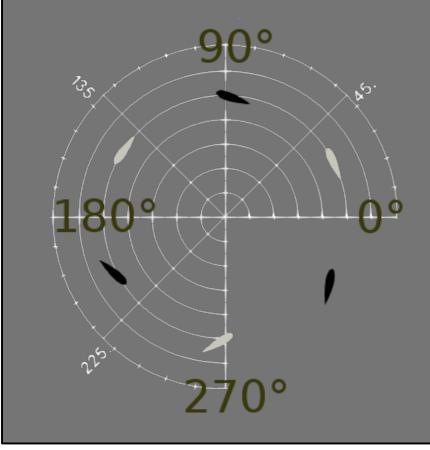
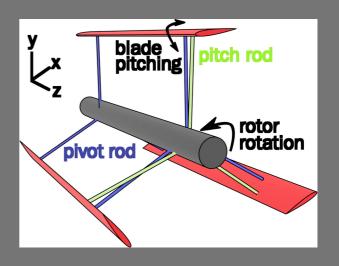


### THE TESTCASE

- Reynolds ~ 100.000
- Mach < 0,3





$$\theta = \theta_o + \theta_s \sin(\omega t)$$

 $\theta$ : local pitch angle

 $\theta_o$ : top/bottom diff, 6°

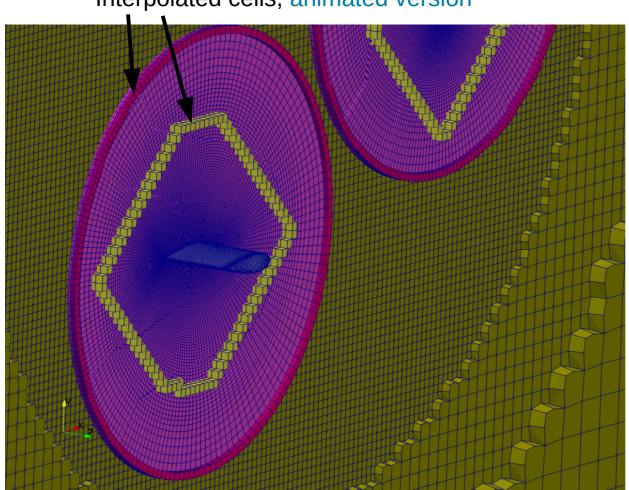
 $\theta_s$ : pitch magnitude, 25°

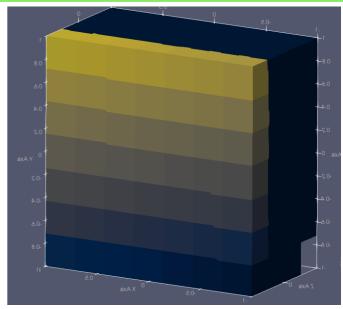
 $\omega$ : rotor vel., 18.67 rad/s

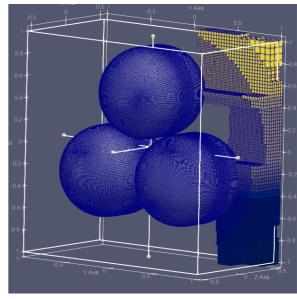
t: time. starting at  $0^{\circ}$ 

# MESH AND PROCESSOR DISTRIBUTION

Interpolated cells, animated version







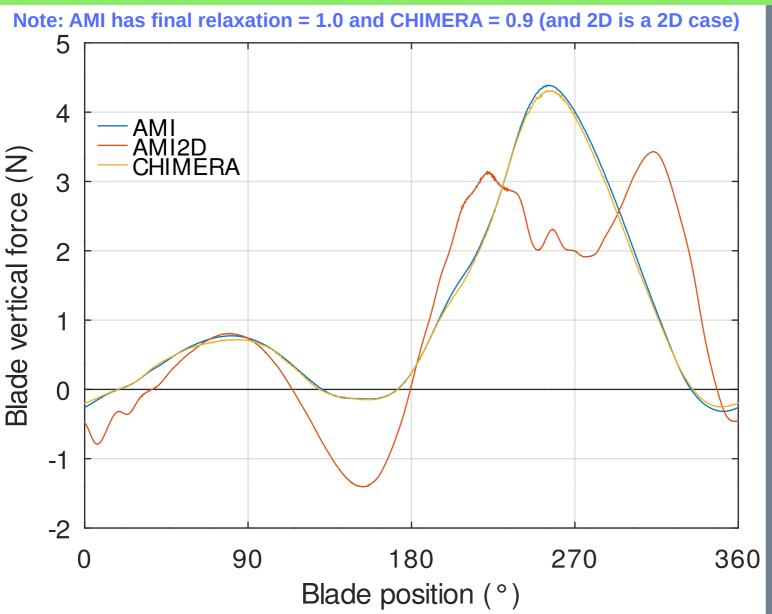
related prior code modifications: https://develop.openfoam.com/Development/openfoam/-/issues/2106

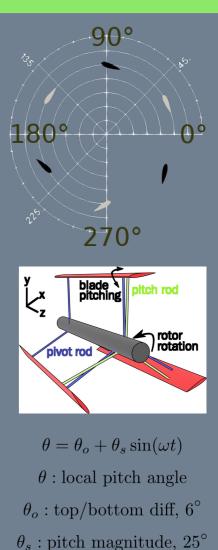
## **OVERSET COMPARISON**

Method	Time for Overset alone per timestep (seconds)
cellVolumeWeight	<b>116</b> – 117
cellVolumeWeight with the splitted decomposition method (i.e.: myDecomposePar)	9 – 11
inverseDistance with the splitted decomposition method and the modified search code	2 – 3 (and 4 – 5 for complete timestep)

3.2 Million cells, 512 Processors, 1/3 Processor-Usage, 0.5° rotation per timestep, Hawk

# RESULTATE - KRÄFTE

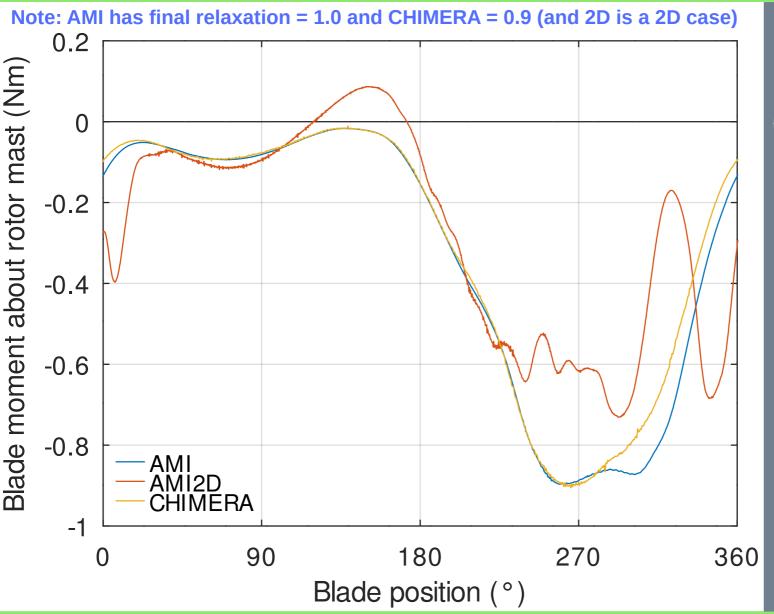


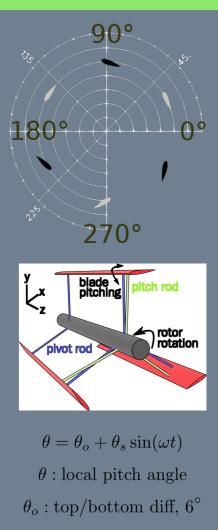


 $\omega$ : rotor vel., 18.67 rad/s

t: time. starting at  $0^{\circ}$ 

#### RESULTATE - LEISTUNG





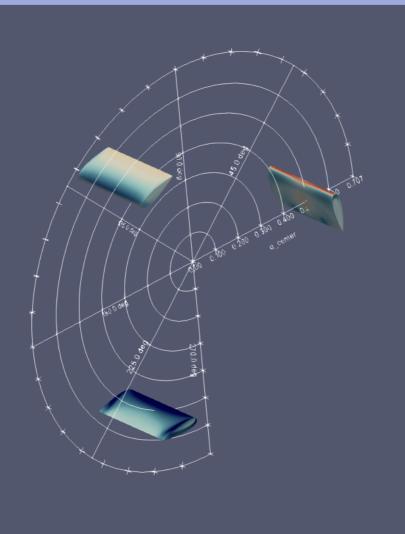
 $\theta_s$ : pitch magnitude,  $25^{\circ}$ 

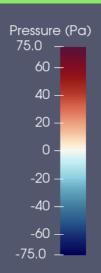
 $\omega$ : rotor vel., 18.67 rad/s

t: time. starting at  $0^{\circ}$ 

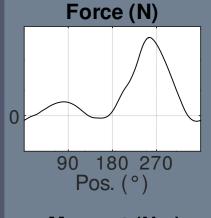
### THE TESTCASE VIDEO

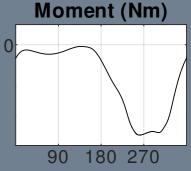
Video: here: http://louisgagnon.com/scBlog/rotor3DCFD.html or directly on YouTube: https://youtu.be/q0pafX63\_x0











Angle: 5.0°





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http://louisgagnon.com/research

**Louis Gagnon**