# Part I

# A First Course on General Relativity

By studying General Relativity, I spotted my weakness of being too submerged in details and not being able to solve problems systematically and as a whole

A person being able to master GR has the best advantage in analyzing business and technical problems right, which is why I study GR and Physics in general (Sorry, Einstein)

# Chapter 1

# **Special Relativity**

# (Not discussed in book) Einstein's Original Paper on "General Relativity"

The original paper is in The Collected Papers of Albert Einstein, Vol.2, page 140, On the Electrodynamics of Moving Bodies

#### 1.0.1 Michelson–Morley experiment

• An excellent experiment intro

## On "Principle of relativity (Galileo)"

#### Galilean invariance

Newton's laws of motion hold in all frames related to one another by a Galilean transformation. In other words, all frames related to one another by such a transformation are inertial (meaning, Newton's equation of motion is valid in these frames). The proof has been given by the book on page 2.

## 1.5 - Construction of the coordinates used by another observer

## Why would the tangent of the angle is the speed in Fig. 1.2?

Suppose  $\mathcal{O}$  and  $\bar{\mathcal{O}}$  both start out at the same position where  $\bar{\mathcal{O}}$  moves along the x at some speed. After  $t_1$ , observer  $\mathcal{O}$  sees  $\bar{\mathcal{O}}$  at position  $x_1$ :

$$\bar{\mathcal{O}}_1 = (x_1, t_1)$$

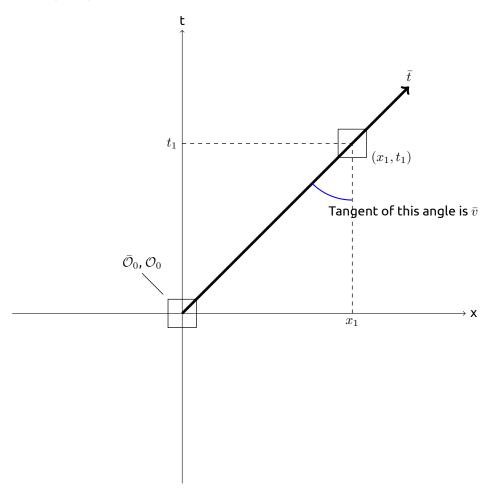
Observer  $\bar{\mathcal{O}}$ , however, still sees themself at x=0:

$$\bar{\mathcal{O}}_1 = (0, t_1)$$

<sup>&</sup>lt;sup>1</sup>Galilean invariance



By definition where " $\bar{t}$  is the locus of events at constant  $\bar{x}=0$ ",  $\bar{t}$  is the straight line that passes the origin and the  $(x_1,t_1)$ :



## 1.6 Invariance of the interval

Why  $(\Delta x)^2 + (\Delta y)^2 + (\Delta z)^2 - (\Delta t)^2 = 0$  for two events in the same light beam?

Let's say, in a simplified 1D case, event  $\mathcal{E} = (x_0, t_0)$  and  $\mathcal{P} = (x_1, t_1)$ .

$$(\Delta x)^2 - (\Delta t)^2 = (x_1 - x_0)^2 - (t_1 - t_0)^2$$

Since the speed of light is 1,

$$(x_1 - x_0)^2 - (t_1 - t_0)^2 = (x_1 - x_0)^2 - (t_1 \times 1 - t_0 \times 1)^2 = (x_1 - x_0)^2 - (x_1 - x_0)^2 = 0$$

Why does the equation contains only  $M_{\alpha\beta}+M_{\beta\alpha}$  terms when  $\alpha\neq\beta$ , which guarantees  $M_{\alpha\beta}=M_{\beta\alpha}$ ?

$$\Delta \bar{s}^2 = \sum_{\alpha=0}^{3} \sum_{\beta=0}^{3} \boldsymbol{M}_{\alpha\beta} \left( \Delta x^{\alpha} \right) \left( \Delta x^{\beta} \right)$$



Before spending too much time on expanding the equation, we can pick up a pair of indices of  $(\alpha, \beta) = (\alpha^*, \beta^*)$  where  $\alpha^* \neq \beta^*$ . Then we would definitely have the following 2 terms in the expansion:

$$M_{\alpha^*\beta^*} \left(\Delta x^{\alpha^*}\right) \left(\Delta x^{\beta^*}\right)$$
 $M_{\beta^*\alpha^*} \left(\Delta x^{\beta^*}\right) \left(\Delta x^{\alpha^*}\right)$ 

Since

$$\left(\Delta x^{\alpha^*}\right)\left(\Delta x^{\beta^*}\right) = \left(\Delta x^{\beta^*}\right)\left(\Delta x^{\alpha^*}\right)$$

We can then group these 2 terms and factor out the product, leaving

$$\left(\Delta x^{\alpha^*}\right)\left(\Delta x^{\beta^*}\right)\left(\boldsymbol{M}_{\alpha^*\beta^*}+\boldsymbol{M}_{\beta^*\alpha^*}\right)$$

The terms of expanded  $\Delta \bar{s}^2$  can be expressed in a matrix of

$$\begin{bmatrix} M_{00}\Delta x^0 \Delta x^0 & M_{01}\Delta x^0 \Delta x^1 & M_{02}\Delta x^0 \Delta x^2 & M_{03}\Delta x^0 \Delta x^3 \\ M_{10}\Delta x^1 \Delta x^0 & M_{11}\Delta x^1 \Delta x^1 & M_{12}\Delta x^1 \Delta x^2 & M_{13}\Delta x^1 \Delta x^3 \\ M_{20}\Delta x^2 \Delta x^0 & M_{21}\Delta x^2 \Delta x^1 & M_{22}\Delta x^2 \Delta x^2 & M_{23}\Delta x^2 \Delta x^3 \\ M_{30}\Delta x^3 \Delta x^0 & M_{31}\Delta x^3 \Delta x^1 & M_{32}\Delta x^3 \Delta x^2 & M_{33}\Delta x^3 \Delta x^3 \end{bmatrix}$$

Because the off-diagonal terms always appear in pairs above, we could effectively replace them with their mean value:

$$oldsymbol{M}_{lpha^*eta^*} = oldsymbol{M}_{eta^*lpha^*} = rac{(oldsymbol{M}_{lpha^*eta^*} + oldsymbol{M}_{eta^*lpha^*})}{2}$$

where  $\alpha^* \neq \beta^*$ . And since  $M_{\alpha\beta} = M_{\beta\alpha}$  if  $\alpha = \beta$ , we conclude that

$$oldsymbol{M}_{lphaeta} = oldsymbol{M}_{etalpha}$$
 for all  $lpha$  and  $eta$ 

#### Why do we have the 2nd term in equation

$$\Delta \bar{s}^2 = \boldsymbol{M}_{00} (\Delta r)^2 + \left[ 2 \left( \sum_{i=1}^3 \boldsymbol{M}_{0i} \Delta x^i \right) \Delta r \right] + \sum_{i=1}^3 \sum_{i=1}^3 \boldsymbol{M}_{ij} \Delta x^i \Delta x^j$$



$$\Delta \bar{s}^2 = \sum_{\alpha=0}^{3} \sum_{\beta=0}^{3} M_{\alpha\beta} \left( \Delta x^{\alpha} \right) \left( \Delta x^{\beta} \right) \tag{1.1}$$

$$=\sum_{\alpha=0}^{0}\sum_{\beta=0}^{3}\boldsymbol{M}_{\alpha\beta}\left(\Delta x^{\alpha}\right)\left(\Delta x^{\beta}\right)+\sum_{\alpha=0}^{3}\sum_{\beta=0}^{0}\boldsymbol{M}_{\alpha\beta}\left(\Delta x^{\alpha}\right)\left(\Delta x^{\beta}\right)+\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha\beta}\left(\Delta x^{\alpha}\right)\left(\Delta x^{\beta}\right)\tag{1.2}$$

$$=\sum_{\beta=0}^{3}\boldsymbol{M}_{0\beta}\Delta t\left(\Delta x^{\beta}\right)+\sum_{\alpha=0}^{3}\boldsymbol{M}_{\alpha 0}\left(\Delta x^{\alpha}\right)\Delta t+\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha \beta}\left(\Delta x^{\alpha}\right)\left(\Delta x^{\beta}\right)\tag{1.3}$$

$$=\boldsymbol{M}_{00}\left(\Delta t\right)^{2}+\sum_{\beta=1}^{3}\boldsymbol{M}_{0\beta}\Delta t\left(\Delta x^{\beta}\right)+\sum_{\alpha=1}^{3}\boldsymbol{M}_{\alpha0}\left(\Delta x^{\alpha}\right)\Delta t+\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha\beta}\left(\Delta x^{\alpha}\right)\left(\Delta x^{\beta}\right)\tag{1.4}$$

$$= \boldsymbol{M}_{00} \left(\Delta t\right)^{2} + \left[2\left[\sum_{i=1}^{3} \boldsymbol{M}_{0i} \Delta t \left(\Delta x^{i}\right)\right]\right] + \sum_{\alpha=1}^{3} \sum_{\beta=1}^{3} \boldsymbol{M}_{\alpha\beta} \left(\Delta x^{\alpha}\right) \left(\Delta x^{\beta}\right)$$
(1.5)

Why would  $m{M}_{0i}=0$  for i=1,2,3 and  $m{M}_{ij}=-m{M}_{00}\delta_{ij}$  in Equation 1.5?

The answer is: **not necessarily**. We are probably looking at a wrong problem.

The solution to exercise 1.8 takes  $\Delta x_1 = -\Delta x_2$  to simplify the equation 1.10. This is not sufficient, because what if  $\Delta x_1 \neq -\Delta x_2$ ? This box takes a general approach where we **do** not assume any relationship between  $\Delta x_1$  and  $\Delta x_2$ 

Note that this statement is based on the aforementioned assumption that  $\Delta \bar{s}^2 = \Delta s^2 = 0$ , which has been proved here. Therefore, by 1.5, we have

$$\Delta \bar{s}^2(\Delta t, \Delta x_1) - \Delta \bar{s}^2(\Delta t, \Delta x_2) \tag{1.6}$$

$$= \boldsymbol{M}_{00} \left(\Delta t\right)^{2} + 2 \left[\sum_{i=1}^{3} \boldsymbol{M}_{0i} \Delta t \left(\Delta x^{i}\right)\right] + \sum_{\alpha=1}^{3} \sum_{\beta=1}^{3} \boldsymbol{M}_{\alpha\beta} \left(\Delta x^{\alpha}\right) \left(\Delta x^{\beta}\right)$$

$$(1.7)$$

$$=2\left[\sum_{i=1}^{3}\boldsymbol{M}_{0i}\Delta t\left(\Delta x_{1}^{i}\right)\right]+\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha\beta}\left(\Delta x_{1}^{\alpha}\right)\left(\Delta x_{1}^{\beta}\right)-$$

$$2\left[\sum_{i=1}^{3} \boldsymbol{M}_{0i} \Delta t \left(\Delta x_{2}^{i}\right)\right] - \sum_{\alpha=1}^{3} \sum_{\beta=1}^{3} \boldsymbol{M}_{\alpha\beta} \left(\Delta x_{2}^{\alpha}\right) \left(\Delta x_{2}^{\beta}\right)$$

$$(1.8)$$

$$=\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha\beta}\left(\Delta x_{1}^{\alpha}\right)\left(\Delta x_{1}^{\beta}\right)-\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha\beta}\left(\Delta x_{2}^{\alpha}\right)\left(\Delta x_{2}^{\beta}\right)+$$

$$2\left[\sum_{i=1}^{3} \boldsymbol{M}_{0i} \Delta t \left(\Delta x_{1}^{i}\right)\right] - 2\left[\sum_{i=1}^{3} \boldsymbol{M}_{0i} \Delta t \left(\Delta x_{2}^{i}\right)\right]$$
(1.9)

$$=\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha\beta}\left[\left(\Delta x_{1}^{\alpha}\right)\left(\Delta x_{1}^{\beta}\right)-\left(\Delta x_{2}^{\alpha}\right)\left(\Delta x_{2}^{\beta}\right)\right]+2\left[\sum_{i=1}^{3}\boldsymbol{M}_{0i}\Delta t\left(\Delta x_{1}^{i}-\Delta x_{2}^{i}\right)\right]=0\tag{1.10}$$

We won't be able to go further unless with some assumed relationships between  $\Delta x_1^i$  and  $\Delta x_2^i$ . But since we do not assume any relations between them, let's step back and re-think about this



problem then and forget about  $\Delta x_1^i$  and  $\Delta x_2^i$ .

We go through all these for the proof of invariance of the interval. This is to work out a relation between  $\Delta s^2$  and  $\Delta \bar{s}^2$ . The detail is about  $\Delta x_1^i$  and  $\Delta x_2^i$  but the goal is to derive some form of

$$\Delta \bar{s}^2 = f\left(\Delta s^2\right) = \sum_{\alpha=0}^{3} \sum_{\beta=0}^{3} \boldsymbol{M}_{\alpha\beta} \left(\Delta x^{\alpha}\right) \left(\Delta x^{\beta}\right)$$

where

$$\Delta s^2 = -(\Delta t)^2 + \sum_{i=1}^{3} (\Delta x^i)^2$$

Let's work on  $f(\Delta s^2)$  directly toward that goal then

Assuming  $\Delta \bar{s}^2 = \Delta s^2 = 0$ , we have  $\Delta t = \pm \Delta x$ ; plugging it into Eq. 1.5 gives us

$$\Delta \bar{s}^{2} = M_{00} \sum_{i=1}^{3} (\Delta x^{i})^{2} + 2 \left[ \sum_{i=1}^{3} M_{0i} (\Delta x^{i})^{2} \right] + \sum_{\alpha=1}^{3} \sum_{\beta=1}^{3} M_{\alpha\beta} (\Delta x^{\alpha}) (\Delta x^{\beta})$$
(1.11)

$$= \left(\boldsymbol{M}_{00} + 2\boldsymbol{M}_{0i}\right) \sum_{i=1}^{3} \left(\Delta x^{i}\right)^{2} + \sum_{\alpha=1}^{3} \sum_{\beta=1}^{3} \boldsymbol{M}_{\alpha\beta} \left(\Delta x^{\alpha}\right) \left(\Delta x^{\beta}\right)$$
(1.12)

Eq.1.12 seems to suggest a linear relationship between  $\Delta s^2$  and  $\Delta \bar{s}^2$ . How do we go about proving it? We now start the formal proof of **Invariance of Interval** 

#### Theorem 1.0.1

Let  $n,p\geq 1$  be integers, d:=n+p and V a vector space over  $\mathbb R$  of dimension d. Let h be an indefinite-inner product a on A with signature type  $(n,p)^b$ . Suppose a is a symmetric bilinear form on A such that the null set of the associated quadratic form of a is contained in that of a (i.e. suppose that for every a0 if a1 if a2 if a3 if a4 is a constant a5 if a6 if a6 if a8 such that a7 if we assume a8 and that a8 also has signature type a8 in the a9 in th

<sup>&</sup>lt;sup>a</sup>Start with page 447 of Introduction to Linear Algebra, 4th Edition for everything you need to know about indefiniteinner product

<sup>&</sup>lt;sup>b</sup>Read Ch. 6 of Introduction to Linear Algebra, 4th Edition and then Matrix Signature