# A single qubit

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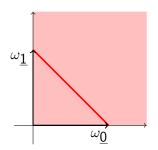
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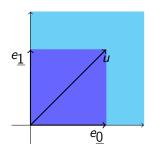
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## A single bit

Let 
$$u = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
.

- Set of states =  $\{\omega \in \mathbb{R}^2 \mid \omega \in C_{\geq 0}, \langle u, \omega \rangle = 1\}.$
- Set of binary measurements =  $\{e \in \mathbb{R}^2 \mid e \in C_{\geq 0}, u e \in C_{\geq 0}\}.$

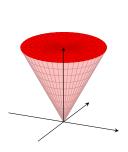


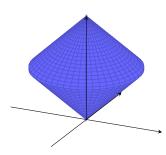


# A single qubit

Let 
$$u = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$
.

- Set of states =  $\{\omega \in V \mid \omega \in C_{\succ 0}, \langle u, \omega \rangle = 1\}.$
- Set of binary measurements =  $\{e \in V \mid e \in C_{\succ 0}, u e \in C_{\succ 0}\}.$





## A single qubit

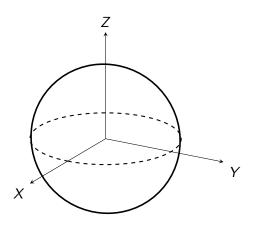
A qubit can be represented by

$$\rho = \frac{1}{2} (I + r_X X + r_Y Y + r_Z Z)$$

for 
$$[r_X r_Y r_Z] \in \mathbb{R}^3$$
 satisfying  $r_X^2 + r_Y^2 + r_Z^2 \le 1$ .

• A qubit can be represented by a point  $[r_X r_Y r_Z]$  in a three-dimensional sphere of radius 1.

# The Bloch sphere



## Pauli matrices

$$Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix}$$

$$X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \begin{bmatrix} 1 & -1 \end{bmatrix}$$

$$Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ i \end{bmatrix} \begin{bmatrix} 1 & -i \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ -i \end{bmatrix} \begin{bmatrix} 1 & i \end{bmatrix}$$

### Braket notation

$$egin{align} |0
angle := egin{bmatrix} 1 \ 0 \end{bmatrix}, & |1
angle := egin{bmatrix} 0 \ 1 \end{bmatrix} \ |+
angle := rac{1}{\sqrt{2}} egin{bmatrix} 1 \ 1 \end{bmatrix}, & |-
angle := rac{1}{\sqrt{2}} egin{bmatrix} 1 \ 1 \end{bmatrix} \ &= rac{1}{\sqrt{2}} (|0
angle + |1
angle), & = rac{1}{\sqrt{2}} (|0
angle - |1
angle) \end{pmatrix}$$

$$|\psi\rangle = \alpha |0\rangle + \beta |1\rangle = \begin{bmatrix} \alpha \\ \beta \end{bmatrix}$$

for 
$$|\alpha|^2 + |\beta|^2 = 1$$
.

$$\langle \psi | = |\psi \rangle^{\dagger} = \alpha^* \langle 0 | + \beta^* \langle 1 | = \begin{bmatrix} \alpha^* & \beta^* \end{bmatrix}$$

### Pauli matrices in braket notation

$$Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \ket{0}\bra{0} - \ket{1}\bra{1}$$

$$X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \ket{+} \bra{+} - \ket{-} \bra{-}$$

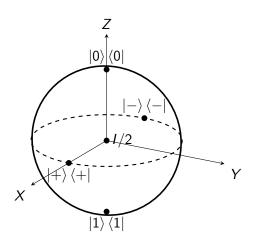
$$Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ i \end{bmatrix} \begin{bmatrix} 1 & -i \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ -i \end{bmatrix} \begin{bmatrix} 1 & i \end{bmatrix}$$

## Special states

$$\rho = \frac{1}{2} \left( I + r_X X + r_Y Y + r_Z Z \right)$$

Coordinate	State
[0, 0, 0]	$\frac{1}{2}I$
[1, 0, 0]	$\frac{1}{2}(I+X)=\ket{+}\bra{+}$
[-1, 0, 0]	$\frac{1}{2}(I-X)=\ket{-}\bra{-}$
[0, 0, 1]	$\frac{1}{2}(I+Z)=\ket{0}\bra{0}$
[0, 0, -1]	$rac{1}{2}(I-Z)=\ket{1}ra{1}$

# Special states in the Bloch sphere



### Pure states and state vector

#### $\rho$ is a pure state

$$\stackrel{\text{def}}{\Longleftrightarrow} \rho \neq p\rho_1 + (1-p)\rho_2 \quad \forall p \in [0,1] \text{ and states } \rho_1, \rho_2 \neq \rho$$
 
$$\iff \rho \text{ is at surface of the Bloch sphere}$$
 
$$\iff r_X^2 + r_Y^2 + r_Z^2 = 1$$
 
$$\iff \lambda_1 \lambda_2 = 0 \ \land \ \lambda_1 + \lambda_2 = 1$$
 
$$\iff \rho \text{ is rank-1 Hermitian with } \mathsf{Tr}(\rho) = 1$$
 
$$\iff \rho = |\psi\rangle \ \langle \psi| \text{ for some } |\psi\rangle \in \mathbb{C}^2 \text{ with } \langle \psi|\psi\rangle = 1$$

Pure state can be represented by a state vector  $|\psi\rangle\in\mathbb{C}^2$  with  $\langle\psi|\psi\rangle=1.$ 

$$|\psi\rangle$$
 and  $|\varphi\rangle:=\mathrm{e}^{i\theta}\,|\psi\rangle$  represent the same state since  $|\psi\rangle\,\langle\psi|=|\varphi\rangle\,\langle\varphi|.$ 

## Inner product of pure states

- $\rho$  is a qubit pure state with a coordinate  $(r_X, r_Y, r_Z)$ .
- $\sigma$  is a qubit pure state with a coordinate  $(-r_X, -r_Y, -r_Z)$ .

$$\operatorname{Tr}(\rho\sigma) = \operatorname{Tr}(\rho(I-\rho)) = \operatorname{Tr}(\rho) - \operatorname{Tr}(\rho^2) = 1 - 1 = 0$$

- $\rho = |\psi\rangle\langle\psi|$ .
- $\sigma = |\varphi\rangle\langle\varphi|$ .

$$\operatorname{Tr}(\rho\sigma) = \operatorname{Tr}(|\psi\rangle \langle \psi| |\varphi\rangle \langle \varphi|) = \langle \psi|\varphi\rangle \operatorname{Tr}(|\psi\rangle \langle \varphi|)$$
$$= \langle \psi|\varphi\rangle \langle \varphi|\psi\rangle = |\langle \psi|\varphi\rangle|^{2}$$

# Unitary operation

Unitary operation

$$ho\mapsto U
ho U^\dagger$$

It is easy to see that

- $\operatorname{Tr}(U\rho U^{\dagger})=1$
- $U\rho U^{\dagger} \succeq 0$

A pure state  $|\psi\rangle$  is mapped to a pure state  $U|\psi\rangle$ .

U and  $e^{i\theta}U$  play the same role.

# Examples of unitary operation

- The identity matrix 1.
- Pauli matrices X, Y and Z.

• Hadamard matrix 
$$H := \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

## Pauli matrices X on the Bloch sphere

$$\rho = \frac{1}{2} (I + r_X X + r_Y Y + r_Z Z)$$

$$X \rho X^{\dagger} = X \rho X = \frac{1}{2} (X^2 + r_X X^3 + r_Y X Y X + r_Z X Z X)$$

$$= \frac{1}{2} (I + r_X X - r_Y Y - r_Z Z)$$

$$[r_X r_Y r_Z] \xrightarrow{X} [r_X, -r_Y, -r_Z]$$

 $\pi$ -rotation with respect to X axis.

Similarly, Y and Z corresponds to  $\pi$ -rotation with respect to Y and Z axes, respectively.

#### Hadamard matrix

Hadamard matrix H is unitary and Hermitian.

$$\begin{split} H := \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} &= |+\rangle \langle 0| + |-\rangle \langle 1| \\ &= |0\rangle \langle +| + |1\rangle \langle -| \\ \\ |0\rangle , |1\rangle &\longleftrightarrow |+\rangle , |-\rangle \\ \\ HXH = H(|+\rangle \langle +| -|-\rangle \langle -|)H \\ &= |0\rangle \langle 0| - |1\rangle \langle 1| = Z \end{split}$$

Similarly, HZH = X.

## Hadamard matrix on the Bloch sphere

$$\rho = \frac{1}{2} \left( I + r_X X + r_Y Y + r_Z Z \right)$$

$$H\rho H^{\dagger} = H\rho H = \frac{1}{2} \left( H^2 + r_X HXH + r_Y HYH + r_Z HZH \right)$$
$$= \frac{1}{2} \left( I + r_X Z - r_Y Y + r_Z X \right)$$

$$[r_X r_Y r_Z] \xrightarrow{H} [r_Z, -r_Y, r_X]$$

Hadamard operation can be decomposed to  $\pi/2$ -rotation with respect to Y axis

$$[r_X r_Y r_Z] \stackrel{R_Y(\pi/2)}{\longmapsto} [-r_Z, r_Y, r_X]$$

and X.

## Multiplications of Pauli matrices

For any unitary matrices U and V, UV is also unitary matrix.

- XY = iZ
- YZ = iX
- ZX = iY

### Rotation matrices

$$R_{X}(\theta) := \cos \frac{\theta}{2} I - i \sin \frac{\theta}{2} X$$

$$R_{X}(\theta)^{\dagger} = R_{X}(-\theta)$$

$$R_{X}(\theta)R_{X}(\theta)^{\dagger} = (\cos \frac{\theta}{2} I - i \sin \frac{\theta}{2} X)(\cos \frac{\theta}{2} I + i \sin \frac{\theta}{2} X)$$

$$= \cos^{2} \frac{\theta}{2} I + \sin^{2} \frac{\theta}{2} X^{2} = I$$

$$R_{X}(\theta)X = XR_{X}(\theta), \quad R_{X}(\theta)Y = YR_{X}(-\theta), \quad R_{X}(\theta)Z = ZR_{X}(-\theta)$$

$$R_{X}(\theta)R_{X}(\tau) = R_{X}(\theta + \tau)$$

$$[100] \stackrel{R_{X}(\theta)}{\longmapsto} [100]$$

$$[010] \stackrel{R_{X}(\theta)}{\longmapsto} [0 \cos \theta \sin \theta]$$

$$[001] \stackrel{R_{X}(\theta)}{\longmapsto} [0 - \sin \theta \cos \theta]$$

## Assignments [Deadline is the next of next Friday]

• Show that 
$$R_Y(\theta) = \begin{bmatrix} \cos \frac{\theta}{2} & -i \sin \frac{\theta}{2} \\ \sin \frac{\theta}{2} & \cos \frac{\theta}{2} \end{bmatrix}$$
 and  $R_Z(\theta) = \begin{bmatrix} e^{-i\theta/2} & 0 \\ 0 & e^{i\theta/2} \end{bmatrix}$ .

• Show that for any  $2 \times 2$  unitary matrix, there exist  $\alpha$ ,  $\beta$ ,  $\gamma$ ,  $\delta \in \mathbb{R}$  such that

$$U = e^{i\alpha} R_Z(\beta) R_Y(\gamma) R_Z(\delta)$$

• [Advanced] For a real unit vector  $\hat{n} = [n_X n_Y n_Z]$ , let

$$R_{\hat{n}}(\theta) := \cos \frac{\theta}{2} I - i \sin \frac{\theta}{2} (n_X X + n_Y Y + n_Z Z).$$

Show that for any  $2 \times 2$  unitary matrix, there exist  $\alpha$ ,  $\theta \in \mathbb{R}$  and a real unit 3d vector  $\hat{n}$  such that  $U = e^{i\alpha}R_{\hat{n}}(\theta)$ .

## General $2 \times 2$ unitary matrices

 $\{I, X, Y, Z\}$  is a orthogonal basis of  $2 \times 2$  complex matrices.

$$U = \alpha_I I + \alpha_X X + \alpha_Y Y + \alpha_Z Z$$

for some  $\alpha_I$ ,  $\alpha_X$ ,  $\alpha_Y$ ,  $\alpha_Z \in \mathbb{C}$ .

$$UU^{\dagger} = (|\alpha_{I}|^{2} + |\alpha_{X}|^{2} + |\alpha_{Y}|^{2} + |\alpha_{Z}^{2}|)I$$

$$+ (\alpha_{I}\alpha_{X}^{*} + \alpha_{I}^{*}\alpha_{X} + i(\alpha_{Y}\alpha_{Z}^{*} - \alpha_{Z}\alpha_{Y}^{*}))X$$

$$+ (\alpha_{I}\alpha_{Y}^{*} + \alpha_{I}^{*}\alpha_{Y} + i(\alpha_{Z}\alpha_{X}^{*} - \alpha_{X}\alpha_{Z}^{*}))Y$$

$$+ (\alpha_{I}\alpha_{Z}^{*} + \alpha_{I}^{*}\alpha_{Z} + i(\alpha_{X}\alpha_{Y}^{*} - \alpha_{Y}\alpha_{X}^{*}))Z$$

$$Re(\alpha_I \alpha_X^*) = Im(\alpha_Y \alpha_Z^*)$$

$$Re(\alpha_I \alpha_Y^*) = Im(\alpha_Z \alpha_X^*)$$

$$Re(\alpha_I \alpha_Z^*) = Im(\alpha_X \alpha_Y^*)$$

### General rotation matrices

$$|\alpha_I|^2 + |\alpha_X|^2 + |\alpha_Y|^2 + |\alpha_Z^2| = 1$$

Assume  $\alpha_I$  is real.

$$\alpha_I \operatorname{Re}(\alpha_X) = \operatorname{Im}(\alpha_Y \alpha_Z^*)$$

$$\alpha_I \operatorname{Re}(\alpha_Y) = \operatorname{Im}(\alpha_Z \alpha_X^*)$$

$$\alpha_I \operatorname{Re}(\alpha_Z) = \operatorname{Im}(\alpha_X \alpha_Y^*)$$

With the direct calculation, we obtain  $\alpha_I^2(\text{Re}(\alpha_X)^2 + \text{Re}(\alpha_Y)^2 + \text{Re}(\alpha_Z)^2) = 0.$