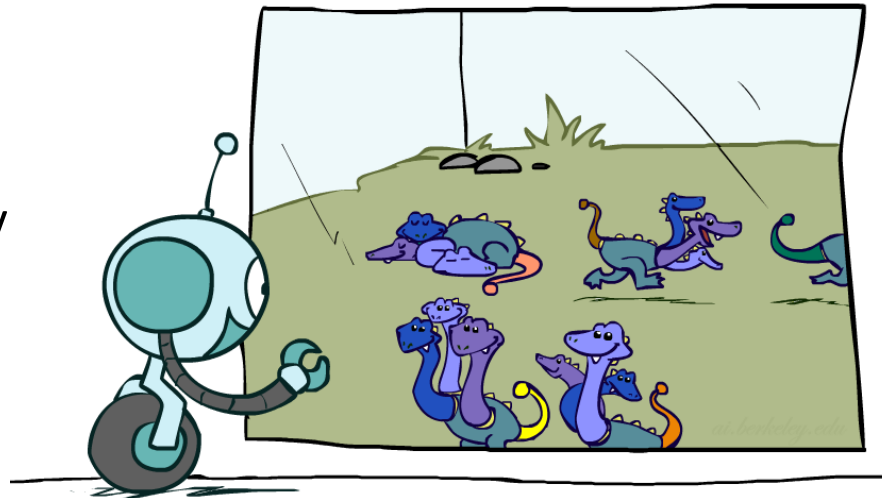
- Single conditional: $P(Y | x)$
 - Entries $P(y | x)$ for fixed x , all y
 - Sums to 1



$$P(W|cold)$$

T	W	P
cold	sun	0.4
cold	rain	0.6

- Family of conditionals:
 $P(Y | X)$
 - Multiple conditionals
 - Entries $P(y | x)$ for all x, y
 - Sums to $|X|$



$$P(W|T)$$

T	W	P
hot	sun	0.8
hot	rain	0.2
cold	sun	0.4
cold	rain	0.6

$$P(W|hot)$$

$$P(W|cold)$$

Factor Zoo III

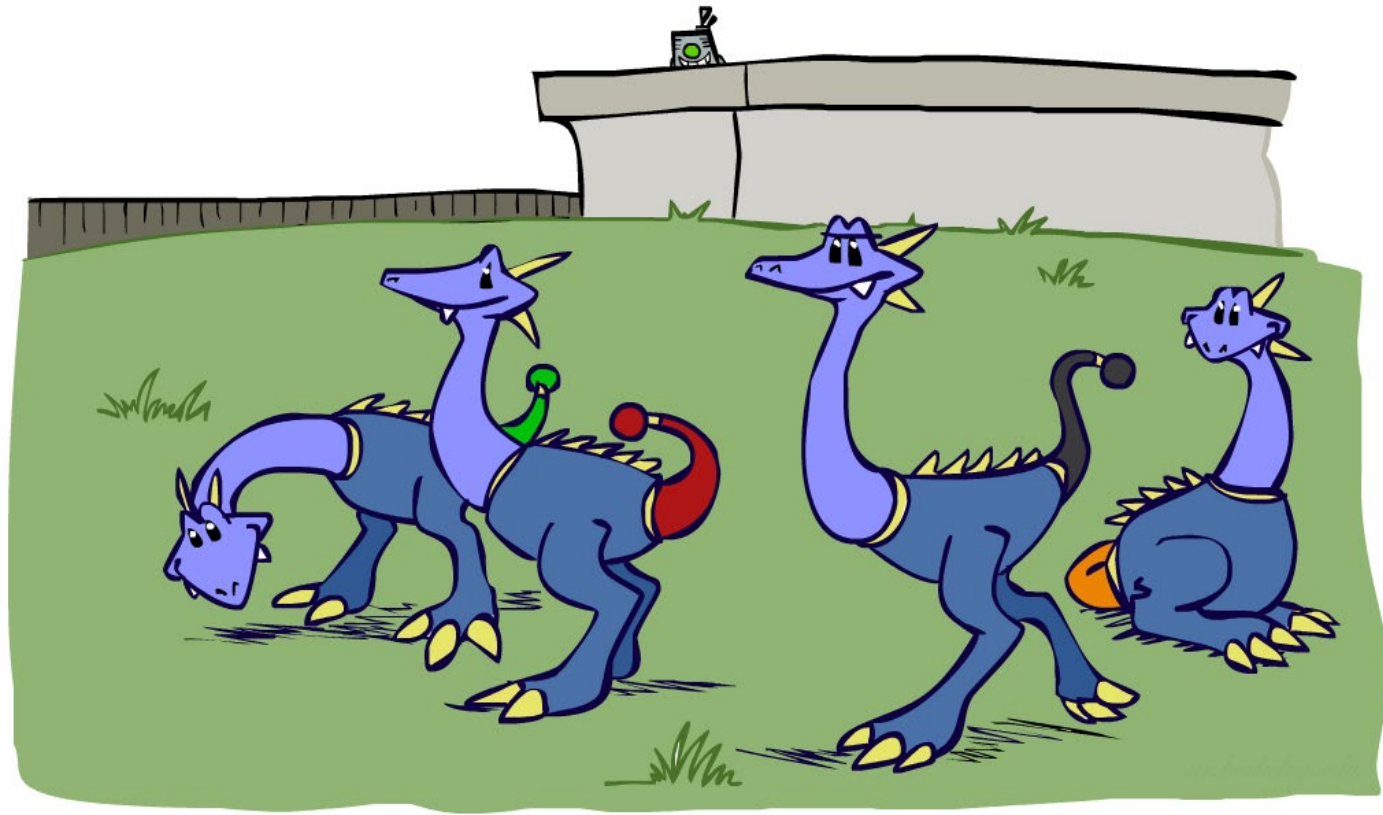
- Specified family: $P(y \mid X)$
 - Entries $P(y \mid x)$ for fixed y , but for all x
 - Sums to ... who knows!

$$P(\text{rain} \mid T)$$

T	W	P
hot	rain	0.2
cold	rain	0.6

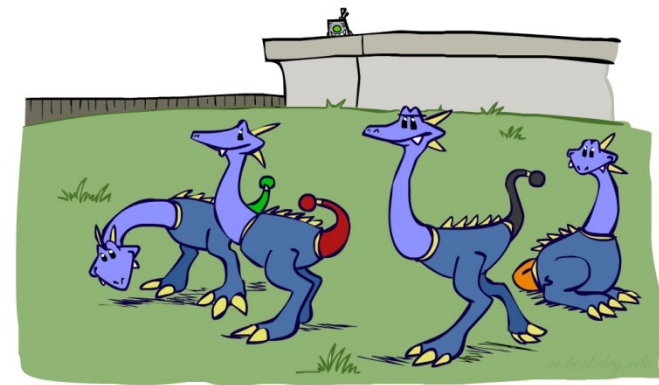
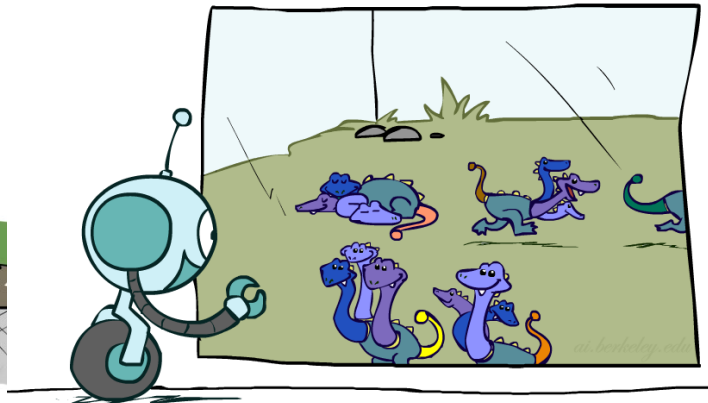
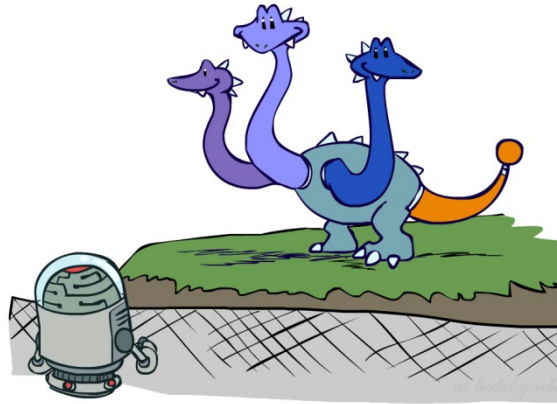
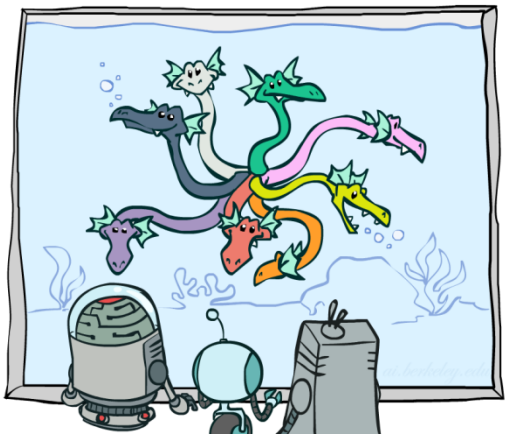
$$P(\text{rain} \mid \text{hot})$$

$$P(\text{rain} \mid \text{cold})$$



Factor Zoo Summary

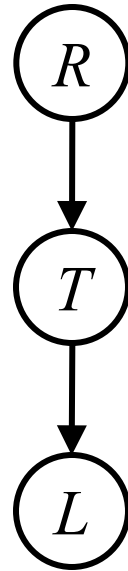
- In general, when we write $P(Y_1 \dots Y_N \mid X_1 \dots X_M)$
 - It is a “factor,” a multi-dimensional array
 - Its values are $P(y_1 \dots y_N \mid x_1 \dots x_M)$
 - Any assigned (=lower-case) X or Y is a dimension missing (selected) from the array



Example: Traffic Domain

- Random Variables

- R: Raining
- T: Traffic
- L: Late for class!



$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

$$P(L) = ?$$

$$= \sum_{r,t} P(r, t, L) \quad \text{JPT enumeration}$$

$$= \sum_{r,t} P(r) P(t|r) P(L|t) \quad \text{Bayesian enumeration}$$

Inference by Enumeration: Procedural Outline

- Track objects called **factors**
- Initial factors are local CPTs (one per node)

$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- Any known values are selected
 - E.g. if we know $L = +\ell$, the initial factors are

$$P(R)$$

+r	0.1
-r	0.9

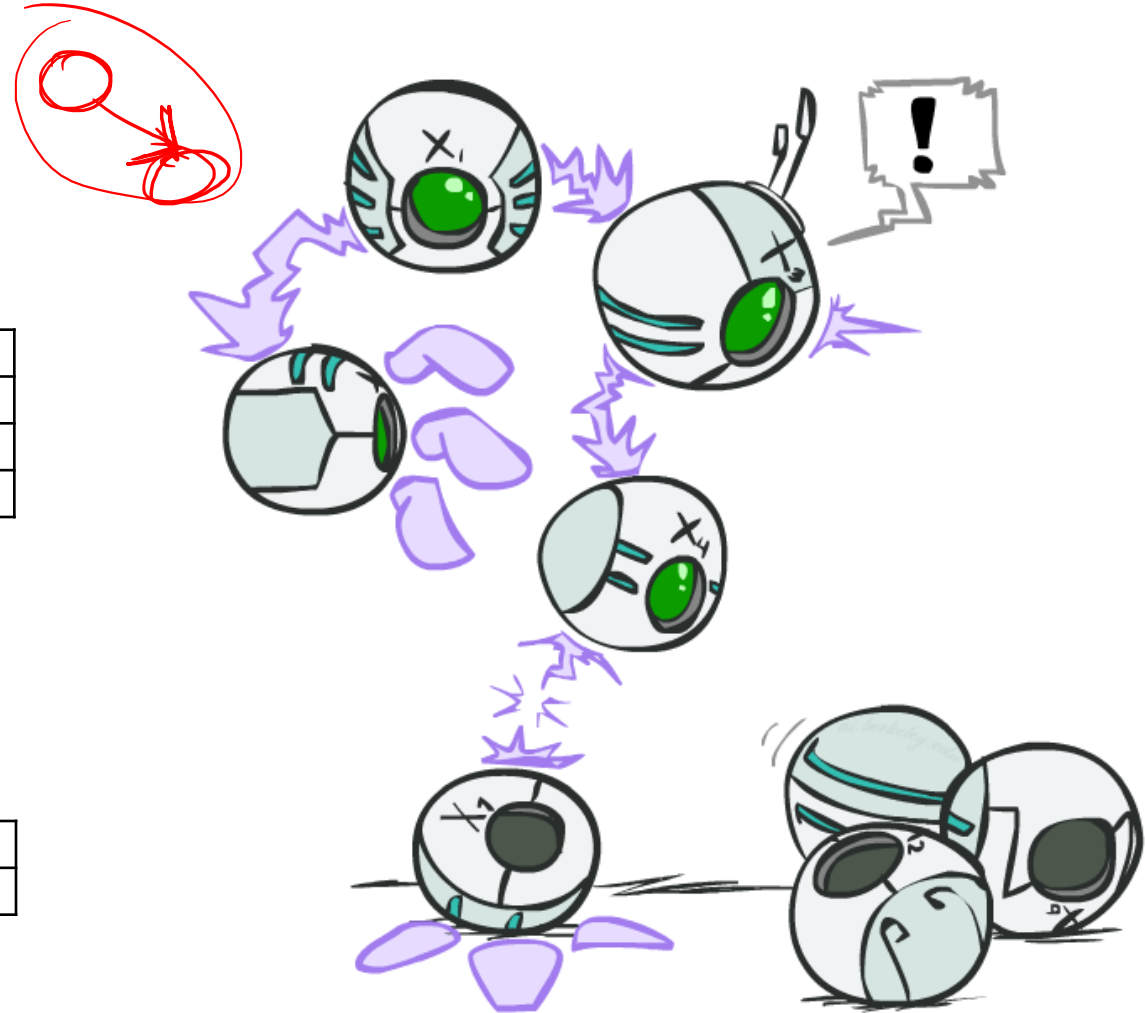
$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(+\ell|T)$$

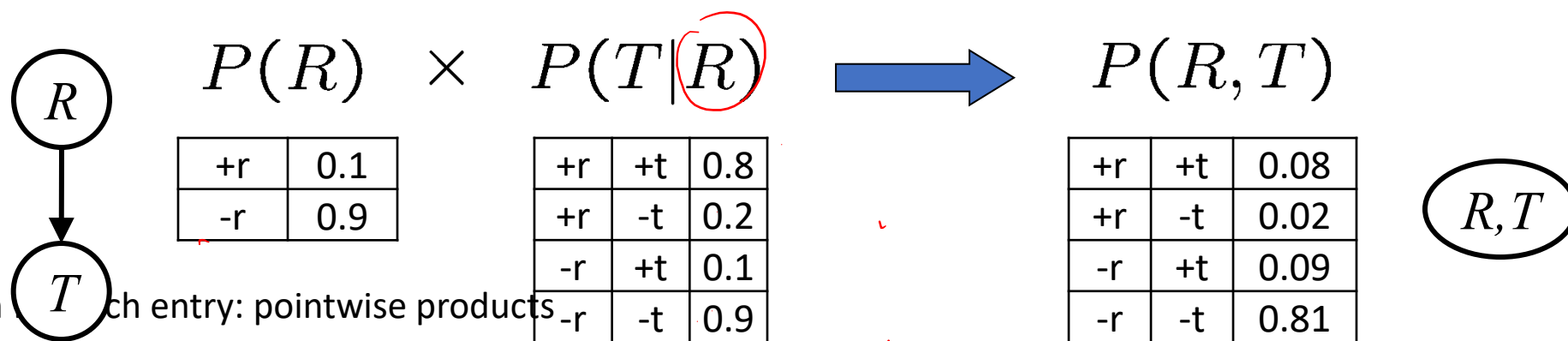
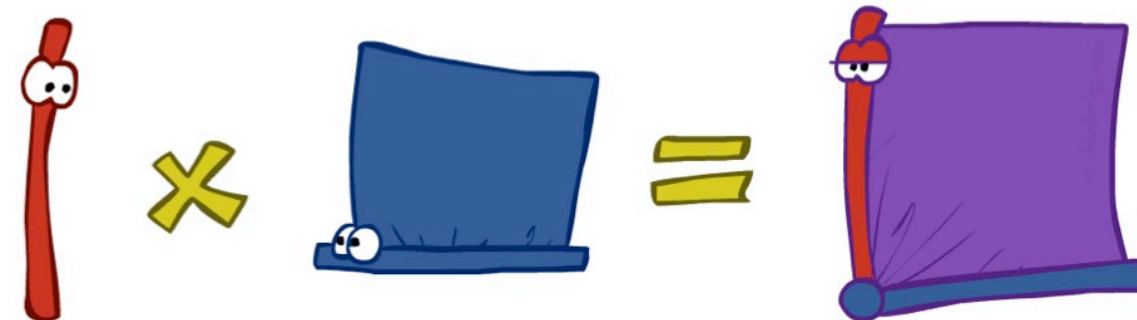
+t	+l	0.3
-t	+l	0.1

- Procedure: Join all factors, eliminate all hidden variables, normalize



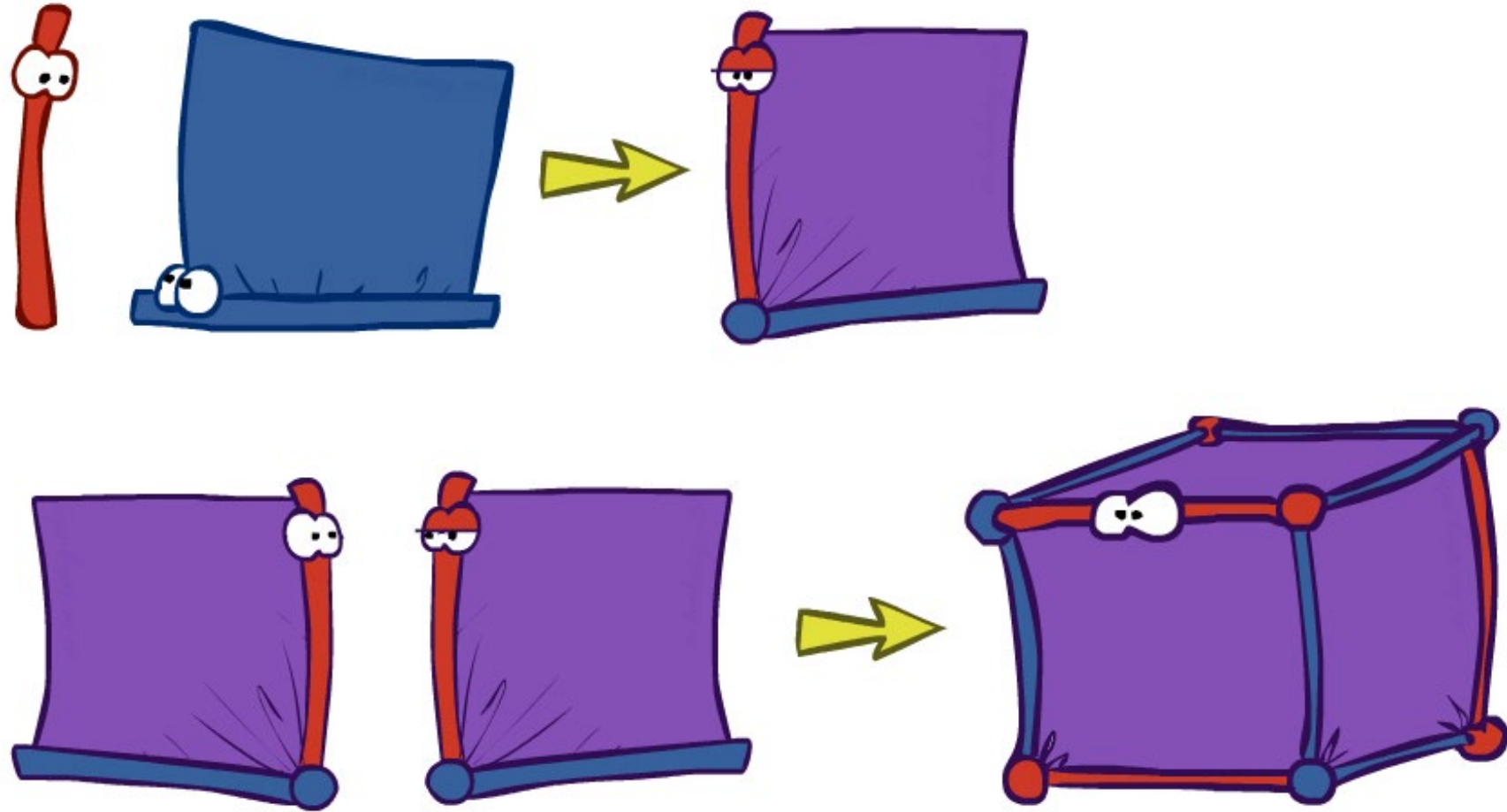
Operation 1: Join Factors

- First basic operation: **joining factors**
- Combining factors:
 - **Just like a database join**
 - Get all factors over the joining variable
 - Build a new factor over the union of the variables involved
- Example: Join on R

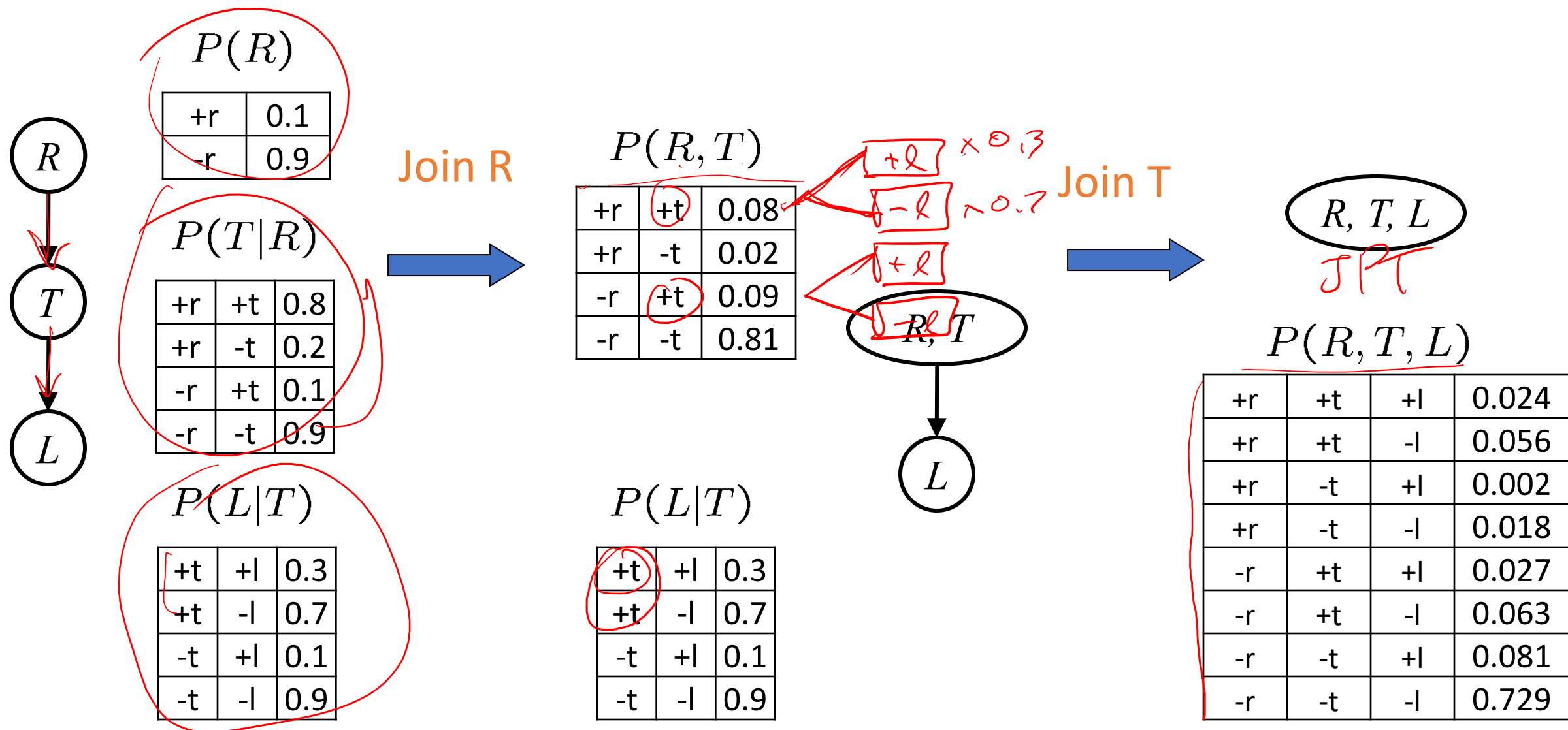


$$\forall r, t : P(r, t) = P(r) \cdot P(t|r)$$

Example: Multiple Joins




Example: Multiple Joins

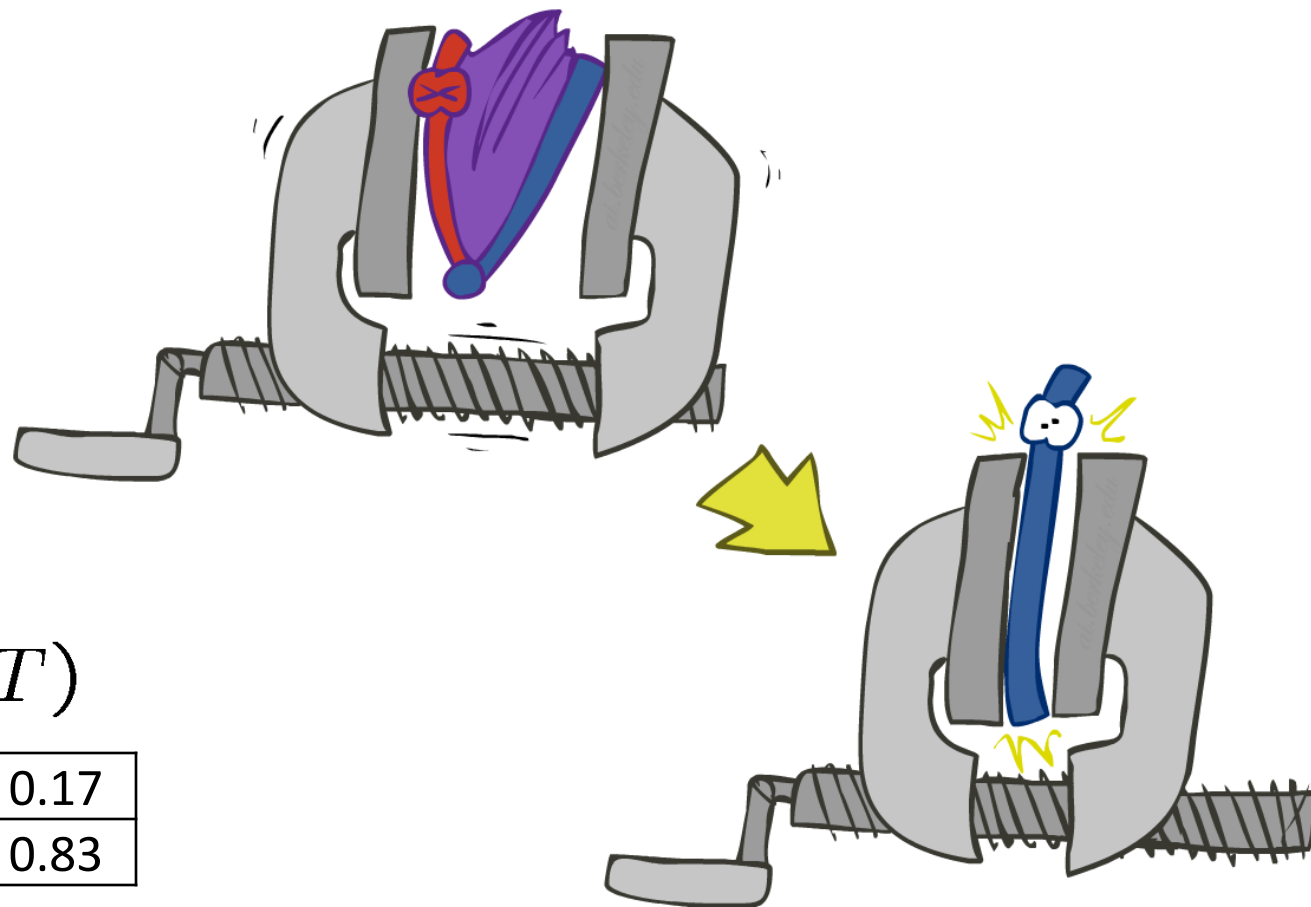


Operation 2: Eliminate

JPT enumer

- Second basic operation: **marginalization**
- Take a factor and sum out a variable
 - Shrinks a factor to a smaller one
 - A **projection** operation
- Example:

$P(R, T)$			sum R 	$P(T)$	
+r	+t	0.08		+t	0.17
+r	-t	0.02		-t	0.83
-r	+t	0.09			
-r	-t	0.81			



Multiple Elimination

$P(R, T, L)$

	R, T, L		
+r	+t	+l	0.024
+r	+t	-l	0.056
+r	-t	+l	0.002
+r	-t	-l	0.018
-r	+t	+l	0.027
-r	+t	-l	0.063
-r	-t	+l	0.081
-r	-t	-l	0.729

Sum out R

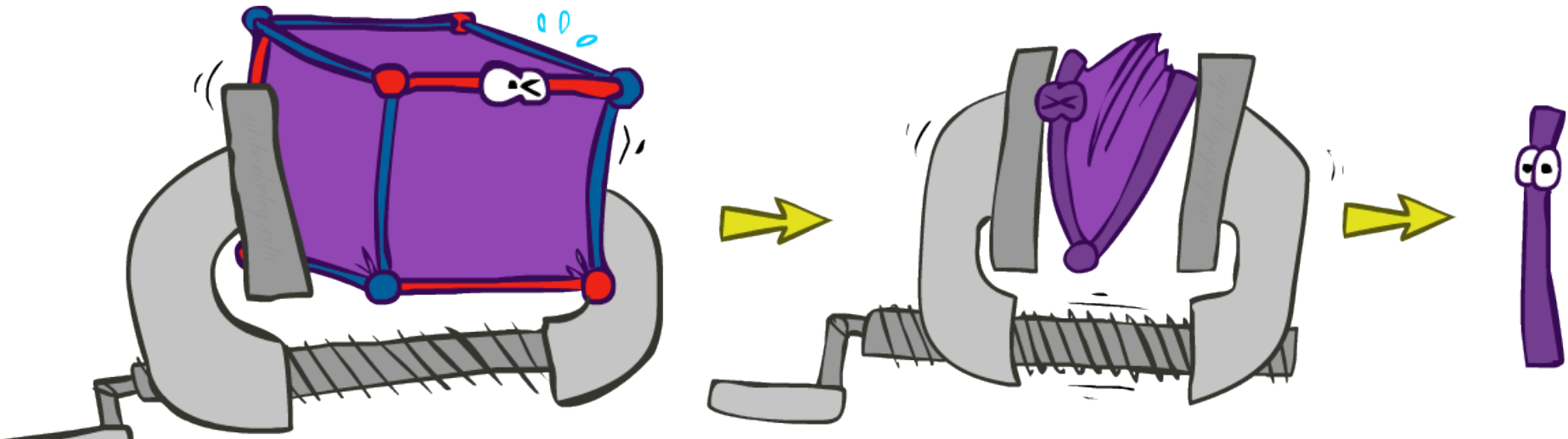
$P(T, L)$

+t	+l	0.051
+t	-l	0.119
-t	+l	0.083
-t	-l	0.747

Sum out T

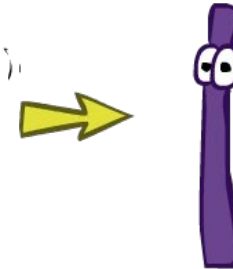
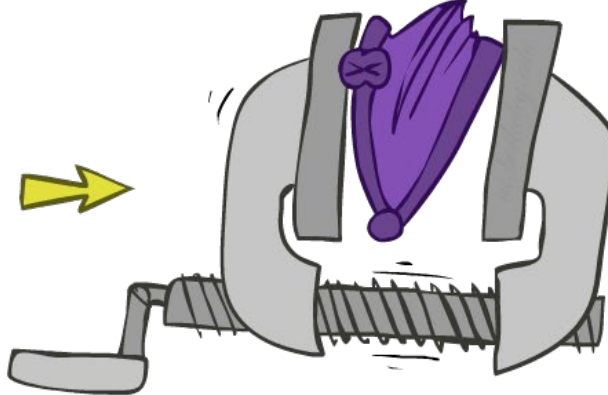
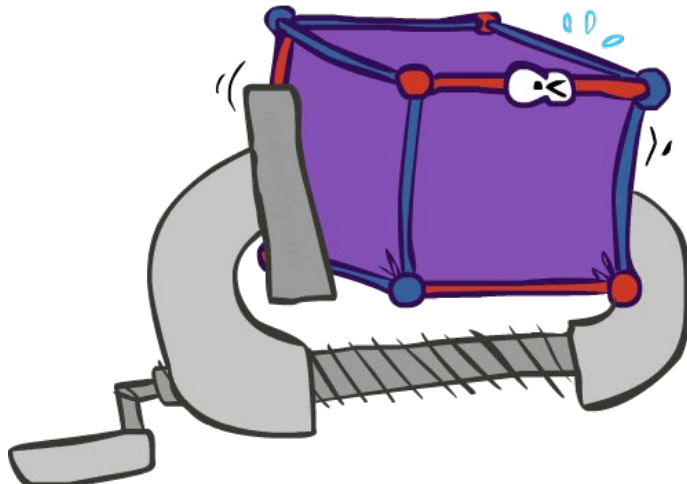
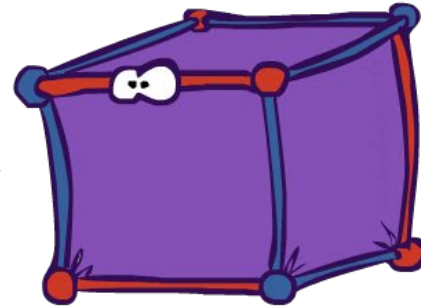
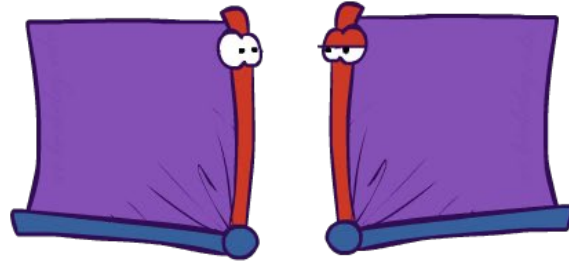
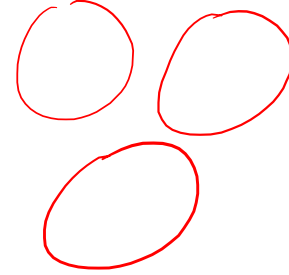
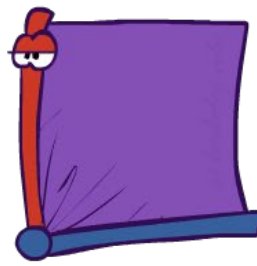
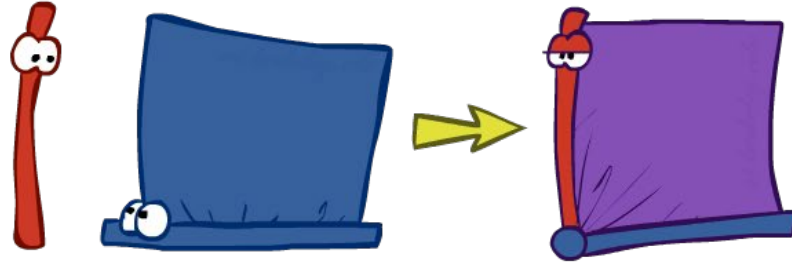
$P(L)$

+l	0.134
-l	0.886

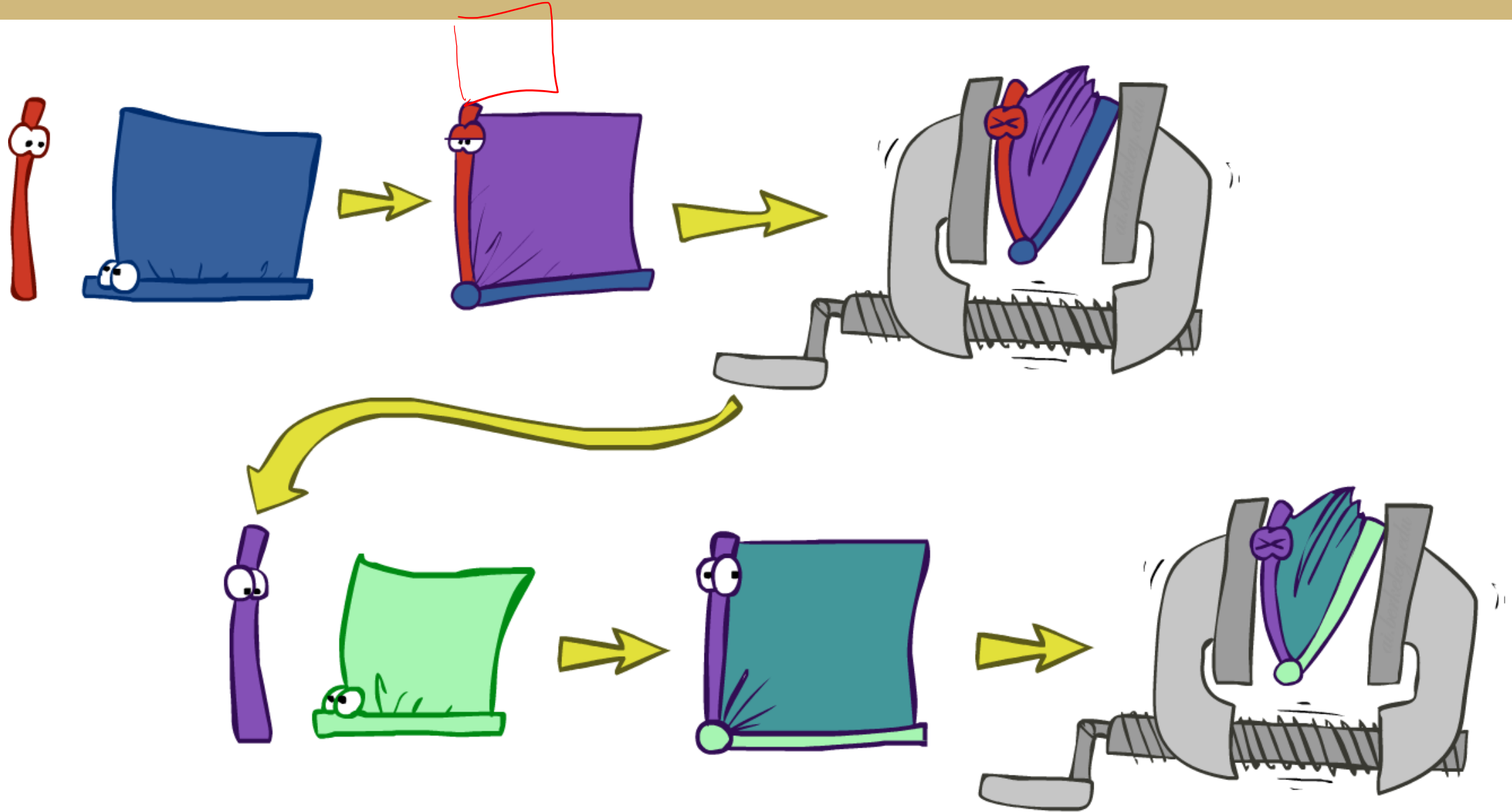


Multiple Join, Multiple Eliminate = Inference by Enumeration

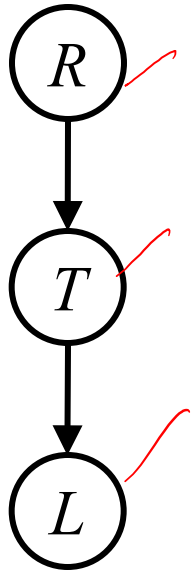
$(J \vee J) \rightarrow J \rightarrow JPT$
 $\nwarrow \quad \nearrow \quad \nwarrow \quad \nearrow$
 $\tau \quad \epsilon \quad \tau \quad \epsilon$



Marginalizing Early (= Variable Elimination)



Traffic Domain



$$\underline{P(L) = ?}$$

- Inference by Enumeration

$$= \sum_t \sum_r P(L|t) \underbrace{P(r)P(t|r)}_{\text{Join on } r}$$

$$\underbrace{\hspace{10em}}_{\text{Join on } t}$$

$$\underbrace{\hspace{10em}}_{\text{Eliminate } r}$$

$$\underbrace{\hspace{10em}}_{\text{Eliminate } t}$$

■ Variable Elimination

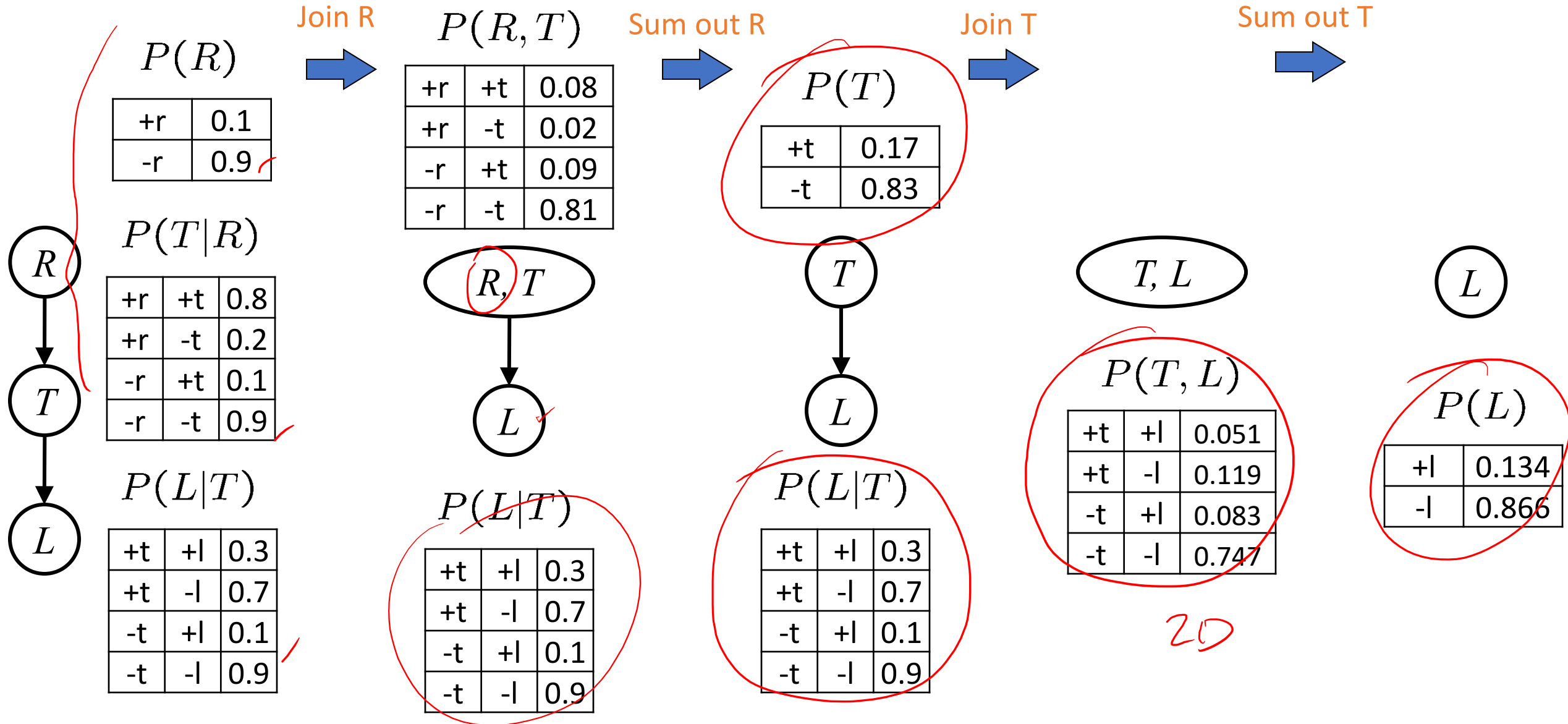
$$= \sum_t \underbrace{P(L|t)}_{1} \sum_r \underbrace{P(r)P(t|r)}_{\text{Join on } r}$$

$$\underbrace{\hspace{10em}}_{\text{Eliminate } r}$$

$$\underbrace{\hspace{10em}}_{\text{Join on } t}$$

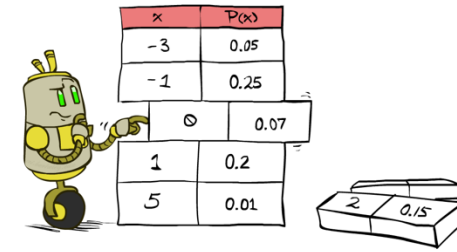
$$\underbrace{\hspace{10em}}_{\text{Eliminate } t}$$

Marginalizing Early! (aka VE)



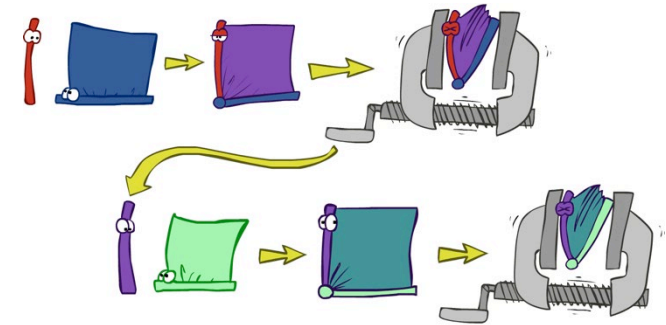
General Variable Elimination

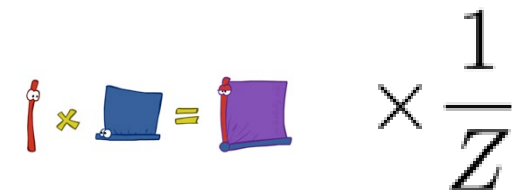
- Query: $P(Q|E_1 = e_1, \dots, E_k = e_k)$
- Start with initial factors:
 - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
 - Pick a hidden variable H
 - Join all factors mentioning H
 - Eliminate (sum out) H
- Join all remaining factors and normalize



x	P(x)
-3	0.05
-1	0.25
0	0.07
1	0.2
5	0.01

$H_1 \dots H_n$

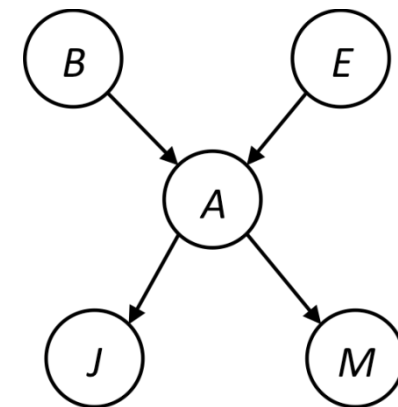



$$\text{stick figure} \times \text{blue square} = \text{purple square} \times \frac{1}{Z}$$

Example

$$P(B|j, m) \propto P(B, j, m)$$

$P(B)$	$P(E)$	$P(A B, E)$	$P(j A)$	$P(m A)$
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Choose A

$$\begin{array}{l}
 P(A|B, E) \\
 P(j|A) \quad \times \\
 P(m|A) \quad \times
 \end{array}
 \xrightarrow{\times}
 \underbrace{P(j, m, A|B, E)}
 \xrightarrow[\text{A}]{\Sigma}
 \underbrace{P(j, m|B, E)}$$

Handwritten red notes: Above the final term, "tj + ms" with arrows pointing to j and m. Below the final term, two vertical lines under m and j.

$P(B)$	$P(E)$	$P(j, m B, E)$
--------	--------	----------------

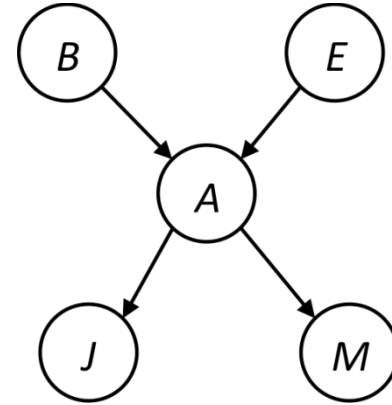
Handwritten red arrows: One under P(B), one under P(E), and one under the entire third term.

Example

$$\boxed{P(B) \quad P(E) \quad P(j, m|B, E)}$$

Choose E

$$\begin{array}{c} P(E) \\ P(j, m|B, E) \end{array} \times \rightarrow \underline{P(j, m, E|B)} \xrightarrow{\Sigma} \underline{P(j, m|B)}$$



$$\boxed{P(B) \quad P(j, m|B)}$$

Finish with B

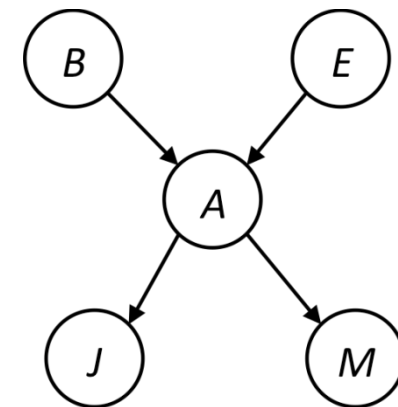
$$\begin{array}{c} P(B) \\ P(j, m|B) \end{array} \times \rightarrow \underline{P(j, m, B)} \xrightarrow{\text{Normalize}} P(B|j, m)$$

$$\begin{bmatrix} +j & +b \\ +j & -b \\ +m & +b \\ +m & -b \end{bmatrix}$$

Same Example in Equations

$$P(B|j, m) \propto P(B, j, m)$$

$P(B)$	$P(E)$	$P(A B, E)$	$P(j A)$	$P(m A)$
--------	--------	-------------	----------	----------



$$\begin{aligned}
 \underbrace{P(B|j, m)} &\propto P(B, j, m) \\
 &= \sum_{e, a} P(B, j, m, e, a) \\
 &= \sum_{e, a} P(B)P(e)P(a|B, e)P(j|a)P(m|a) \\
 &= \sum_e P(B)P(e) \left(\sum_a P(a|B, e)P(j|a)P(m|a) \right) \\
 &= \sum_e P(B)P(e)f_1(B, e, j, m) \\
 &= P(B) \sum_e P(e)f_1(B, e, j, m) \\
 &= P(B)f_2(B, j, m)
 \end{aligned}$$

marginal obtained from joint by summing out

use Bayes' net joint distribution expression

use $x^*(y+z) = xy + xz$

joining on a , and then summing out gives f_1

use $x^*(y+z) = xy + xz$

joining on e , and then summing out gives f_2

All we are doing is exploiting $uwv + uwz + uxy + uxz + vwy + vwz + vxy + vxz = (u+v)(w+x)(y+z)$ to improve computational efficiency!

Variable Elimination Ordering

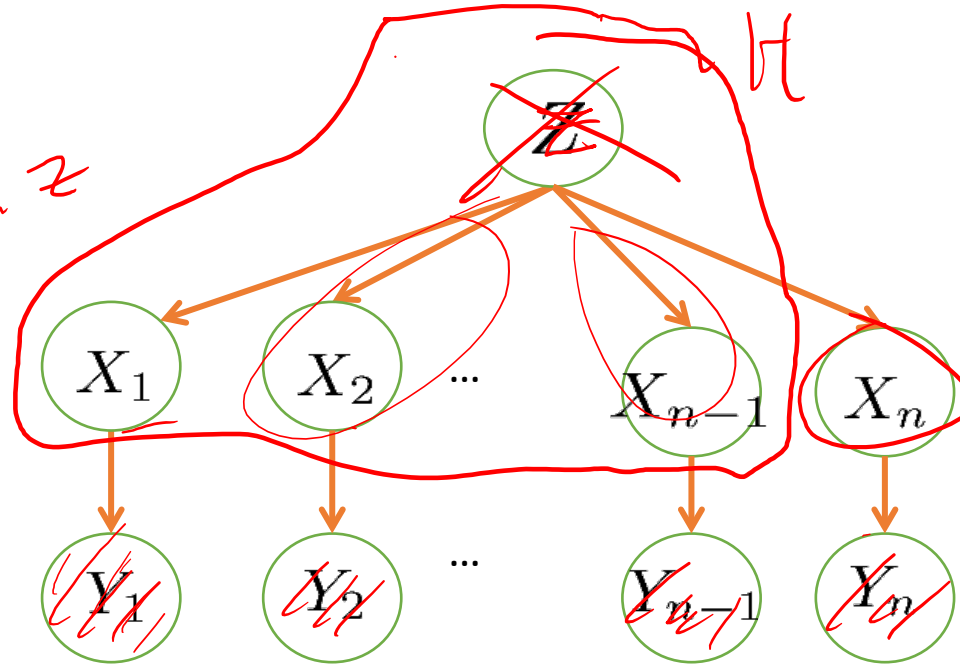
- For the query $P(X_n | y_1, \dots, y_n)$ work through the following two different orderings : Z, X_1, \dots, X_{n-1} and X_1, \dots, X_{n-1}, Z . What is the size of the maximum factor generated for each of the orderings?

Opt 1 z, x_1, \dots

Opt 2 $x_1 \dots x_{n-1}, z$

$$\begin{aligned} &P(z) \\ &P(x_1 | z) \\ &P(x_2 | z) \\ &\vdots \\ &P(x_{n-1} | z) \end{aligned}$$

→ $2^n + 2$



Query

Evidenzen

④ Dpt2

1)

Join

2)

→ ←

- Answer: 2^{n+1} versus 2^2 (assuming binary)
- In general: the ordering can greatly affect efficiency.

$$P(y_1 | x_1)$$

$$P(x_1 | z)$$
$$P(Y_1, X_1 | z)$$

VE: Computational and Space Complexity

~ Time

- The computational and space complexity of variable elimination is determined by the largest factor
- The elimination ordering can greatly affect the size of the largest factor.
 - E.g., previous slide's example 2^n vs. 2
- Does there always exist an ordering that only results in small factors?
 - No!