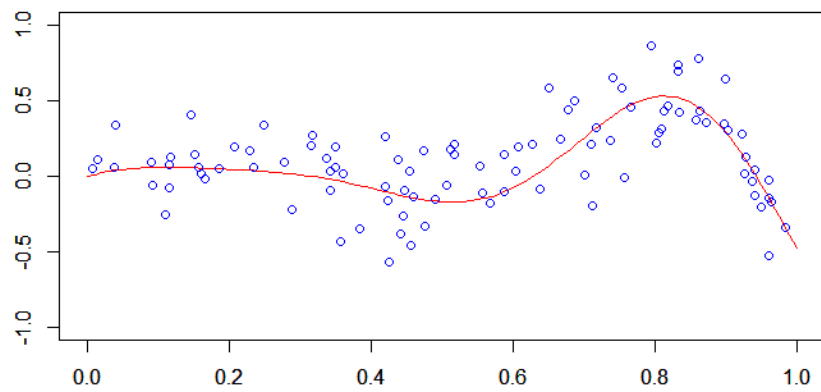
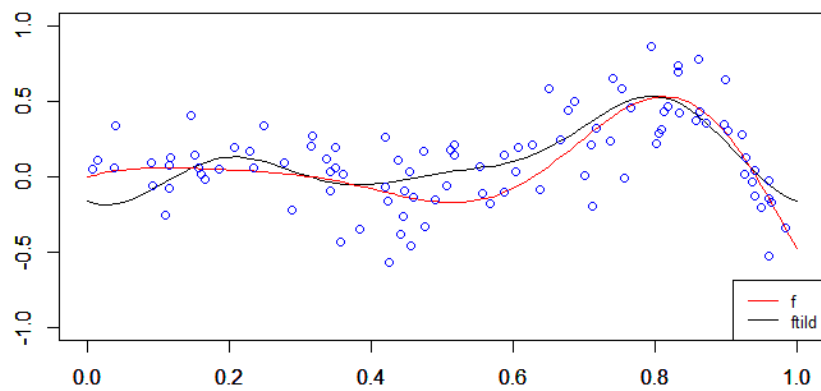


Annexe :

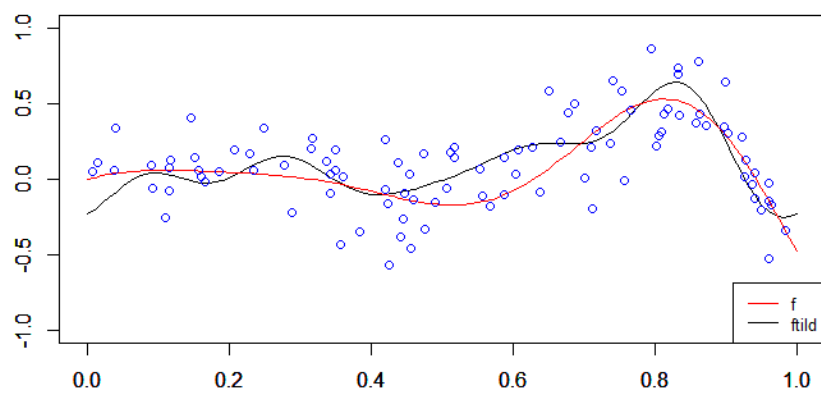
Gr1 : Nuage de points et f



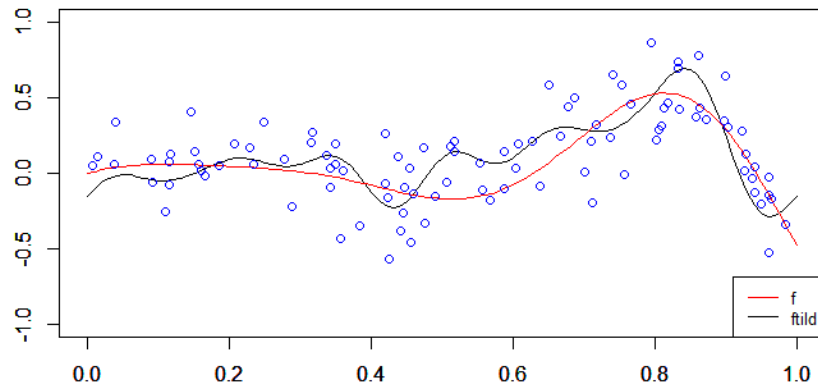
Gr2 : Nuage de points, f et estimateur f_{tild} (N=5)



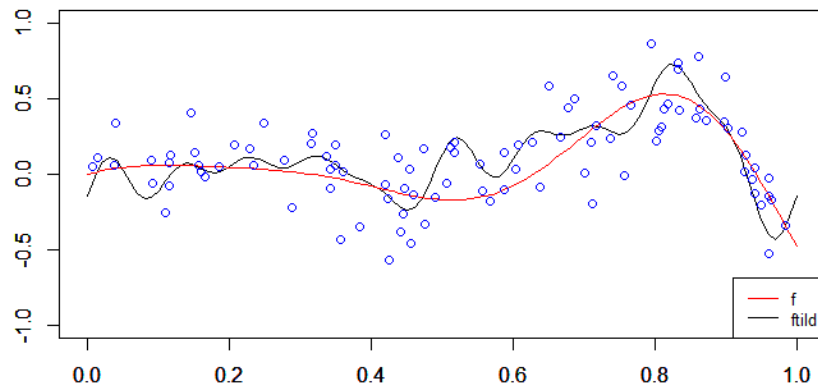
Gr3 : Nuage de points, f et estimateur f_{tild} (N=10)



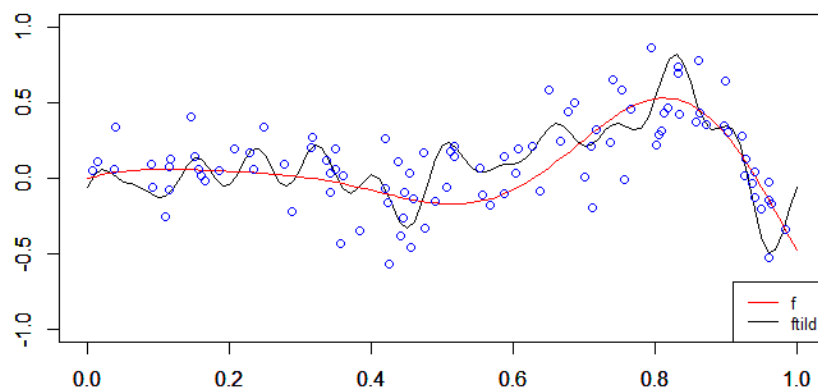
Gr4 : Nuage de points, f et estimateur f_{tild} (N=15)



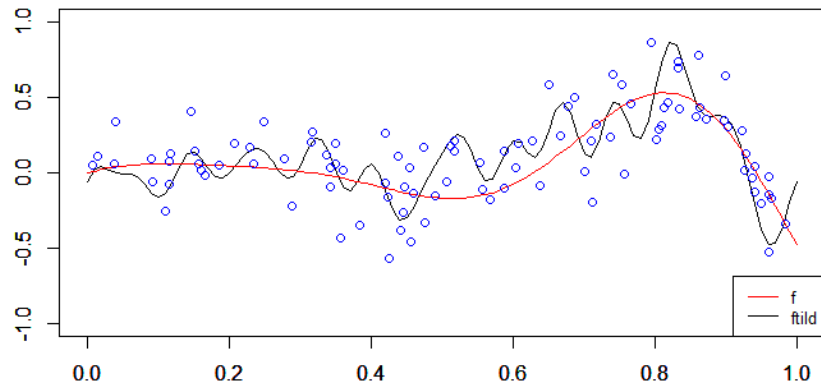
Gr5 : Nuage de points, f et estimateur f_{tild} (N=20)



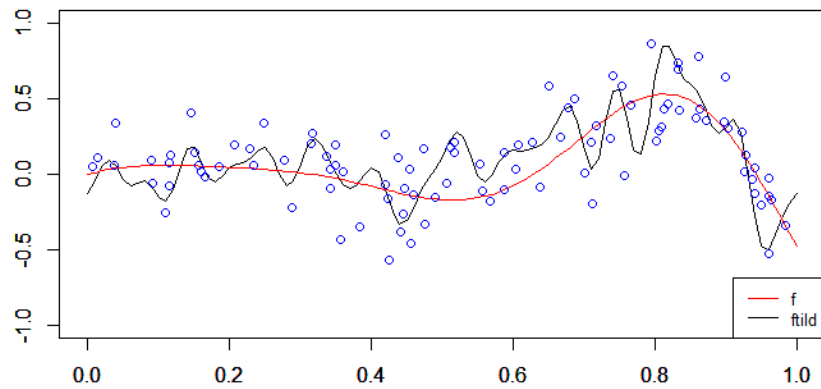
Gr6 : Nuage de points, f et estimateur f_{tild} (N=25)



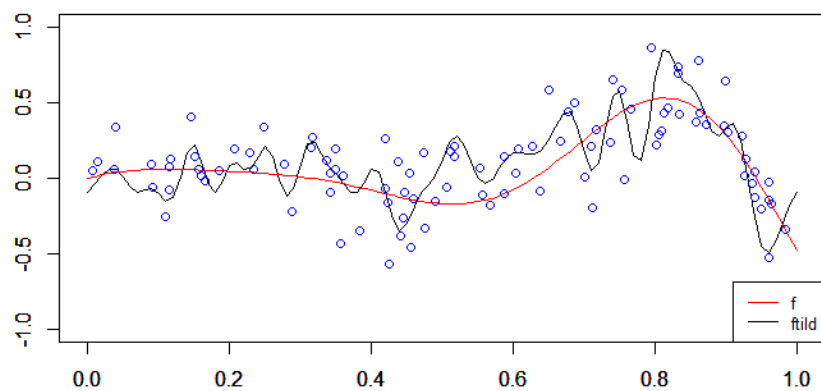
Gr7 : Nuage de points, f et estimateur f_{tild} (N=30)



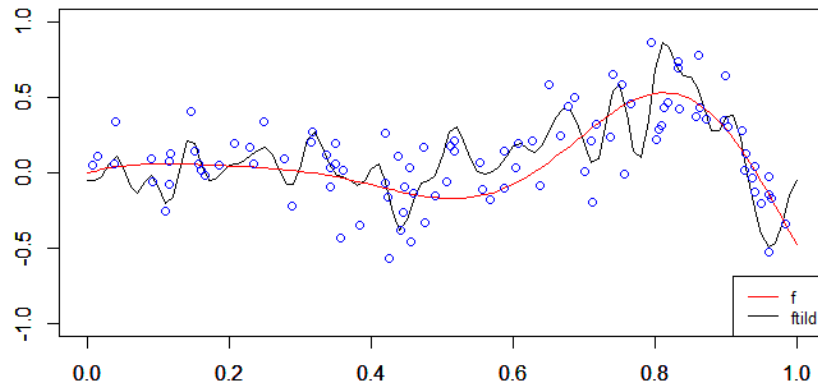
Gr8 : Nuage de points, f et estimateur f_{tild} (N=35)



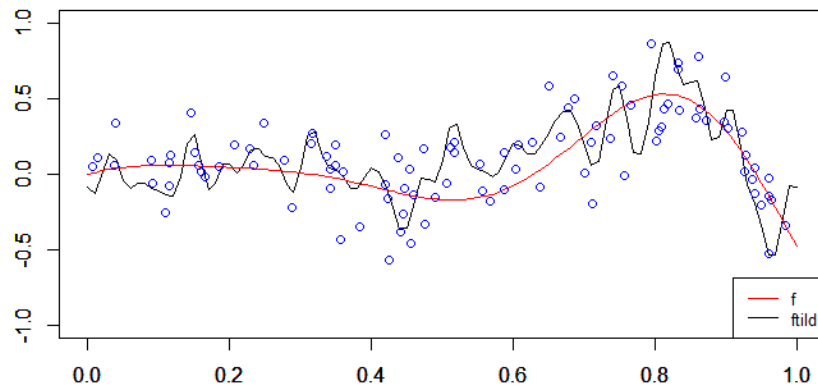
Gr9 : Nuage de points, f et estimateur f_{tild} (N=40)



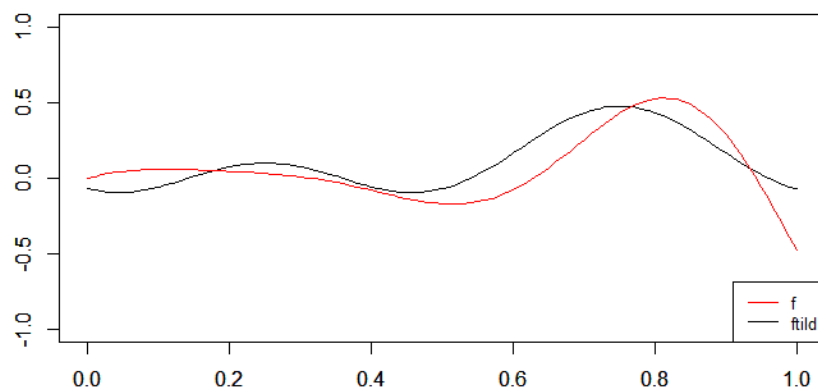
Gr10 : Nuage de points, f et estimateur f_{tild} (N=45)



Gr11 : Nuage de points, f et estimateur f_{tild} (N=50)



Gr12 : f et estimateur f_{tild} (N=Nch)



Répartition de Nch

