A single qubit

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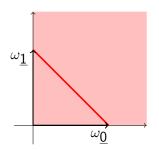
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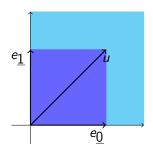
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A single bit

Let
$$u = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
.

- Set of states = $\{\omega \in \mathbb{R}^2 \mid \omega \in C_{\geq 0}, \langle u, \omega \rangle = 1\}.$
- Set of binary measurements = $\{e \in \mathbb{R}^2 \mid e \in C_{\geq 0}, u e \in C_{\geq 0}\}.$

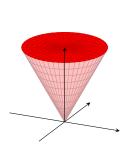


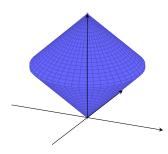


A single qubit

Let
$$u = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$
.

- Set of states = $\{\omega \in V \mid \omega \in C_{\succ 0}, \langle u, \omega \rangle = 1\}.$
- Set of binary measurements = $\{e \in V \mid e \in C_{\succ 0}, u e \in C_{\succ 0}\}.$





A single qubit

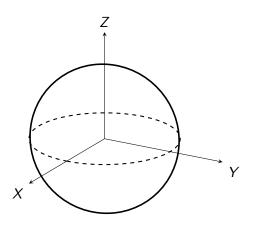
• A qubit can be represented by

$$\rho = \frac{1}{2} (I + r_X X + r_Y Y + r_Z Z)$$

for
$$[r_X \ r_Y \ r_Z] \in \mathbb{R}^3$$
 satisfying $r_X^2 + r_Y^2 + r_Z^2 \le 1$.

• A qubit can be represented by a point $[r_X \ r_Y \ r_Z]$ in a three-dimensional sphere of radius 1.

The Bloch sphere



Pauli matrices

$$Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix}$$

$$X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \begin{bmatrix} 1 & -1 \end{bmatrix}$$

$$Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ i \end{bmatrix} \begin{bmatrix} 1 & -i \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ -i \end{bmatrix} \begin{bmatrix} 1 & i \end{bmatrix}$$

Braket notation

$$egin{align} |0
angle := egin{bmatrix} 1 \ 0 \end{bmatrix}, & |1
angle := egin{bmatrix} 0 \ 1 \end{bmatrix} \ |+
angle := rac{1}{\sqrt{2}} egin{bmatrix} 1 \ 1 \end{bmatrix}, & |-
angle := rac{1}{\sqrt{2}} egin{bmatrix} 1 \ 1 \end{bmatrix} \ &= rac{1}{\sqrt{2}} (|0
angle + |1
angle), & = rac{1}{\sqrt{2}} (|0
angle - |1
angle) \end{split}$$

$$|\psi\rangle = \alpha |0\rangle + \beta |1\rangle = \begin{bmatrix} \alpha \\ \beta \end{bmatrix}$$

for
$$|\alpha|^2 + |\beta|^2 = 1$$
.

$$\langle \psi | = | \psi \rangle^{\dagger} = \alpha^* \langle 0 | + \beta^* \langle 1 | = \begin{bmatrix} \alpha^* & \beta^* \end{bmatrix}$$

Pauli matrices in braket notation

$$Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \ket{0}\bra{0} - \ket{1}\bra{1}$$

$$X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \ket{+} \bra{+} - \ket{-} \bra{-}$$

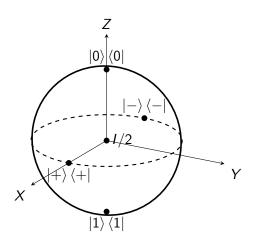
$$Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ i \end{bmatrix} \begin{bmatrix} 1 & -i \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ -i \end{bmatrix} \begin{bmatrix} 1 & i \end{bmatrix}$$

Special states

$$\rho = \frac{1}{2} \left(I + r_X X + r_Y Y + r_Z Z \right)$$

Coordinate	State
[0 0 0]	$\frac{1}{2}I$
[1 0 0]	$\frac{1}{2}(I+X)=\ket{+}\bra{+}$
$[-1\ 0\ 0]$	$\frac{1}{2}(I-X)=\ket{-}\bra{-}$
[0 0 1]	$\frac{1}{2}(I+Z)=\ket{0}\bra{0}$
[0 0 -1]	$rac{1}{2}(I-Z)=\ket{1}ra{1}$

Special states in the Bloch sphere



Pure states and state vector

ρ is a pure state

$$\stackrel{\text{def}}{\Longleftrightarrow} \rho \neq p\rho_1 + (1-p)\rho_2 \quad \forall p \in [0,1] \text{ and states } \rho_1, \rho_2 \neq \rho$$

$$\iff \rho \text{ is at surface of the Bloch sphere}$$

$$\iff r_X^2 + r_Y^2 + r_Z^2 = 1$$

$$\iff \lambda_1 \lambda_2 = 0 \ \land \ \lambda_1 + \lambda_2 = 1$$

$$\iff \rho \text{ is rank-1 Hermitian with } \mathsf{Tr}(\rho) = 1$$

$$\iff \rho = |\psi\rangle \ \langle \psi| \text{ for some } |\psi\rangle \in \mathbb{C}^2 \text{ with } \langle \psi|\psi\rangle = 1$$

Pure state can be represented by a state vector $|\psi\rangle\in\mathbb{C}^2$ with $\langle\psi|\psi\rangle=1.$

$$|\psi\rangle$$
 and $|\varphi\rangle:=\mathrm{e}^{i\theta}\,|\psi\rangle$ represent the same state since $|\psi\rangle\,\langle\psi|=|\varphi\rangle\,\langle\varphi|.$

Inner product of pure states

- ρ is a qubit pure state with a coordinate $[r_X r_Y r_Z]$.
- σ is a qubit pure state with a coordinate $[-r_X r_Y r_Z]$.

$$\operatorname{Tr}(\rho\sigma) = \operatorname{Tr}(\rho(I-\rho)) = \operatorname{Tr}(\rho) - \operatorname{Tr}(\rho^2) = 1 - 1 = 0$$

- $\rho = |\psi\rangle\langle\psi|$.
- $\sigma = |\varphi\rangle\langle\varphi|$.

$$\operatorname{Tr}(\rho\sigma) = \operatorname{Tr}(|\psi\rangle \langle \psi| |\varphi\rangle \langle \varphi|) = \langle \psi|\varphi\rangle \operatorname{Tr}(|\psi\rangle \langle \varphi|)$$
$$= \langle \psi|\varphi\rangle \langle \varphi|\psi\rangle = |\langle \psi|\varphi\rangle|^{2}$$

Unitary operation

Unitary operation

$$ho \mapsto U
ho U^{\dagger}$$

It is easy to see that

- $\operatorname{Tr}(U\rho U^{\dagger})=1$
- $U\rho U^{\dagger} \succeq 0$

A pure state $|\psi\rangle$ is mapped to a pure state $U\,|\psi\rangle.$

U and $e^{i\theta}U$ play the same role.

Examples of unitary operation

- The identity matrix I.
- Pauli matrices X, Y and Z.

• Hadamard matrix
$$H:=rac{1}{\sqrt{2}}egin{bmatrix} 1 & 1 \ 1 & -1 \end{bmatrix}$$

Pauli matrices X on the Bloch sphere

$$\rho = \frac{1}{2} (I + r_X X + r_Y Y + r_Z Z)$$

$$X \rho X^{\dagger} = X \rho X = \frac{1}{2} (X^2 + r_X X^3 + r_Y X Y X + r_Z X Z X)$$

$$= \frac{1}{2} (I + r_X X - r_Y Y - r_Z Z)$$

$$[r_X \ r_Y \ r_Z] \stackrel{X}{\longmapsto} [r_X \ -r_Y \ -r_Z]$$

 π -rotation with respect to X axis.

Similarly, Y and Z corresponds to π -rotation with respect to Y and Z axes, respectively.

Hadamard matrix

Hadamard matrix H is unitary and Hermitian.

$$\begin{split} H := \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} &= |+\rangle \langle 0| + |-\rangle \langle 1| \\ &= |0\rangle \langle +| + |1\rangle \langle -| \\ \\ |0\rangle , |1\rangle &\longleftrightarrow |+\rangle , |-\rangle \\ \\ HXH = H(|+\rangle \langle +| -|-\rangle \langle -|)H \\ &= |0\rangle \langle 0| - |1\rangle \langle 1| = Z \end{split}$$

Similarly, HZH = X.

Hadamard matrix on the Bloch sphere

$$\rho = \frac{1}{2} \left(I + r_X X + r_Y Y + r_Z Z \right)$$

$$H\rho H^{\dagger} = H\rho H = \frac{1}{2} \left(H^2 + r_X HXH + r_Y HYH + r_Z HZH \right)$$
$$= \frac{1}{2} \left(I + r_X Z - r_Y Y + r_Z X \right)$$

$$[r_X \ r_Y \ r_Z] \xrightarrow{H} [r_Z \ -r_Y \ r_X]$$

Hadamard operation can be decomposed to $\pi/2$ -rotation with respect to Y axis

$$[r_X \ r_Y \ r_Z] \stackrel{R_Y(\pi/2)}{\longmapsto} [r_Z \ r_Y \ -r_X]$$

and X.

Multiplications of Pauli matrices

For any unitary matrices U and V, UV is also unitary matrix.

- XY = iZ
- YZ = iX
- ZX = iY

Rotation matrices

$$R_X(\theta) := \cos \frac{\theta}{2} I - i \sin \frac{\theta}{2} X$$

$$R_X(\theta)^{\dagger} = R_X(-\theta)$$

$$R_X(\theta) R_X(\theta)^{\dagger} = (\cos \frac{\theta}{2} I - i \sin \frac{\theta}{2} X)(\cos \frac{\theta}{2} I + i \sin \frac{\theta}{2} X)$$

$$= \cos^2 \frac{\theta}{2} I + \sin^2 \frac{\theta}{2} X^2 = I$$

$$R_X(\theta)X = XR_X(\theta), \quad R_X(\theta)Y = YR_X(-\theta), \quad R_X(\theta)Z = ZR_X(-\theta)$$

$$R_X(\theta)R_X(\tau) = R_X(\theta + \tau)$$

$$[1\ 0\ 0] \stackrel{R_X(\theta)}{\longmapsto} [1\ 0\ 0]$$

$$[0\ 1\ 0] \stackrel{R_X(\theta)}{\longmapsto} [0\ \cos\theta\ \sin\theta]$$

$$[0\ 0\ 1] \stackrel{R_X(\theta)}{\longmapsto} [0\ -\sin\theta\ \cos\theta]$$

Assignments [Deadline is the next of next Friday]

• Show that
$$R_Y(\theta) = \begin{bmatrix} \cos \frac{\theta}{2} & -i \sin \frac{\theta}{2} \\ \sin \frac{\theta}{2} & \cos \frac{\theta}{2} \end{bmatrix}$$
 and $R_Z(\theta) = \begin{bmatrix} e^{-i\theta/2} & 0 \\ 0 & e^{i\theta/2} \end{bmatrix}$.

• Show that for any 2×2 unitary matrix, there exist α , β , γ , $\delta \in \mathbb{R}$ such that

$$U = e^{i\alpha} R_Z(\beta) R_Y(\gamma) R_Z(\delta)$$

• [Advanced] For a real unit vector $\hat{n} = [n_X \ n_Y \ n_Z]$, let

$$R_{\hat{n}}(\theta) := \cos \frac{\theta}{2} I - i \sin \frac{\theta}{2} (n_X X + n_Y Y + n_Z Z).$$

Show that for any 2×2 unitary matrix, there exist α , $\theta \in \mathbb{R}$ and a real unit 3d vector \hat{n} such that $U = e^{i\alpha}R_{\hat{n}}(\theta)$.

General 2×2 unitary matrices

 $\{I, X, Y, Z\}$ is a orthogonal basis of 2×2 complex matrices.

$$U = \alpha_I I + \alpha_X X + \alpha_Y Y + \alpha_Z Z$$

for some α_I , α_X , α_Y , $\alpha_Z \in \mathbb{C}$.

$$UU^{\dagger} = (|\alpha_{I}|^{2} + |\alpha_{X}|^{2} + |\alpha_{Y}|^{2} + |\alpha_{Z}^{2}|)I$$

$$+ (\alpha_{I}\alpha_{X}^{*} + \alpha_{I}^{*}\alpha_{X} + i(\alpha_{Y}\alpha_{Z}^{*} - \alpha_{Z}\alpha_{Y}^{*}))X$$

$$+ (\alpha_{I}\alpha_{Y}^{*} + \alpha_{I}^{*}\alpha_{Y} + i(\alpha_{Z}\alpha_{X}^{*} - \alpha_{X}\alpha_{Z}^{*}))Y$$

$$+ (\alpha_{I}\alpha_{Z}^{*} + \alpha_{I}^{*}\alpha_{Z} + i(\alpha_{X}\alpha_{Y}^{*} - \alpha_{Y}\alpha_{X}^{*}))Z$$

$$Re(\alpha_I \alpha_X^*) = Im(\alpha_Y \alpha_Z^*)$$

$$Re(\alpha_I \alpha_Y^*) = Im(\alpha_Z \alpha_X^*)$$

$$Re(\alpha_I \alpha_Z^*) = Im(\alpha_X \alpha_Y^*)$$

General rotation matrices

$$|\alpha_I|^2 + |\alpha_X|^2 + |\alpha_Y|^2 + |\alpha_Z^2| = 1$$

Assume α_I is real.

$$\alpha_I \operatorname{Re}(\alpha_X) = \operatorname{Im}(\alpha_Y \alpha_Z^*)$$

$$\alpha_I \operatorname{Re}(\alpha_Y) = \operatorname{Im}(\alpha_Z \alpha_X^*)$$

$$\alpha_I \operatorname{Re}(\alpha_Z) = \operatorname{Im}(\alpha_X \alpha_Y^*)$$

With the direct calculation, we obtain $\alpha_I(\text{Re}(\alpha_X)^2 + \text{Re}(\alpha_Y)^2 + \text{Re}(\alpha_Z)^2) = 0.$