

$$2.3) B.10.6) G(s) = \frac{Y(s)}{U(s)} = \frac{10}{(s+1)(s+2)(s+3)} = \frac{10}{s^3 + 3s^2 + 11s + 6}$$

Colocando as matrizes na forma controlável:

$$A_{c1} = \begin{bmatrix} -a_2 & -a_1 & -a_0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -3 & -11 & -6 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} ; \quad B = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$C = [a_2 \ a_1 \ a_0] = [0 \ 0 \ 10] ; \quad D = [0]$$

Para os novos polos, calcularemos  $A_{c2}$ :

$$\Delta(s) = (s+2+j2\sqrt{3})(s+2-j2\sqrt{3})(s+10) = (s^2 + (2+j2\sqrt{3})s + (2-j2\sqrt{3})s)(s+10)$$

$$\Delta(s) = (s^2 + 4s + 16)(s+10) = s^3 + 14s^2 + 56s + 160$$

$$A_{c2} = \begin{bmatrix} -a_2 & -a_1 & -a_0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} -14 & -56 & -160 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \rightarrow A_{c2} = A_{c1} - BK$$

$$\begin{bmatrix} -14 & -56 & -160 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} -3-K_1 & -11-K_2 & -6-K_3 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \rightarrow \begin{aligned} -14 &= -3-K_1 \\ -56 &= -11-K_2 \\ -160 &= -6-K_3 \end{aligned}$$

$$\left. \begin{aligned} K_1 &= -3+14 = 11 \\ K_2 &= -11+56 = 45 \\ K_3 &= -6+160 = 154 \end{aligned} \right\} K = [11 \ 45 \ 154] //$$