

Solutions to Homework 9

Physics 5393

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P-1.8 Suppose $|i\rangle$ and $|j\rangle$ are eigenkets of some Hermitian operator $\tilde{\mathbf{A}}$. Under what condition can we conclude that $|i\rangle + |j\rangle$ is also an eigenket of $\tilde{\mathbf{A}}$? Justify your answer.

Only under the condition that the two eigenkets are degenerate

$$\tilde{\mathbf{A}}(|i\rangle + |j\rangle) = a_{ij}(|i\rangle + |j\rangle).$$

P-3.4 Consider the 2×2 matrix defined by

$$\mathbf{U} = \frac{a_0 + i\vec{\sigma} \cdot \vec{\mathbf{a}}}{a_0 - i\vec{\sigma} \cdot \vec{\mathbf{a}}}$$

where a_0 is a real number and $\vec{\mathbf{a}}$ is a three-dimensional vector with real components.

a) Prove that \mathbf{U} is unitary and unimodular.

Keep in mind that both the numerator and denominator are matrices and therefore \mathbf{U} must be a matrix. Given this, the matrix can be better expressed as follows

$$\mathbf{U} = \mathbf{A} \left(\mathbf{A}^\dagger \right)^{-1},$$

where $\mathbf{A} = a_0 + i\vec{\sigma} \cdot \vec{\mathbf{a}}$ and $\mathbf{A} = a_0 + i\vec{\sigma} \cdot \vec{\mathbf{a}}$. To prove unitary, we must calculate

$$\begin{aligned} \mathbf{U}\mathbf{U}^\dagger &= \left[\mathbf{A} \left(\mathbf{A}^\dagger \right)^{-1} \right] \left[\mathbf{A} \left(\mathbf{A}^\dagger \right)^{-1} \right]^\dagger \\ &= \left[\mathbf{A} \left(\mathbf{A}^\dagger \right)^{-1} \right] \left[(\mathbf{A})^{-1} \mathbf{A}^\dagger \right] \\ &= \mathbf{A} \left(\mathbf{A}\mathbf{A}^\dagger \right)^{-1} \mathbf{A}^\dagger, \end{aligned}$$

where use is made of $\mathbf{A}^{-1}\mathbf{B}^{-1} = (\mathbf{B}\mathbf{A})^{-1}$; this follows from matrix multiplication being associative

$$(\mathbf{A}\mathbf{B})(\mathbf{A}\mathbf{B})^{-1} = \mathbf{I} \quad \Rightarrow \quad \mathbf{A}(\mathbf{B}\mathbf{B}^{-1})\mathbf{A}^{-1} = \mathbf{I}$$

The term $\mathbf{A}\mathbf{A}^\dagger$ can be simplified as follows

$$\begin{aligned} \mathbf{A}\mathbf{A}^\dagger &= [a_0 + i\vec{\sigma} \cdot \vec{\mathbf{a}}] [a_0 - i\vec{\sigma} \cdot \vec{\mathbf{a}}] \\ &= [a_0^2 \mathbf{I} + (\vec{\sigma} \cdot \vec{\mathbf{a}})^2] \\ &= [a_0^2 + a^2] \mathbf{I} \equiv \alpha \mathbf{I}, \end{aligned}$$

where $a^2 = a_1^2 + a_2^2 + a_3^2$ and its inverse is

$$\left(\mathbf{A}\mathbf{A}^\dagger \right)^{-1} = \frac{1}{\alpha} \mathbf{I}.$$

The remaining part of the proof is

$$\mathbf{U}\mathbf{U}^\dagger = \mathbf{A} \left(\frac{1}{\alpha} \mathbf{I} \right) \mathbf{A}^\dagger = \mathbf{A}\mathbf{A}^\dagger \left(\frac{1}{\alpha} \mathbf{I} \right) = \frac{\alpha}{\alpha} \mathbf{I} = \mathbf{I}.$$

To determine if the matrix is unimodular (determinant is one), we expand \mathbf{A} and \mathbf{A}^\dagger

$$\mathbf{A} = \begin{pmatrix} a_0 + ia_3 & ia_1 + a_2 \\ ia_1 - a_2 & a_0 - ia_3 \end{pmatrix} \quad \mathbf{A}^\dagger = \begin{pmatrix} a_0 - ia_3 & -ia_1 + a_2 \\ -ia_1 - a_2 & a_0 + ia_3 \end{pmatrix}.$$

The determinant of both matrices is α . The determinant of an inverse is

$$\det [\mathbf{A}^{-1}] = \frac{1}{\det [\mathbf{A}]}.$$

Therefore $\det[\mathbf{U}] = 1$.

- b) In general, a 2×2 unitary unimodular matrix represents a rotation in three dimensions. Find the axis and angle of rotation appropriate for \mathbf{U} in terms of a_0 , a_1 , a_2 , and a_3 .
The first step is to write the matrix in a form that can be easily manipulated. This can be done by multiplying by \mathbf{I}

$$\begin{aligned} \mathbf{U} &= \mathbf{A}(\mathbf{A}^\dagger)^{-1} = \mathbf{A} [\mathbf{A}\mathbf{A}^{-1}] (\mathbf{A}^\dagger)^{-1} = \mathbf{A}^2 (\mathbf{A}^\dagger \mathbf{A})^{-1} \\ &= \frac{1}{\alpha^2} \begin{pmatrix} a_0^2 - a^2 + 2ia_0a_3 & 2a_0a_2 + 2ia_0a_1 \\ -2a_0a_2 + 2ia_0a_1 & a_0 - a^2 - 2ia_0a_3 \end{pmatrix}. \end{aligned}$$

From here, we use the expression for a unitary unimodular matrix given in the textbook

$$\begin{aligned} \cos\left(\frac{\phi}{2}\right) &= \text{Re}(a) = \frac{a_0^2 - a^2}{\alpha^2} \Rightarrow \sin\left(\frac{\phi}{2}\right) = \sqrt{1 - \cos^2(\phi/2)} = \frac{2a_0|a|}{\alpha^2} \\ -n_y \sin\left(\frac{\phi}{2}\right) &= \text{Re}(b) = \frac{2a_0a_2}{\alpha^2} \Rightarrow n_y = -\frac{a_2}{|a|} \\ -n_x \sin\left(\frac{\phi}{2}\right) &= \text{Im}(b) = \frac{2a_0a_1}{\alpha^2} \Rightarrow n_x = -\frac{a_1}{|a|} \\ -n_z \sin\left(\frac{\phi}{2}\right) &= \text{Im}(a) = \frac{2a_0a_3}{\alpha^2} \Rightarrow n_z = -\frac{a_3}{|a|}. \end{aligned}$$

P-3.5 The spin dependent Hamiltonian of an electron-positron system in the presence of a uniform in the z -direction can be written as

$$\tilde{\mathbf{H}} = A\tilde{\mathbf{S}}^{(e^-)} \cdot \tilde{\mathbf{S}}^{(e^+)} + \frac{eB}{mc} \left(\tilde{\mathbf{S}}_z^{(e^-)} - \tilde{\mathbf{S}}_z^{(e^+)} \right).$$

Suppose the spin function of the system is given by $\chi_+^{(e^-)} \chi_-^{(e^+)}$.

- a) Is this an eigenfunction of $\tilde{\mathbf{H}}$ in the limit $A \rightarrow 0$, $eB/mc \neq 0$? If it is, what is the energy eigenvalue? If not, what is the expectation value of $\tilde{\mathbf{H}}$?

The Hamiltonian for this case is

$$\tilde{\mathbf{H}} = \frac{eB}{mc} \left[\tilde{\mathbf{S}}_z^{(e^-)} - \tilde{\mathbf{S}}_z^{(e^+)} \right].$$

If we apply it to the spin function $\chi_+^{(e-)} \chi_-^{(e+)}$, we find

$$\frac{eB}{mc} [\tilde{\mathbf{S}}_z^{(e-)} - \tilde{\mathbf{S}}_z^{(e+)}] |+- \rangle = \frac{eB}{mc} \left[\frac{\hbar}{2} - \left(-\frac{\hbar}{2} \right) \right] |+- \rangle = \frac{eB\hbar}{mc} |+- \rangle,$$

where $|+- \rangle = \chi_+^{(e-)} \chi_-^{(e+)}$ is an eigenstate of this Hamiltonian.

b) Solve the same problem for $A \neq 0$, $eB/mc \rightarrow 0$.

To solve this part of the problem, use Eq. 3.8.19 in the textbook

$$\tilde{\mathbf{S}}^{(e-)} \cdot \tilde{\mathbf{S}}^{(e+)} = \tilde{\mathbf{S}}_z^{(e-)} \tilde{\mathbf{S}}_z^{(e+)} + \frac{1}{2} \tilde{\mathbf{S}}_+^{(e-)} \tilde{\mathbf{S}}_-^{(e+)} + \frac{1}{2} \tilde{\mathbf{S}}_-^{(e-)} \tilde{\mathbf{S}}_+^{(e+)}.$$

Applying this on the spin function, we find

$$[\tilde{\mathbf{S}}^{(e-)} \cdot \tilde{\mathbf{S}}^{(e+)}] |+- \rangle = \left[-\frac{\hbar^2}{4} |+- \rangle + 0 + \frac{\hbar^2}{2} |+- \rangle \right] = \frac{\hbar^2}{4} [2 |+- \rangle - |+- \rangle].$$

The expectation value is

$$\langle +- | \tilde{\mathbf{H}} | +- \rangle = -A \frac{\hbar^2}{4}.$$

P-3.9 What is the meaning of the following equation?

$$\mathbf{U}^{-1} \tilde{\mathbf{A}}_k \mathbf{U} = \sum_l \mathbf{R}_{kl} \tilde{\mathbf{A}}_l,$$

where the three components of $\tilde{\mathbf{A}}$ are matrices. From this equation show that matrix elements $\langle m | \tilde{\mathbf{A}}_k | n \rangle$ transform like vectors.

The equation states that the rotated operators $\tilde{\mathbf{A}}_k$ are linear combinations of the unrotated operators

$$\tilde{\mathbf{A}}'_k = \sum_l \mathbf{R}_{kl} \tilde{\mathbf{A}}_l.$$

The matrix elements are given by

$$\langle m | \tilde{\mathbf{A}}'_k | n \rangle = \sum_l \mathbf{R}_{kl} \langle m | \tilde{\mathbf{A}}_l | n \rangle,$$

therefore, the matrix elements transform like components of a vector

$$V'_k = \sum_l \mathbf{R}_{kl} V_l.$$

P-3.38 The $j = 1$ rotation operator.

b) Show that for $j = 1$ only, it is legitimate to replace $e^{-i\tilde{\mathbf{J}}_y\beta/\hbar}$ by

$$\tilde{\mathbf{1}} - i \left(\frac{\tilde{\mathbf{J}}_y}{\hbar} \right) \sin \beta - \left(\frac{\tilde{\mathbf{J}}_y}{\hbar} \right)^2 (1 - \cos \beta)$$

We start by expanding the operator

$$\exp\left(\frac{-i\tilde{\mathbf{J}}_y\beta}{\hbar}\right) = \left[1 - \frac{1}{2!}\left(\frac{\tilde{\mathbf{J}}_y\beta}{\hbar}\right)^2 + \frac{1}{4!}\left(\frac{\tilde{\mathbf{J}}_y\beta}{\hbar}\right)^4 - \dots\right] - i\left[\left(\frac{\tilde{\mathbf{J}}_y\beta}{\hbar}\right) - \frac{1}{3!}\left(\frac{\tilde{\mathbf{J}}_y\beta}{\hbar}\right)^3 + \dots\right].$$

By brute force, one can show

$$\frac{\tilde{\mathbf{J}}_y}{\hbar} = \left(\frac{\tilde{\mathbf{J}}_y}{\hbar}\right)^3 \Rightarrow \left(\frac{\tilde{\mathbf{J}}_y}{\hbar}\right)^n = \begin{cases} \left(\frac{\tilde{\mathbf{J}}_y}{\hbar}\right) & n = \text{odd} \\ \left(\frac{\tilde{\mathbf{J}}_y}{\hbar}\right)^2 & n = \text{even.} \end{cases} \quad (1)$$

Therefore,

$$\exp\left(\frac{-i\tilde{\mathbf{J}}_y\beta}{\hbar}\right) = 1 - \left(\frac{\tilde{\mathbf{J}}_y}{\hbar}\right)^2 + \left(\frac{\tilde{\mathbf{J}}_y}{\hbar}\right)^2 \left[1 - \frac{\beta^2}{2!} + \frac{\beta^4}{4!} - \dots\right] - i\left(\frac{\tilde{\mathbf{J}}_y}{\hbar}\right) \left[\beta - \frac{\beta^3}{3!} + \dots\right],$$

and finally

$$\exp\left(\frac{-i\tilde{\mathbf{J}}_y\beta}{\hbar}\right) = 1 - \left(\frac{\tilde{\mathbf{J}}_y}{\hbar}\right)^2 [1 - \cos \beta] - i\left(\frac{\tilde{\mathbf{J}}_y}{\hbar}\right) \sin \beta.$$

c) Using (b), prove

$$d^{(j=1)}(\beta) = \begin{pmatrix} \frac{1}{2}(1 + \cos \beta) & -\frac{1}{\sqrt{2}} \sin \beta & \frac{1}{2}(1 - \cos \beta) \\ \frac{1}{\sqrt{2}} \sin \beta & \cos \beta & -\frac{1}{\sqrt{2}} \sin \beta \\ \frac{1}{2}(1 - \cos \beta) & \frac{1}{\sqrt{2}} \sin \beta & \frac{1}{2}(1 + \cos \beta) \end{pmatrix}$$

The operator $\tilde{\mathbf{J}}_y$ is given in part (a) and its square is given by

$$\left(\tilde{\mathbf{J}}_y\right)^2 = \left(\frac{\hbar}{2}\right)^2 \begin{pmatrix} 2 & 0 & -2 \\ 0 & 4 & 0 \\ -2 & 0 & 2 \end{pmatrix}.$$

Combining all the pieces, we arrive at the desired result

$$d^{(j=1)}(\beta) = \begin{pmatrix} \frac{1}{2}(1 + \cos \beta) & -\frac{1}{\sqrt{2}} \sin \beta & \frac{1}{2}(1 - \cos \beta) \\ \frac{1}{\sqrt{2}} \sin \beta & \cos \beta & -\frac{1}{\sqrt{2}} \sin \beta \\ \frac{1}{2}(1 - \cos \beta) & \frac{1}{\sqrt{2}} \sin \beta & \frac{1}{2}(1 + \cos \beta) \end{pmatrix}$$