

Yousef Alaa Awad

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EDUCATION

University of Central Florida

Bachelor of Science in Computer Engineering | GPA: 3.73

Orlando, FL

Expected May 2027

SKILLS

Hardware Design & Verification: Verilog, SystemVerilog, RTL Design, Testbenches, Timing Closure, FPGA Prototyping

Hardware Tools: Vivado, ModelSim, Verilator, Synthesis, Simulation, XDC/SDC Constraints

Embedded Systems: ROS/ROS2, ESP32, Teensy 4.1, Sensor Integration, Real-Time C++, Firmware Optimization

Compiler Development: Custom Compiler Development, Lexical Analysis, Parsing, Binary Generation

Programming Languages: C++, C, Rust, Bash, Assembly (x86, RISC-V), Python

EXPERIENCE

Embedded Software Engineering Intern

Orlando, FL

Lockheed Martin Work Experience Program

Apr 2025 – Present

- Developed C++ tools to automate data analysis within the Hardware-in-the-Loop (HIL) testing environment, significantly reducing manual processing time by 20% and improving the efficiency of test result validation workflows.
- Optimized existing C++ scripts within the CI/CD pipeline to accelerate build and test execution speed, resulting in a 10% reduction in overall integration time and enhanced software release frequency for system updates.

Undergraduate Researcher

Orlando, FL

U.N.A.R.Y Lab

Sep 2024 – Present

- Developing a hardware compiler in Python that translates high-level YAML descriptions of a novel BCI architecture directly into an optimized unary/stochastic computational graph for hardware synthesis.
- Creating the hardware optimization stage for an integrated compiler pipeline, processing YAML specifications to produce optimized graphs and driver inputs, automating hardware abstraction for seamless, user-friendly high-level programming.

PROJECTS

REWORK: Chikorita Filter – FPGA Vision Accelerator

Aug 2025 – Present

- Architecting a low-latency FPGA DSP pipeline in Verilog/VHDL for the IEEE SoutheastCon Competition, implementing parallel modules for real-time vision preprocessing, motor control, and IR communication.
- Developing and verifying the FPGA-to-CPU interface (AXI/Memory-Mapped) to stream sensor data for Kalman filter processing, enabling successful hardware/software sensor fusion.

KnightCore – Full RISC-V SoC – 2025 AMD Hardware Competition

Apr 2025 – Aug 2025

- Collaborated within a 5-member team to design and implement a complete System-on-Chip (SoC), featuring a custom 32-bit RISC-V CPU and full custom GPU, capable of vector math and memory management on the Red Pitaya 125-14 board.
- Developed a comprehensive verification environment using the CocotB framework, creating testbenches for all modules. Authored directed and randomized stress tests, and assertion-based checks to ensure correctness and ISA compliance.

Anqa 32-bit RISC-V Processor

Feb 2025 – Present

- Designed a 32-bit RISC-V CPU core, implementing key components like a parameterized adder (half/full/multi-bit) and instruction decoding logic for the RV32I base instruction set (arithmetic, logical, load/store, branch).
- Developed a Verilog implementation plan using Vivado, detailing the ALU, register file, single-cycle datapath design, and instruction pipeline stages, with comprehensive documentation for future development.

CyndaQuil Compiler/Language

Sep 2024 – Jan 2025

- Designed and implemented 'CyndaQuilLanguage', a custom programming language, developing its compiler in C++ and C with Makefile and CMake, showcasing expertise in language design, parsing, and code generation for efficient execution.
- Engineered low-level system components and optimized performance, integrating Assembly and C to enhance hardware-software interfacing, ensuring minimal latency and efficient computation for embedded systems.

LEADERSHIP

IEEE UCF

Treasurer

Apr 2025 – Present

- Managed the IEEE UCF chapter's finances, developing and tracking over a \$6000+ budget across multiple projects and events, ensuring accurate allocation of resources and financial accountability.

SouthEastCon Hardware/Robotics Competition Software Lead

Sep 2024 – Apr 2025

- Led software pipeline for 10+ team using ROS2, enabling low-latency control between modular hardware and decision nodes. Used Gazebo and OpenCV for validation, contributing to 1st place in Design and 2nd in Performance at competition.
- Developed embedded firmware on Teensy 4.1 for sensor fusion and actuator control with modular, real-time C++ code. Optimized for high-frequency loops and low resource use, improving system responsiveness and performance.
- Managed Git/GitHub workflows with branching strategies, code reviews, and issue tracking to ensure team-wide consistency. Built CI/CD pipelines for automated testing and deployment, and implemented HIL testing for early hardware validation.