view_frames Result Recorded at time: 1654243327.042 odom map Broadcaster: /static_transform_publisher_1654243079733442111 Average rate: 58.943 Hz Most recent transform: 1654243327.132 (-0.090 sec old) Buffer length: 5.039 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 38.085 Hz Average rate: 10000.000 Hz Average rate: 38.085 Hz Average rate: 38.085 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 1654243327.025 (0.018 sec old) Most recent transform: 0.000 (1654243327.042 sec old) Most recent transform: 0.000 (1654243327.042 sec old) Most recent transform: 0.000 (1654243327.042 sec old) Most recent transform: 1654243327.025 (0.018 sec old) Most recent transform: 1654243327.025 (0.018 sec old) Buffer length: 4.910 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.910 sec Buffer length: 4.910 sec torso_lift_link torso_fixed_link l_wheel_link laser_link r_wheel_link estop_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 38.085 Hz Average rate: 10000.000 Hz Average rate: 38.085 Hz Average rate: 38.085 Hz Most recent transform: 1654243327.025 (0.018 sec old) Most recent transform: 1654243327.025 (0.018 sec old) Most recent transform: 1654243327.025 (0.018 sec old) Most recent transform: 0.000 (1654243327.042 sec old) Buffer length: 0.000 sec Buffer length: 4.910 sec Buffer length: 4.910 sec Buffer length: 4.910 sec head_pan_link bellows_link shoulder_pan_link bellows_link2 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 38.085 Hz Average rate: 38.085 Hz Most recent transform: 1654243327.025 (0.018 sec old) Most recent transform: 1654243327.025 (0.018 sec old) Buffer length: 4.910 sec Buffer length: 4.910 sec head_tilt_link shoulder_lift_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 38.085 Hz Most recent transform: 1654243327.025 (0.018 sec old) Most recent transform: 0.000 (1654243327.042 sec old) Buffer length: 0.000 sec Buffer length: 4.910 sec upperarm_roll_link head_camera_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 38.085 Hz Most recent transform: 1654243327.025 (0.018 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.910 sec head_camera_rgb_frame elbow_flex_link head_camera_depth_frame Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 38.085 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1654243327.042 sec old) Most recent transform: 0.000 (1654243327.042 sec old) Most recent transform: 1654243327.025 (0.018 sec old) Buffer length: 0.000 sec Buffer length: 4.910 sec Buffer length: 0.000 sec forearm_roll_link head_camera_depth_optical_frame head_camera_rgb_optical_frame Broadcaster: /robot_state_publisher Broadcaster: /ar_track_alvar Average rate: 8.020 Hz Average rate: 38.085 Hz Most recent transform: 1654243327.025 (0.018 sec old) Most recent transform: 1654243326.765 (0.277 sec old) Buffer length: 4.738 sec Buffer length: 4.910 sec ar_marker_1 wrist_flex_link Broadcaster: /robot_state_publisher Average rate: 38.085 Hz Most recent transform: 1654243327.025 (0.018 sec old) Buffer length: 4.910 sec wrist_roll_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1654243327.042 sec old) Buffer length: 0.000 sec gripper_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 38.368 Hz Average rate: 38.368 Hz Most recent transform: 1654243326.996 (0.046 sec old) Most recent transform: 1654243326.996 (0.046 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec r_gripper_finger_link l_gripper_finger_link