Part I

A First Course on General Relativity

By studying General Relativity, I spotted my weakness of being too submerged in details and not being able to solve problems systematically and as a whole

A person being able to master GR has the best advantage in analyzing business and technical problems right, which is why I study GR and Physics in general (Sorry, Einstein)

Chapter 1

Special Relativity

On "Principle of relativity (Galileo)"

Galilean invariance

Newton's laws of motion hold in all frames related to one another by a Galilean transformation. In other words, all frames related to one another by such a transformation are inertial (meaning, Newton's equation of motion is valid in these frames). The proof has been given by the book on page 2.

1.5 - Construction of the coordinates used by another observer

Why would the tangent of the angle is the speed in Fig. 1.2?

Suppose \mathcal{O} and $\bar{\mathcal{O}}$ both start out at the same position where $\bar{\mathcal{O}}$ moves along the x at some speed. After t_1 , observer \mathcal{O} sees $\bar{\mathcal{O}}$ at position x_1 :

$$\bar{\mathcal{O}}_1 = (x_1, t_1)$$

Observer $\bar{\mathcal{O}}$, however, still sees themself at x=0:

$$\bar{\mathcal{O}}_1 = (0, t_1)$$

By definition where " \bar{t} is the locus of events at constant $\bar{x}=0$ ", \bar{t} is the straight line that passes the origin and the (x_1,t_1) :

¹Galilean invariance





1.6 Invariance of the interval

Why $(\Delta x)^2 + (\Delta y)^2 + (\Delta z)^2 - (\Delta t)^2 = 0$ for two events in the same light beam?

Let's say, in a simplified 1D case, event $\mathcal{E}=(x_0,t_0)$ and $\mathcal{P}=(x_1,t_1)$.

$$(\Delta x)^2 - (\Delta t)^2 = (x_1 - x_0)^2 - (t_1 - t_0)^2$$

Since the speed of light is 1,

$$(x_1 - x_0)^2 - (t_1 - t_0)^2 = (x_1 - x_0)^2 - (t_1 \times 1 - t_0 \times 1)^2 = (x_1 - x_0)^2 - (x_1 - x_0)^2 = 0$$

Why does the equation contains only $M_{\alpha\beta}+M_{\beta\alpha}$ terms when $\alpha\neq\beta$, which guarantees $M_{\alpha\beta}=M_{\beta\alpha}$?

$$\Delta \bar{s}^2 = \sum_{\alpha=0}^{3} \sum_{\beta=0}^{3} \boldsymbol{M}_{\alpha\beta} \left(\Delta x^{\alpha} \right) \left(\Delta x^{\beta} \right)$$

Before spending too much time on expanding the equation, we can pick up a pair of indices of $(\alpha, \beta) = (\alpha^*, \beta^*)$ where $\alpha^* \neq \beta^*$. Then we would definitely have the following 2 terms in the expansion:



$$\boldsymbol{M}_{\alpha^*\beta^*} \left(\Delta x^{\alpha^*}\right) \left(\Delta x^{\beta^*}\right)$$

$$\boldsymbol{M}_{\beta^*\alpha^*} \left(\Delta x^{\beta^*}\right) \left(\Delta x^{\alpha^*}\right)$$

Since

$$\left(\Delta x^{\alpha^*}\right)\left(\Delta x^{\beta^*}\right) = \left(\Delta x^{\beta^*}\right)\left(\Delta x^{\alpha^*}\right)$$

We can then group these 2 terms and factor out the product, leaving

$$\left(\Delta x^{\alpha^*}\right)\left(\Delta x^{\beta^*}\right)\left(\boldsymbol{M}_{\alpha^*\beta^*}+\boldsymbol{M}_{\beta^*\alpha^*}\right)$$

The terms of expanded $\Delta \bar{s}^2$ can be expressed in a matrix of

$$\begin{bmatrix} \boldsymbol{M}_{00} \Delta x^0 \Delta x^0 & \boldsymbol{M}_{01} \Delta x^0 \Delta x^1 & \boldsymbol{M}_{02} \Delta x^0 \Delta x^2 & \boldsymbol{M}_{03} \Delta x^0 \Delta x^3 \\ \boldsymbol{M}_{10} \Delta x^1 \Delta x^0 & \boldsymbol{M}_{11} \Delta x^1 \Delta x^1 & \boldsymbol{M}_{12} \Delta x^1 \Delta x^2 & \boldsymbol{M}_{13} \Delta x^1 \Delta x^3 \\ \boldsymbol{M}_{20} \Delta x^2 \Delta x^0 & \boldsymbol{M}_{21} \Delta x^2 \Delta x^1 & \boldsymbol{M}_{22} \Delta x^2 \Delta x^2 & \boldsymbol{M}_{23} \Delta x^2 \Delta x^3 \\ \boldsymbol{M}_{30} \Delta x^3 \Delta x^0 & \boldsymbol{M}_{31} \Delta x^3 \Delta x^1 & \boldsymbol{M}_{32} \Delta x^3 \Delta x^2 & \boldsymbol{M}_{33} \Delta x^3 \Delta x^3 \end{bmatrix}$$

Because the off-diagonal terms always appear in pairs above, we could effectively replace them with their mean value:

$$oldsymbol{M}_{lpha^*eta^*} = oldsymbol{M}_{eta^*lpha^*} = rac{(oldsymbol{M}_{lpha^*eta^*} + oldsymbol{M}_{eta^*lpha^*})}{2}$$

where $\alpha^* \neq \beta^*$. And since $M_{\alpha\beta} = M_{\beta\alpha}$ if $\alpha = \beta$, we conclude that

$$\boldsymbol{M}_{\alpha\beta} = \boldsymbol{M}_{\beta\alpha}$$
 for all α and β

Why do we have the 2nd term in equation

$$\Delta \bar{s}^2 = \boldsymbol{M}_{00} (\Delta r)^2 + \left[2 \left(\sum_{i=1}^3 \boldsymbol{M}_{0i} \Delta x^i \right) \Delta r \right] + \sum_{i=1}^3 \sum_{i=1}^3 \boldsymbol{M}_{ij} \Delta x^i \Delta x^j$$



$$\Delta \bar{s}^2 = \sum_{\alpha=0}^{3} \sum_{\beta=0}^{3} M_{\alpha\beta} \left(\Delta x^{\alpha} \right) \left(\Delta x^{\beta} \right) \tag{1.1}$$

$$=\sum_{\alpha=0}^{0}\sum_{\beta=0}^{3}\boldsymbol{M}_{\alpha\beta}\left(\Delta x^{\alpha}\right)\left(\Delta x^{\beta}\right)+\sum_{\alpha=0}^{3}\sum_{\beta=0}^{0}\boldsymbol{M}_{\alpha\beta}\left(\Delta x^{\alpha}\right)\left(\Delta x^{\beta}\right)+\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha\beta}\left(\Delta x^{\alpha}\right)\left(\Delta x^{\beta}\right)\tag{1.2}$$

$$=\sum_{\beta=0}^{3}\boldsymbol{M}_{0\beta}\Delta t\left(\Delta x^{\beta}\right)+\sum_{\alpha=0}^{3}\boldsymbol{M}_{\alpha 0}\left(\Delta x^{\alpha}\right)\Delta t+\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha \beta}\left(\Delta x^{\alpha}\right)\left(\Delta x^{\beta}\right)\tag{1.3}$$

$$= \boldsymbol{M}_{00} \left(\Delta t\right)^{2} + \sum_{\beta=1}^{3} \boldsymbol{M}_{0\beta} \Delta t \left(\Delta x^{\beta}\right) + \sum_{\alpha=1}^{3} \boldsymbol{M}_{\alpha0} \left(\Delta x^{\alpha}\right) \Delta t + \sum_{\alpha=1}^{3} \sum_{\beta=1}^{3} \boldsymbol{M}_{\alpha\beta} \left(\Delta x^{\alpha}\right) \left(\Delta x^{\beta}\right)$$
(1.4)

$$= \boldsymbol{M}_{00} \left(\Delta t\right)^{2} + \left[2\left[\sum_{i=1}^{3} \boldsymbol{M}_{0i} \Delta t \left(\Delta x^{i}\right)\right]\right] + \sum_{\alpha=1}^{3} \sum_{\beta=1}^{3} \boldsymbol{M}_{\alpha\beta} \left(\Delta x^{\alpha}\right) \left(\Delta x^{\beta}\right)$$
(1.5)

Why would $m{M}_{0i}=0$ for i=1,2,3 and $m{M}_{ij}=-m{M}_{00}\delta_{ij}$ in Equation 1.57

The answer is: **not necessarily**. We are probably looking at a wrong problem.

The solution to exercise 1.8 takes $\Delta x_1 = -\Delta x_2$ to simplify the equation 1.10. This is not sufficient! What if $\Delta x_1 \neq -\Delta x_2$? This box takes a general approach where we **do not assume any relationship between** Δx_1 **and** Δx_2

Note that this statement is based on the aforementioned assumption that $\Delta \bar{s}^2 = \Delta s^2 = 0$, which has been proved here. Therefore, by 1.5, we have

$$\Delta \bar{s}^2(\Delta t, \Delta x_1) - \Delta \bar{s}^2(\Delta t, \Delta x_2)$$
 (1.6)

$$= \boldsymbol{M}_{00} \left(\Delta t\right)^{2} + 2 \left[\sum_{i=1}^{3} \boldsymbol{M}_{0i} \Delta t \left(\Delta x^{i}\right)\right] + \sum_{\alpha=1}^{3} \sum_{\beta=1}^{3} \boldsymbol{M}_{\alpha\beta} \left(\Delta x^{\alpha}\right) \left(\Delta x^{\beta}\right)$$

$$(1.7)$$

$$=2\left[\sum_{i=1}^{3}\boldsymbol{M}_{0i}\Delta t\left(\Delta x_{1}^{i}\right)\right]+\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha\beta}\left(\Delta x_{1}^{\alpha}\right)\left(\Delta x_{1}^{\beta}\right)-$$

$$2\left[\sum_{i=1}^{3} \boldsymbol{M}_{0i} \Delta t \left(\Delta x_{2}^{i}\right)\right] - \sum_{\alpha=1}^{3} \sum_{\beta=1}^{3} \boldsymbol{M}_{\alpha\beta} \left(\Delta x_{2}^{\alpha}\right) \left(\Delta x_{2}^{\beta}\right)$$

$$(1.8)$$

$$=\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha\beta}\left(\Delta x_{1}^{\alpha}\right)\left(\Delta x_{1}^{\beta}\right)-\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha\beta}\left(\Delta x_{2}^{\alpha}\right)\left(\Delta x_{2}^{\beta}\right)+$$

$$2\left[\sum_{i=1}^{3} \boldsymbol{M}_{0i} \Delta t \left(\Delta x_{1}^{i}\right)\right] - 2\left[\sum_{i=1}^{3} \boldsymbol{M}_{0i} \Delta t \left(\Delta x_{2}^{i}\right)\right]$$
(1.9)

$$=\sum_{\alpha=1}^{3}\sum_{\beta=1}^{3}\boldsymbol{M}_{\alpha\beta}\left[\left(\Delta x_{1}^{\alpha}\right)\left(\Delta x_{1}^{\beta}\right)-\left(\Delta x_{2}^{\alpha}\right)\left(\Delta x_{2}^{\beta}\right)\right]+2\left[\sum_{i=1}^{3}\boldsymbol{M}_{0i}\Delta t\left(\Delta x_{1}^{i}-\Delta x_{2}^{i}\right)\right]=0\tag{1.10}$$

We won't be able to go further unless with some assumed relationships between Δx_1^i and Δx_2^i . But since we do not assume any relations between them, let's step back and re-think about this



problem then and forget about Δx_1^i and Δx_2^i .

We go through all these for the proof of invariance of the interval. This is to work out a relation between Δs^2 and $\Delta \bar{s}^2$. The detail is about Δx_1^i and Δx_2^i but the goal is to derive some form of

$$\Delta \bar{s}^2 = f\left(\Delta s^2\right) = \sum_{\alpha=0}^{3} \sum_{\beta=0}^{3} \boldsymbol{M}_{\alpha\beta} \left(\Delta x^{\alpha}\right) \left(\Delta x^{\beta}\right)$$

where

$$\Delta s^2 = -(\Delta t)^2 + \sum_{i=1}^{3} (\Delta x^i)^2$$

Let's work on $f(\Delta s^2)$ directly toward that goal then

Assuming $\Delta \bar{s}^2 = \Delta s^2 = 0$, we have $\Delta t = \pm \Delta x$; plugging it into Eq. 1.5 gives us

$$\Delta \bar{s}^{2} = M_{00} \sum_{i=1}^{3} (\Delta x^{i})^{2} + 2 \left[\sum_{i=1}^{3} M_{0i} (\Delta x^{i})^{2} \right] + \sum_{\alpha=1}^{3} \sum_{\beta=1}^{3} M_{\alpha\beta} (\Delta x^{\alpha}) (\Delta x^{\beta})$$
(1.11)

$$= (M_{00} + 2M_{0i}) \sum_{i=1}^{3} (\Delta x^{i})^{2} + \sum_{\alpha=1}^{3} \sum_{\beta=1}^{3} M_{\alpha\beta} (\Delta x^{\alpha}) (\Delta x^{\beta})$$
(1.12)

Eq.1.12 seems to suggest a linear relationship between Δs^2 and $\Delta \bar{s}^2$. How do we go about proving it? We now start the formal proof of **Invariance of Interval**

Theorem 1.0.1

Let $n,p\geq 1$ be integers, d:=n+p and V a vector space over $\mathbb R$ of dimension d. Let h be an indefinite-inner product a on V with signature type (n,p). Suppose g is a symmetric bilinear form on V such that the null set of the associated quadratic form of h is contained in that of g (i.e. suppose that for every $v\in V$, if h(v,v)=0 then g(v,v)=0). Then, there exists a constant $C\in \mathbb R$ such that g=Ch. Futhermore, if we assume $n\neq p$ and that g also has signature type (n,p), then we have C>0

^aIndefinite Linear Algebra and Applications