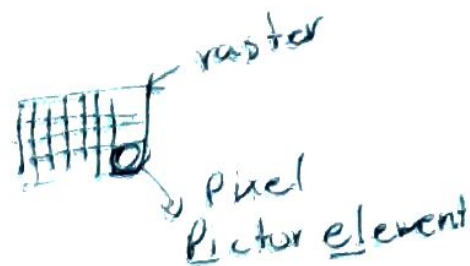


homogeneous transformations

graphics pipeline

input



- color ✓
- light
- vectors/normals
- geometrical info

transformations

- scale
- rotate
- translation

image

- resolution: 70 dpi
- dimension: H x W
- ratio: 16:9 (exact ratio)

3D model

set of 3D points, edges, faces

To simplify transformations.

we use homogeneous space / transformations

3D space \rightarrow H 3D space

$(x, y, z) \rightarrow (x, y, z, 1)$

$(\frac{x}{w}, \frac{y}{w}, \frac{z}{w}) \leftarrow (x, y, z, w)$

Scale

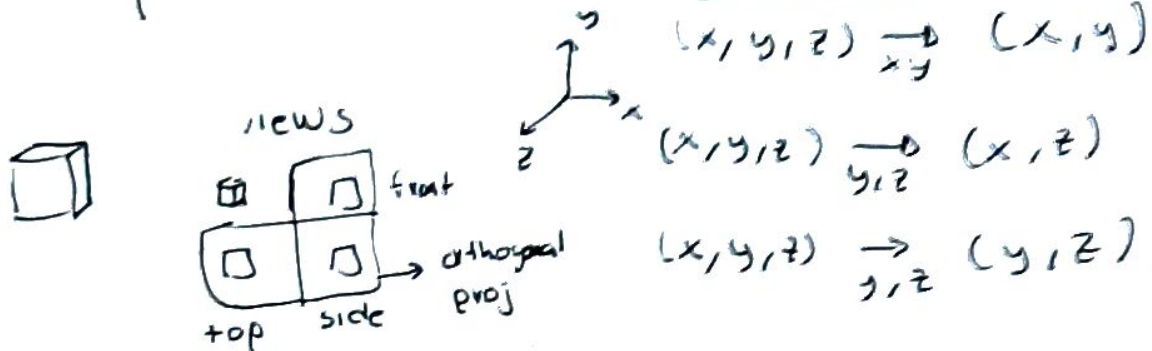
$$\begin{bmatrix} S_x & 0 & 0 \\ 0 & S_y & 0 \\ 0 & 0 & S_z \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} S_x \cdot x \\ S_y \cdot y \\ S_z \cdot z \end{bmatrix}$$

translation

$$\begin{matrix} 1 \times 4 \\ \begin{bmatrix} 1 & 0 & 0 & t_x \\ 0 & 1 & 0 & t_y \\ 0 & 0 & 1 & t_z \\ 0 & 0 & 0 & 1 \end{bmatrix} \end{matrix} \begin{matrix} P \\ \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} \end{matrix} = \begin{matrix} P1 \\ \begin{bmatrix} x + t_x \\ y + t_y \\ z + t_z \\ 1 \end{bmatrix} \end{matrix}$$

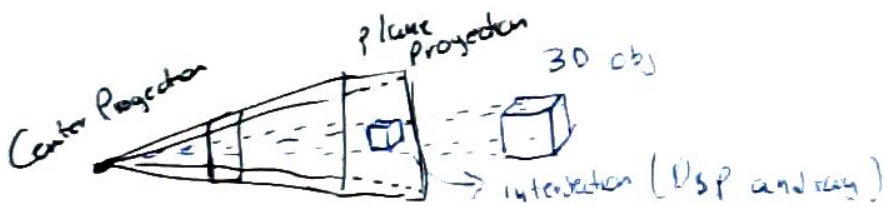
Changes in perspective.

Medium { -2D surface



Perspective projection

pinhole camera

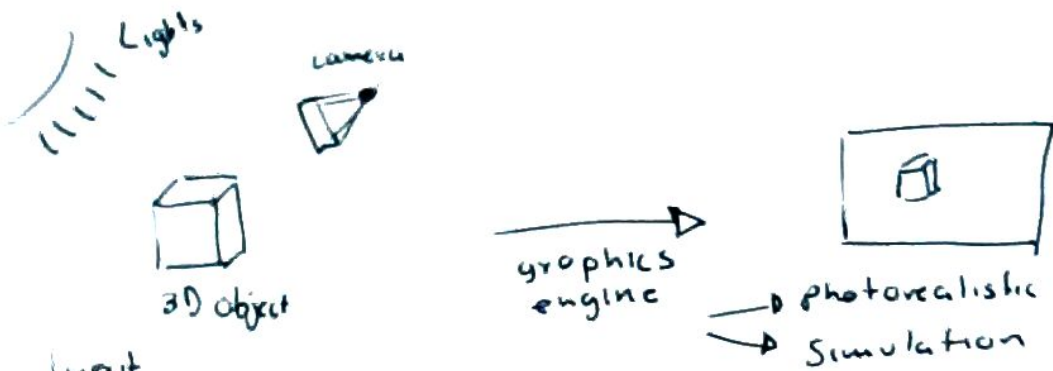


$$\begin{matrix} 3D \\ P(x, y, z) \end{matrix} \xRightarrow{f} \begin{matrix} 2D \\ \left(\frac{x \cdot f}{z}, \frac{y \cdot f}{z} \right) \end{matrix}$$

Matrix Proj P $P^{-1}H$ $P^{-1}3D$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & \frac{1}{f} & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \\ \frac{z}{f} \end{bmatrix} \Rightarrow \begin{bmatrix} \frac{x \cdot f}{z} \\ \frac{y \cdot f}{z} \\ \frac{z}{f} \\ 1 \end{bmatrix}$$

Graphic primitives (operations)



Input

- 3D obj
- lights
- material
- camera
- Textures
- shadows
- extra

H S V
↓ ↓ ↘ value
Hue Saturation