GPIO FPGA IP

Revision: 1.00

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1 Theory of Operation

The GPIO IP module allows software running on the S3's M4 microprocessor to control up to 32 individual GPIO's (General-Purpose I/O's). Each of the GPIO's may be mapped to device pins. Each GPIO may be designated as an input or output, and data can be read from, or written to, each I/O pin via control registers. The control registers are connected to the Wishbone interface, so that software running in the M4 microprocessor can control each of the GPIO's.

If a particular application requires more than 32 GPIO pins, additional instantiations of this GPIO IP module can be inserted into the FPGA.

2 Address Map Specification

2.1 Memory Map

The EOS 3B system maps the FPGA IP into the address range of 0x40020000 to 0x4003FFFF. This address range provides 128K bytes of address range for FPGA based IP. Each instantiation of this GPIO IP module should be allocated a base address within the FPGA's address space. The register offsets described in this document are all relative to the GPIO IP's base address that you have chosen for your design. The GPIO IP module currently uses 256 bytes of address space, although this address space may not be fully utilized.

2.1.1 GPIO Address Table

Table 1 shows the allocation of the GPIO module's address space.

Table 1: GPIO Register Table

| Register | Register Name | Reset Value | Description |
|----------------|------------------------|-------------|-----------------------------------|
| 0x00 | GPIO Input Data | | Input data from each GPIO pin. |
| 0x04 | GPIO Output Data | 0x00000000 | Output data for each GPIO pin. |
| 0x08 | GPIO Direction Control | 0x00000000 | Output enables for each GPIO pin. |
| 0x0C - 0xFF | Reserved | 0×00 | |

2.2 Description of Registers

The following sections will detail the registers for the GPIO IP module.

2.2.1 Conventions

| Access Tag | Name | Meaning | |
|------------|-----------|---------------------------------------|--|
| R | Read | field may be read by the user/sw | |
| W | Write | field may be written by the user/sw | |
| U | Update | field may be updated by hardware | |
| S | Set | field may be set by the user | |
| С | Clear | field may be cleared by the user | |
| RO | Read Only | field can only be read by the user/sw | |

2.2.2 GPIO Registers

2.2.2.1 [0x00] GPIO Input Data

Each bit of this register corresponds to one GPIO, and each GPIO signal may be connected to one device pin. The input data seen by each GPIO may be read from this register.

Table 2: GPIO Input Data

| Name | Bit(s) | Туре | Description |
|---------------|--------|------|----------------------------|
| GPIO_IN[31:0] | [31:0] | RO | Input data from each GPIO. |

2.2.2.2 [0x04] GPIO Output Data

Each bit of this register corresponds to one GPIO, and each GPIO signal may be connected to one device pin. The output data to be driven out on each GPIO can be set in this register. Note that in order to drive a value out of the device, a given GPIO must be placed in "output mode" (see register 0x08: GPIO Direction Control).

Table 3: GPIO Output Data

| Name | Bit(s) | Туре | Description |
|----------------|--------|------|----------------------------|
| GPIO_OUT[31:0] | [31:0] | R/W | Output data for each GPIO. |

2.2.2.3 [0x08] GPIO Direction Control

This register controls the output-enable for each GPIO, thereby setting the direction for each GPIO (input mode vs. output mode).

Table 4: GPIO Output Data

| Name | Bit(s) | Туре | Description |
|---------------|--------|------|--|
| GPIO_OE[31:0] | [31:0] | R/W | Output-enable for each GPIO. 0 = input mode, tri-state 1 = output mode |

3 Revision History

| Date | Revision | Author | Description |
|------------|----------|---------|-----------------|
| 7 Oct 2020 | 1.00 | Randy O | Initial Release |
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